

# Automatically Speeding Up LOCAL Algorithms

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Naor, Stockmeyer, SICOMP 1995

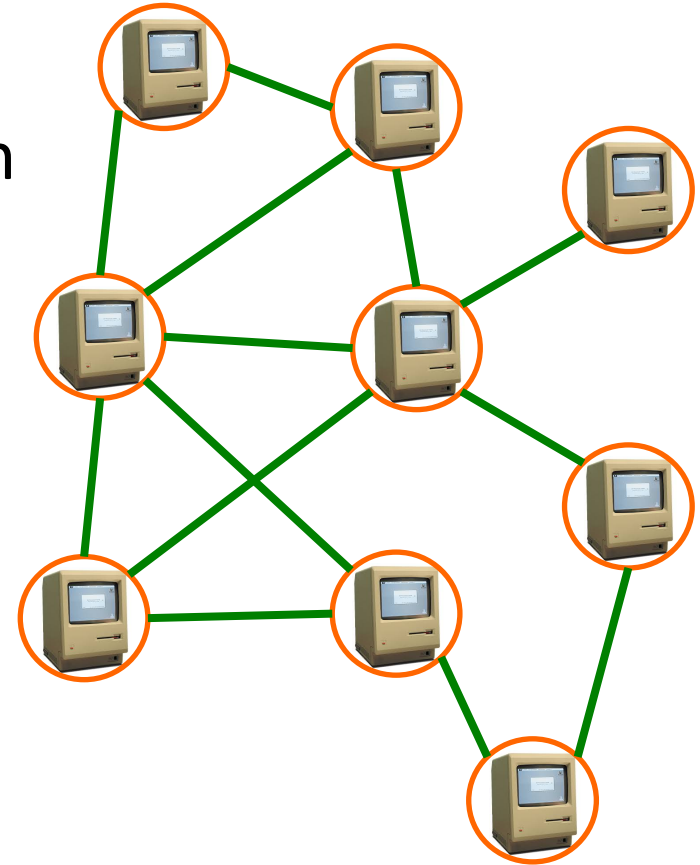
Chang, Kopelowitz, Pettie, FOCS 2016

Chang, Pettie, FOCS 2017, SICOMP 2018

# The LOCAL Model

[Linial'92]

- A graph  $G=(V,E)$ 
  - **Vertex** = processor
  - **Edge** = bidirected communication
  - Time: ***synchronized*** rounds. In each round, each vertex sends a message to each neighbor.
  - ***Computation is free.***
  - ***Message size is unbounded.***
  - “Time” = number of rounds
- ***Randomized*** LOCAL
  - Can generate an ***unbounded number of random bits***



# The LOCAL Model

[Linial'92]

- What a vertex  $v$  knows:
  - Global graph parameters:  $n = |V|$ ,  $\Delta = \max_u \deg(u)$
  - A unique  $O(\log n)$ -bit  $ID(v)$ .
  - A *port-numbering* of its  $\deg(v)$  incident edges.

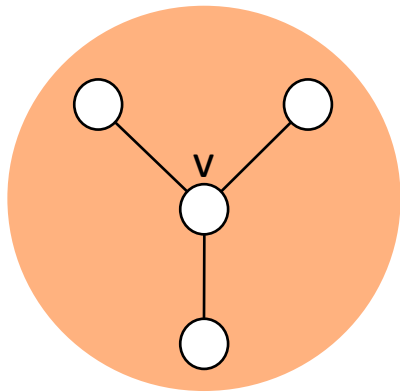
# The LOCAL Time Hierarchy

- Q: Which *time complexities* are obtainable by “*natural*” problems.
  - To reduce the number of problem parameters, assume  $\Delta = O(1)$ .

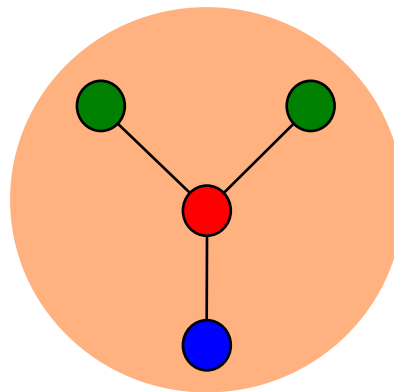
# What is a “*natural problem*” ?

[Naor-Stockmeyer'95]

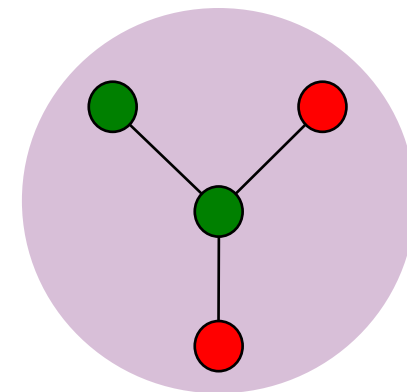
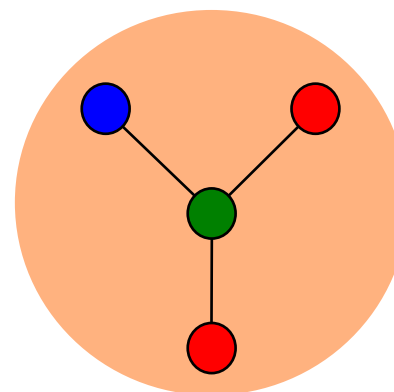
- Locally Checkable Labeling (LCL) problem:  $\text{NTIME}(O(1))$ 
  - Input and Output alphabets  $\Sigma_{\text{in}}, \Sigma_{\text{out}}$ , integer radius  $r$ .
    - $|\Sigma_{\text{in}}|, |\Sigma_{\text{out}}|$  may depend on  $\Delta$ , but are independent of  $n$ .
  - Set  $\mathbf{C}$  of acceptable radius- $r$  centered subgraphs.
- Problem: given  $V \rightarrow \Sigma_{\text{in}}$ , compute  $V \rightarrow \Sigma_{\text{out}}$  such that every vertex's radius- $r$  view is in  $\mathbf{C}$ .



radius-1 view from  $v$



some acceptable configurations for 3-coloring.



an unacceptable configuration

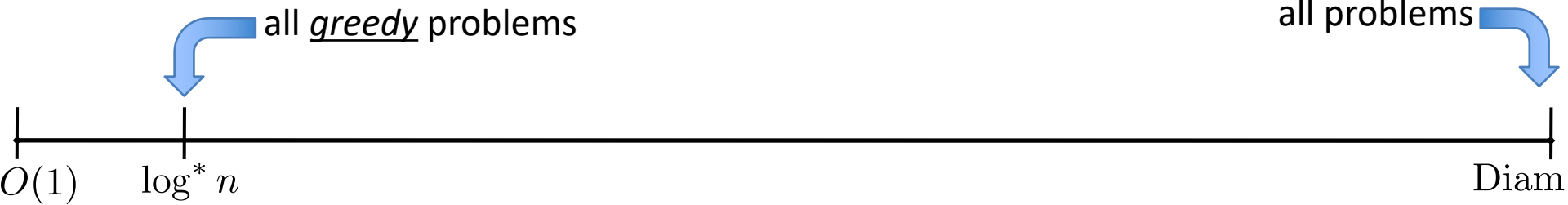
# Greedy vs. Nongreedy LCL Problems

- The canonical **greedy** problems:
  - Maximal independent set
  - Maximal matching
  - $(\Delta+1)$ -vertex coloring
  - $(2\Delta-1)$ -edge coloring

} every partial solution extends to a total solution
- Some **non-greedy** problems
  - (approximate) maximum matching
  - Sinkless orientation
  - $\Delta$ -vertex coloring
  - $(2\Delta-2)$ -edge coloring
  - Frugal coloring
  - Defective coloring
  - Versions of List coloring, etc.

# Time Hierarchies: $\Delta=O(1)$

1.  $O(\Delta^2)$ -color the graph in  $\log^* n$  time. [Linial's algorithm '92]
2. Apply greedy algorithm to each color class, one at a time.

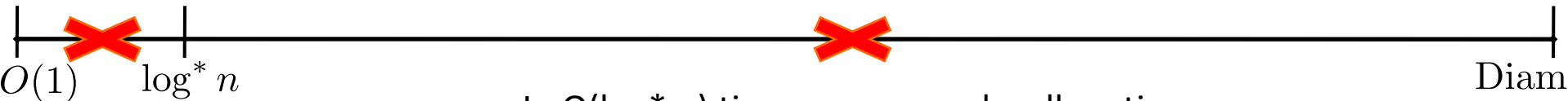


# Time Hierarchies: $\Delta=O(1)$

$n$ -path/cycle,  $(\sqrt{n} \times \sqrt{n})$ -grid/torus

Naor, Stockmeyer'95

via hypergraph Ramsey argument...  
any  $O(1)$  time algorithm can be made  
*order-invariant* w.r.t. vertex IDs.



In  $O(\log^* n)$  time, we can make all vertices  
**think** they are in an  $O(1)$ -size path/cycle/grid/torus.

Chang, Pettie'17

Brandt, Hirvonen, Korhonen, Lempiäinen,  
Östergård, Purcell, Rybicki, Suomela'17

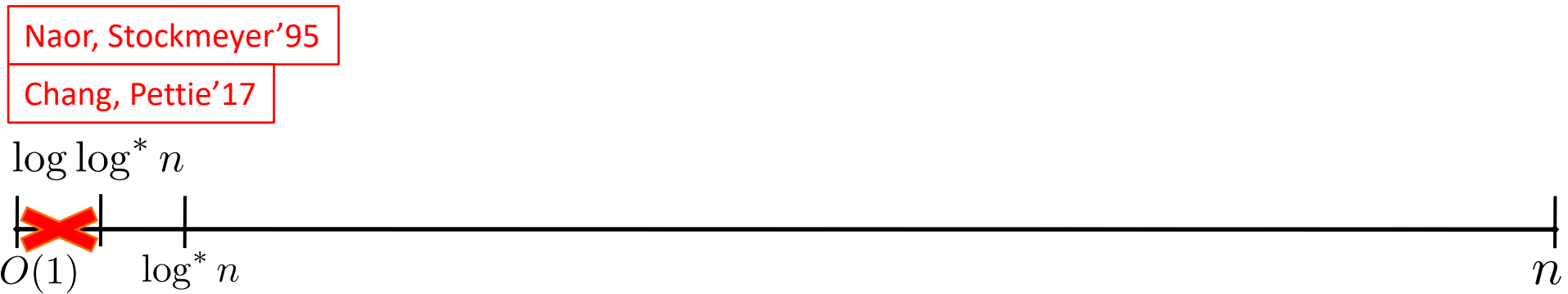
Chang, Kopelowitz, Pettie'16

Brandt, Hirvonen, Korhonen, Lempiäinen,  
Östergård, Purcell, Rybicki, Suomela'17



# Time Hierarchies: $\Delta=O(1)$

## General graphs, Trees

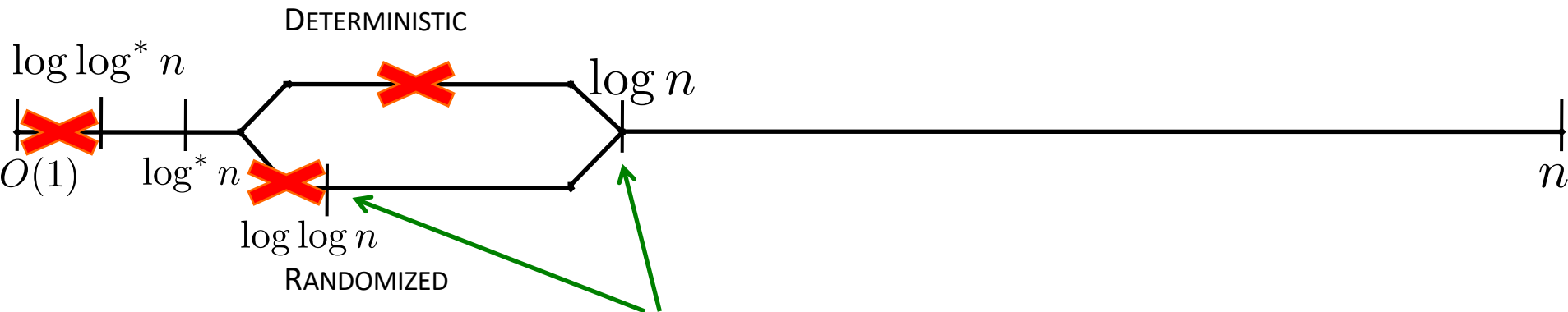


# Time Hierarchies: $\Delta=O(1)$

## General graphs, Trees

Chang, Kopelowitz, Pettie'16

$$\text{Det}_{\mathcal{P}}(n, \Delta) \leq \text{Rand}_{\mathcal{P}}(2^{n^2}, \Delta)$$



### Exponential Separations:

- $\Delta$ -coloring degree- $\Delta$  trees
- Sinkless Orientation
- $(2\Delta-2)$ -edge coloring trees

Brandt, Fischer, Hirvonen, Keller, Lempiäinen, Rybicki, Suomela, Uitto'16

Chang, Kopelowitz, Pettie'16

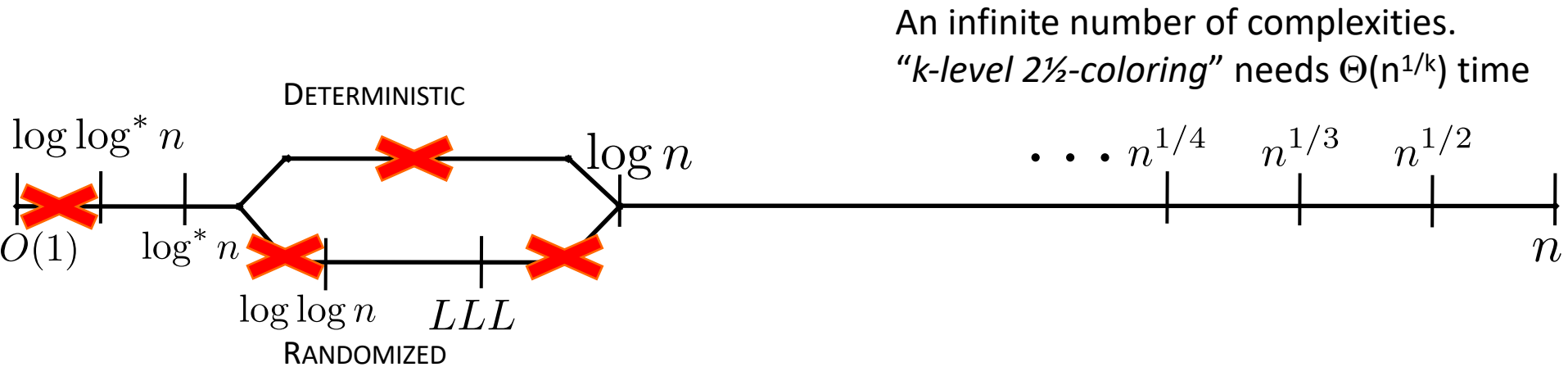
Pettie, Su'15

Ghaffari, Su'17

Chang, He, Li, Pettie, Uitto'18

# Time Hierarchies: $\Delta=O(1)$

## General graphs, Trees

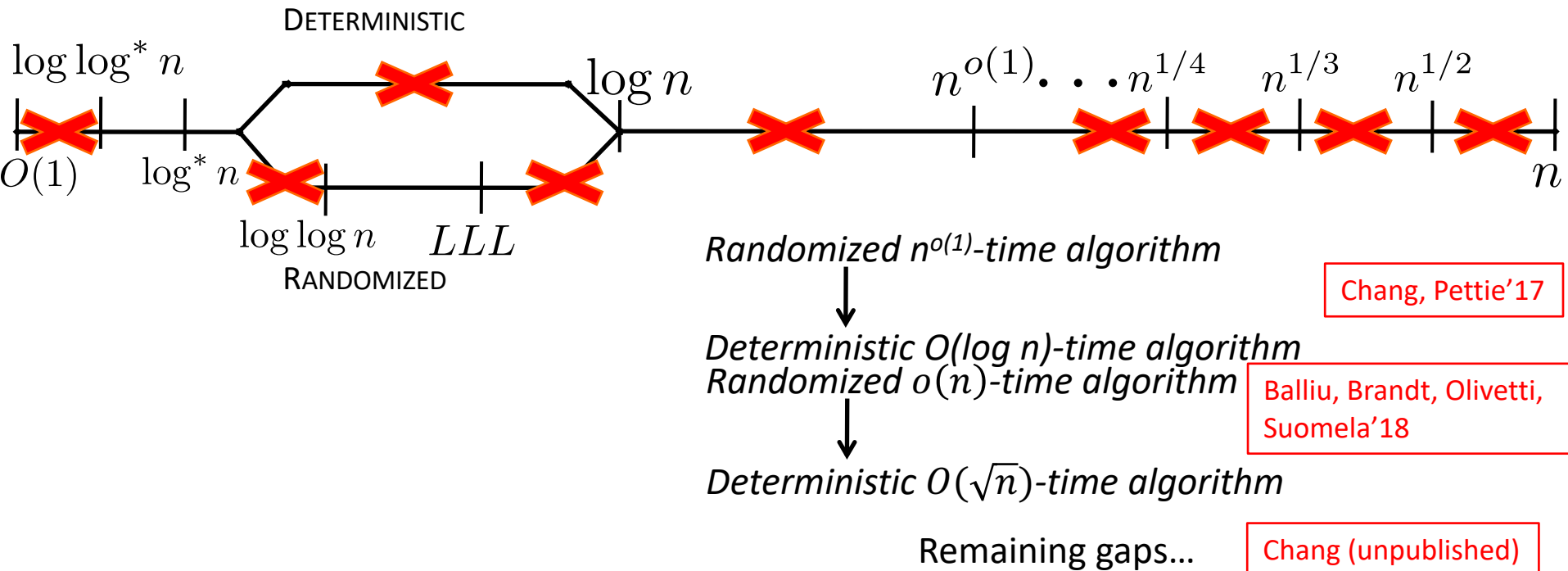


***Lovász Local Lemma is “complete” for sublogarithmic randomized time!***

Every  $o(\log n)$ -time randomized algorithm can be automatically sped up to run in  $O(LLL)$  time.

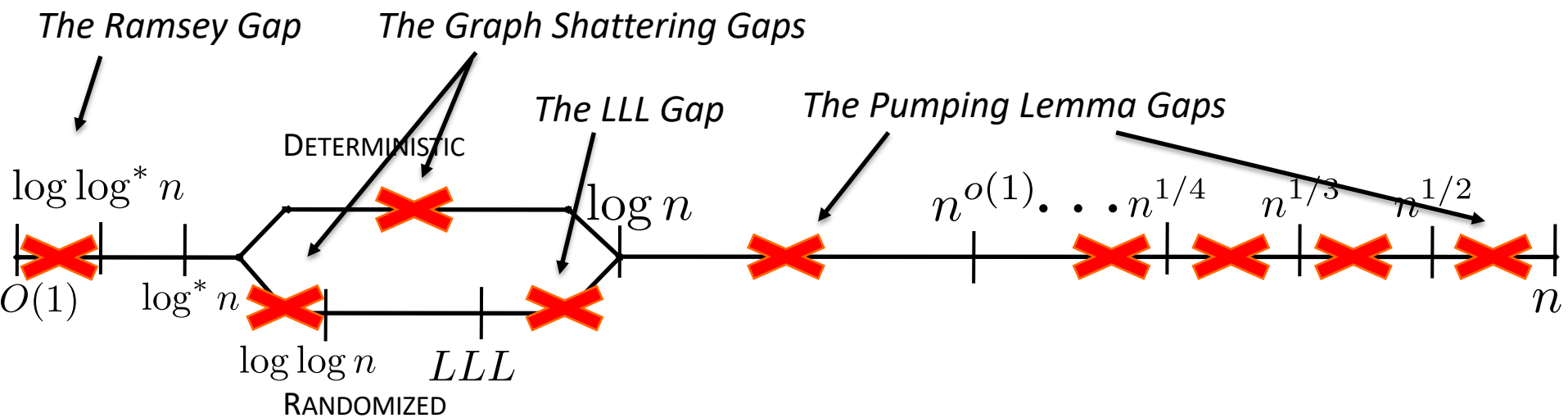
# Time Hierarchies: $\Delta=O(1)$

## Trees



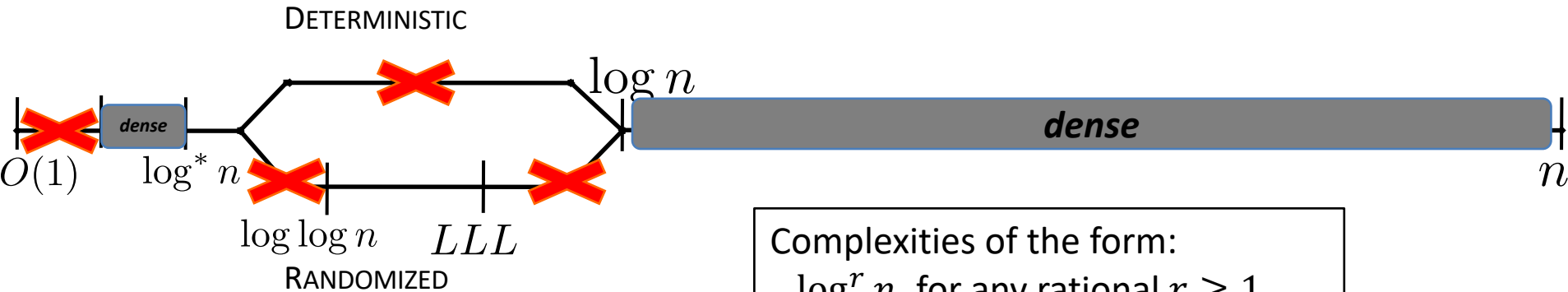
# Time Hierarchies: $\Delta=O(1)$

## Trees



# Time Hierarchies: $\Delta=O(1)$

## General Graphs



Complexities of the form:

- $\log^r (\log^* n)$ , for any rational  $r \geq 1$ .
- $2^{\log^r (\log^* n)}$ , for any rational  $r \in (0,1)$
- $(\log^* n)^r$ , for any rational  $r \in (0,1)$

Complexities of the form:

- $\log^r n$ , for any rational  $r \geq 1$ .
- $2^{\log^r n}$ , for any rational  $r \in (0,1)$
- $n^r$ , for any rational  $r \in (0,1)$
- $\frac{n}{\log^r n}$ , for any integer  $r \geq 1$

Balliu, Hirvonen, Korhonen, Keller,  
Lempiäinen, Olivetti, Suomela 2018

Balliu, Brandt, Olivetti, Suomela 2018

# Little white lies

- What does “n” refer to in the LOCAL model?
  - (1)  $n = |V|$  = size of the graph.
  - (2)  $O(\log n)$  = bits in vertex IDs.
  - (3)  $1/\text{poly}(n)$  = standard error bound for *randomized* algs.

# The Ramsey Gap

[Naor-Stockmeyer'95], [Chang-Pettie'17]

- **Step 1**: Show that any sufficiently fast algorithm can be made “order invariant.”
- **Step 2**: Show that any order invariant algorithm can be tricked into thinking  $n=O(1)$ .

General algorithm

```
...  
Z = MSB(ID(u) XOR ID(v))  
...
```

Order-invariant algorithm

```
...  
If (ID(u) < ID(v)) then  
    ...  
Else  
    ...  
...
```



- $R = R(p, m, c)$  : any  $c$ -coloring of the edges of a  $p$ -uniform hypergraph with  $R$  vertices has a monochromatic  $m$ -clique.

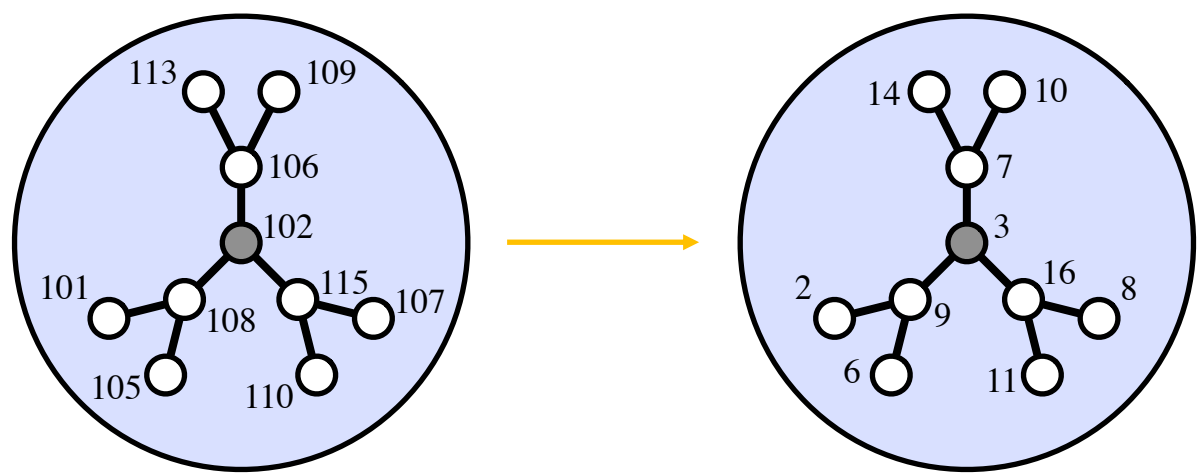
$$p = 1: R(p, m, c) = c(m - 1) + 1$$

$$p > 1: R(p, m, c) \leq 2c^{R(p-1, m, c)^p}$$

- $\log^*(R(p, m, c)) = p + \log^*(m) + \log^*(c) + O(1)$

- Some algorithm runs in  $t = o(\log(\log^* n))$  time and solves an LCL problem with radius  $r$ .
  - $p = \Delta^t$  upper bound on number of IDs we can see.
  - $m = \Delta^{t+r}$
- Consider  $p$  IDs  $x_1 < x_2 < x_3 < \dots < x_p$
- The **color** of hyper-edge  $(x_1, x_2, \dots, x_p)$  encodes
  - For every distinct radius- $t$  subgraph  $H$  centered @  $v$ ,
    - For every one of  $p!$  assignments of IDs to nodes in  $H$ ,
      - The output of  $v$  when the algorithm is run with this ID assignment and neighborhood  $H$ .

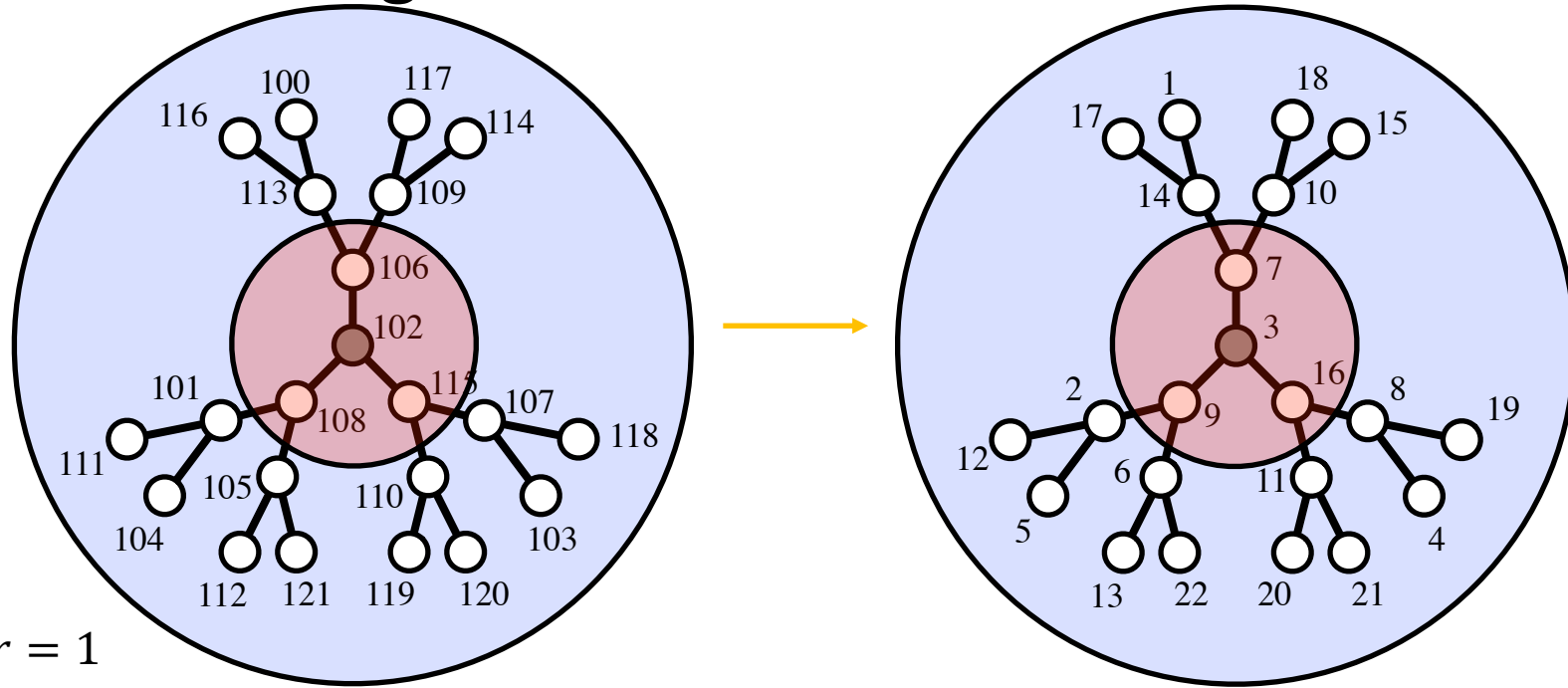
- There exists a monochromatic  $m$ -clique. W.l.o.g., suppose  $S = \{1,2,3, \dots, m\}$  is monochromatic.
- New algorithm:  $H = t$ -neighborhood of  $v$ . Reassign IDs in  $H$  to be from  $S$  in an *order-preserving* way. Run the old algorithm.



$t = 2, r = 1$

Map IDs to  $\{2,3,6,7,8,9,10,11,14\}$

- There exists a monochromatic  $m$ -clique. W.l.o.g., suppose  $S = \{1,2,3, \dots, m\}$  is monochromatic.
- New algorithm:  $H = t$ -neighborhood of  $v$ . Reassign IDs in  $H$  to be from  $S$  in an *order-preserving* way. Run the old algorithm.



# The “Graph Shattering” Gaps

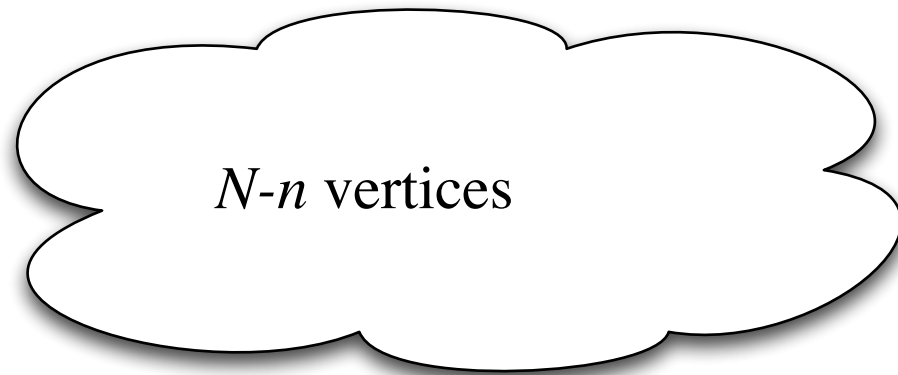
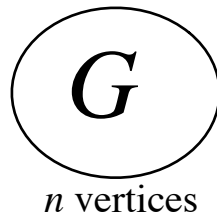
[Chang, Kopelowitz, Pettie'16]

- No **det.** complexities in  $\omega(\log^* n) - o(\log n)$ 
  - **Theorem.** Any  $o(\log n)$ -time *deterministic* algorithm can be sped up to run in  $O(\log^* n)$  time.
- No **rand.** complexities in  $\omega(\log^* n) - o(\log \log n)$ 

Alt. proof: [Fischer, Ghaffari'17]
- **Theorem.** If  $A_{rand}$  solves an LCL in  $T(n, \Delta)$  time with failure probability  $1/n$ , then there exists an  $A_{det}$  that solves it in  $T(2^{n^2}, \Delta)$  time.

# Derandomization

- $A_{rand}$  generates a string of  $r(n)$  random bits.
- $A_{det}$  will generate “random” bits using a ***magic*** function  $\phi : \{0,1\}^{O(\log n)} \rightarrow \{0,1\}^{r(n)}$ .
  - $v$ 's string of local random bits will be  $\phi(ID(v))$ .
- Imagine running  $A_{det}$  on  $G$  with a ***random***  $\phi$ , but telling vertices they're in a graph with  $N = 2^{n^2}$  vertices.



Probability of failure  $< 1/N$ .

- The probability that a *random*  $\phi$  fails to work for *every* graph topology and *every* ID-assignment is

$$2^{\binom{n}{2}} \cdot 2^{O(n \log n)} \cdot \left(\frac{1}{N}\right) < 1$$

Number of graphs      Number of ID assignments      Failure prob.

- Hence there is exists a magic  $\phi$  that always works!

$$Det(n, \Delta) \leq Rand(2^{n^2}, \Delta)$$

# A Randomized Complexity Gap

- **Theorem.** No randomized LCL complexities in  $\omega(\log^* n) - o(\log \log n)$ .

**Proof.** Suppose  $A_{rand}$  solves some LCL in  $o(\log \log n)$  time.

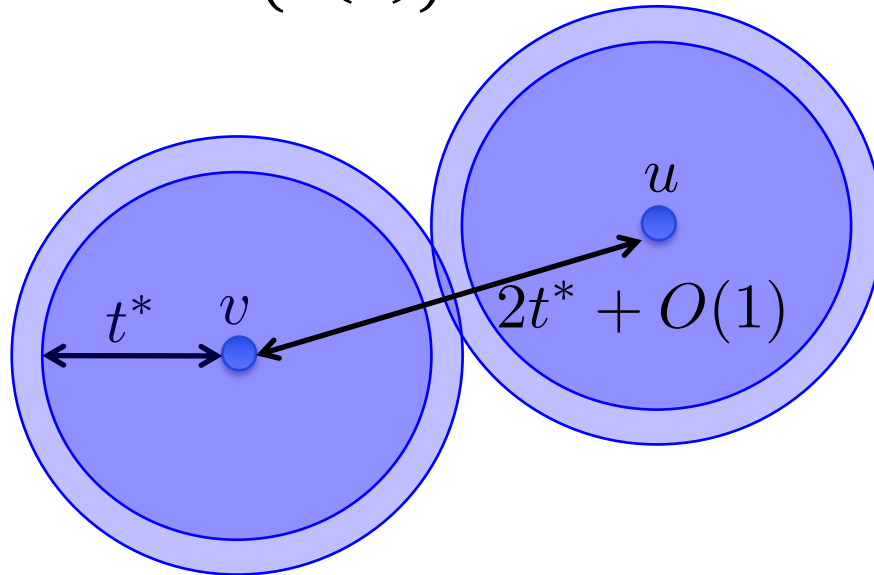
- This implies an  $A_{det}$  that solves it in  $o(\log n)$  time.
- Any deterministic  $o(\log n)$ -time algorithm can be sped up to run in  $O(\log^* n)$  time. [Chang, Kopelowitz, Pettie'16]



# The Lovasz Local Lemma Gap

- The *distributed* (symmetric) LLL problem:
  - Network and dependency graph  $G=(V,E)$  are identical
  - $V$  : “bad events”;  $u \in V$  depends on set of discr. r.v.s  $vbl(u)$
  - $E = \{(u,v) : vbl(u) \cap vbl(v) \neq \emptyset\}$
  - $d$  = maximum degree in  $G$ ,  $p$  = maximum  $\Pr(v)$ .
    - Satisfies some **LLL Criterion**, e.g.,  $ep(d+1) < 1$ ,  $p(ed)^c < 1$ .
- Compute a variable assignment such that no bad event occurs.

- Suppose  $A$  solves some LCL problem in *sublogarithmic* time with failure probability  $1/n$ .
  - For any  $\varepsilon > 0$ , can write time as  $T(n, \Delta) \leq C(\Delta) + \varepsilon \log_{\Delta} n$
- $n^* = \min.$  value such that:  $T(n, \Delta) = t^* \leq \frac{1}{2c} \log_{\Delta} n^* - O(1)$ 
  - Follows that  $t^* = O(C(\Delta))$ .



every vertex sees a subgraph that is *consistent with an  $n^*$ -vertex graph.*

- Build the dependency graph:
  - $X_v$  = the random bits generated locally at  $v$ .
  - $\text{vbl}(v) = \{X_u \mid u \in N^{t^*+O(1)}(v)\}$
  - $E_v$  = the event that  $v$ 's neighborhood is incorrectly labeled, when running alg. A with “ $n$ ” =  $n^*$ .
  - $H = (\{E_v\}, \{(E_u, E_v) \mid \text{dist}(u, v) \leq 2t^*+O(1)\})$
  - LLL parameters:  $p = 1/n^*$ ,  $d = \Delta^{2t^*+O(1)}$ 

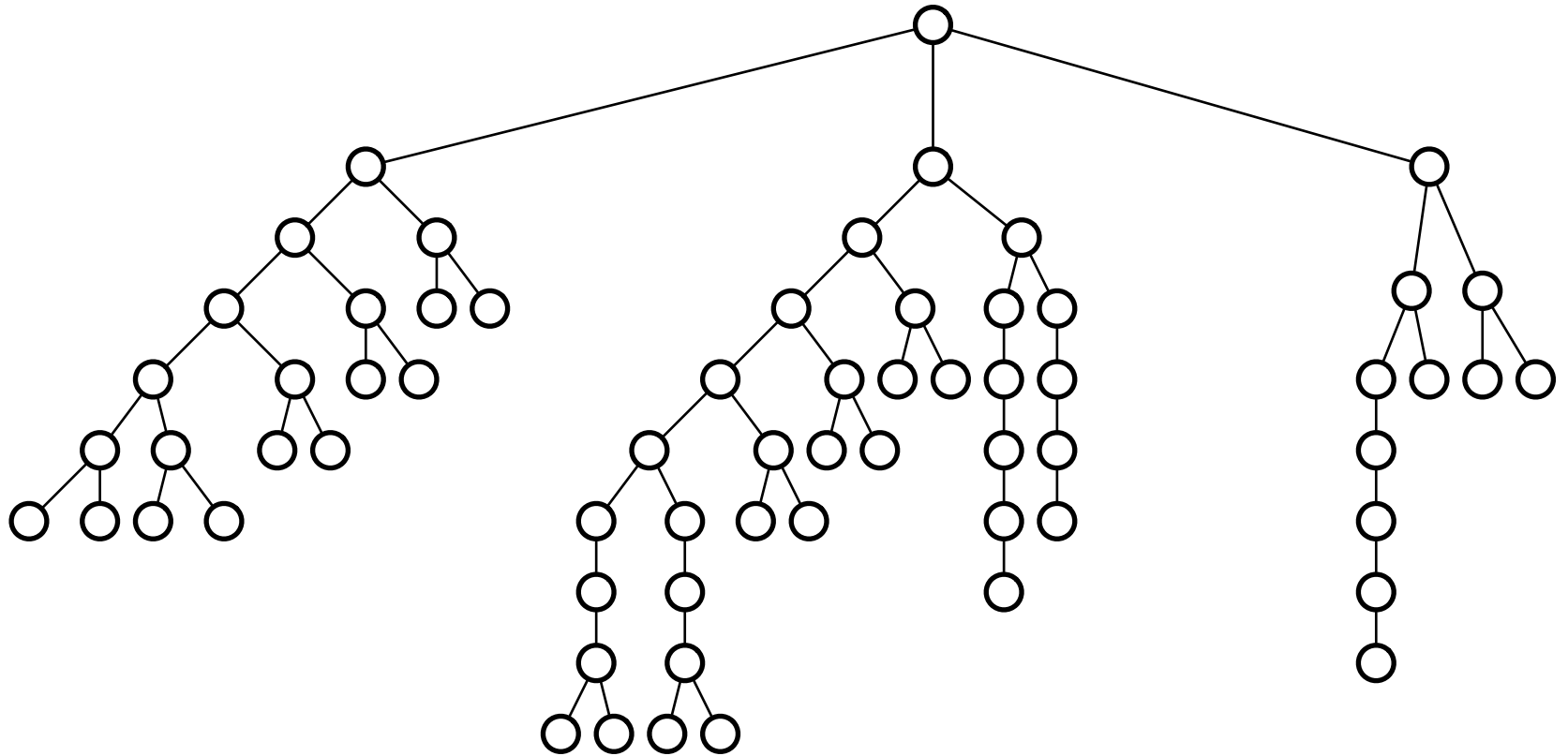
$$pd^c = p \cdot \Delta^{c(2t^*+O(1))} < (1/n^*)n^* = 1$$
- Run a distributed LLL algorithm on “H.”
  - 1 step in H simulated with  $O(C(\Delta))$  steps in G.
  - Alg. A can be automatically sped up to  $O(C(\Delta) \cdot T_{\text{LLL}})$  time.

# Pumping Lemma Speedups

- **Theorem:** any *randomized*  $n^{o(1)}$ -time LCL algorithm on *trees* can be converted into a *deterministic*  $O(\log n)$ -time algorithm.

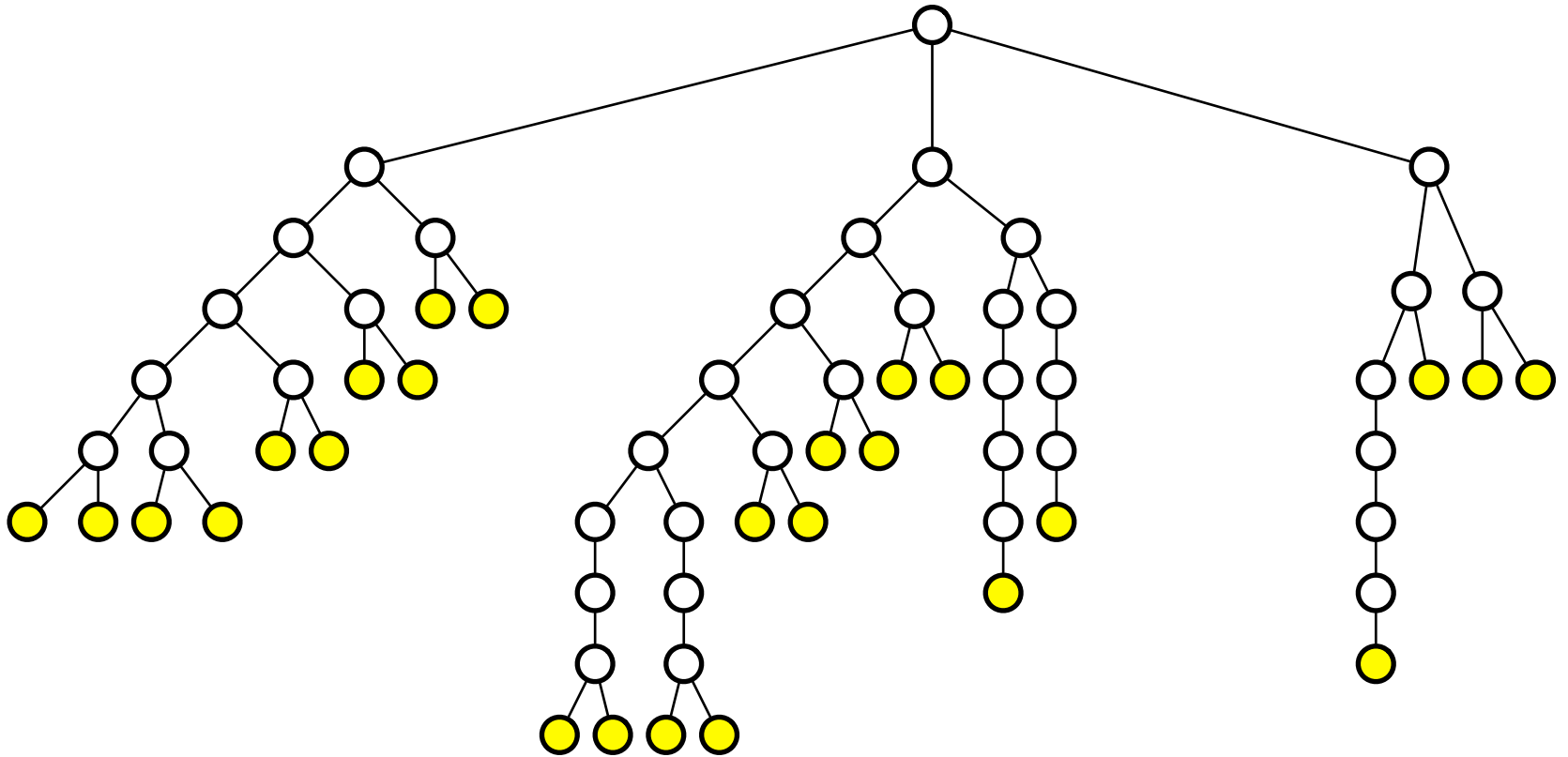
# Rake and Compress

[Miller and Reif 1989]



# Rake and Compress

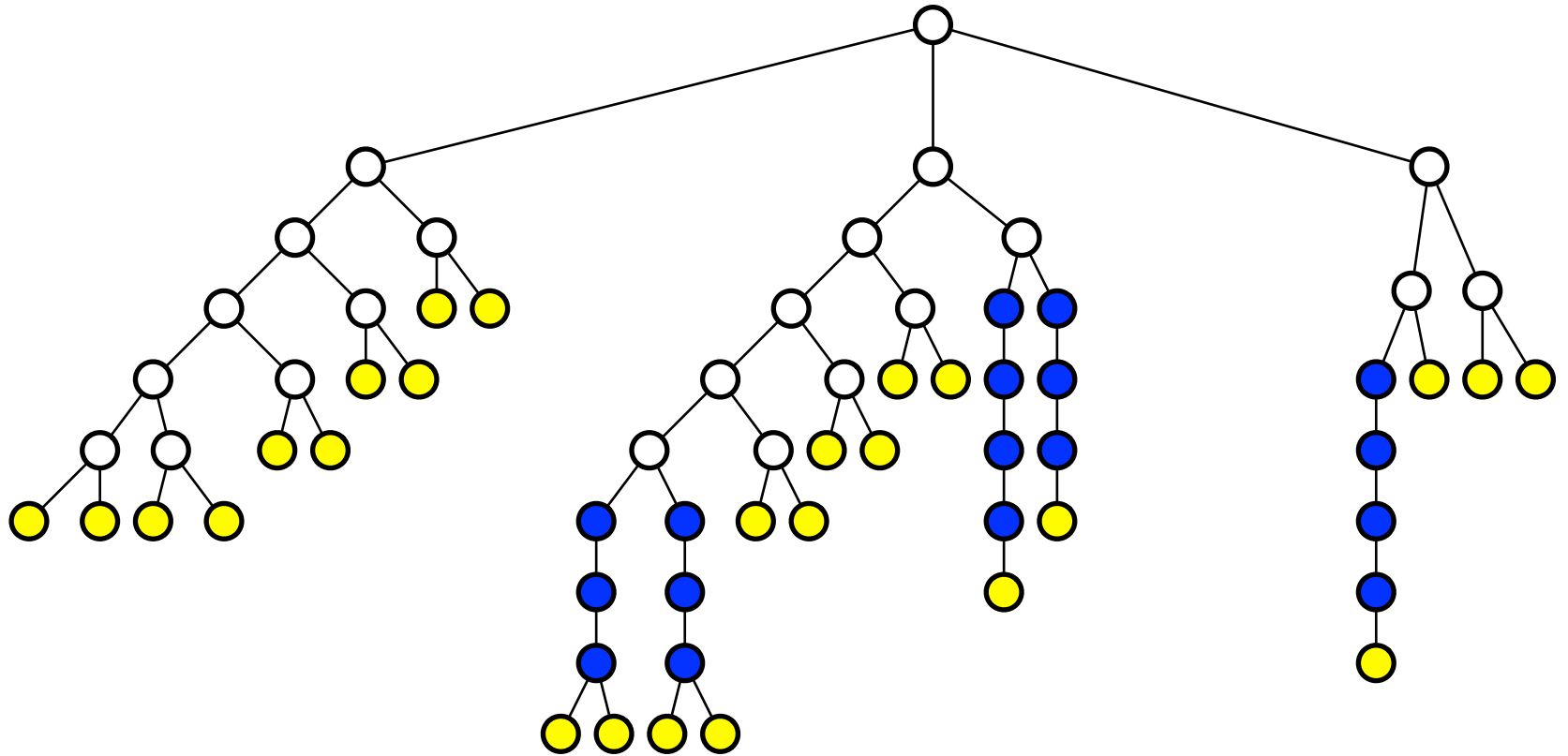
[Miller and Reif 1989]



- ***Rake***: remove all leaves

# Rake and Compress

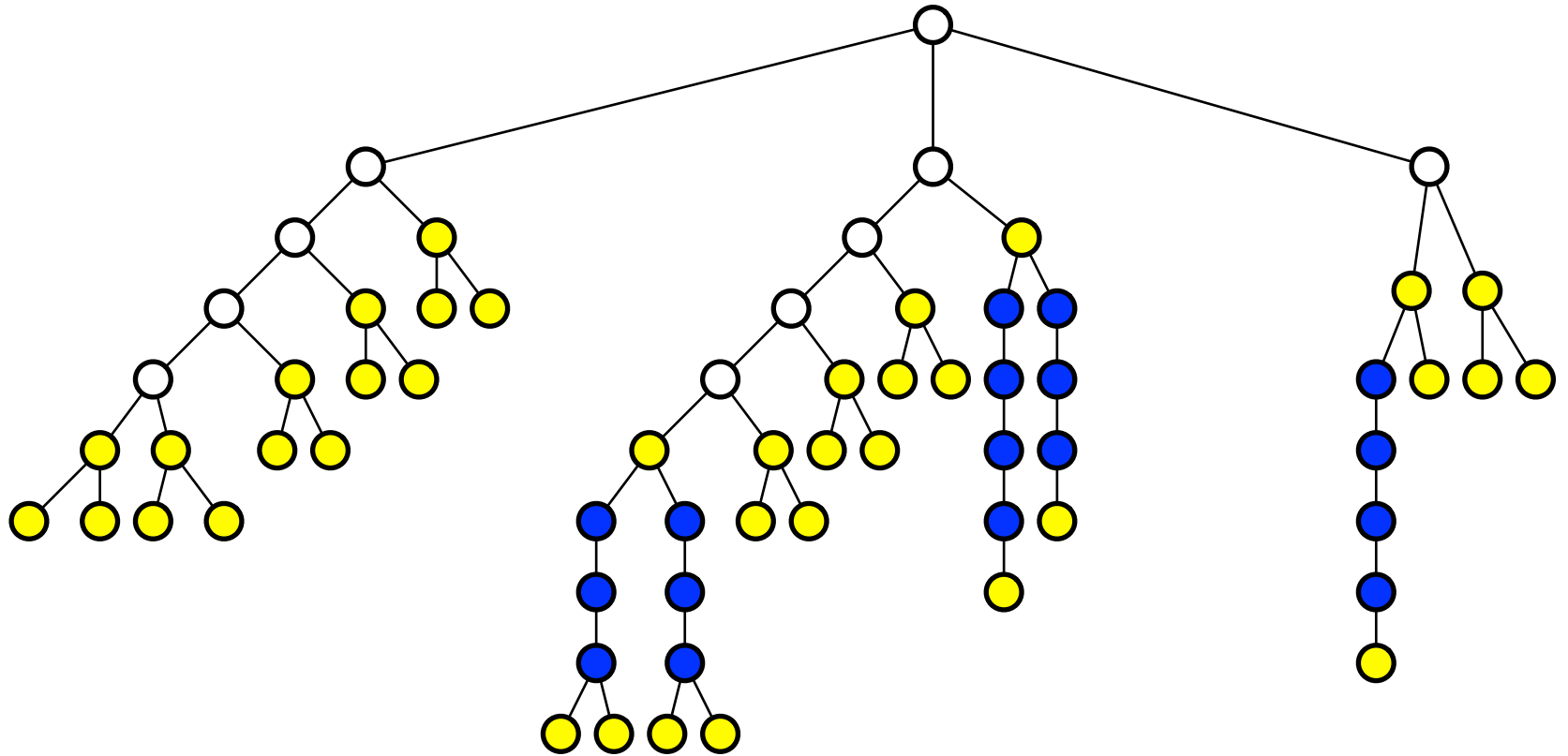
[Miller and Reif 1989]



- ***Rake***: remove all leaves
- ***Compress***: remove chains of degree-2 vertices.

# Rake and Compress

[Miller and Reif 1989]



- **Rake:** remove all leaves
- **Compress:** remove chains of degree-2 vertices.







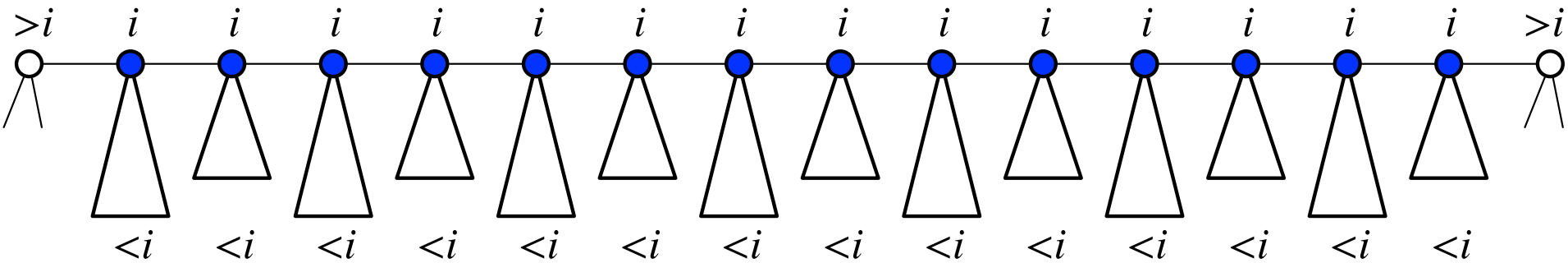
# Rake and Compress

[Miller and Reif 1989]

- **Case 1:**  $O(\log n)$  rakes suffice to decompose the tree
  - Diam. =  $O(\log n)$ ; any LCL can be solved in  $O(\log n)$  time.
- **Case 2:** compress occasionally removes  $\omega(1)$ -length paths.

# Removing Long Paths

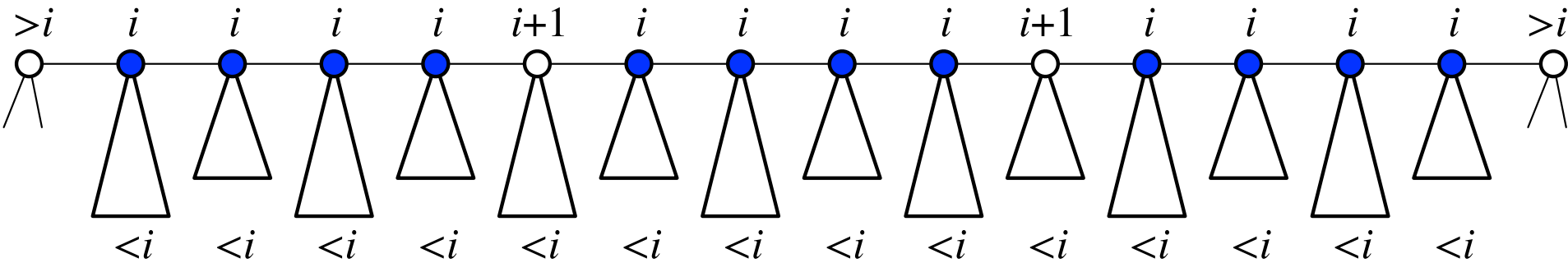
[Miller and Reif 1989]



- A sufficiently long path of **nodes** removed in  $i^{\text{th}}$  iteration
- Subtrees removed in iterations  $< i$ .
- Bookended by nodes removed in iteration  $> i$ .

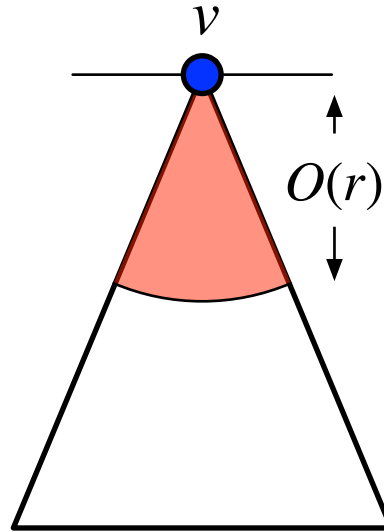
# Removing Long Paths

[Miller and Reif 1989]



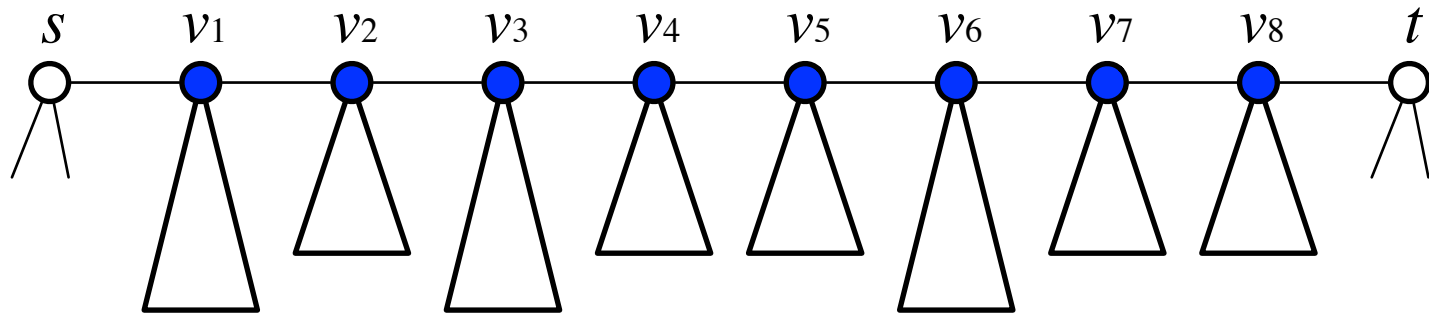
- A sufficiently long path of **nodes** removed in  $i^{\text{th}}$  iteration
- Subtrees removed in iterations  $< i$ .
- Bookended by nodes removed in iteration  $> i$ .
- Can assume w.l.o.g. that the path has **length  $O(1)$**  by “promoting” a well-spaced set of nodes to level- $(i+1)$ .

# Class



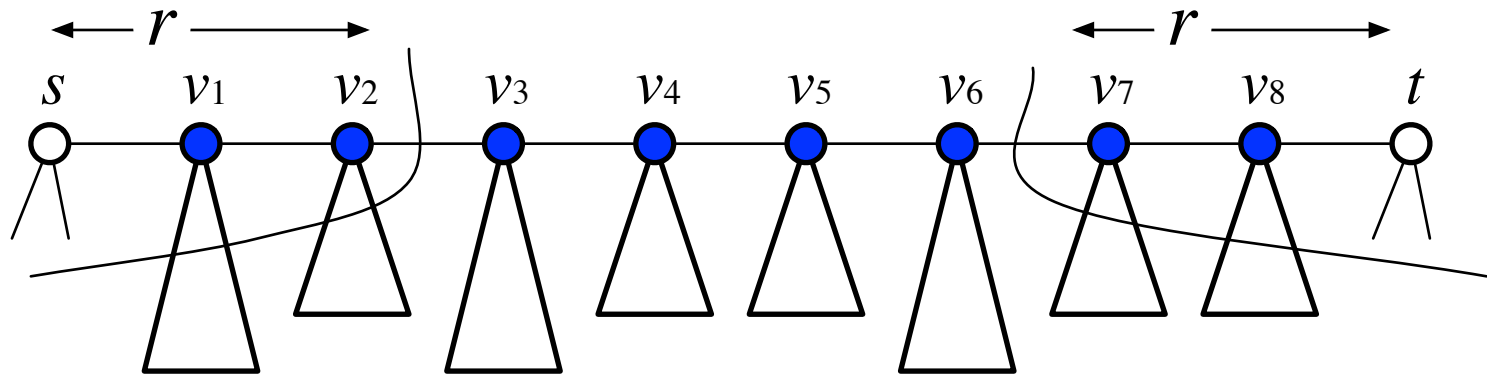
- ***Class*( $v$ )** : the set of all labelings of  $N^{O(r)}(v)$  that can be extended to the ***whole*** subtree rooted at  $v$ .
- # Classes =  $O(1)$ . ( $\Delta$  and  $\Sigma_{out}$  constants.)

# Type



- $c_i = \text{Class}(v_i)$
- Relevant information ( $c_1, c_2, c_3, \dots$ )

# Type

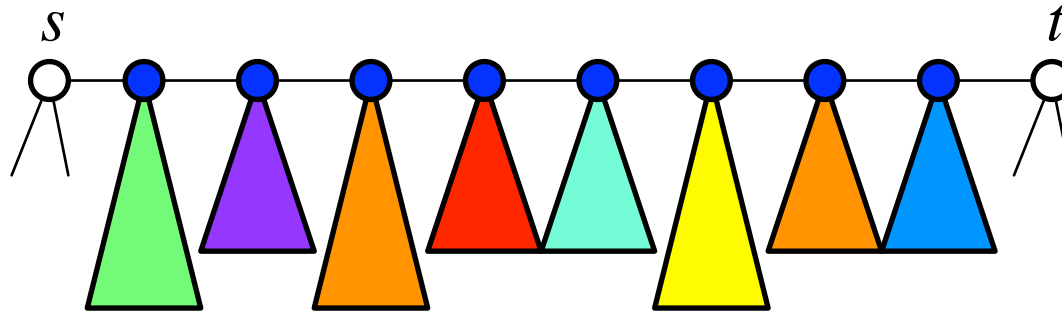


- $c_i = \text{Class}(v_i)$
- Relevant information  $(c_1, c_2, c_3, \dots)$
- **Type(s,t)** : set of all labelings of  $N^r(s) \cup N^r(t)$  that can be extended to subtrees of  $v_1, v_2, \dots$
- Type(s,t) computable by a finite automaton that scans class vector  $(c_1, c_2, c_3, \dots)$ .

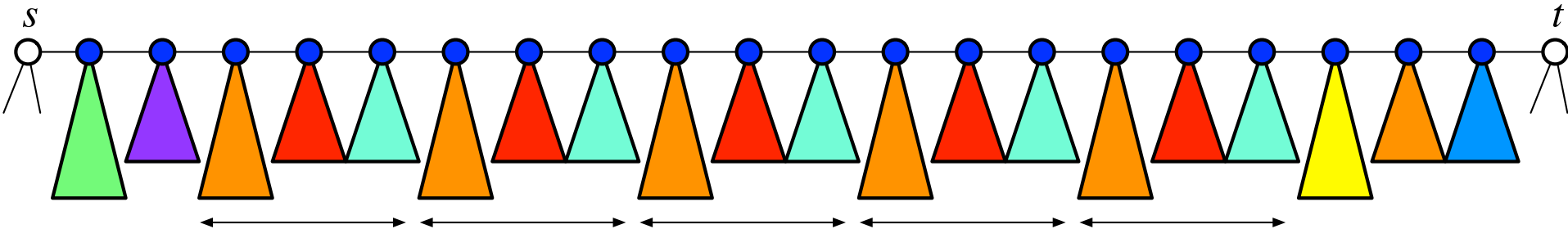


# Pumping Trees

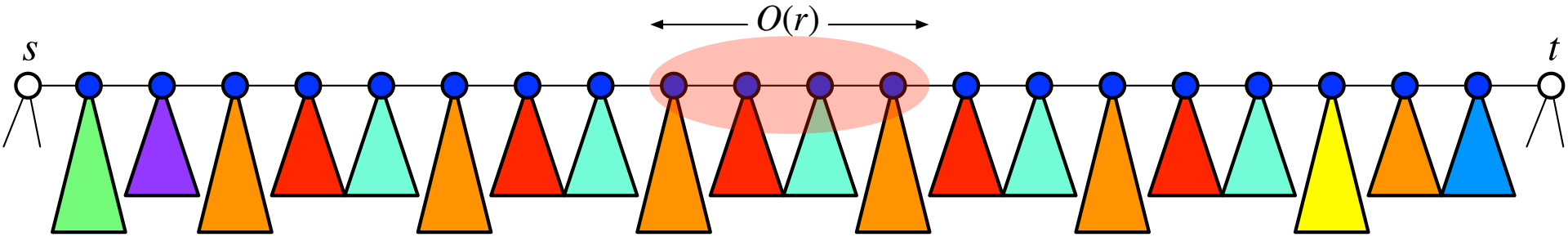
- If the path is sufficiently long, the automaton will enter some state twice.



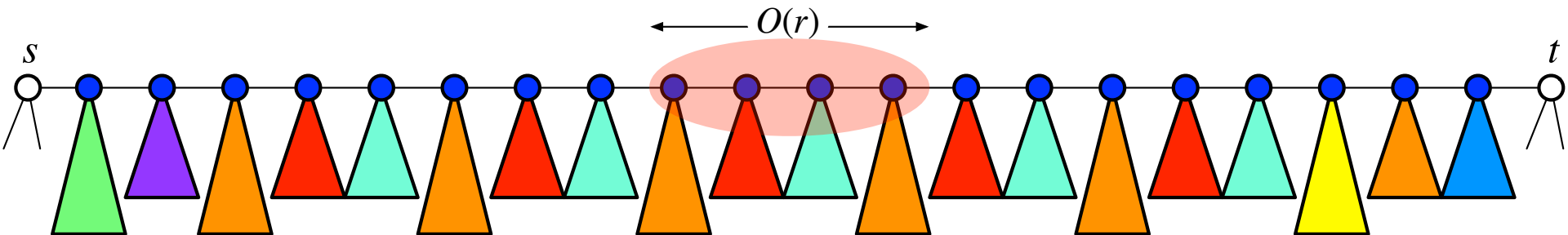
- Can create a “pumped” tree;  $\text{Type}(s,t)$  is unchanged.



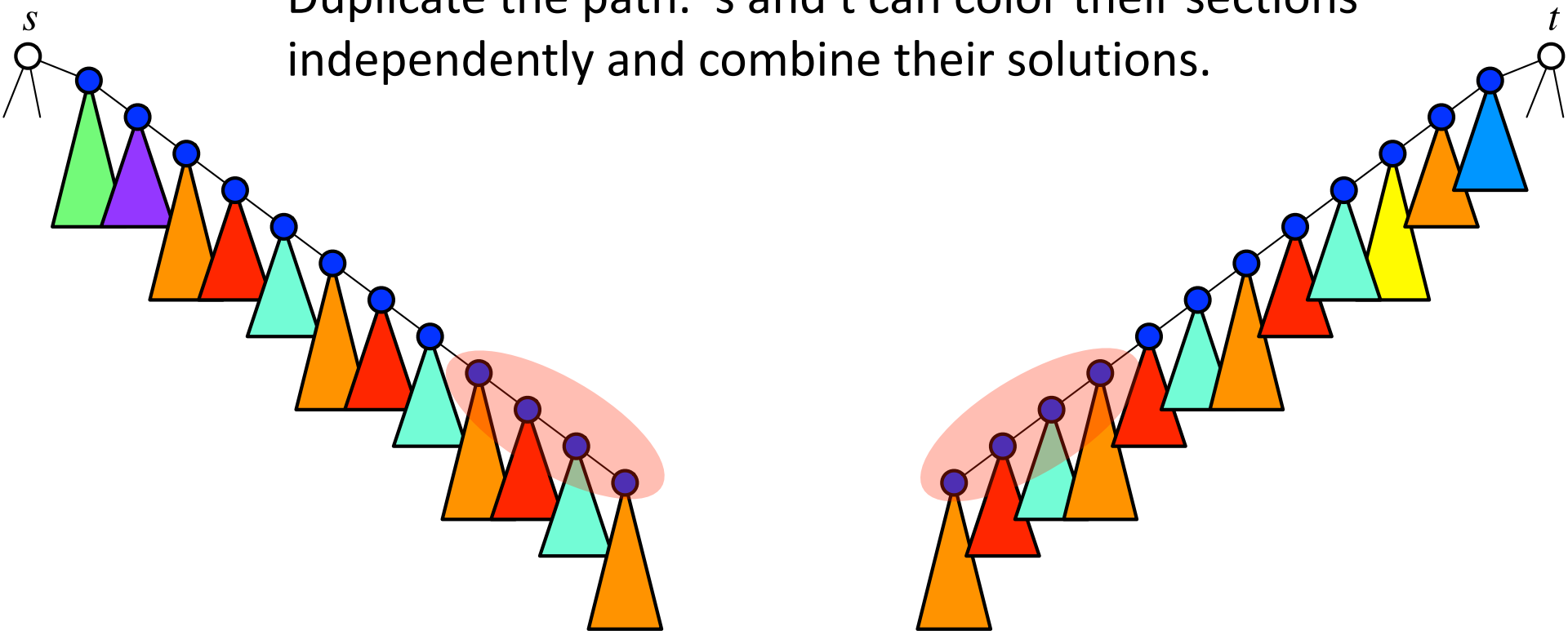
# Pumped Trees



- Pump the path to be *very* long.
- Any  $n^{o(1)}$ -time algorithm run on the “middle” of the path does not depend on  $s$  nor  $t$ .
- Pre-commit to the output labeling of an  $O(r)$  neighborhood around the middle.



Duplicate the path.  $s$  and  $t$  can color their sections independently and combine their solutions.



- Apply ***pumping***, ***precommit***, and ***duplication*** to every Compress operation.
- Any subtree can be freely replaced by a (smaller) subtree of the same Class.
- The  $n^{o(1)}$ -neighborhood of any vertex in the final “imaginary” tree is a function of the  $O(\log n)$ -neighborhood in the actual tree.
- Any correct labeling in the imaginary tree can be converted to one in the actual tree.

# Open Question

What is the LOCAL complexity of the LLL ?

- Probably need to solve rand. and det. complexities simultaneously.  $\Theta(\log \log n)$  rand. and  $\Theta(\log n)$  det.?
- Conceivable that the “original” LLL with criterion  $ep(d + 1) < 1$  is a harder problem.

*Thank you!*