# Large Scale Algorithms, Clustering and the MPC model

Silvio Lattanzi Google Zurich

#### **Outline**

Models, MapReduce and Simple Examples

Capacitated Metric Clustering at Scale How can we cluster the world map efficiently?

Hierarchical Graph Clustering at Scale Can we obtain a hierarchical clustering efficiently?

#### Incredible amount of online data



Google searches today



Blog posts written today



Tweets sent today



4,055,053,771

Videos viewed today on YouTube



45,866,158

Photos uploaded today on Instagram



73,178,241

Tumblr posts today



Facebook active users



Google+ active users



Twitter active users

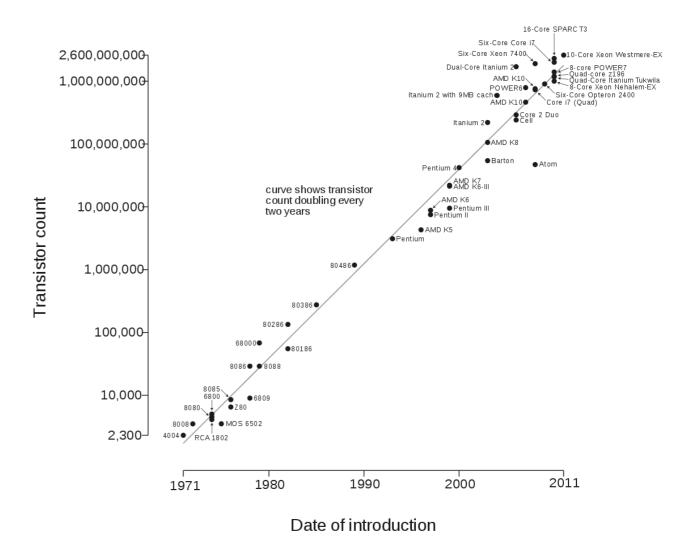
Stats from <a href="http://www.internetlivestats.com/">http://www.internetlivestats.com/</a>.

#### Moore's Law

#### Moore's Law

Number of transistors double roughly every two years

#### Microprocessor Transistor Counts 1971-2011 & Moore's Law



## **Hard Drive evolution**

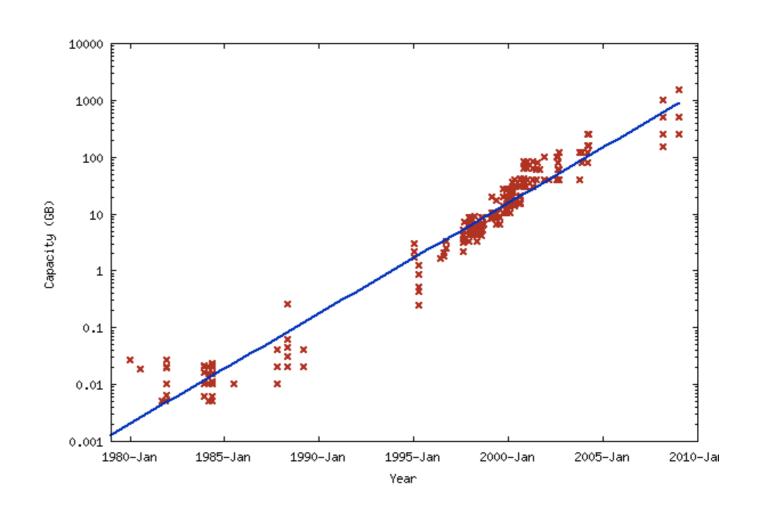
#### **Hard Drive evolution**

80s: 10M  $\rightarrow$  100M

90s: 100M  $\rightarrow$  10G

00s: 10G  $\rightarrow$  1T

 $10s:1T \rightarrow 100T$ 

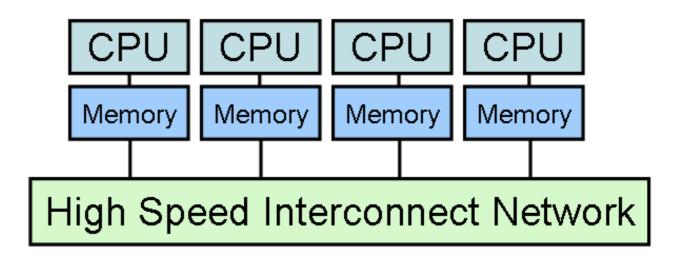


Data >> Hard drive

## Models, MapReduce and Simple Examples

## Classic Parallel programming

Computers coordinate autonomously



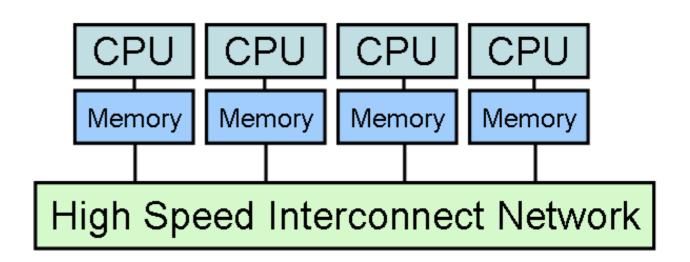
## Classic Parallel programming

Computers coordinate autonomously

Hard to read and understand

Hard to write

Hard to debug



## A simple model for parallel computing

#### Main properties:

- 1. Synchronous vs. Asynchronous
- Partition Data:Adversarial or Random
- 3. Communication
  - A. Topology (complete or not)
  - B. Amount (bounded or not)
- 4. Size of machines
- 5. Fault-tolerance

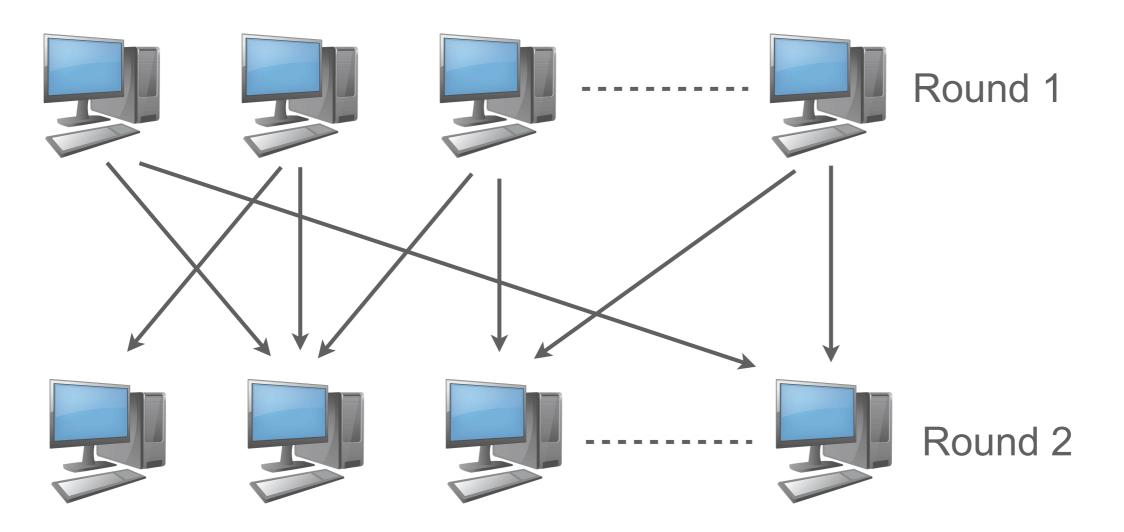


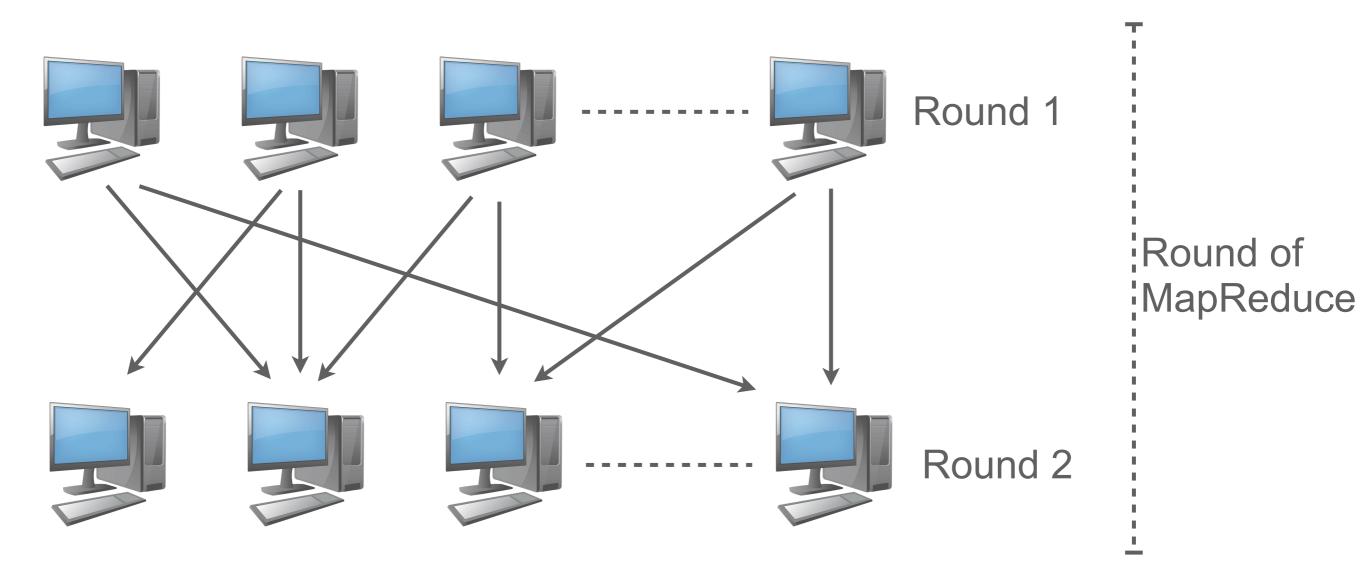
## A simple model for parallel computing

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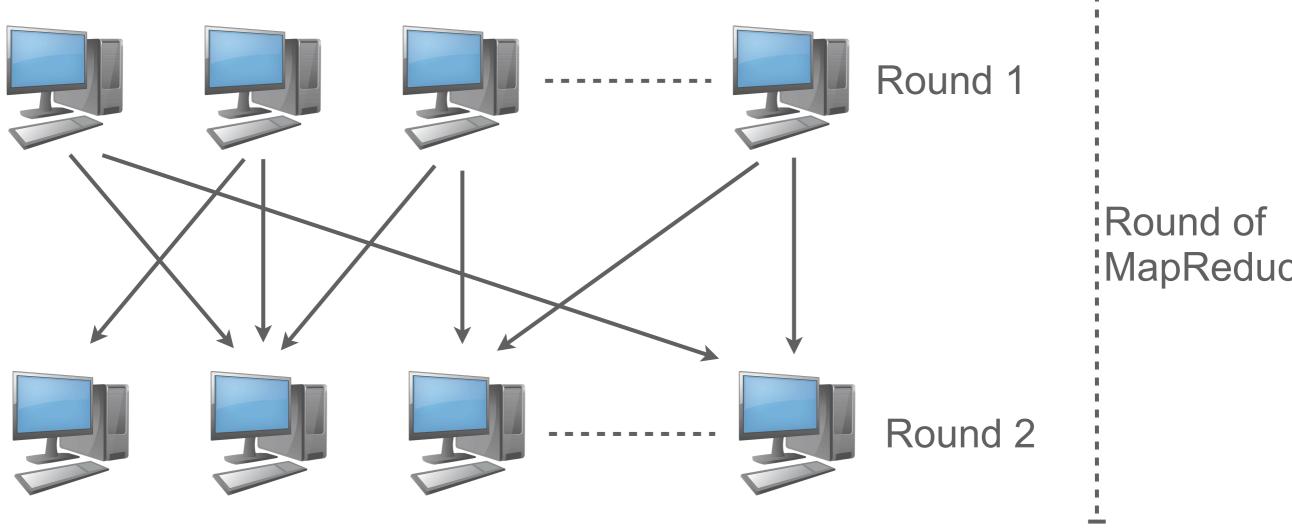
- 1. **Synchronous** vs. Asynchronous
- Partition Data:Adversarial or Random
- 3. Communication
  - A. Topology (complete or not)
  - B. Amount (**bounded** or not)
- 4. Size of machines ~ largish
- 5. Fault-tolerance: transparent to user



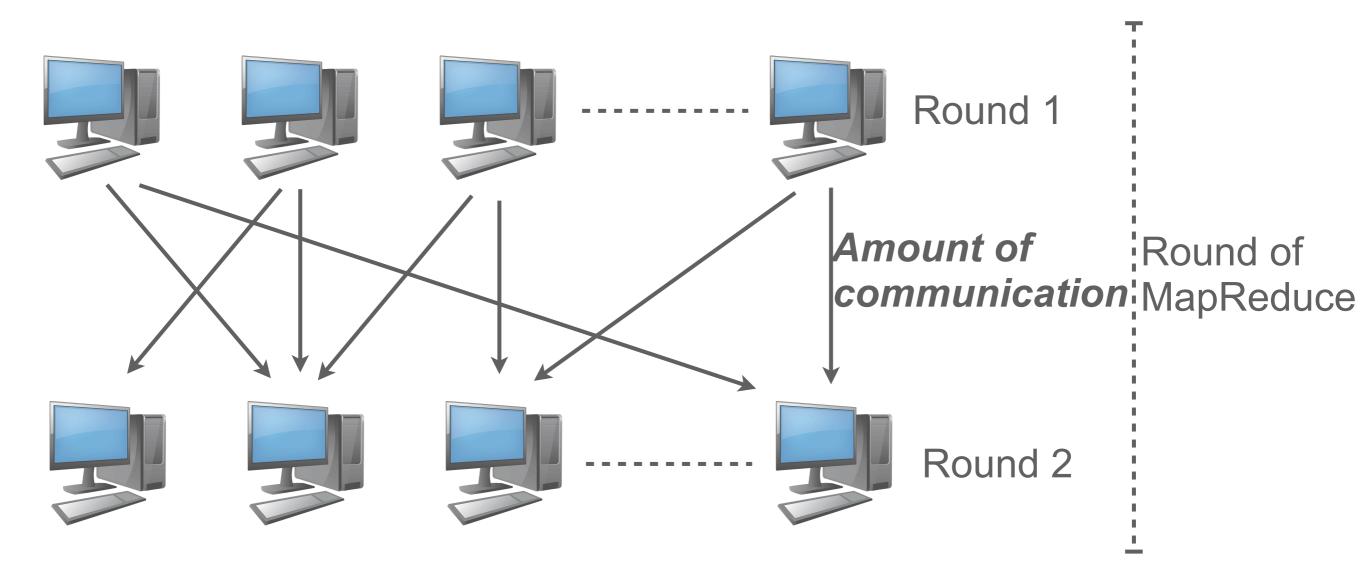




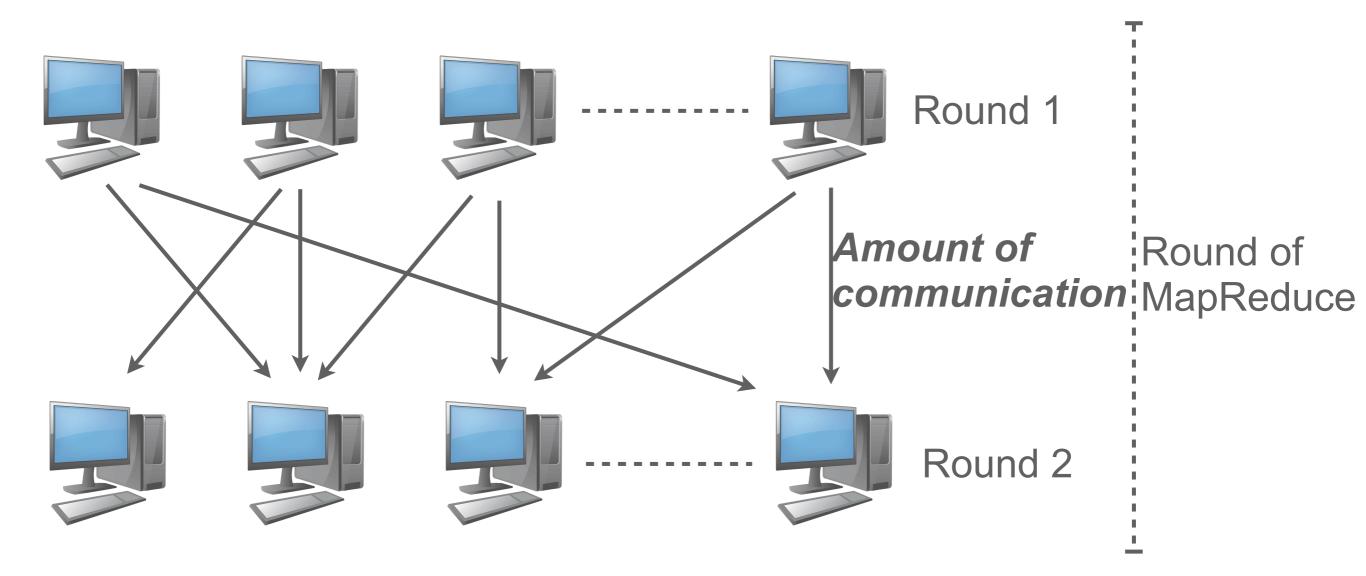
#### # machines



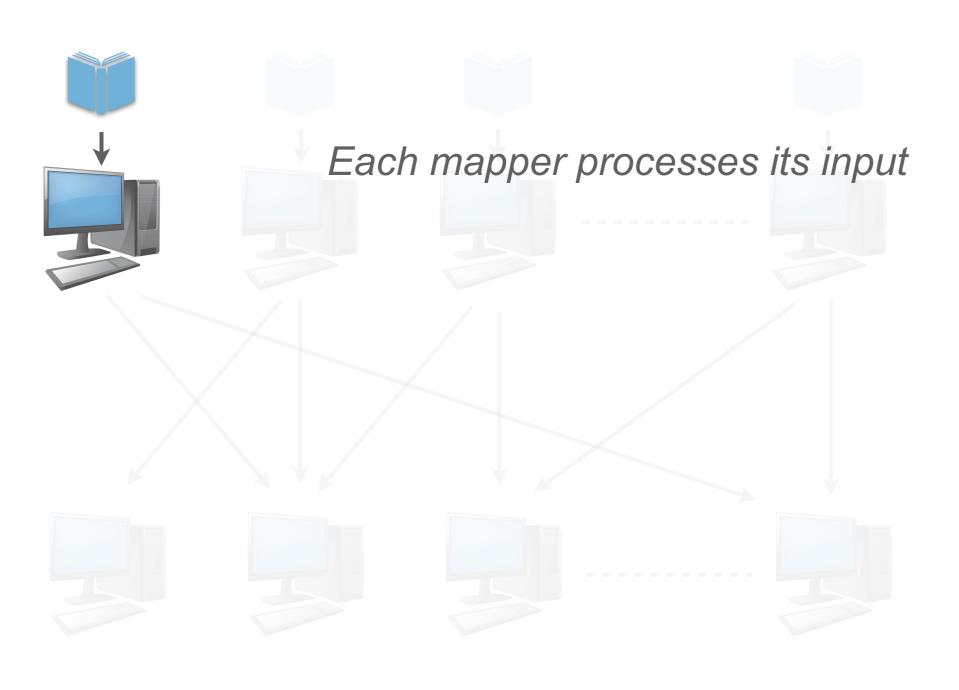
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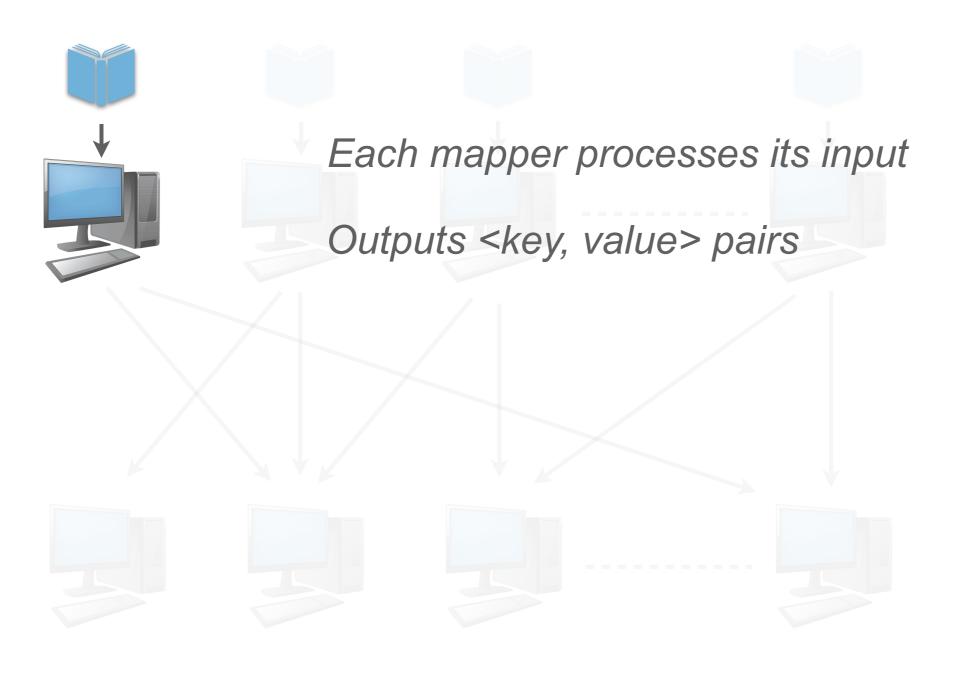


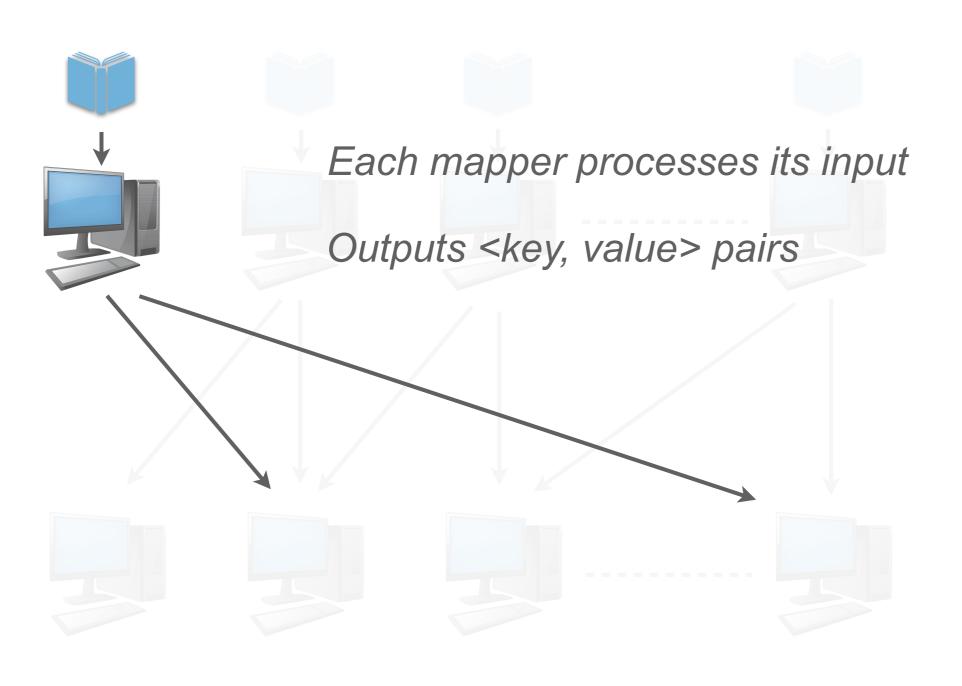
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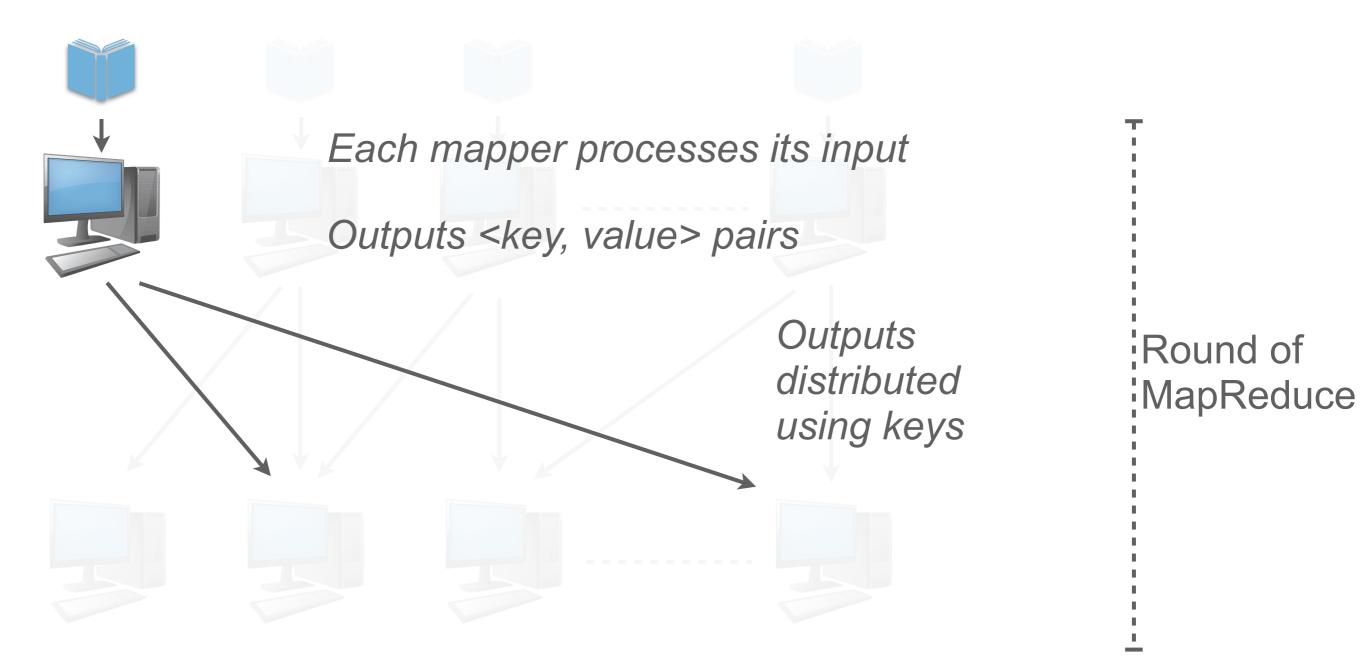


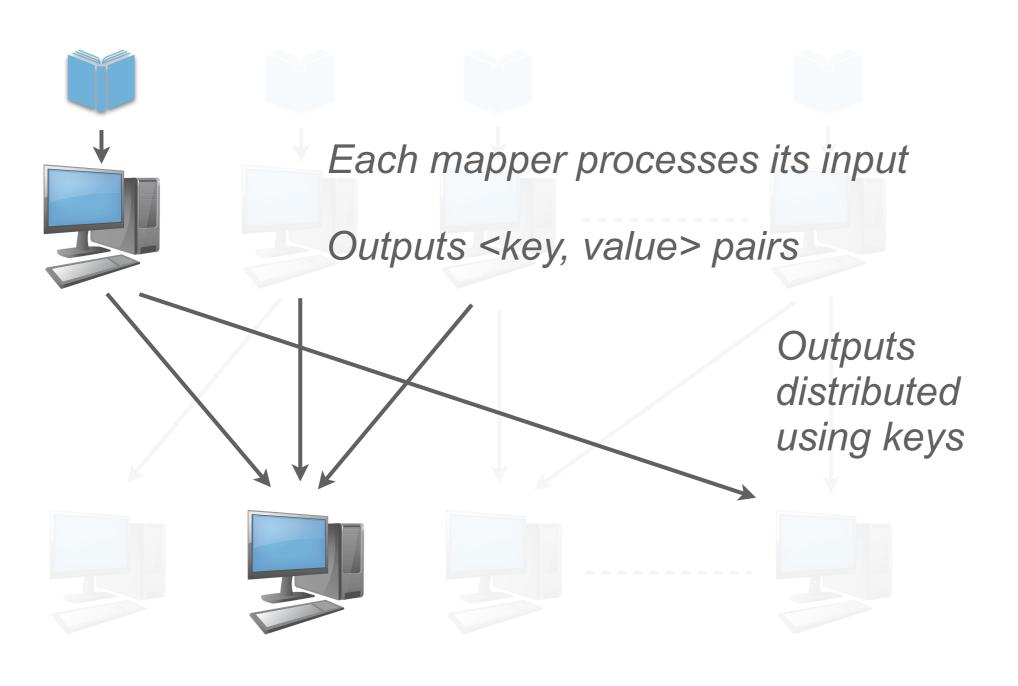
# rounds

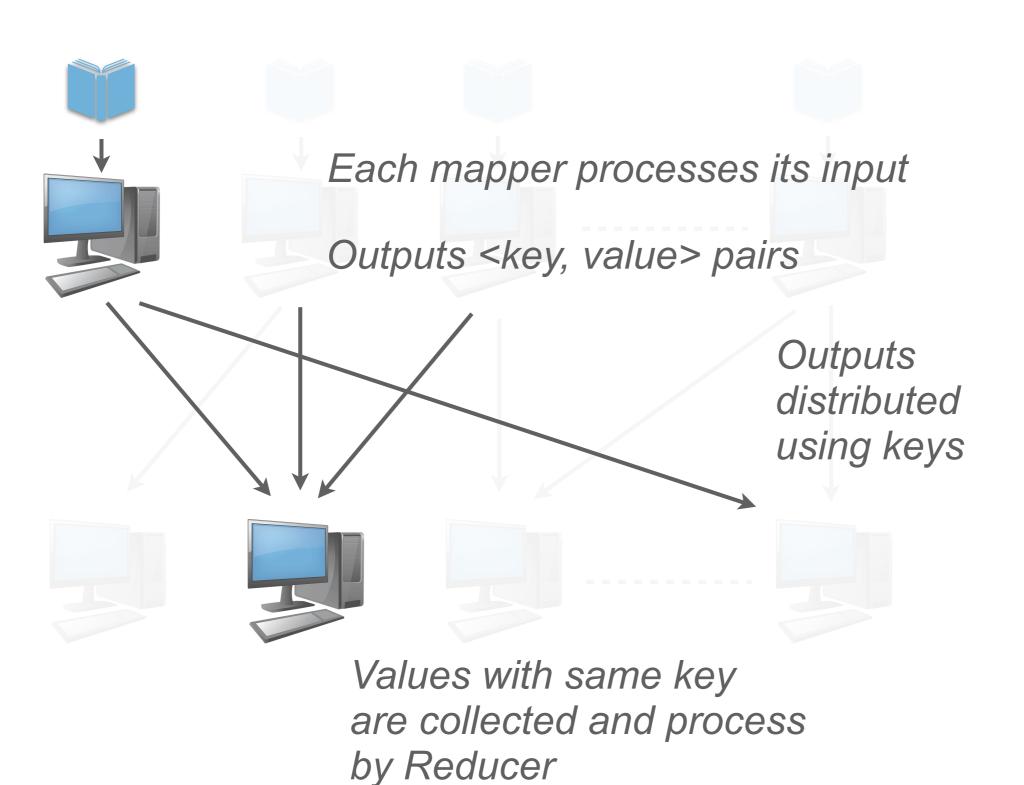


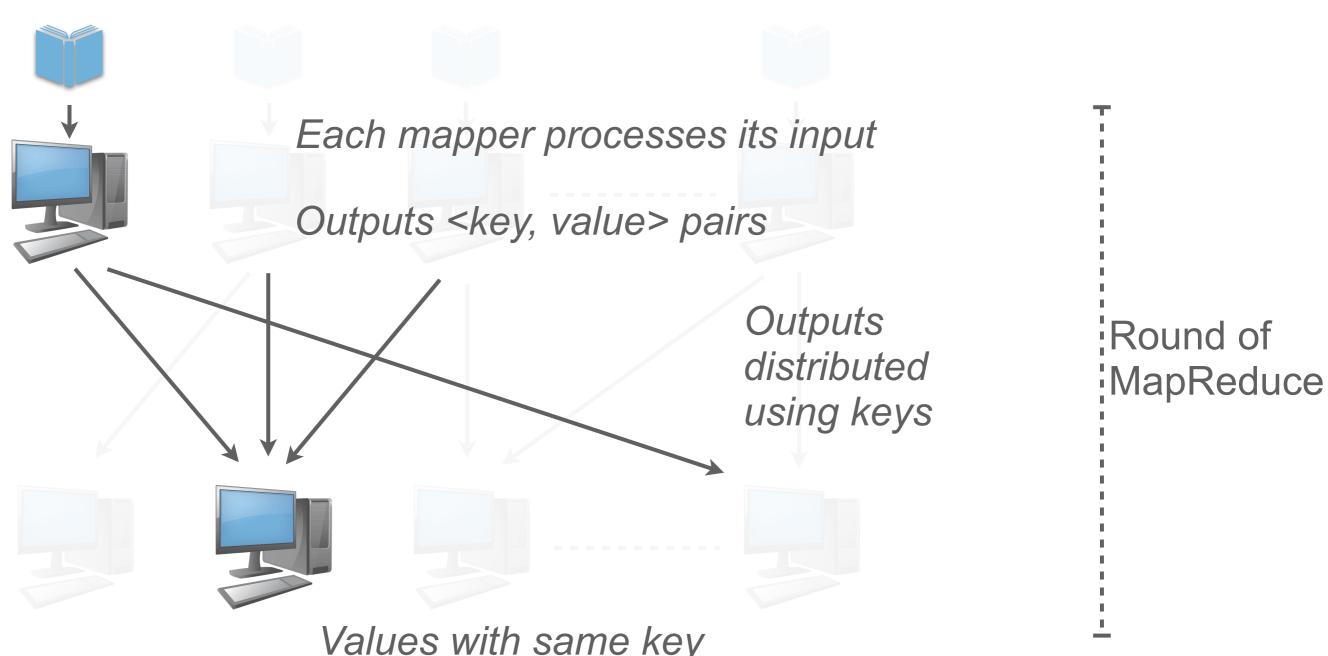








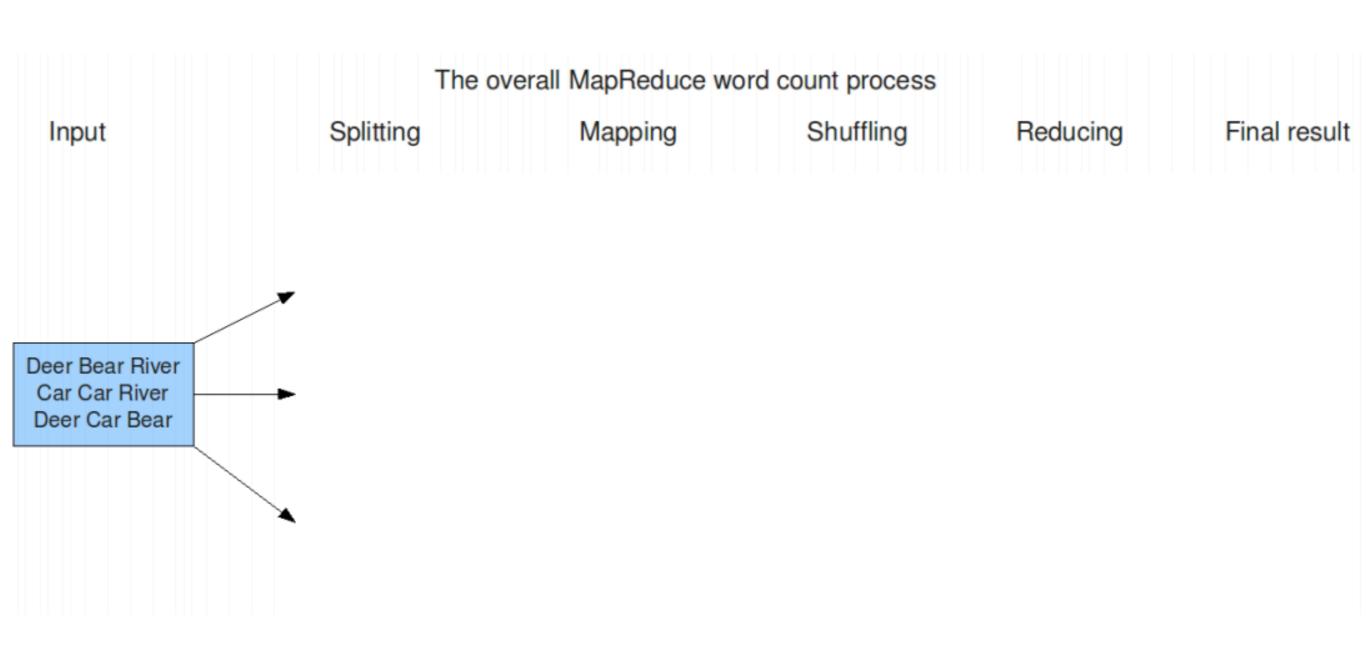


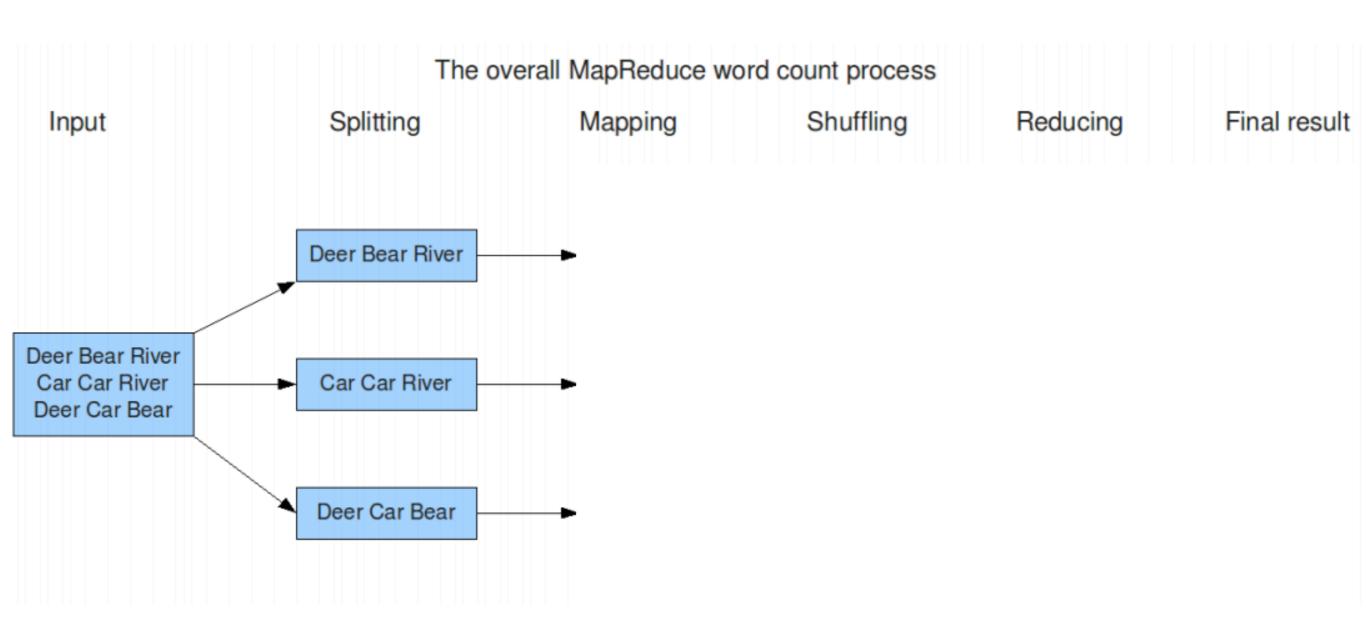


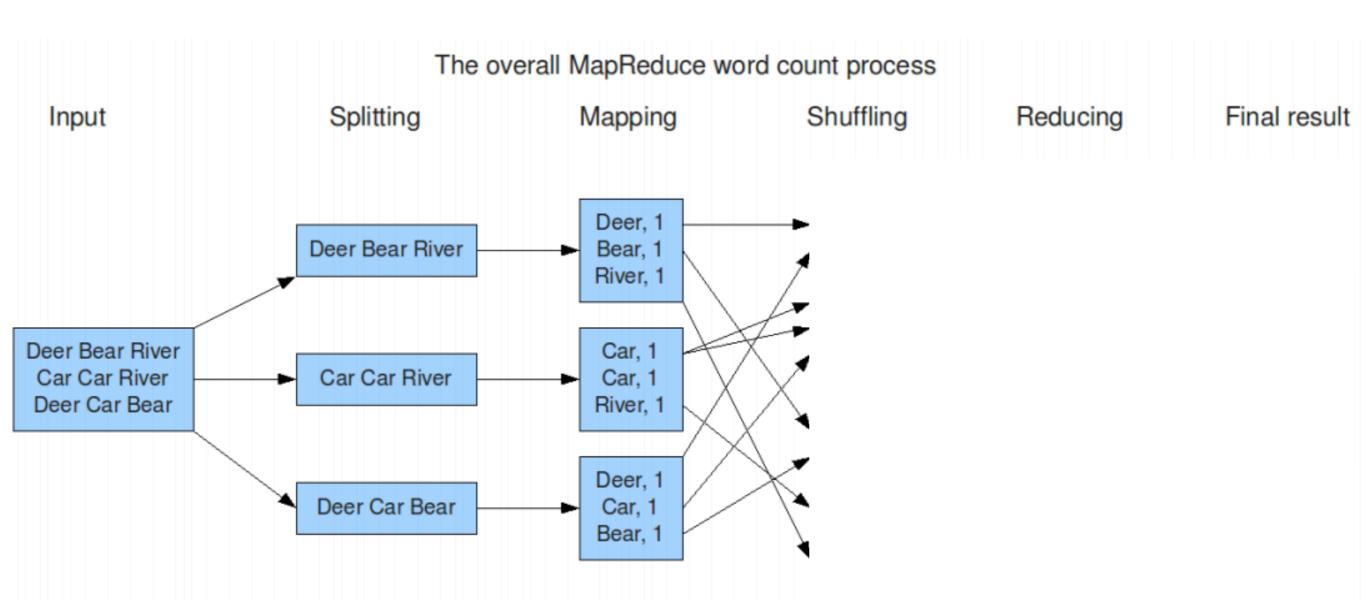
Values with same key are collected and process by Reducer

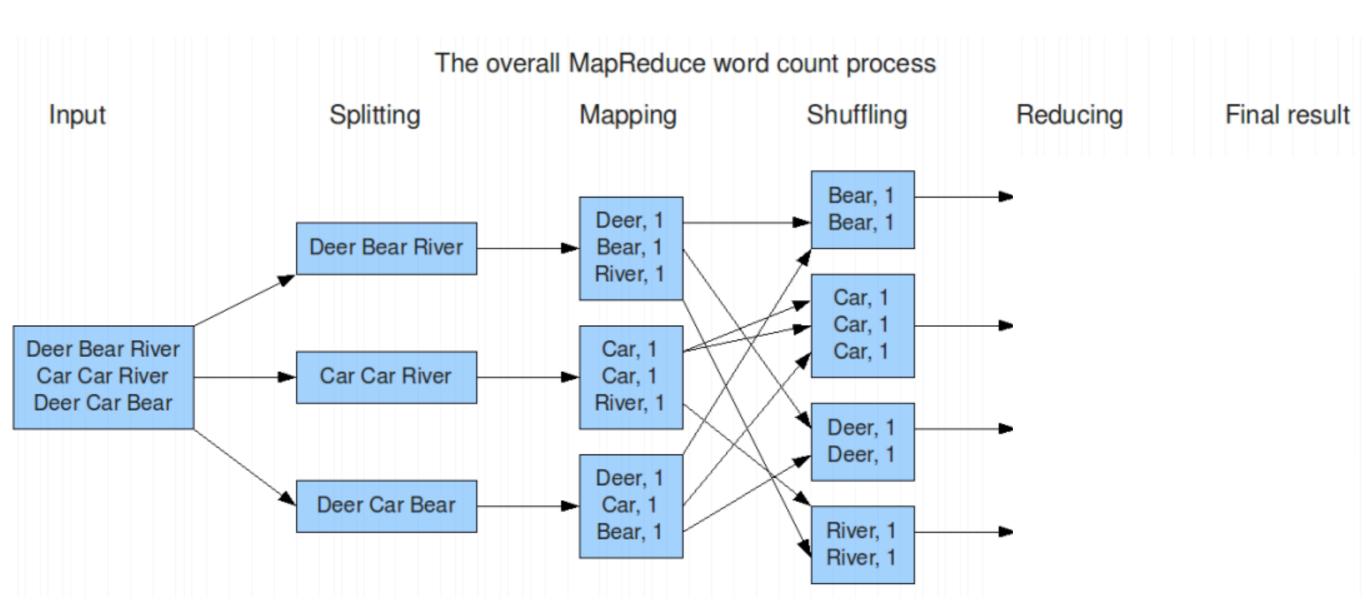
MapReduce: simplified data processing on large clusters

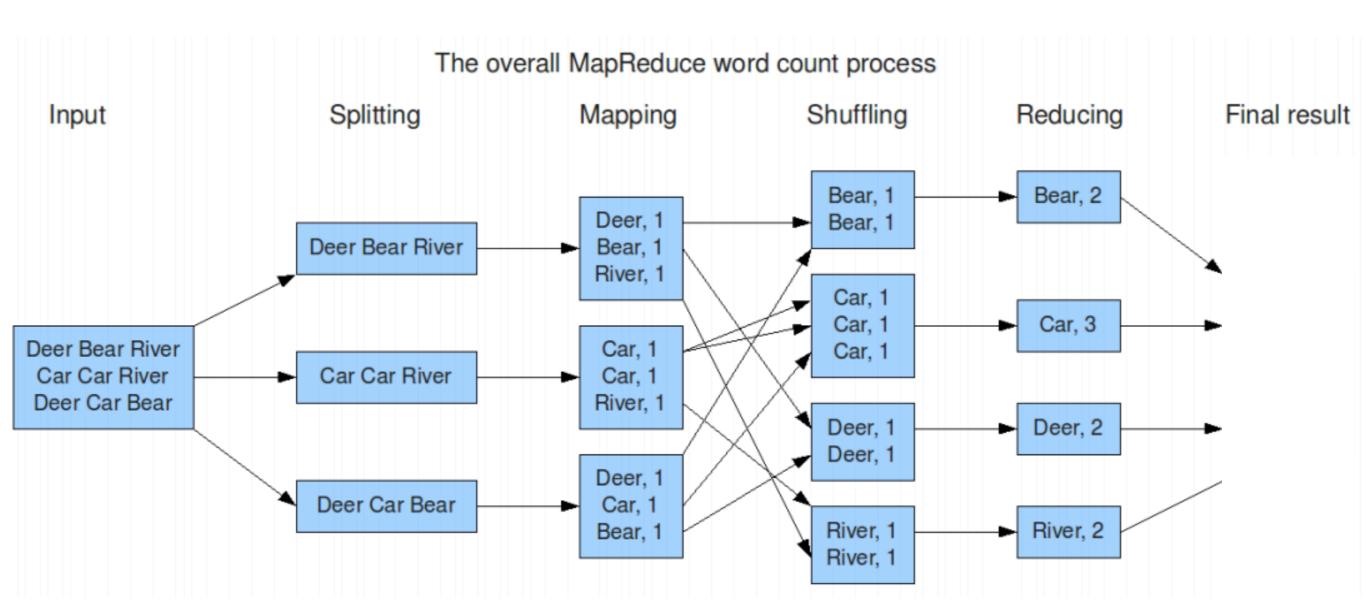
J Dean, S Ghemawat Communications of the ACM 51 (1), 107-113

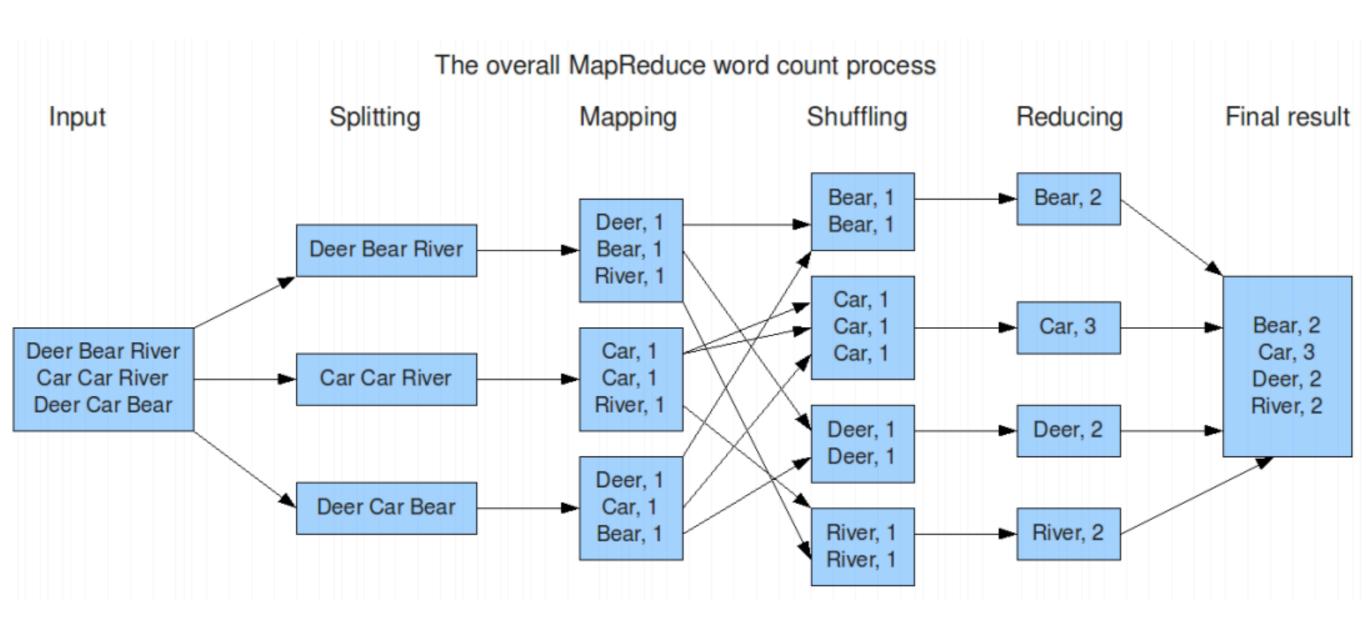




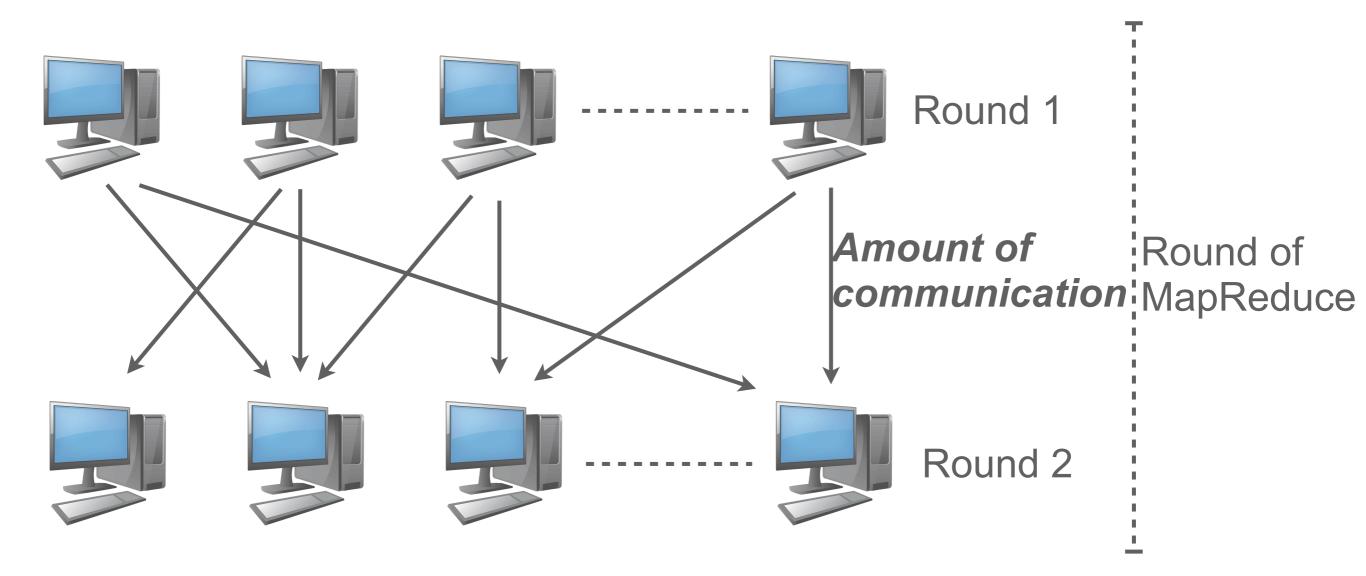








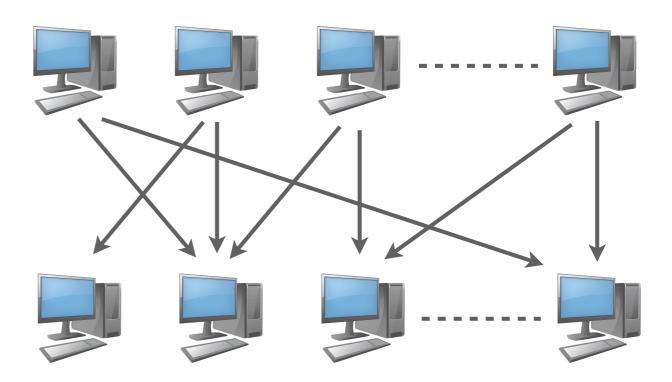
#### # machines



# rounds

# machines (M)

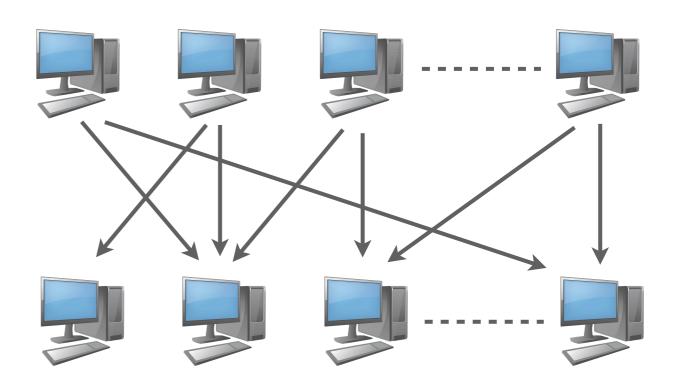
Input size to machines(S)



Input size N

# machines (M)

Input size to machines(S)



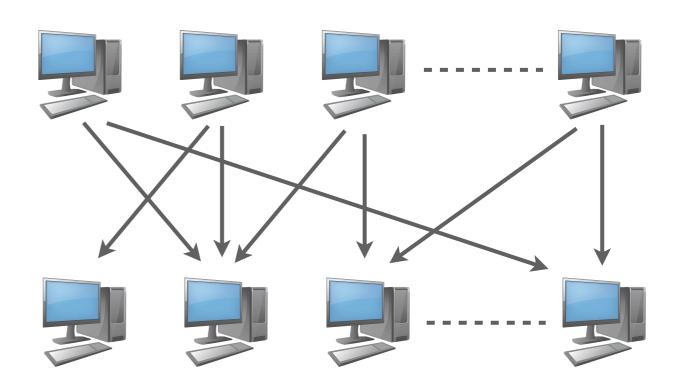
#### Input size N

# machines (M)

$$O\left(N^{1-\epsilon}\right)$$

for constant  $\epsilon > 0$ 

Input size to machines(S)



#### Input size N

#### # machines (M)

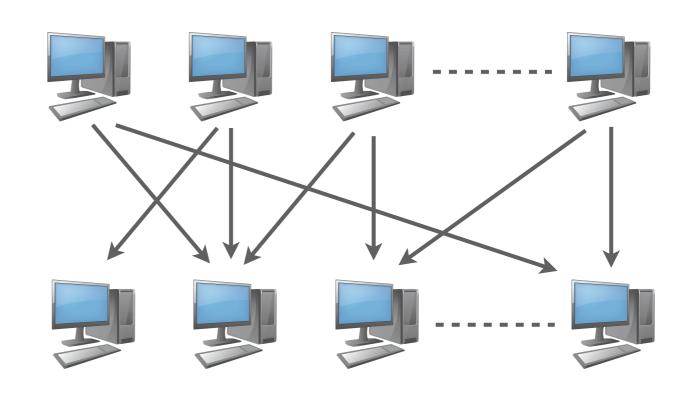
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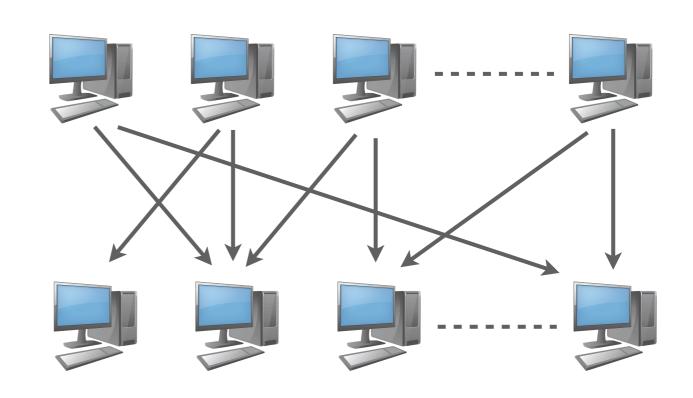
for constant  $\epsilon > 0$ 

#### # rounds (R)

O(1) ideal

 $O(\log N)$  happy

O(polylogN) content



## MapReduce model

#### Input size N

#### # machines (M)

$$O\left(N^{1-\epsilon}\right)$$

for constant  $\epsilon > 0$ 

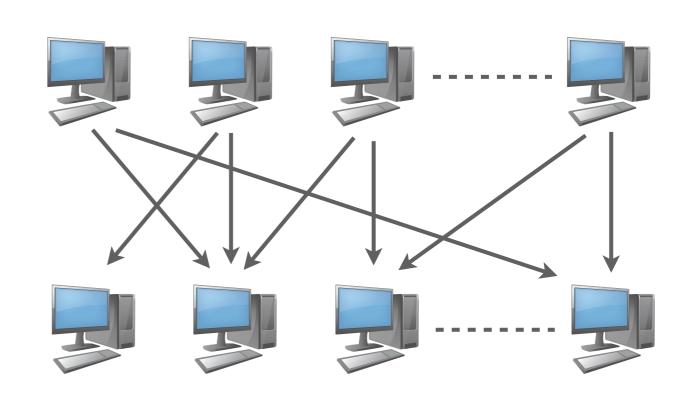
## Input size to machines(S)

$$O\left(N^{1-\epsilon}\right)$$

for constant  $\epsilon > 0$ 

## # rounds (R)

O(1) ideal  $O(\log N)$  happy O(polylogN) content



#### A model of computation for MapReduce

H Karloff, S Suri, S Vassilvitskii

Proceedings of the twenty-first annual ACM-SIAM symposium on Discrete Algorithms

## Other models: parallel

#### **PRAMS**

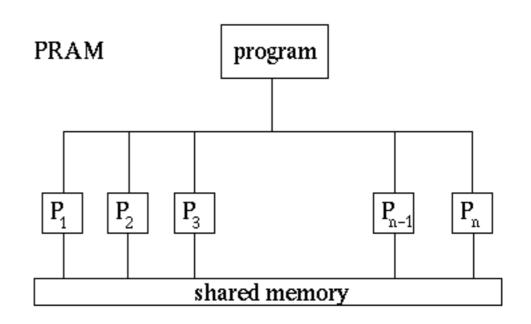
# machines (M)

 $O(N^c)$ 

for constant c > 0

Input size to machines(S)

O(1)



## Other models: parallel

## **PRAMS**

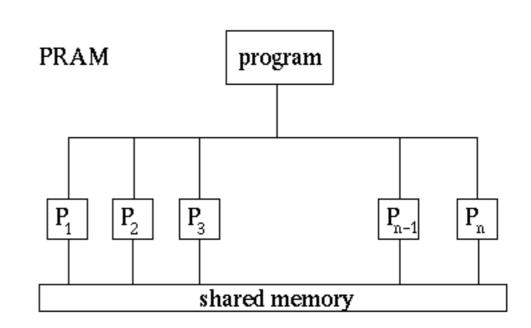
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Input size to machines(S)

O(1)

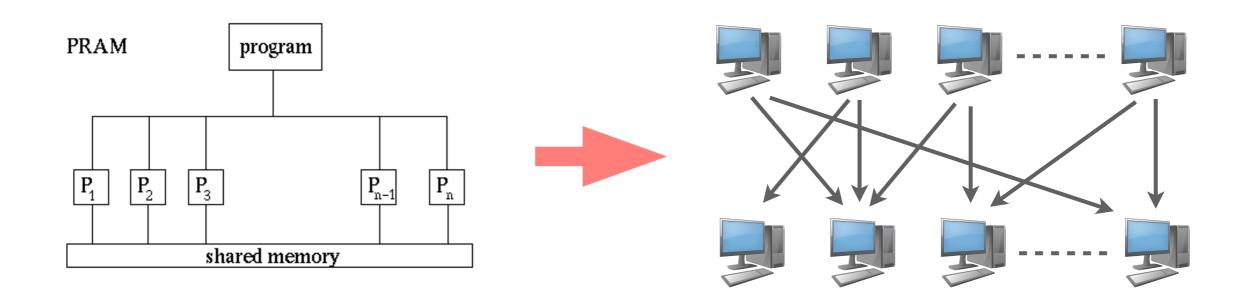


Reduction between EREW PRAMs and MapReduce algorithms

## EREW PRAM vs. MapReduce

#### **Theorem**

Let  $\mathcal{A}$  be a EREW PRAM algorithm for problem  $\mathcal{P}$  using  $O\left(N^{2-2\epsilon}\right)$  memory and R rounds. Then there exists a MapReduce algorithm using the same number of rounds.

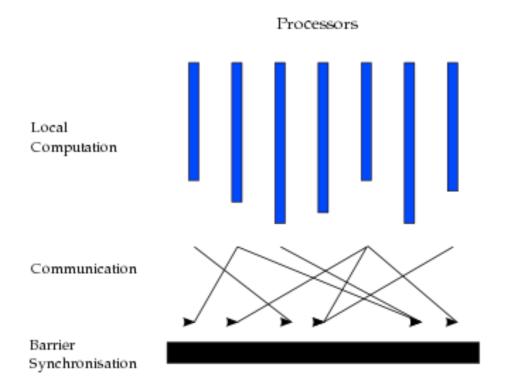


## Other models: parallel

#### **BSP**

Not assume synchronization

Not assume fault-tolerance

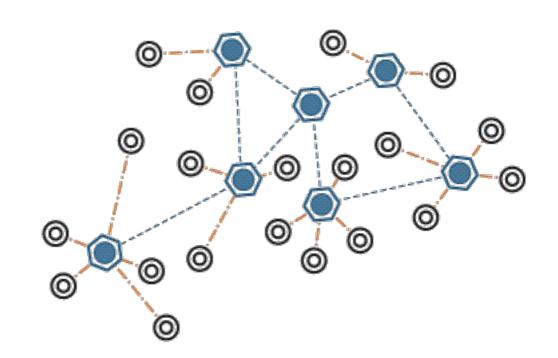


## Other models: distributed

#### LOCAL

Restricted topology

**CONGEST** 



#### Limited bandwidth

Many connections between the two models, both for upper and lower bounds.

#### Prefix sum problem

Let 
$${\bf v}$$
 be a vector. Compute  $, \forall j, \ PS(j) = \sum_{i \leq j} {\bf v}[i]$ 

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Using MapReduce it is possible to solve the problem in O(1) rounds

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Using MapReduce:

#### Prefix sum problem

Let v be a vector. Compute, 
$$\forall j, \ PS(j) = \sum_{i \leq j} v[i]$$

Using MapReduce:

Suppose the input is sorted,

$$v[0] - v[s-1]$$

$$v[s] - v[2s - 1]$$

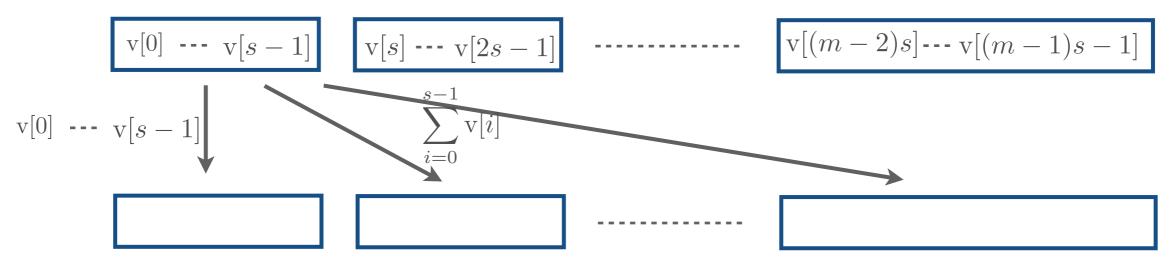
$$v[(m-2)s] - v[(m-1)s - 1]$$

#### Prefix sum problem

Let v be a vector. Compute, 
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#### Using MapReduce:

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Let  $\mathbf{v}$  be a vector. Compute  $, \forall j, \ PS(j) = \sum_{i \leq j} \mathbf{v}[i]$ 

Using MapReduce:

Sorting also takes O(1)

 $\sqrt{N}$  machines, each containing  $\sqrt{N}$  elements

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 $\sqrt{N}$  machines, each containing  $\sqrt{N}$  elements

Sort in each machine.

Compute the  $N^{1/2-\epsilon}$ -quantiles.

#### Prefix sum problem

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Using MapReduce:

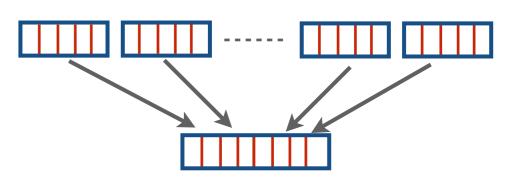
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Sort quantiles, and use them to partition data in N machines and sort again.



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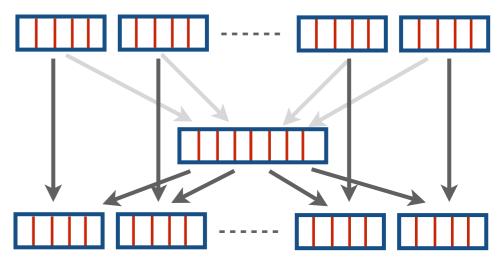
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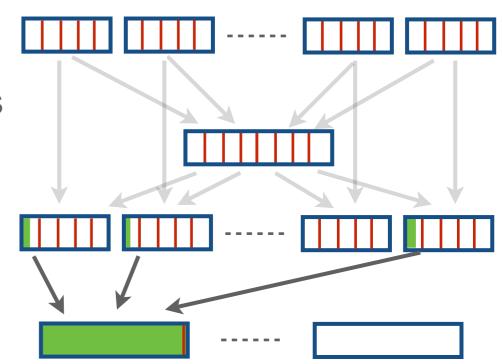
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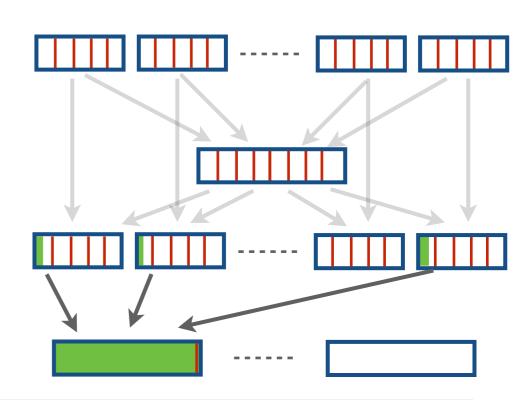
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Using MapReduce:

Sorting also takes O(1)

3 rounds



#### Prefix sum problem

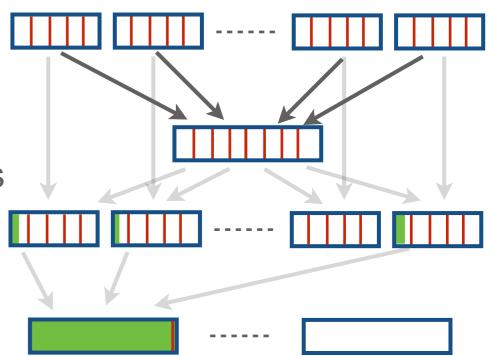
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Using MapReduce:

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1st round

 $\sqrt{N}$  machines, each sending  $N^{1/2-\epsilon}$  elements



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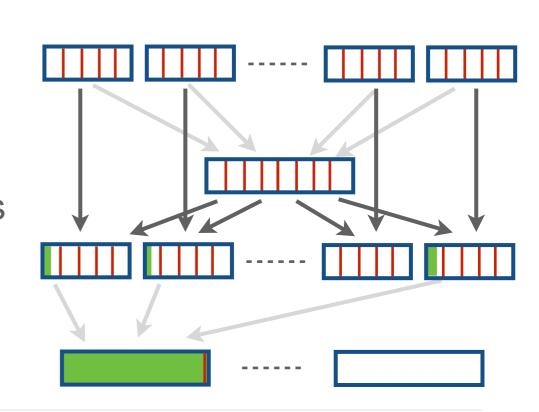
Using MapReduce:

Sorting also takes O(1)

2nd round

 $\sqrt{N}$  machines, each sending  $\sqrt{N}$  elements to different machines

1 machine sending  $N^{1-\epsilon}$  elements to all machines



#### Prefix sum problem

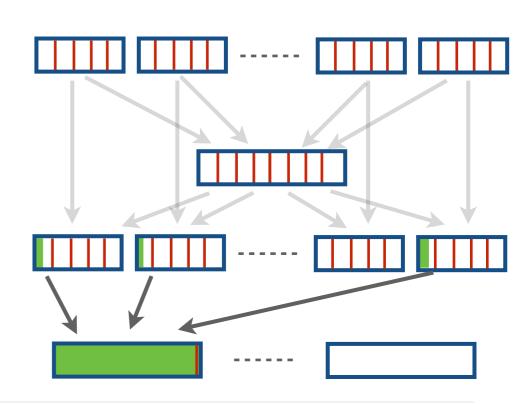
Let  ${\bf v}$  be a vector. Compute  $, \forall j, \ PS(j) = \sum_{i \leq j} {\bf v}[i]$ 

Using MapReduce:

Sorting also takes O(1)

3rd round

 $\sqrt{N}$  machines, each sending at most  $N^{\epsilon}$  elements to different machines



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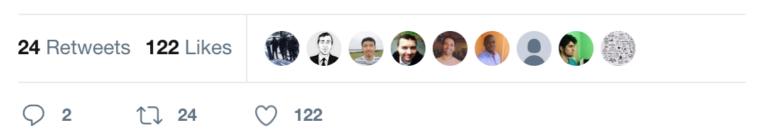
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## MapReduce has been deprecated

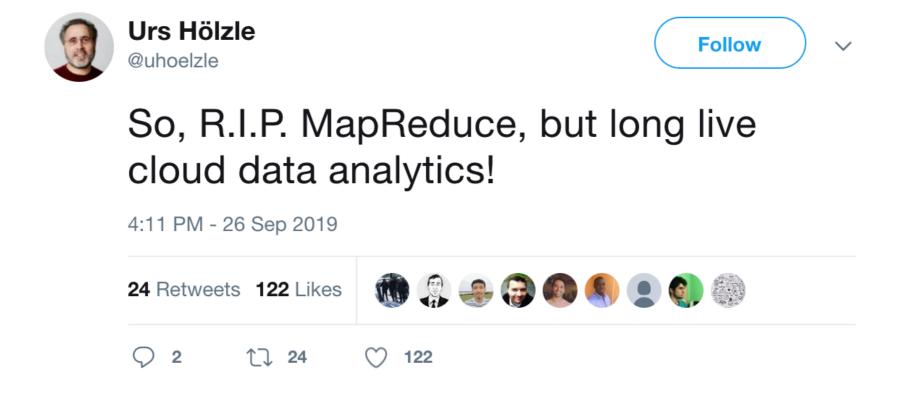


So, R.I.P. MapReduce, but long live cloud data analytics!

4:11 PM - 26 Sep 2019



## MapReduce has been deprecated



Why is this still interesting?

## **Beyond MapReduce**



Different systems but same theoretical abstraction works.

## **MPC** model

#### Input size N

#### # machines (M)

 $O\left(N^{1-\epsilon}\right)$  for constant  $\epsilon > 0$ 

Possibly smaller

#### Input size to machines(S)

 $O\left(N^{1-\epsilon}\right) \ \ \text{for constant} \ \ \epsilon>0$ 

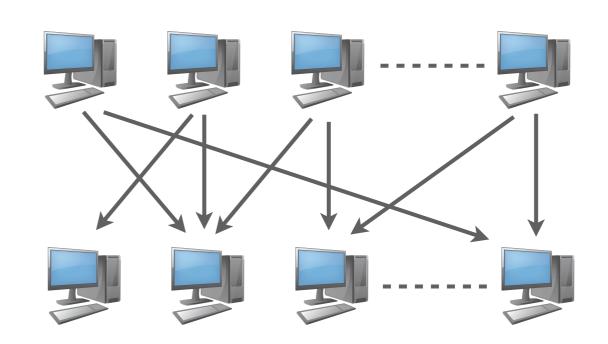
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Some commonalities with EREW PRAM and distributed but different algorithmic power

## Very active area of research

- Connectivity [KSV10], [LMSV11], [ASW18], [ASS+18], [BDE+19]...
- Matching [LMSV11],[ABB+17],[CML+18],[GGK+18],[GU19],...
- Metric clustering [EIM11],[BEL13],[BBLM14],[BW18],...
- Submodular optimization [KMVV13],[MZ15],[BENW16],[BEM18]...

...

# Capacitated Metric clustering At Scale

## Why is it important?

How can we cluster these graphs?



US graph: N = x0
Millions
distances: geodesic

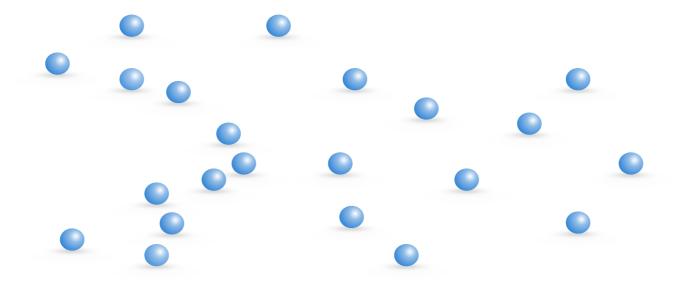


World graph: N = x00 Millions distances: geodesic

## How can we solve such problem?

We use to main ingredients:

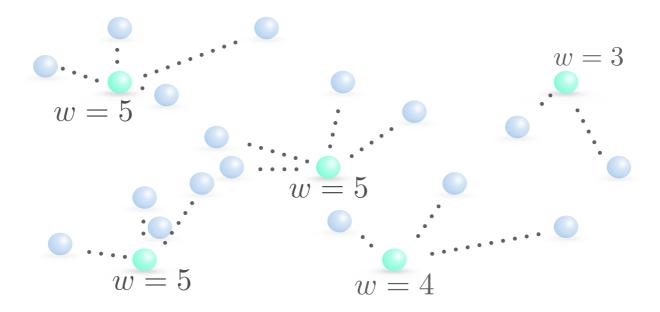
Composable Core-set



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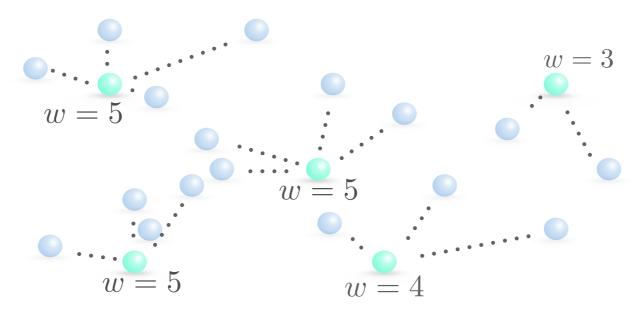
Composable Core-set



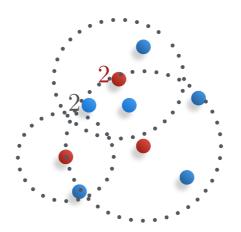
## How can we solve such problem?

We use to main ingredients:

Composable Core-set



Transform an unbalanced solution in a capacitated one



## Composable core-set

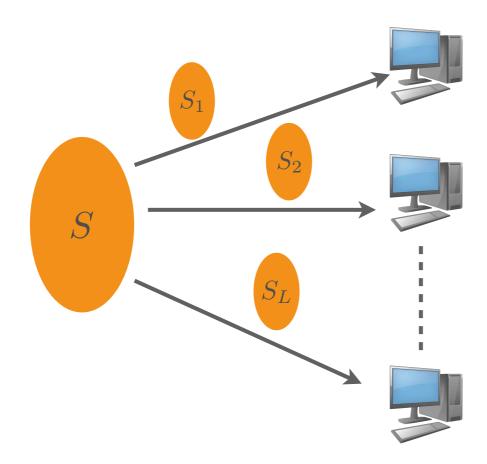
Let f be a function defined for a subset of  $\Delta$  . A function  $c(\Delta)$  is an approximate composable core set if

$$f(c(S_1) \cup \cdots \cup c(S_L)) \approx f(S_1 \cup \cdots \cup S_L)$$

## Composable core-set

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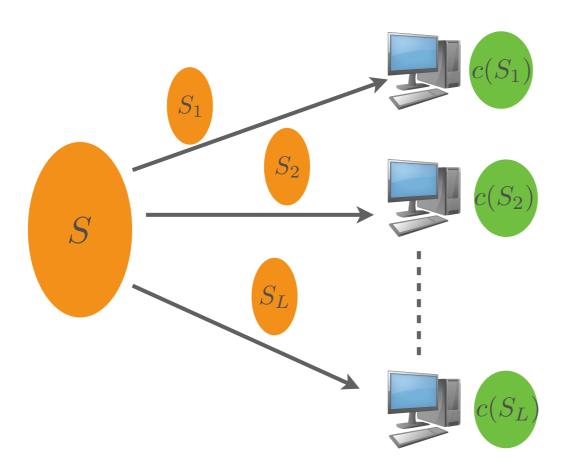
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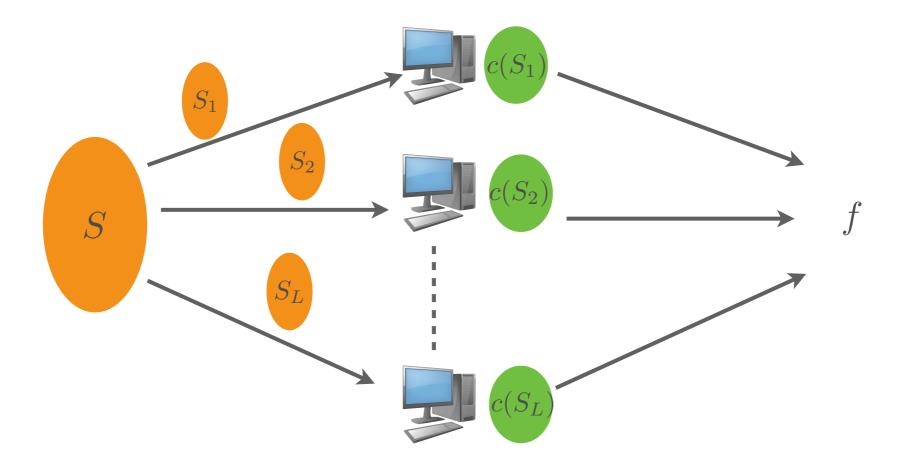
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## Composable core-set

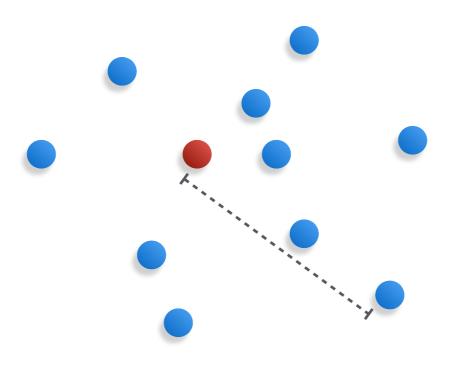
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# Composable core-set for k-clustering

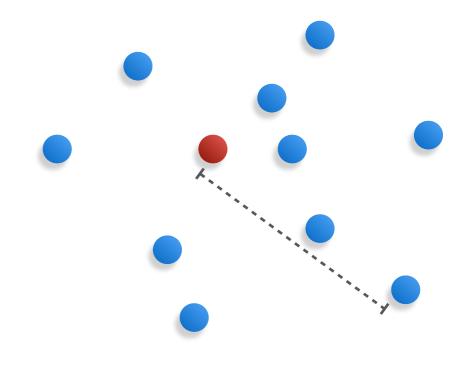
Many  $\epsilon$ -coresets for clustering problems are composable coresets.

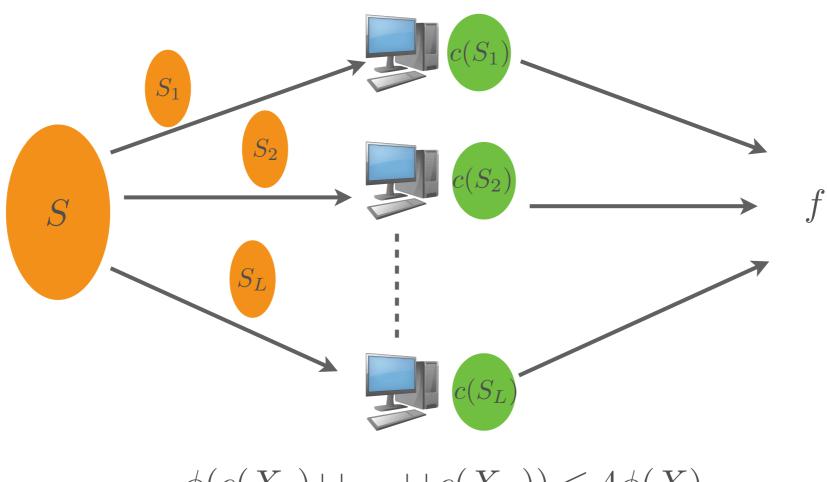


#### k - center

k- center

$$\phi(X,C) = \max_{x \in X} \min_{c \in C} d(x,c)$$

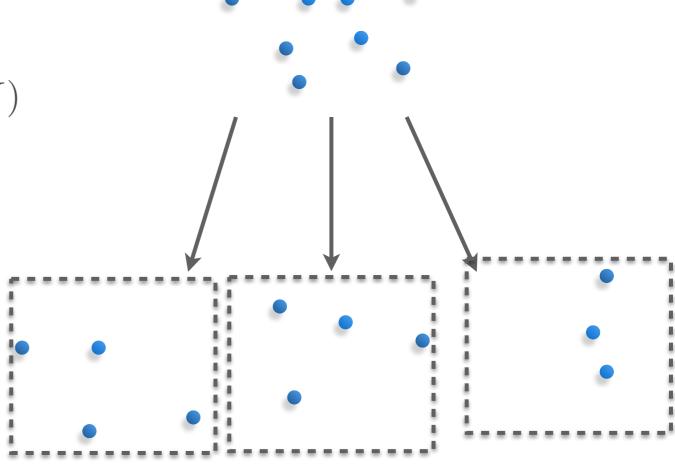




$$\phi(c(X_1) \cup \cdots \cup c(X_L)) \le 4\phi(X)$$

#### Lemma

$$\phi(c(X_1) \cup \cdots \cup c(X_L)) \le 4\phi(X)$$

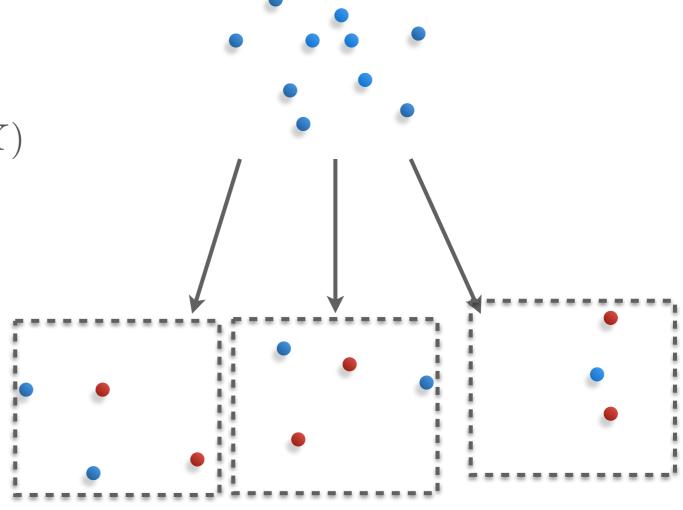


#### Lemma

$$\phi(c(X_1) \cup \cdots \cup c(X_L)) \le 4\phi(X)$$

Proof

Solve k-center independently



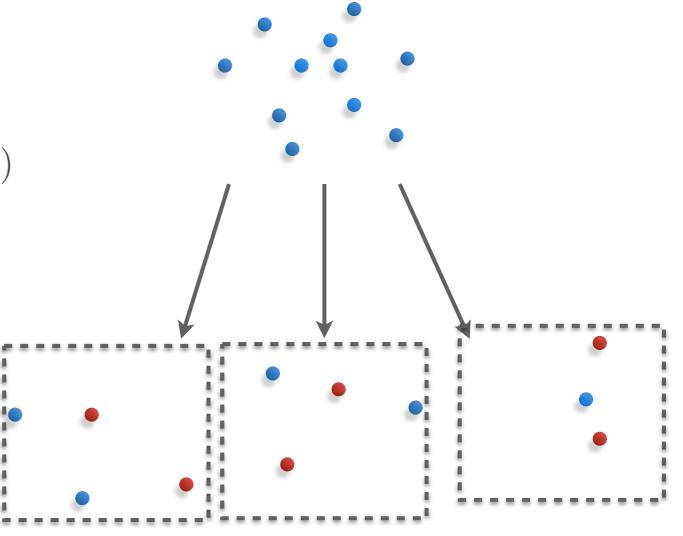
#### Lemma

$$\phi(c(X_1) \cup \cdots \cup c(X_L)) \le 4\phi(X)$$

Proof

Solve k-center independently

Cost of each  $X_i$  instance is smaller than twice global cost



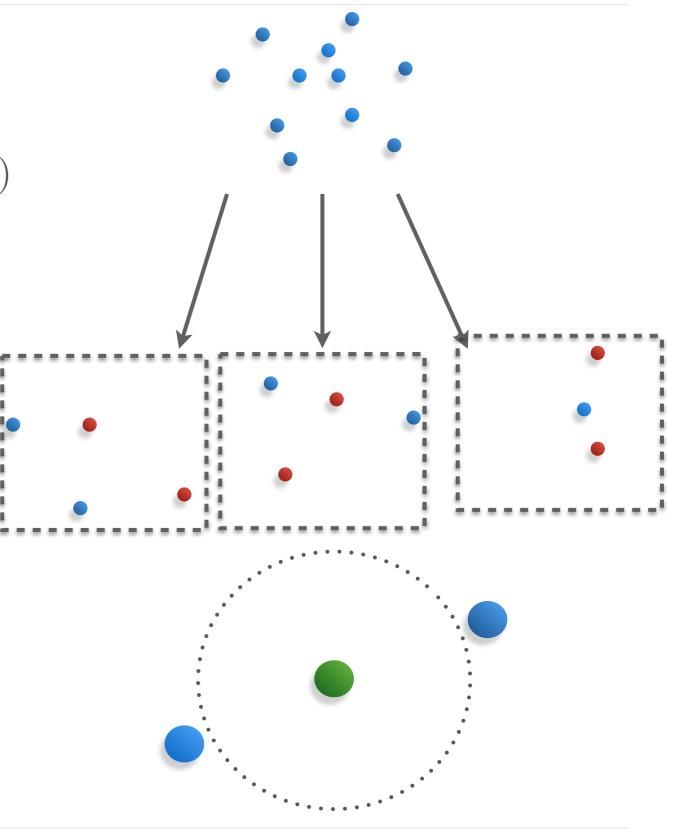
#### Lemma

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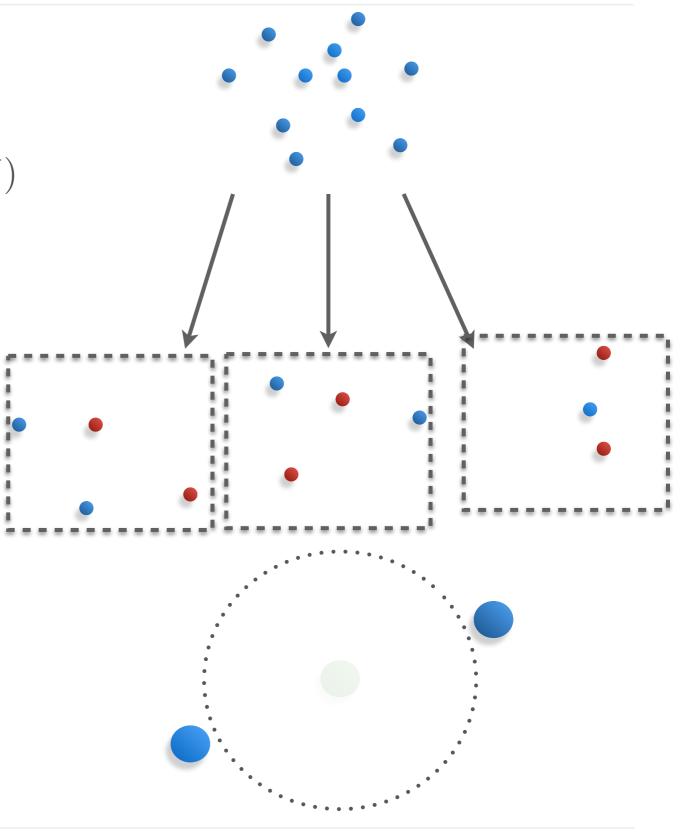
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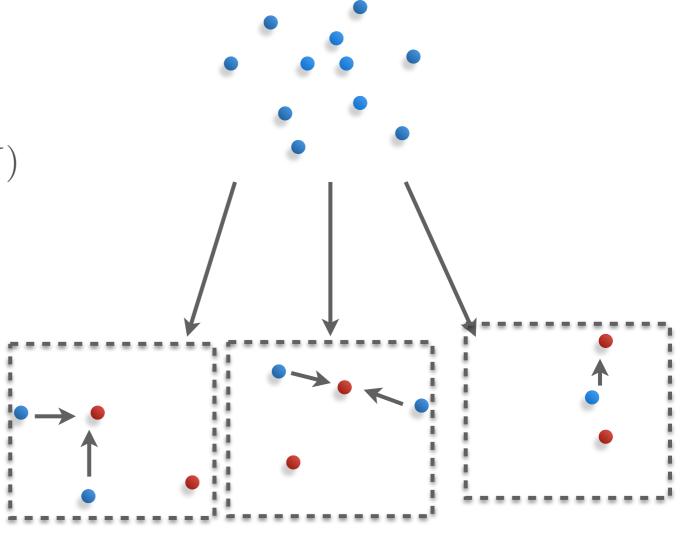
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Map points to center at cost  $2\phi(X)$ 



#### Lemma

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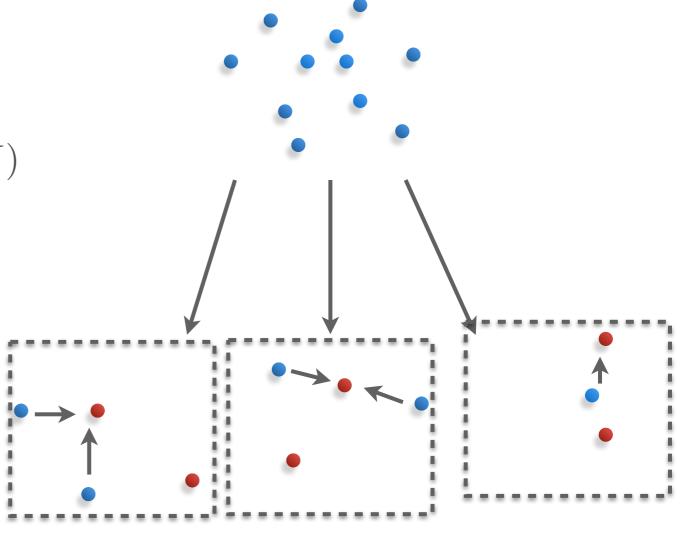
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Map points to center at cost  $2\phi(X)$ 

Cost of k-center on center is at most  $2 \phi(X)$ 



#### Lemma

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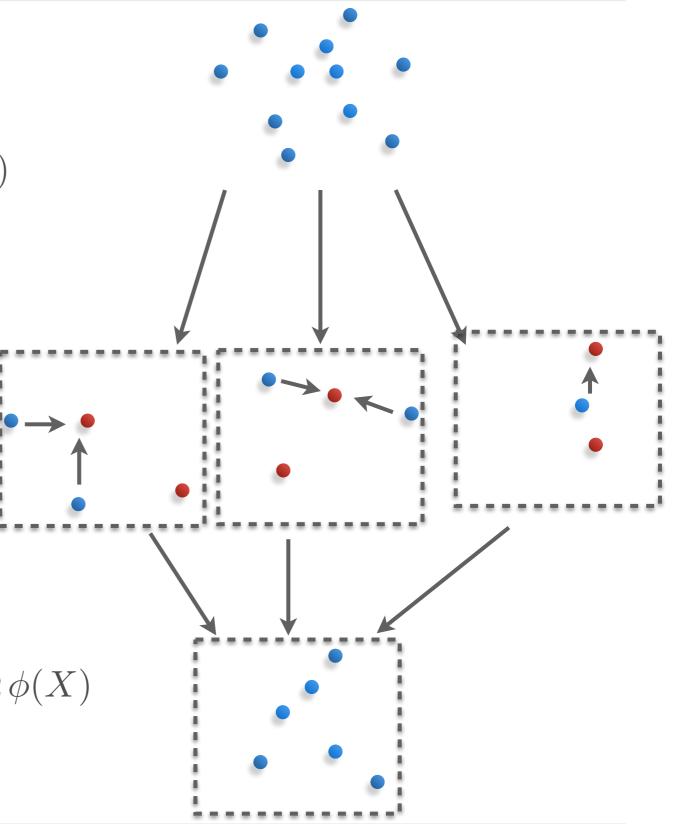
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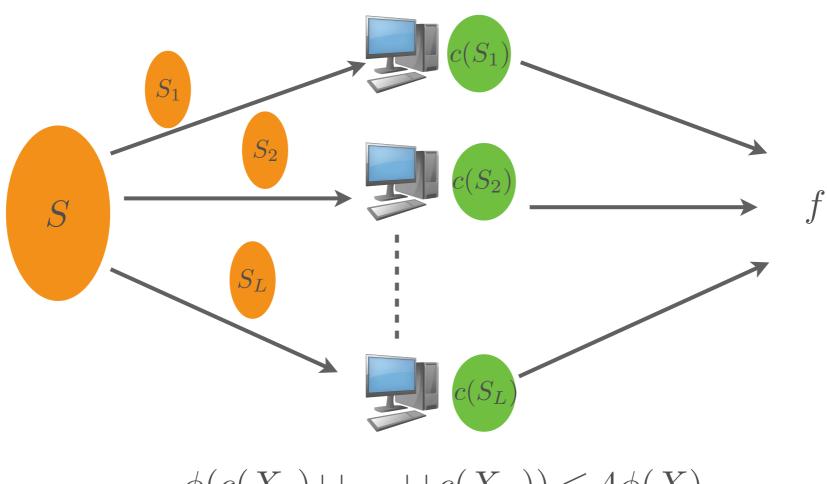
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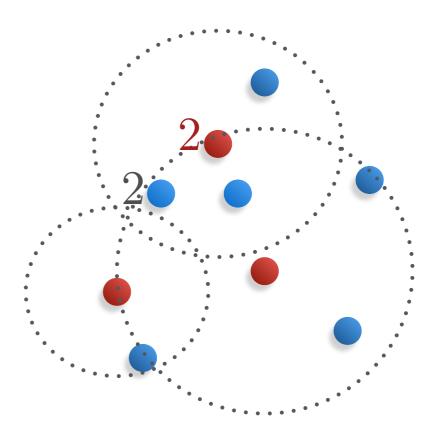
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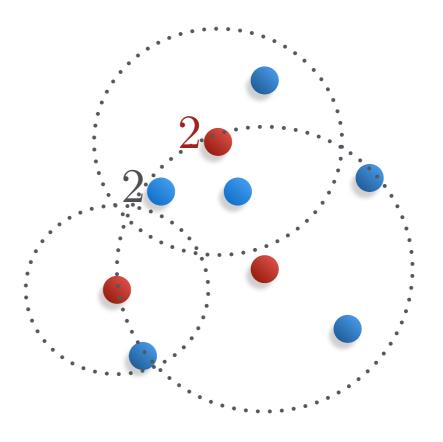


The algorithm has to run using space proportional to the compressed instance.



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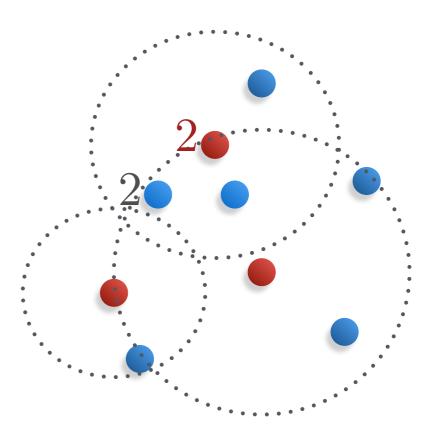
Use sequential algorithm in unconstrained setting to get a  ${\cal O}(1)$ -approximation



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Use sequential algorithm in unconstrained setting to get a  ${\cal O}(1)$ -approximation

If a cluster is too large use as additional centers the closest nodes to the center

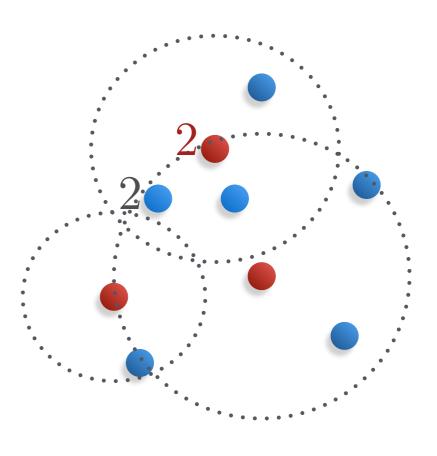


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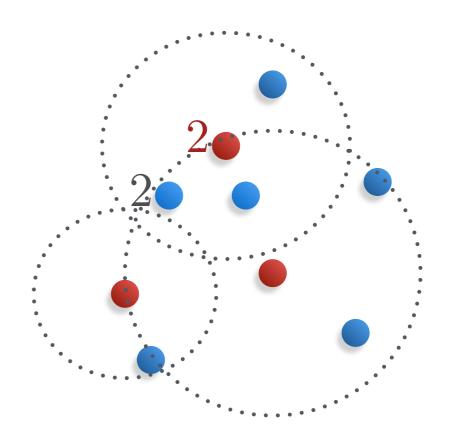
Cost of the clustering at most doubles



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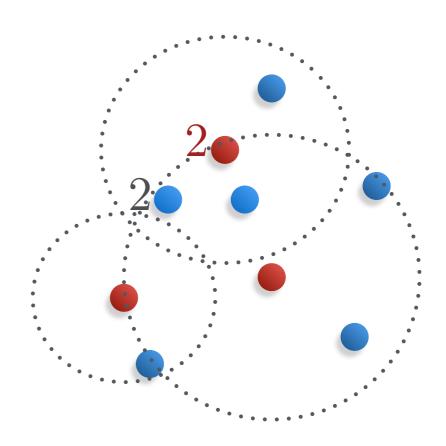
Cost of the clustering at most doubles

Number of additional clusters: 
$$\sum_{C} \frac{n_C}{L} = \frac{n}{L} = k$$

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$$\sum_{C} \frac{n_{C}}{L} = \frac{n}{L} = k$$

Bicriteria (O(1),2) algorithm

## **Experiments**



US graph: N = x0 Millions

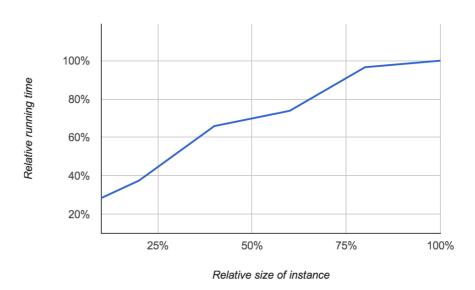
	size of seq. inst.	increase in OPT
US	1/300	1.52
World	1/1000	1.58

#### <u>Distributed Balanced Clustering via Mapping Coresets.</u>

MohammadHossein Bateni, Aditya Bhaskara, Silvio Lattanzi, Vahab S. Mirrokni NIPS 2014: 2591-2599



World graph: N = x00 Millions

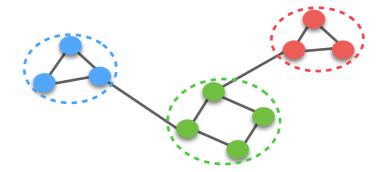


# Hierarchical Graph clustering at scale

## Density based clustering

Detecting dense structure in the graph is a well-studied problem with many practical applications

Community detection

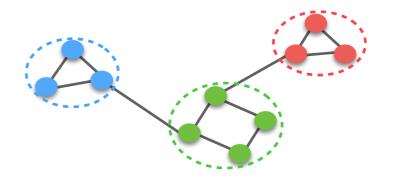


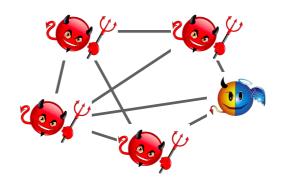
# **Density based clustering**

Detecting dense structure in the graph is a well-studied problem with many practical applications

Community detection

Spam detection

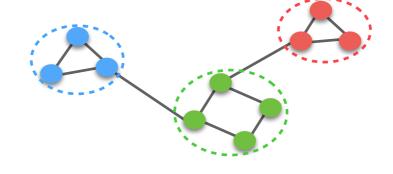




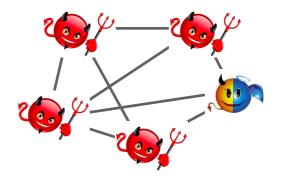
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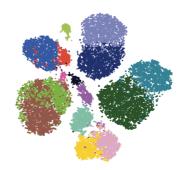
Community detection



Spam detection



Computational biology



. .

# Minimum versus average degree

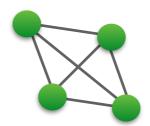
What should we look for?

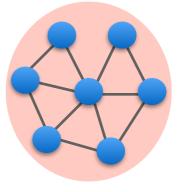
# Minimum versus average degree

What should we look for?

A subgraph with high average degree

$$\frac{|E|}{|N|}$$



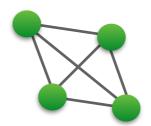


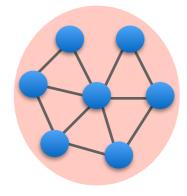
## Minimum versus average degree

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#### A subgraph with high average degree

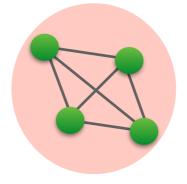
$$\frac{|E|}{|N|}$$

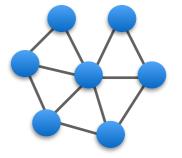




#### A subgraph with high minimum degree

$$\min d_v$$

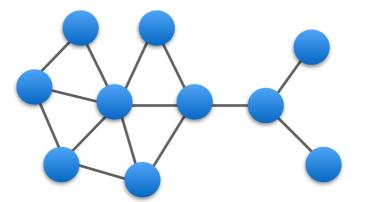




#### K-core definition

A K-core is a maximal subgraph of minimum degree K

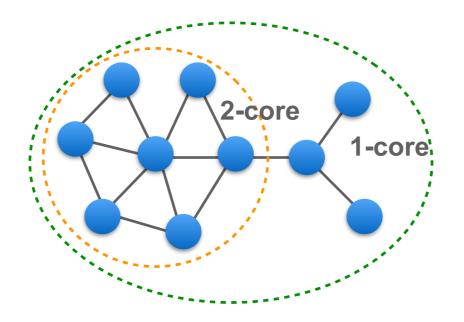
The coreness number of vertex v is maximum K for which v is part of the K-core

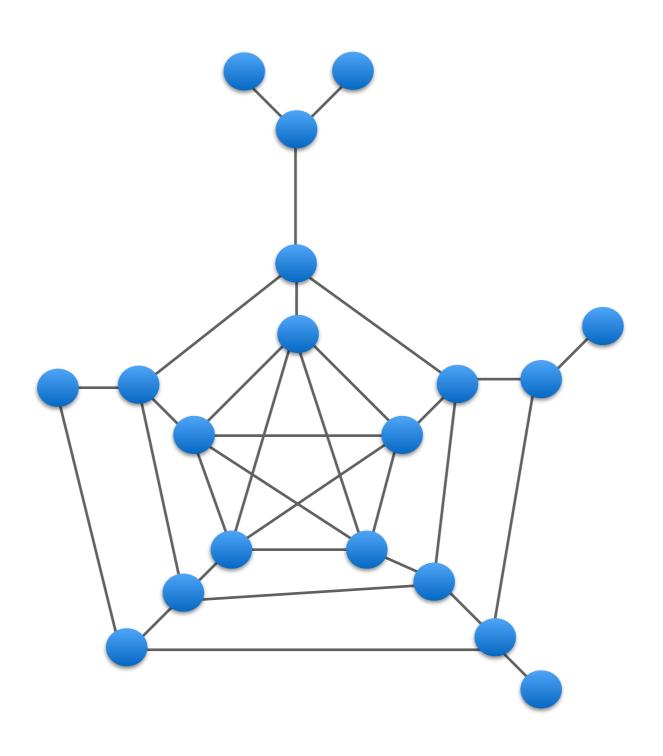


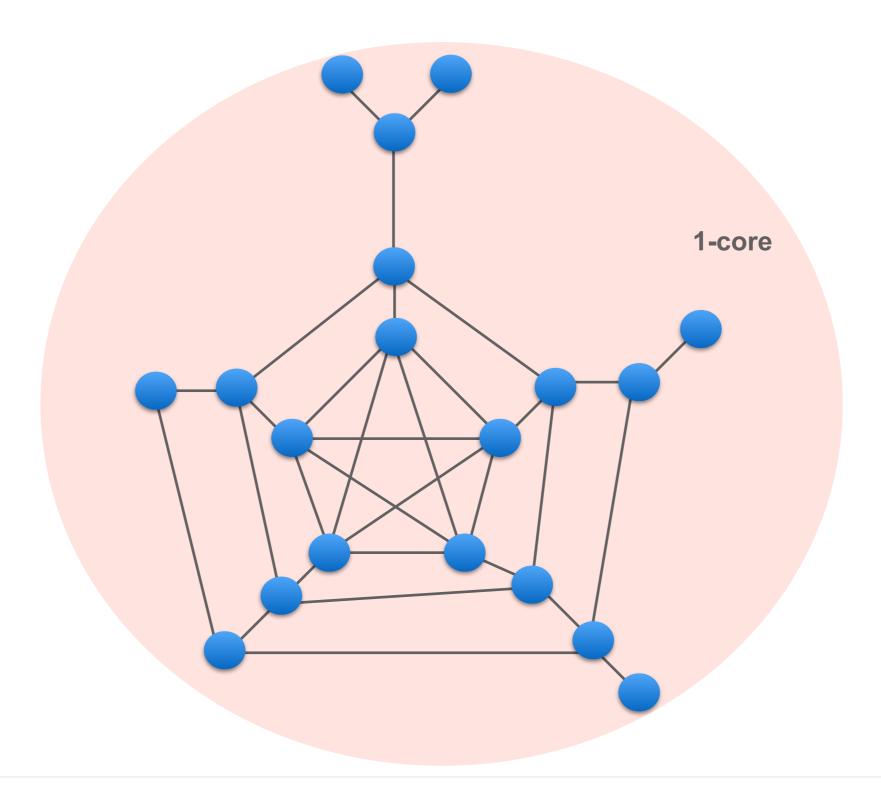
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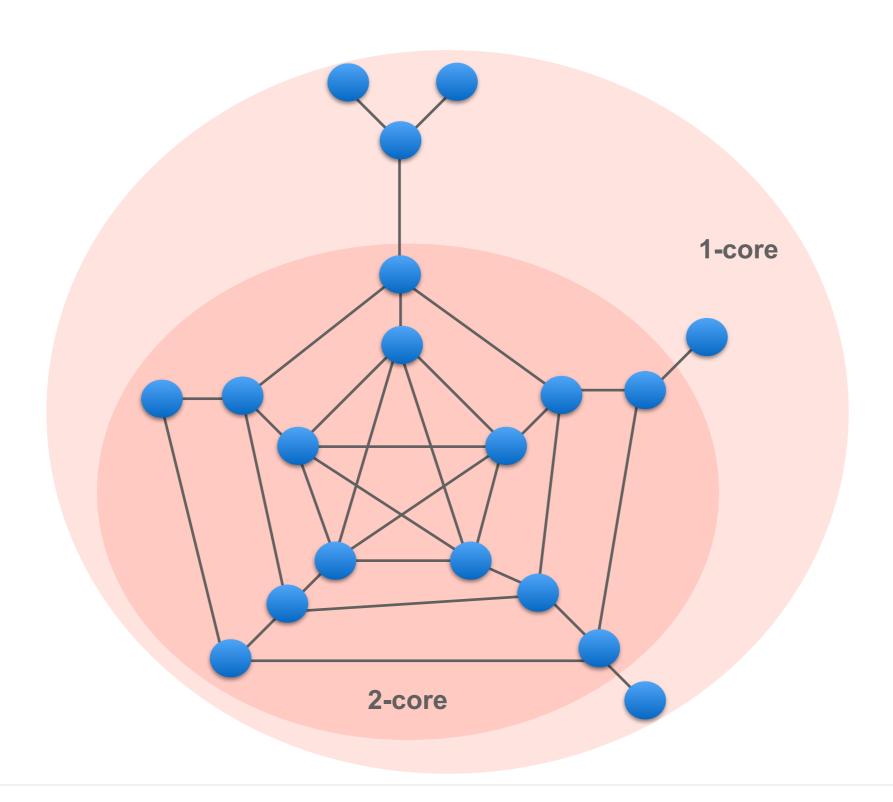
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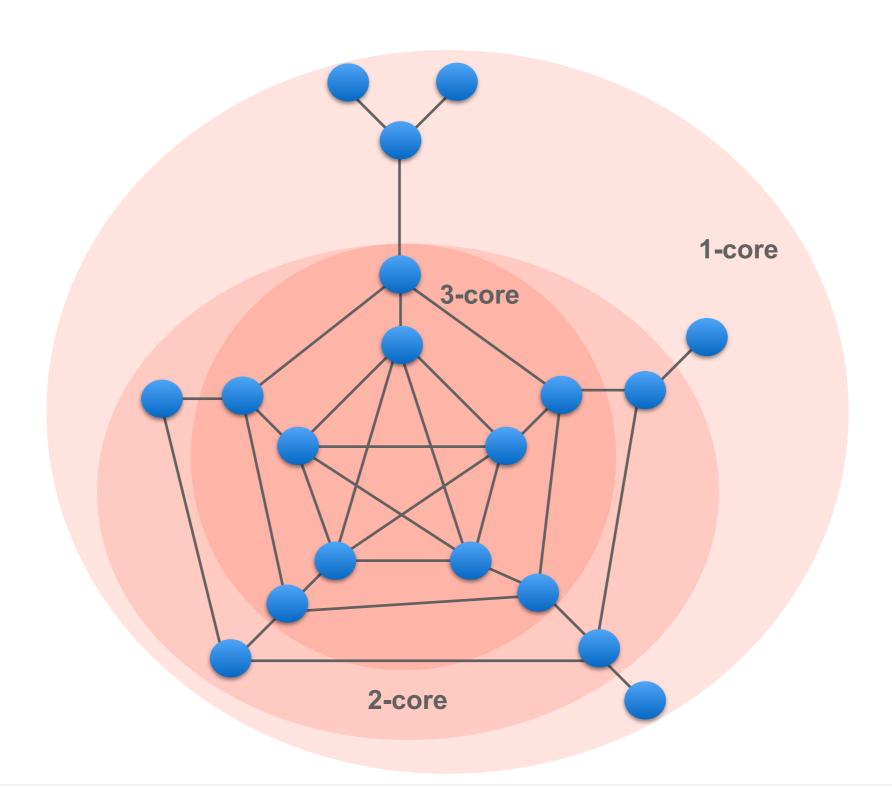
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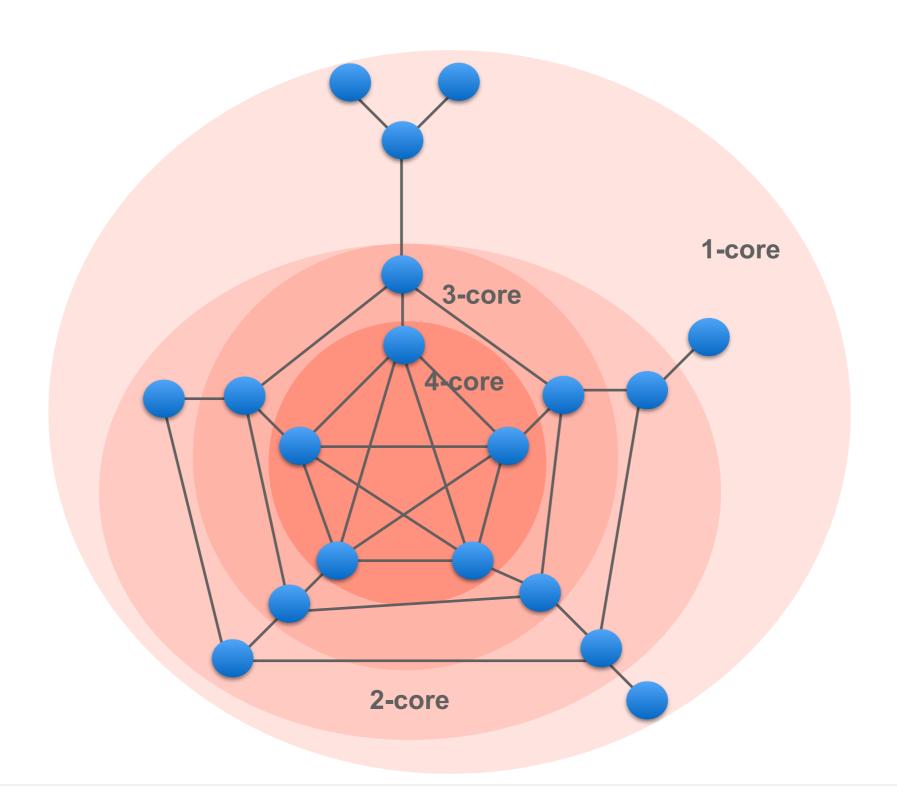






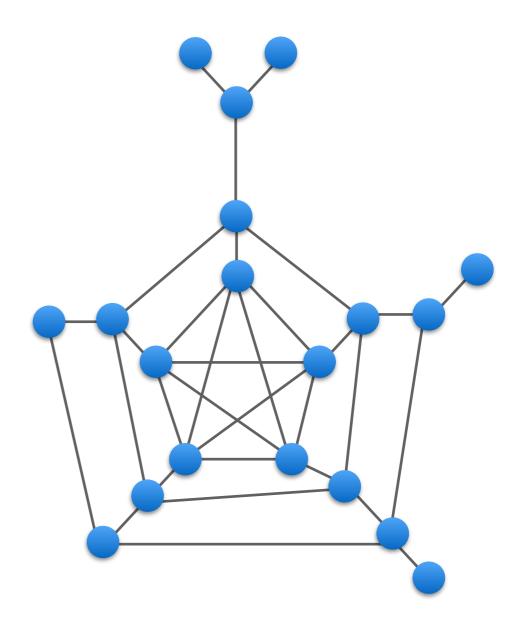






# Sequential algorithm

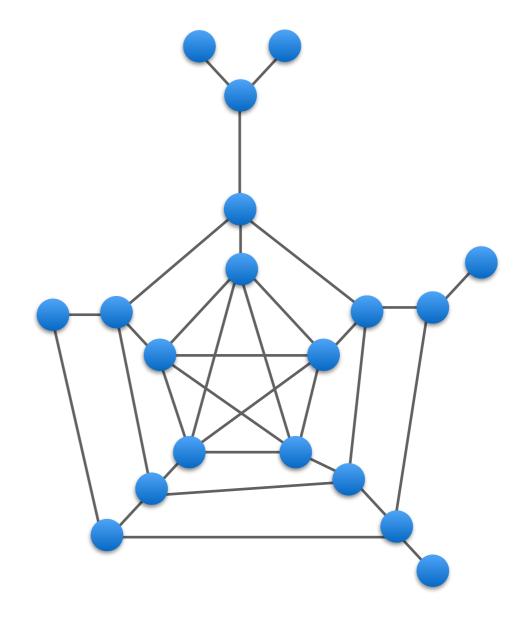
There is a simple algorithm to compute the coreness number of every node



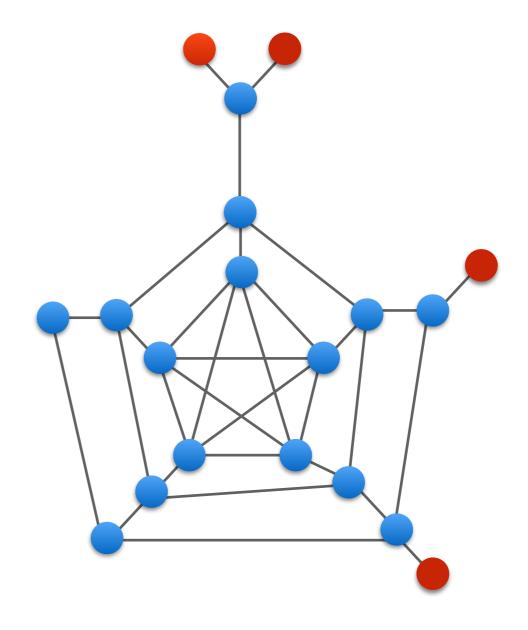
# Sequential algorithm

There is a simple algorithm to compute the coreness number of every node

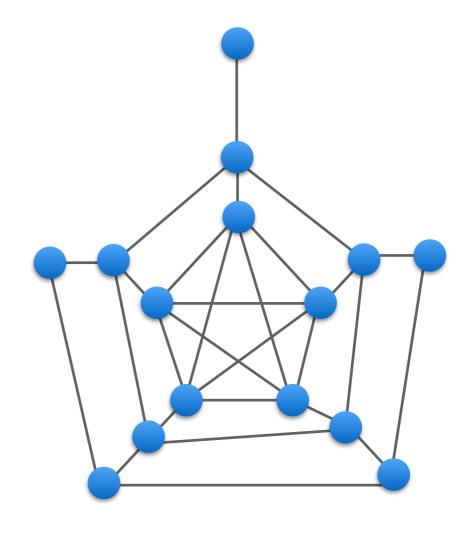
Remove all nodes of minimum degree from the graph and assign their current degree as their coreness number



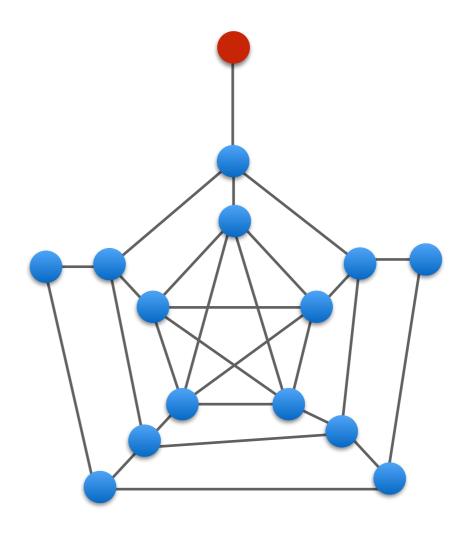
There is a simple algorithm to compute the coreness number of every node



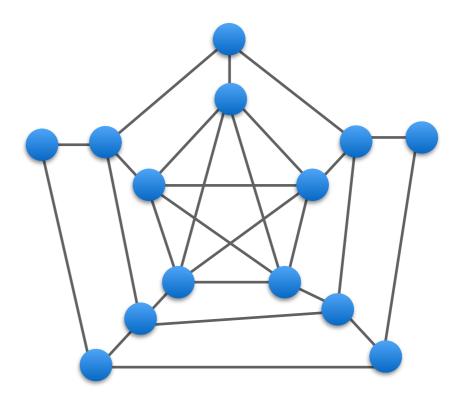
There is a simple algorithm to compute the coreness number of every node



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There is a simple algorithm to compute the coreness number of every node



### **Approximating K-core**

A  $(1 - \epsilon)$ -approximate K-core is a subgraph where:

- every node has degree at least  $(1-\epsilon){\rm K}$
- contains the K-core

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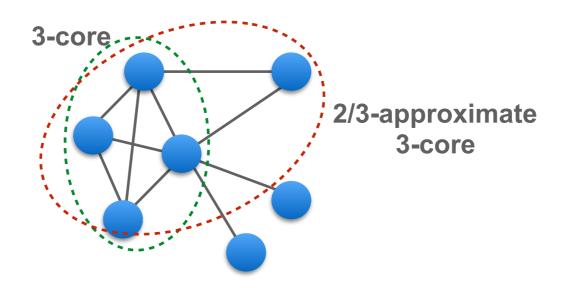
The  $(1-\epsilon)$ -approximate coreness number of vertex v is maximum K for which v is part of a  $(1-\epsilon)$ -approximate K-core

### **Approximating K-core**

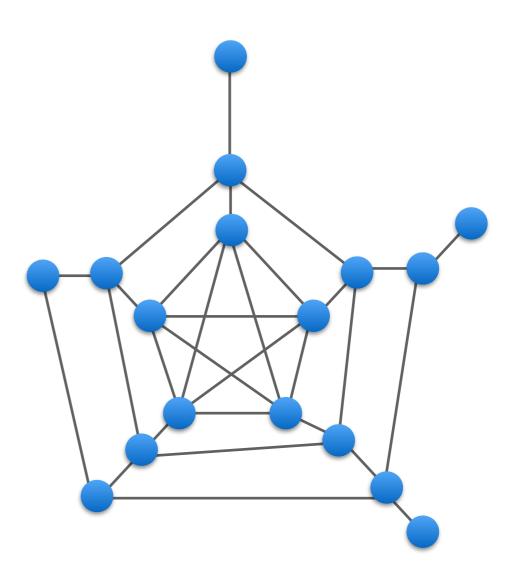
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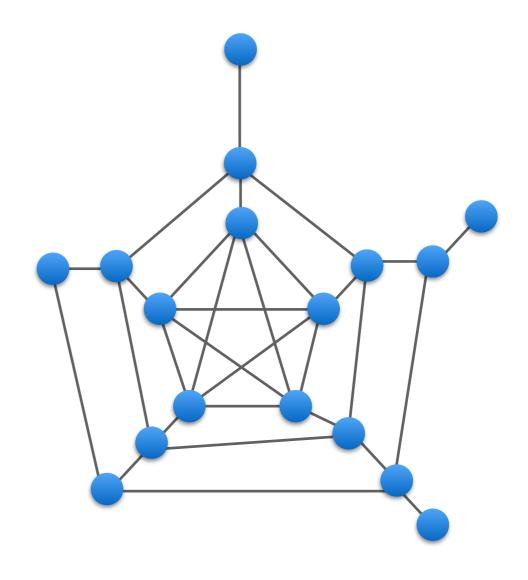
Find a small summary that can be used to approximate the instance



Find a small summary that can be used to approximate the instance

#### First idea:

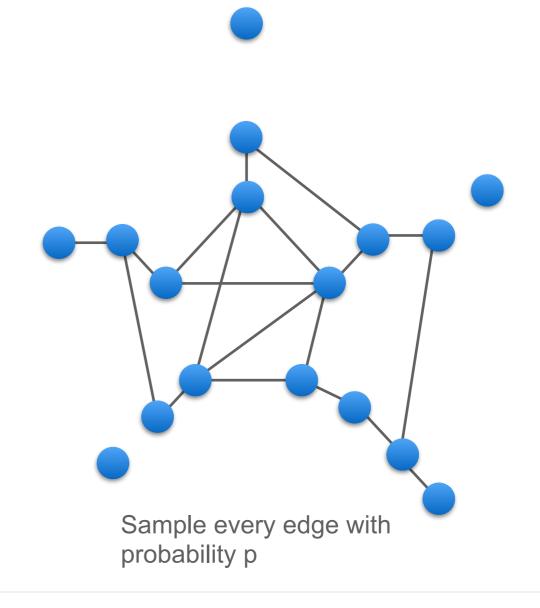
Use uniform sampling to sparsity the graph and then use sequential algorithm



Find a small summary that can be used to approximate the instance

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Use uniform sampling to sparsity the graph and then use sequential algorithm

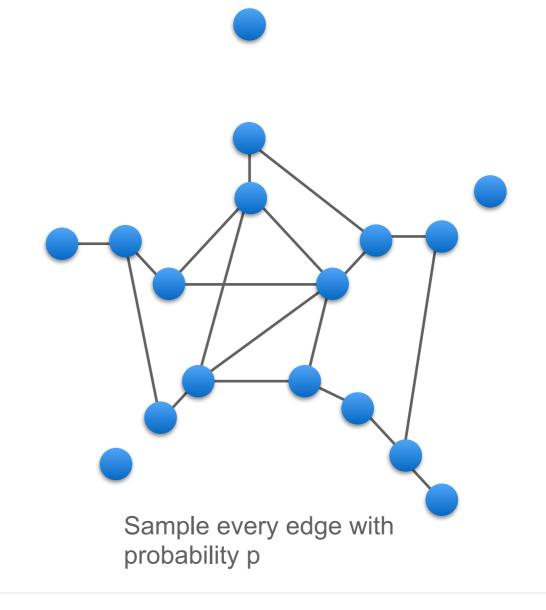


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#### Issue:

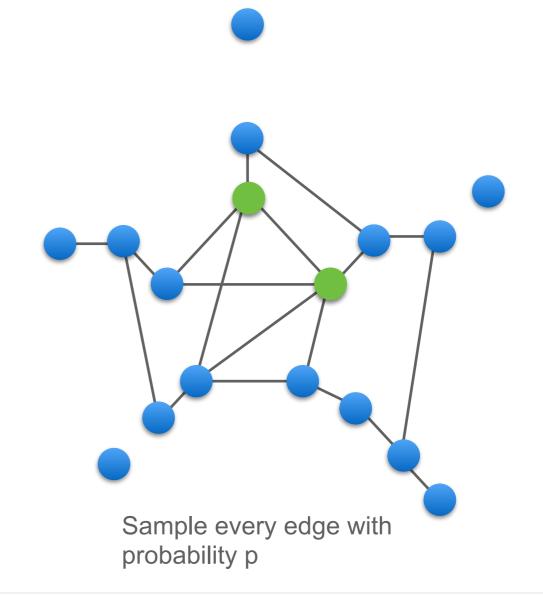


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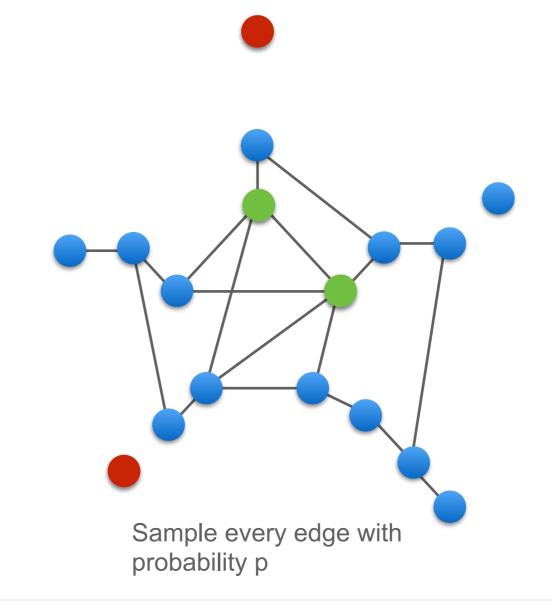


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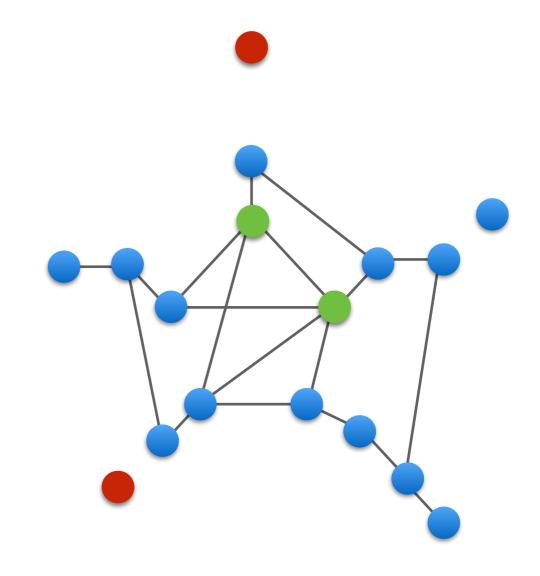
Find a small summary that can be used to approximate the instance

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Use uniform sampling to

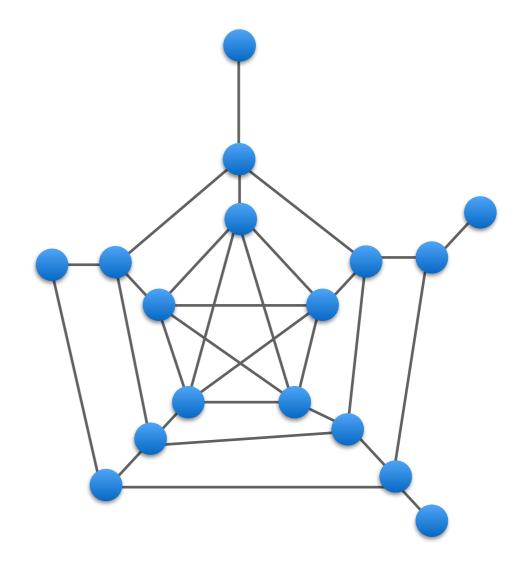
We want to estimate the coreness of every node

#### Issue:



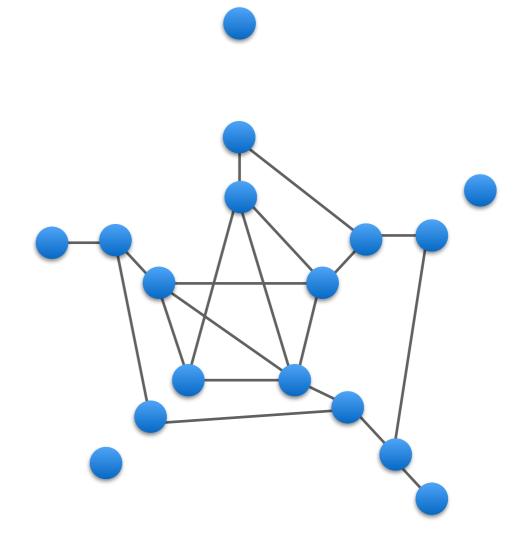
Find a small summary that can be used to approximate the instance

- Sample edge with probability p
- For nodes with high degree in the sample estimate the coreness number and add them to S
- Remove edges with both endpoints in S
- Multiply p by 2 and restart



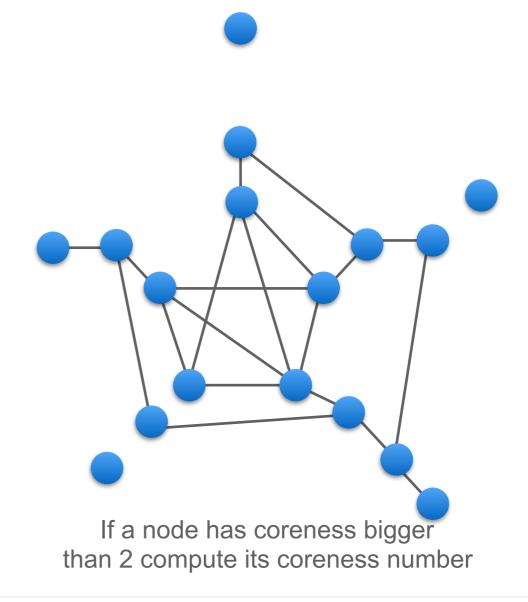
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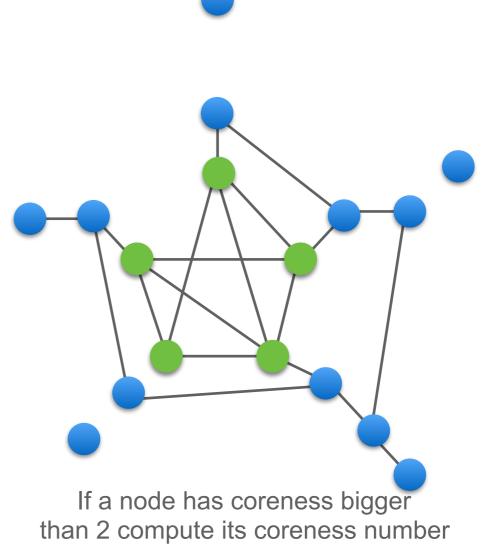
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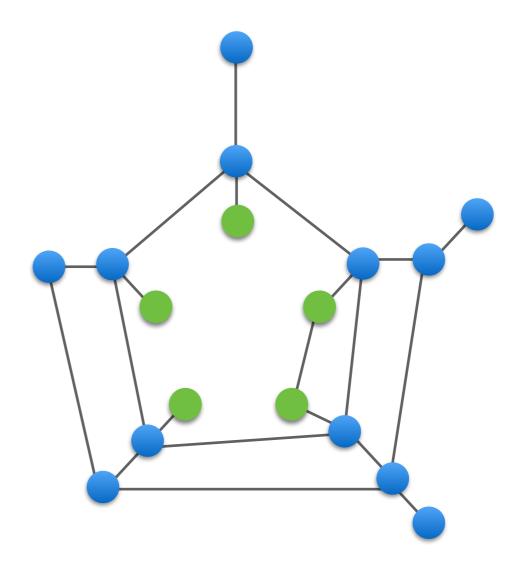
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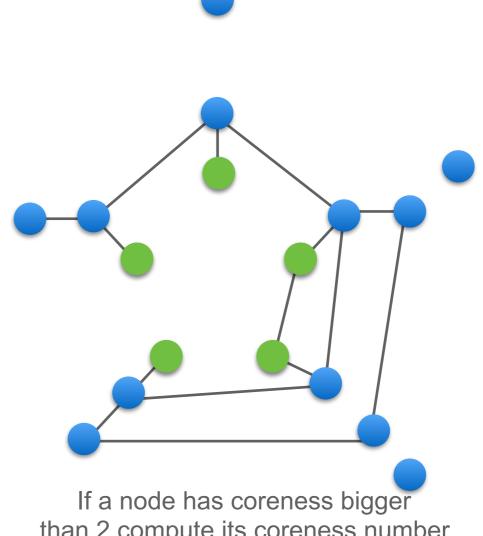
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Find a small summary that can be used to approximate the instance

#### Our algorithm:

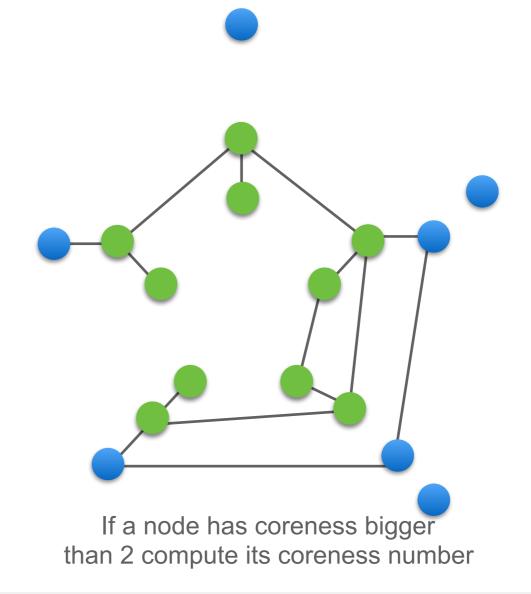
- Sample edge with probability p
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than 2 compute its coreness number

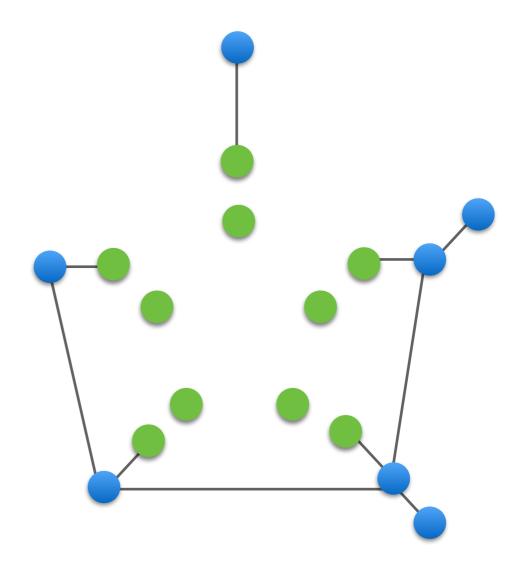
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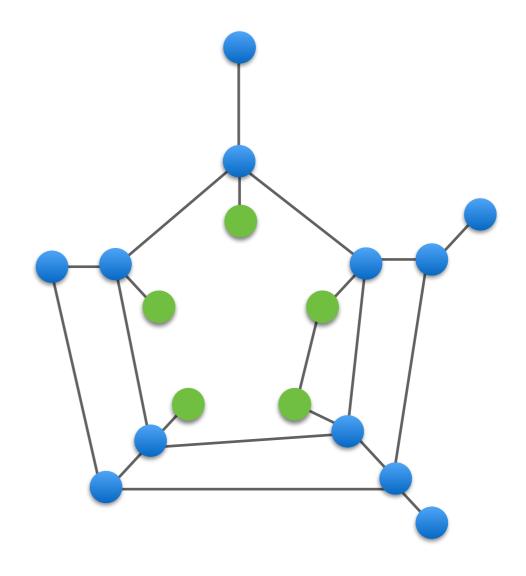


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#### Our algorithm:

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To estimate the coreness number, we run the sequential algorithm but we never remove nodes in S



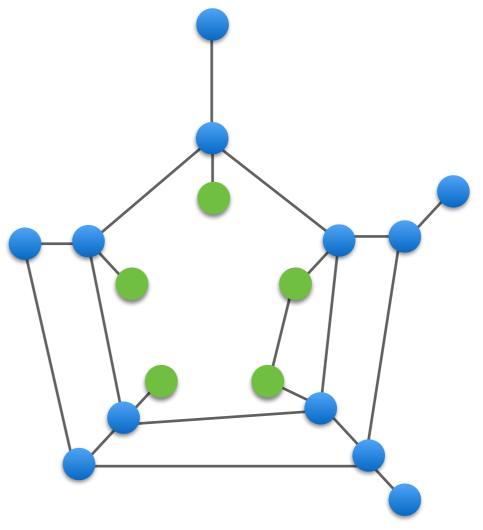
### Main properties

#### Quality of the solution

If a node has expected logarithmic coreness after sampling, its coreness number can be estimated precisely

#### Size of the sample

After each sample the number of edges left in the graph is almost linear in the number of nodes



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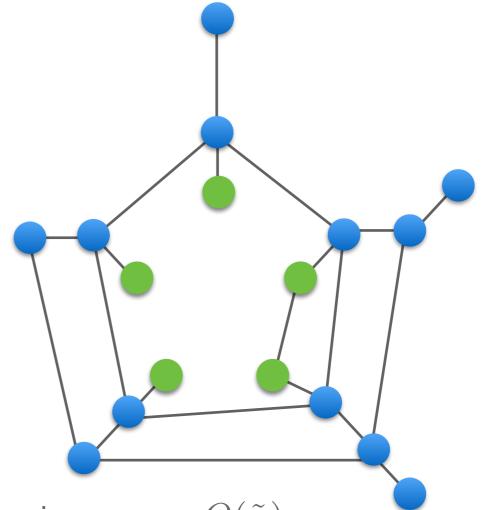
Parallel and streaming algorithms for K-core decomposition
Hossein Esfandiari, Silvio Lattanzi, Vahab S. Mirrokni
ICML 2018

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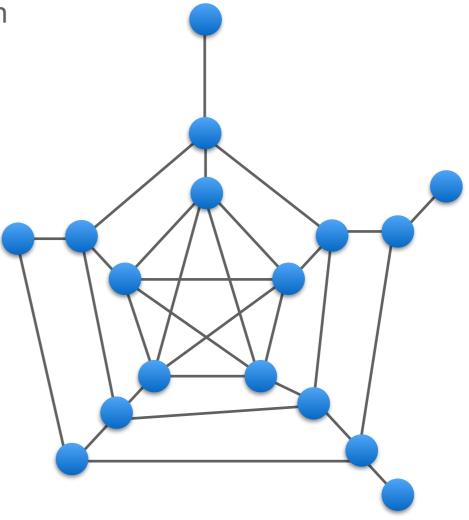


In  $O(\log n)$  rounds we get a good approximation using memory  $O(\tilde{n})$ 

### Can we do better?

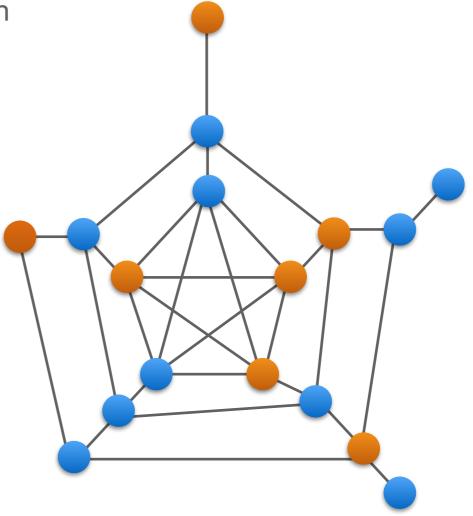
#### Sample vertices instead of edges

Sample vertices and consider the induce subgraph



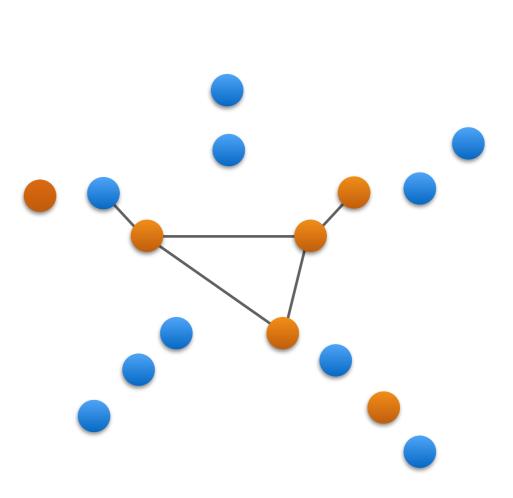
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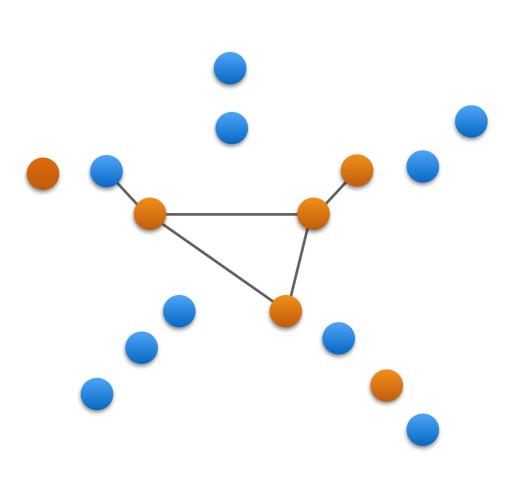


#### Sample vertices instead of edges

Sample vertices and consider the induce subgraph

#### Main advantage

Every edge is present with probability  $p^2$  For every sampled node a neighbour is sampled with probability p



#### Sample vertices instead of edges

Sample vertices and consider the induce subgraph

#### Main advantage

Every edge is present with probability  $p^2$  For every sampled node a neighbour is sampled with probability p

#### Reduction in a parallel round

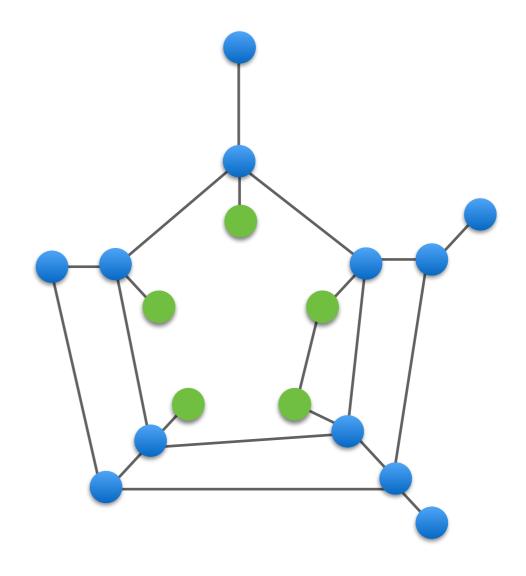
Every round we can reduce the maximum corners number exponentially

Find a small summary that can be used to approximate the instance

#### Our algorithm:

- Sample nodes with probability p
- For nodes with high coreness number in the sample estimate the coreness number and add them to S
- Remove edges with both endpoints in S
- Let  $p = p^{0.9}$

To estimate the coreness number, we run the sequential algorithm but we never remove nodes in S



### Main properties

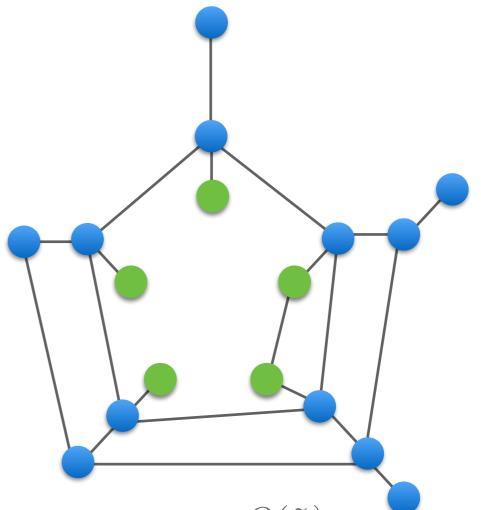
Improved Parallel Algorithms for Density-Based Network Clustering
Mohsen Ghaffari, Silvio Lattanzi, Slobodan Mitrovic
ICML 2019

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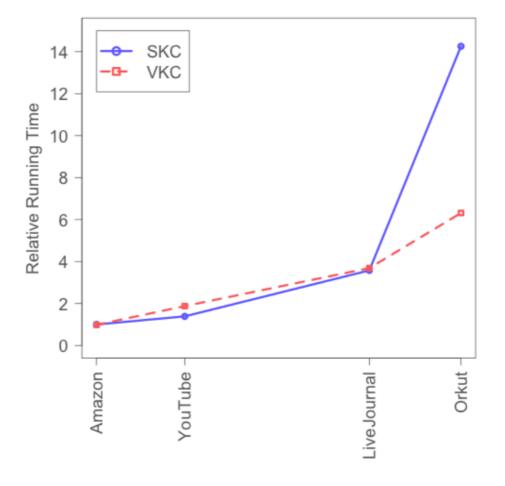


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### **Experiments**

Improved Parallel Algorithms for Density-Based Network Clustering
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ICML 2019

Graph	# Nodes	# Edges
Amazon	334,863	925,872
Youtube	1,134,890	2,987,624
LiveJournal	3,997,962	34,681,189
Orkut	3,072,441	117,185,083



# Conclusions and Future Work

### **Conclusions and Future Work**

Nice model that captures many real world scenarios

Very active area of research with many interesting results

Many open problems with practical applications

## **Thanks**