Lower Bounds for Distributed Sketching

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This Talk

- Distributed Sketching Model
- Is it an interesting model theoretically?
- Some lower bounds
- Open problems

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- Distributed Sketching Model
- Is it an interesting model <u>theoretically</u>?
- Some lower bounds
- Open problems

- Based on joint works with
 - Gillat Kol and Rotem Oshman (PODC 2020)
 - Gillat Kol and Zhijun Zhang (FOCS 2022)

• A Graph G = (V, E)



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- Input: edges of the vertex
- A referee with no input





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- Processors simultaneously send a message to the referee





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- Input: edges of the vertex
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- Processors simultaneously send a message to the referee
- Referee outputs the solution
- Access to shared randomness







This model is also called Broadcast Congested Clique (one-round algorithms)

*∧*éree

- Referee outputs the solution
- Access to shared randomness

This model is also called Broadcast Congested Clique (one-round algorithms) It is also closely related to Dynamic Graph Streaming (single-pass algorithms)

*r*éree

- Referee outputs the solution
- Access to shared randomness

- Everything same as before
- Blackboard instead of a referee





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- Everything same as before
- Blackboard instead of a referee
- Read the blackboard at the end of the round



- Everything same as before
- Blackboard instead of a referee
- Read the blackboard at the end of the round
- Communicate based on the new information in the next round





sefore

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 \frown

It is also closely related to Dynamic Graph Streaming (multi-pass algorithms)



 Every problem can be solved with O(n) size messages in a single round







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Every node write all its edges on the board





- Every problem can be solved with O(n) size messages in a single round
- Too much communication!

Every node write all its edges on the board











Are There Even "Non-Trivial" Algorithms in this Model?

• Can we find a spanning tree of this graph in a single round?





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"Non-Trivial" Algorithms?

- Can we find a spanning tree of this graph in a single round?
- How can the two endpoints inform the referee about the crucial edge?
- Important observation: Edges are shared by both endpoints
- Other nodes can also inform the referee about this edge!



• Assign a unique number to each edge





- Assign a unique number to each edge
- Direct edges and write the number or its negation on each edge based on direction



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- Direct edges and write the number or its negation on each edge based on direction



- Assign a unique number to each edge
- Direct edges and write the number or its negation on each edge based on direction
- Each node sends sum of the numbers on its edges











Distributed Sketching Algorithms

• AGM sketch of Ahn, Guha, and McGregor [AGM12a]: $O(\log^3(n))$ size messages for finding a spanning forest of every graph with high probability.

n: number of vertices

Distributed Sketching Algorithms

- AGM sketch of Ahn, Guha, and McGregor [AGM12a]: $O(\log^3(n))$ size messages for finding a spanning forest of every graph with high probability.
- Extended to various other problems:
 - MST and edge connectivity [AGM12a]
 - Vertex connectivity [GMT15][AS22]
 - Subgraph Counting [AGM12b]
 - Sparsifiers and approximate min/max cuts [AGM13, KLMMS14]
 - Spanners and approximate shortest paths [FKN21]
 - Densest Subgraph, degeneracy, and arboricity [BHNT15, MTSV15, CT16]
 - Graph coloring [ACK19][BCG20][AKM22][HKNT22]

Majority of these results only need a single round!

n: number of vertices

What About Lower Bounds?

• A key tool for proving lower bounds: communication complexity

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- Some reasons:
 - There are surprisingly strong algorithms that defy intuition
 - Edge sharing makes the model different from ``typical" distributed communication complexity lower bounds
 - Number-in-hand vs Number-on-forehead

- A key tool for proving lower bounds: communication complexity
- Proving lower bounds in this model can be challenging
- Some reasons: It is more challenging but not impossible!
 - There are surprisingly strong algorithms that defy intuition
 - Edge sharing makes the model different from ``typical" distributed communication complexity lower bounds
 - Number-in-hand vs Number-on-forehead

• Three categories of lower bounds:

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- Problems that are "hard" even for close to *n* rounds

 $\Omega(n)$ total communication is needed regardless of # rounds

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- E.g., spanning forest and connectivity [NY19,Y21]
- Problems that are "hard" initially but become "easy" in a few number of rounds (are round-sensitive)

 $\log^{O(1)}(n)$ communication needs at least $\Omega(\log \log n)$ rounds

- E.g., MIS and maximal matching [AKO20, AKZ22]

Distributed Sketching Lower Bounds for MIS and Maximal Matching

Maximal Matching and Maximal Independent Set



Maximal Matching and Maximal Independent Set



Algorithms for MIS and Matching?

- Luby's algorithm [L86] gives protocols for both problems with $O(\log n)$ round and $O(\log n)$ communication per-player
- [GGKMR18] gives an $O(\log \log n)$ round algorithm for MIS with $\log^{O(1)}(n)$ communication per-player on average

[A, Kol, Oshman; 2020]

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Corollary: $\Omega(\log \log n)$ rounds are necessary for $\log^{O(1)}(n)$ communication

Lower Bounds for Maximal Matchings

- On each side:
 - *n* vertices
 - $-\sqrt{n}$ fooling vertices
 - $n \sqrt{n}$ principal vertices



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Any maximal matching needs many special edges

A similar-in-spirit construction to lower bounds for approximate matching in dynamic streams [K15,<u>A</u>KLY16]



• Analysis?



- Analysis?
- From the perspective of principal vertices:



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- "On their own", sending $o(\sqrt{n})$ bits only reveals o(1) bits about the special edges
- But fooling vertices's messages can change this


Send edges specifically to this principal vertex

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Send sum of edge IDS

- Analysis?
- From the perspective of fooling vertices:
- \sqrt{n} fooling vertices can reveal o(n) information in total no matter what they know
- So we can "decompose" the revealed information between fooling and principal vertices

A símílar ídea was used first by [NY19,Y21] for spanning forest



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- The total information revealed about the special edges:



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- The total information revealed about the special edges:

$\mathbb{I}(\text{special edges}; \text{msg}) \leqslant$

$$n \cdot \frac{o(\sqrt{n})}{\sqrt{n}} + \sqrt{n} \cdot o(\sqrt{n}) = o(n)$$



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$$n \cdot \frac{o(\sqrt{n})}{\sqrt{n}} + \sqrt{n} \cdot o(\sqrt{n}) = o(n)$$

of principal vertices # of fooling vertices
Their limited knowledge Their limited bandwidth



- Analysis?
- The total information revealed about the special edges: o(n) bits
- Not enough to reveal enough edges for the maximal matching



• Conclusion:

Any single-round protocol for maximal matching requires $\Omega(\sqrt{n})$ communication per-player in worst case

- On each side:
 - N blocks of vertices with $N^{1/5}$ vertices
 - $N^{2/5}$ fooling blocks
 - $N N^{2/5}$ principal blocks





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A fooling instance: Marginally to each vertex looks like an actual (r-1) instance

Based on a brilliant idea introduced by [ANRW15] for one-sided matching problem



- From the perspective of principal blocks:
 - They play in $N^{2/5} (r-1)$ -round instances
 - They need to solve their special instance
- Obliviousness implies with $o(N^{1/5})$ communication per-player, only o(1) bits is revealed about their special instance in the first round



- From the perspective of fooling blocks:
- Limited bandwidth implies with $o(N^{1/5})$ communication per-player, they can only reveal $o(N^{4/5})$ bits in total in the first round



- So, after the first round:
- o(1) bits is revealed about most principal (r 1) round instances
- So, the distributions of these instances remain almost the same even after the first message
- But the players now only have (*r* - 1) rounds to solve these instances



• The standard approach at this point: round elimination



 $N^{2/5}$

- The standard approach at this point: round elimination
- This is "communication complexity round elimination" as opposed to "LOCAL round elimination"
 - [Duris, Galil, and Schnitger; STOC 1984]
 - [Nisan, Wigderson; STOC 1991]



- Use any *r*-round protocol to get an (*r* 1)-protocol:
 - Embed the (r 1)-round instance in a random principal instance
 - Sample the first message of the protocol without communication
 - Run the protocol from its second-round onwards
 - Simulate the remaining players



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 - They continue "injecting noise" throughout the protocol, not only in the first round
- Main novelty: a new round elimination approach based on a non-simultaneous simulation of other players via only their messages not their inputs



• Conclusion:

Any *r*-round protocol for maximal matching requires $\Omega(n^{1/10^{r+1}})$ communication per-player in worst case

- We can prove "some" multi-round lower bounds for roundsensitive problems
- Two key techniques:
 - A novel round elimination via simulating players through their messages and not their inputs
 - Core component: break the dependency of edge sharing by limiting the number of "fooling vertices"
 - There are "few" players whose removal makes proving the rest of the argument an "easy" number-in-hand communication argument

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- They don't seem tight even for one-round protocols

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- Two key techniques:

This is a lossy argument in general (both here and elsewhere)

- A novel round elimination via simulating players through their messages and not their inputs
- Core component: break the dependency of edge sharing by limiting the number of "fooling vertices"
 - There are "few" players whose removal makes proving the rest of the argument an "easy" number-in-hand communication argument.
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 we have no "handle" on the type of information revealed by these vertices only it size

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 - Extend [AKZ22] lower bound to average communication (to match [GGKMR18] protocol)
 - Prove $\Omega(n)$ one-round lower bounds for MIS and matching (to match trivial bounds)

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