

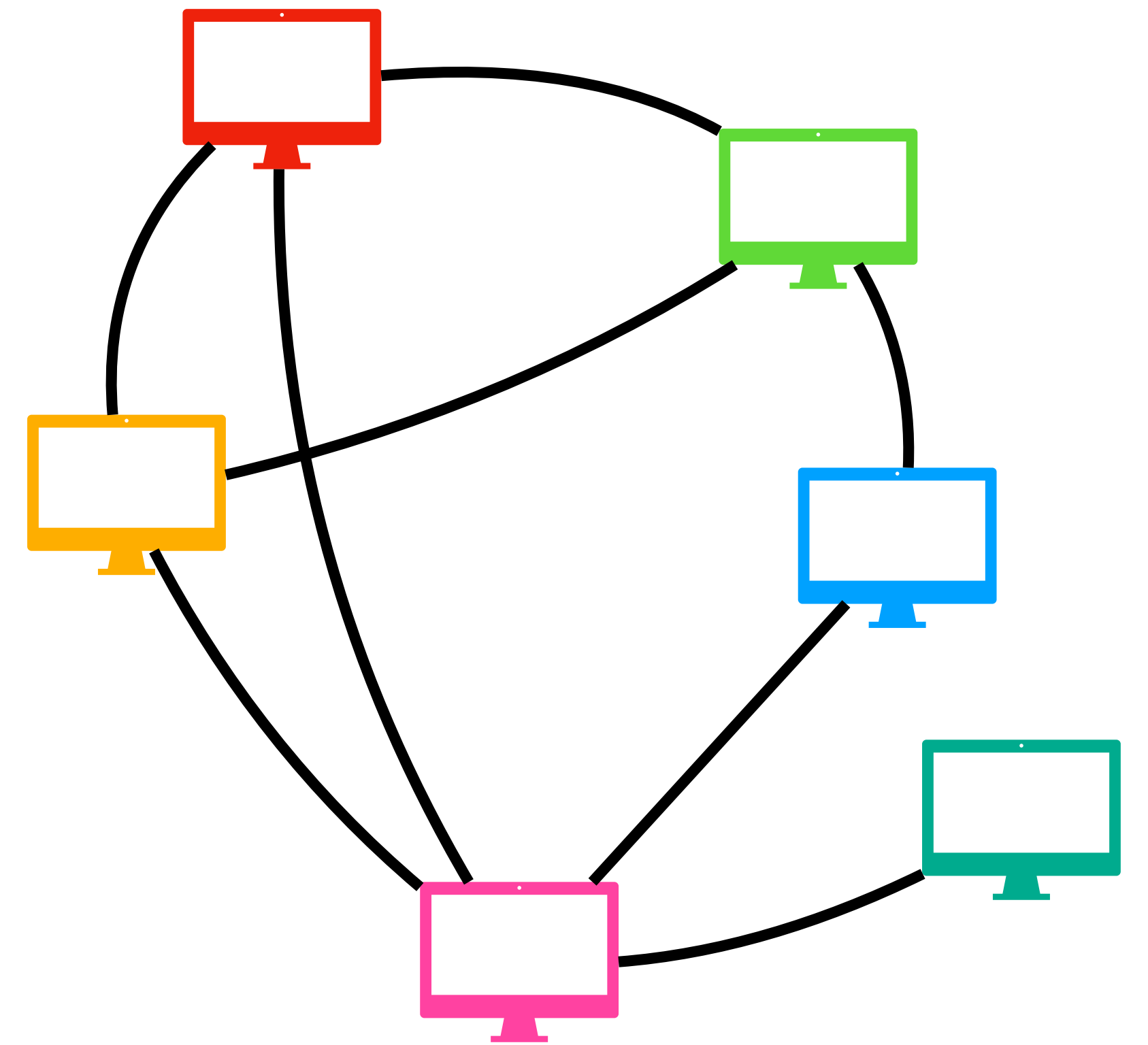
Message Complexity of Distributed Graph Algorithms

Shreyas Pai
IIT Madras



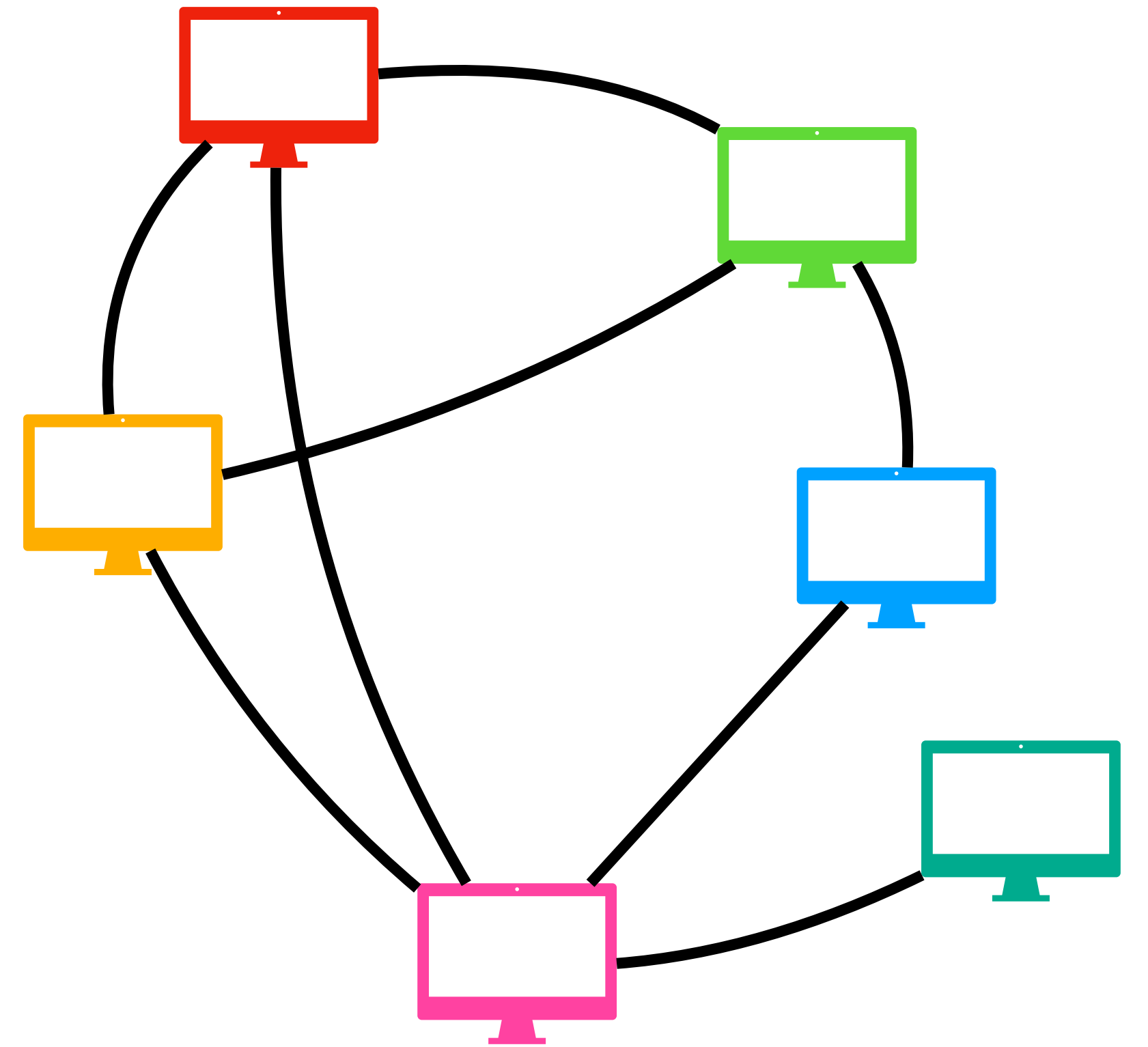
Advances in Distributed Graph Algorithms, ADGA 2024

The CONGEST Model



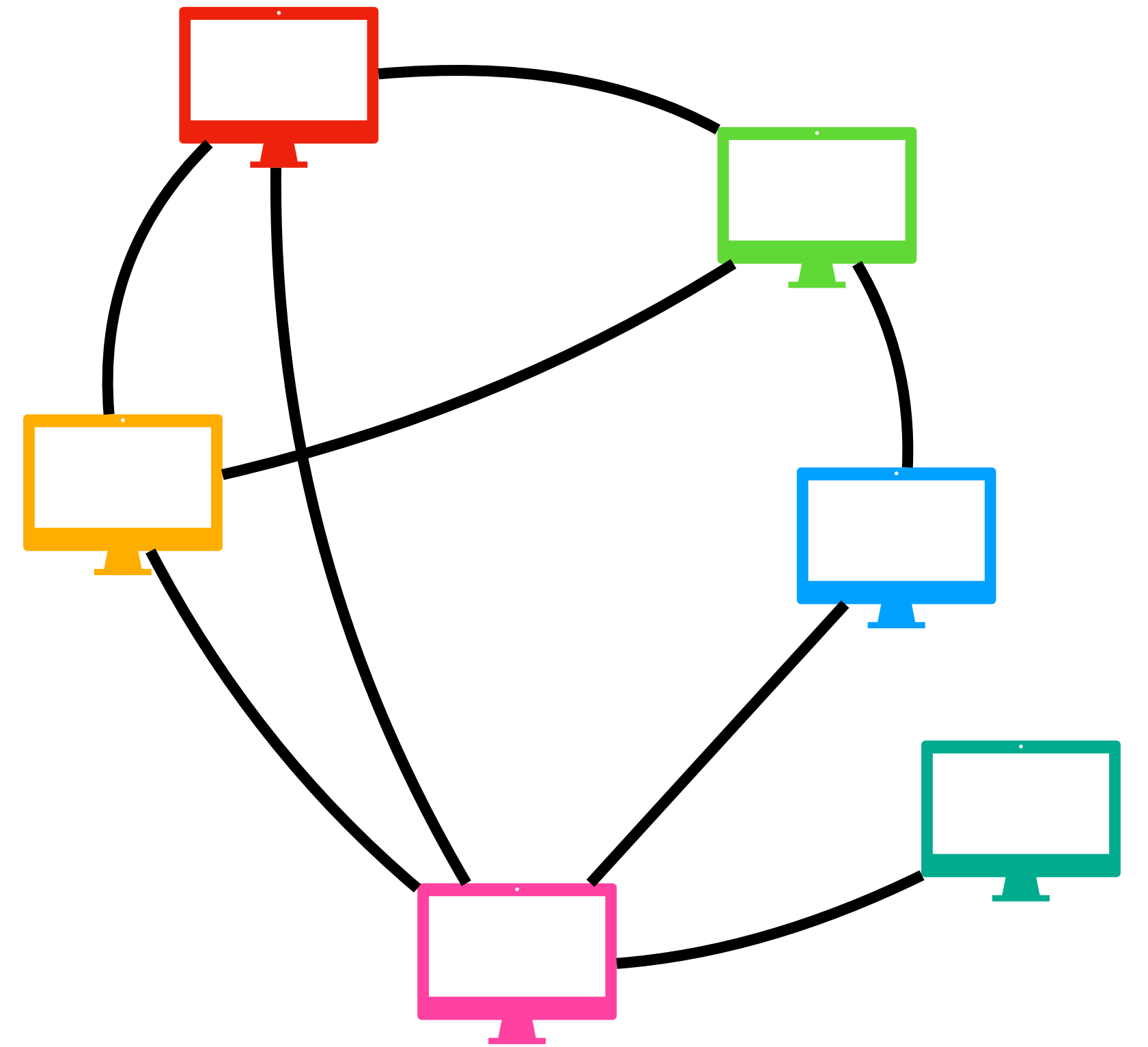
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- Given a graph G which is the communication network.



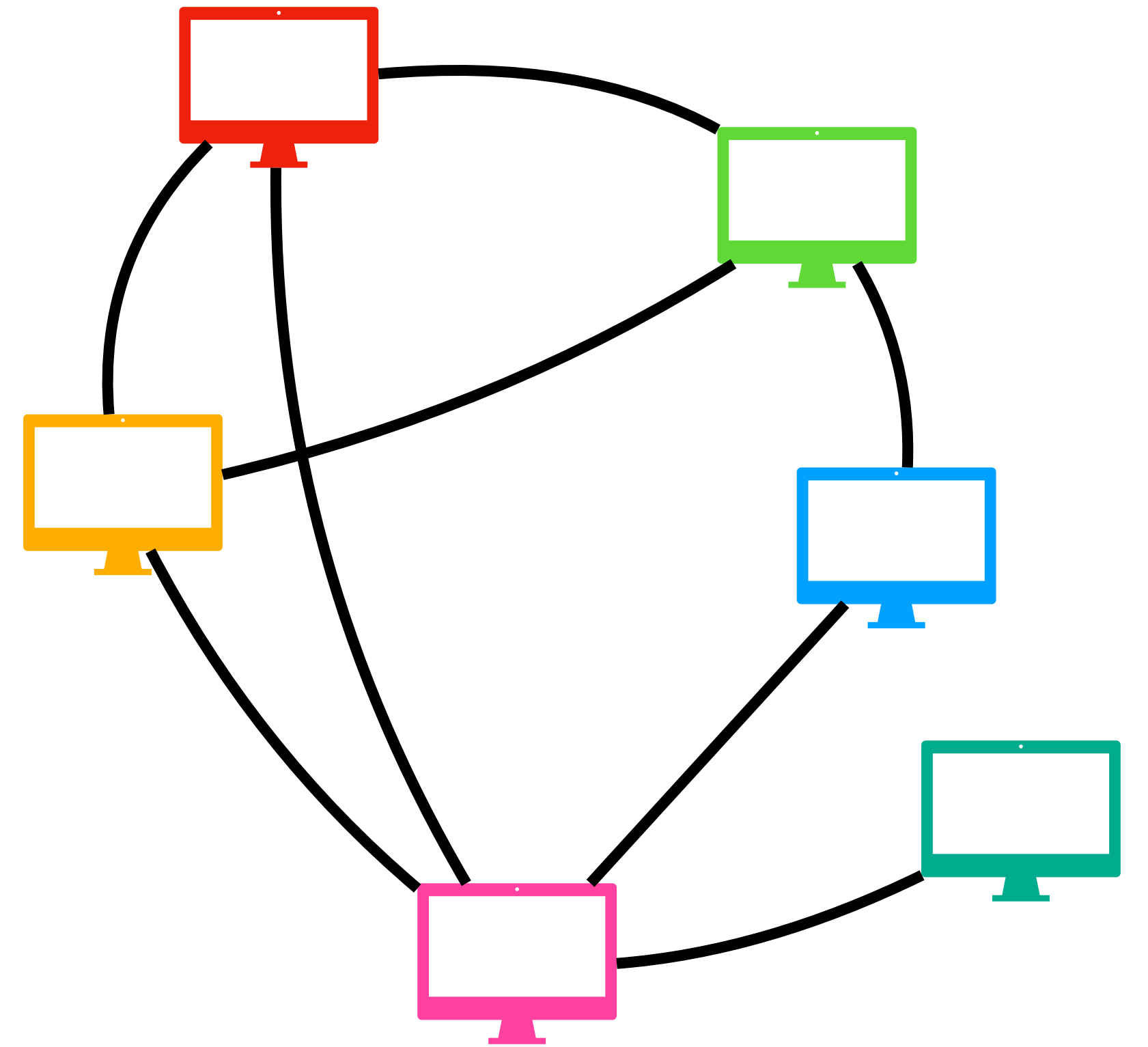
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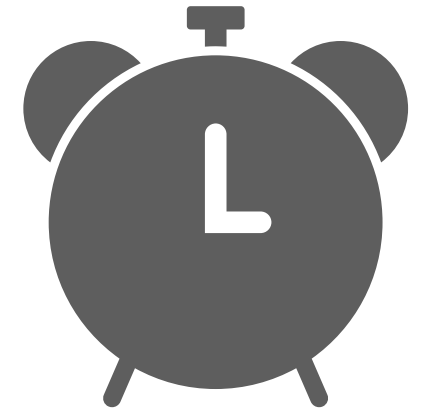


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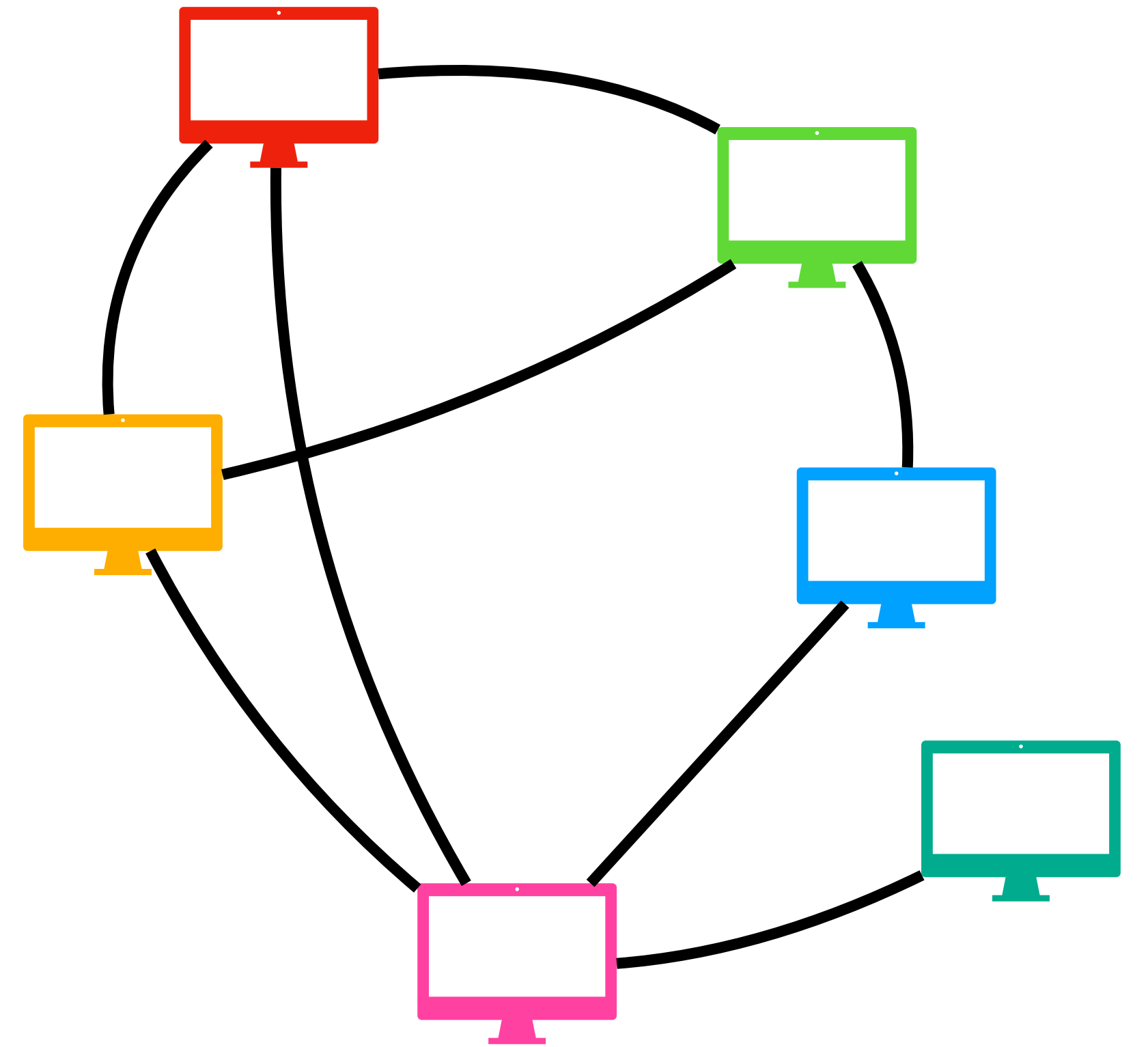
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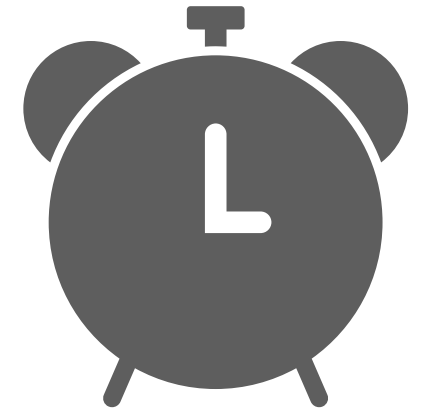
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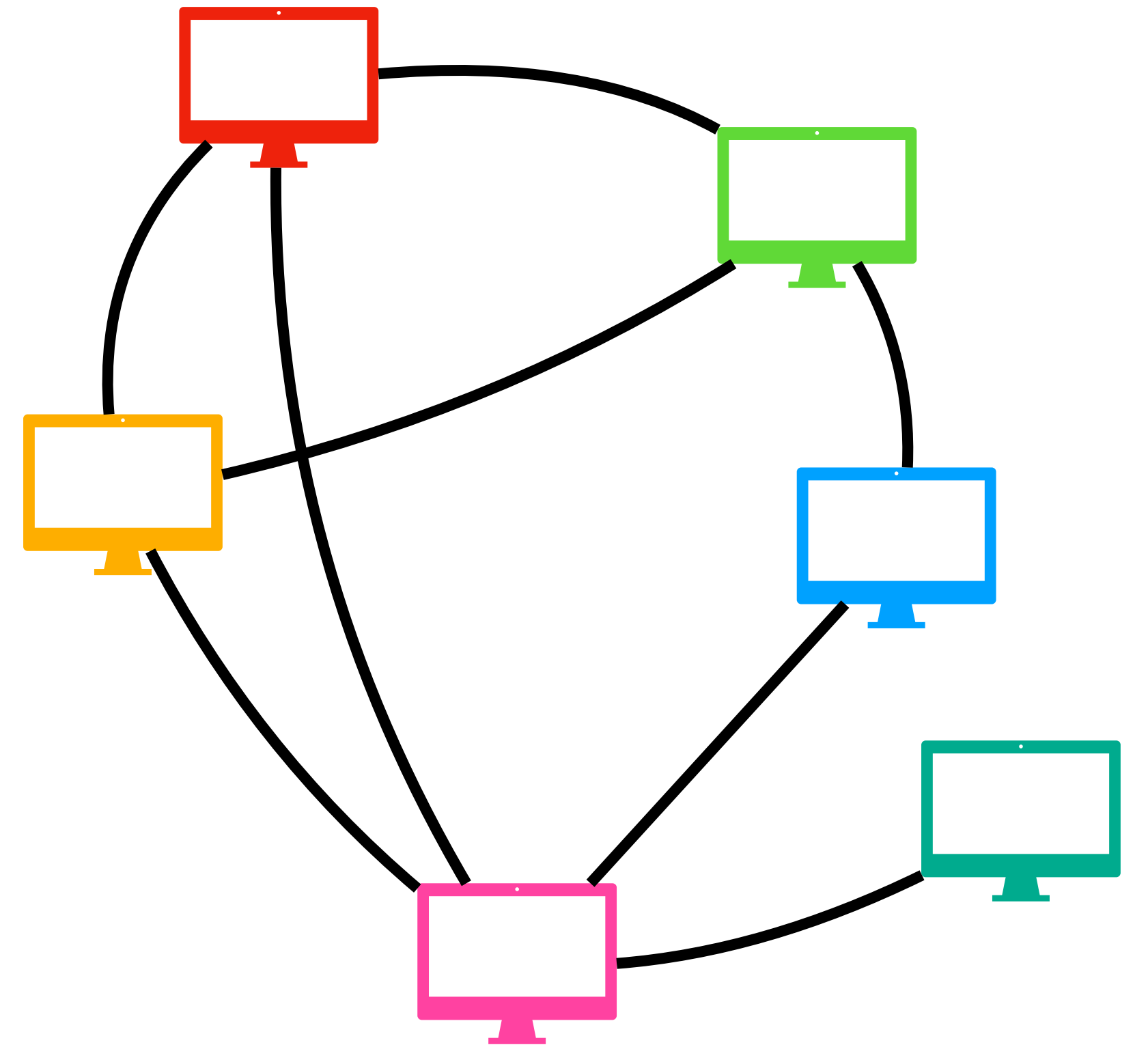
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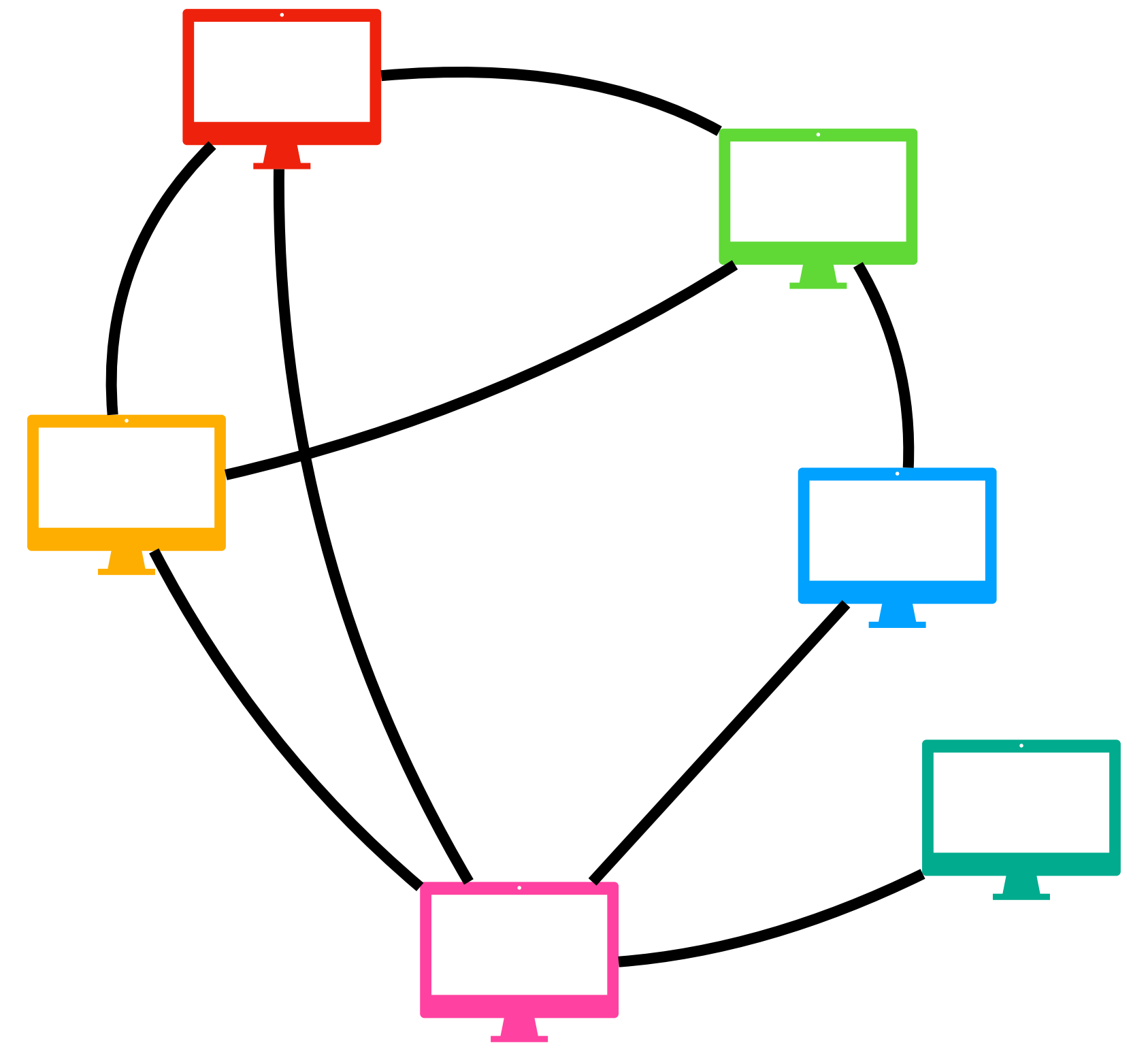
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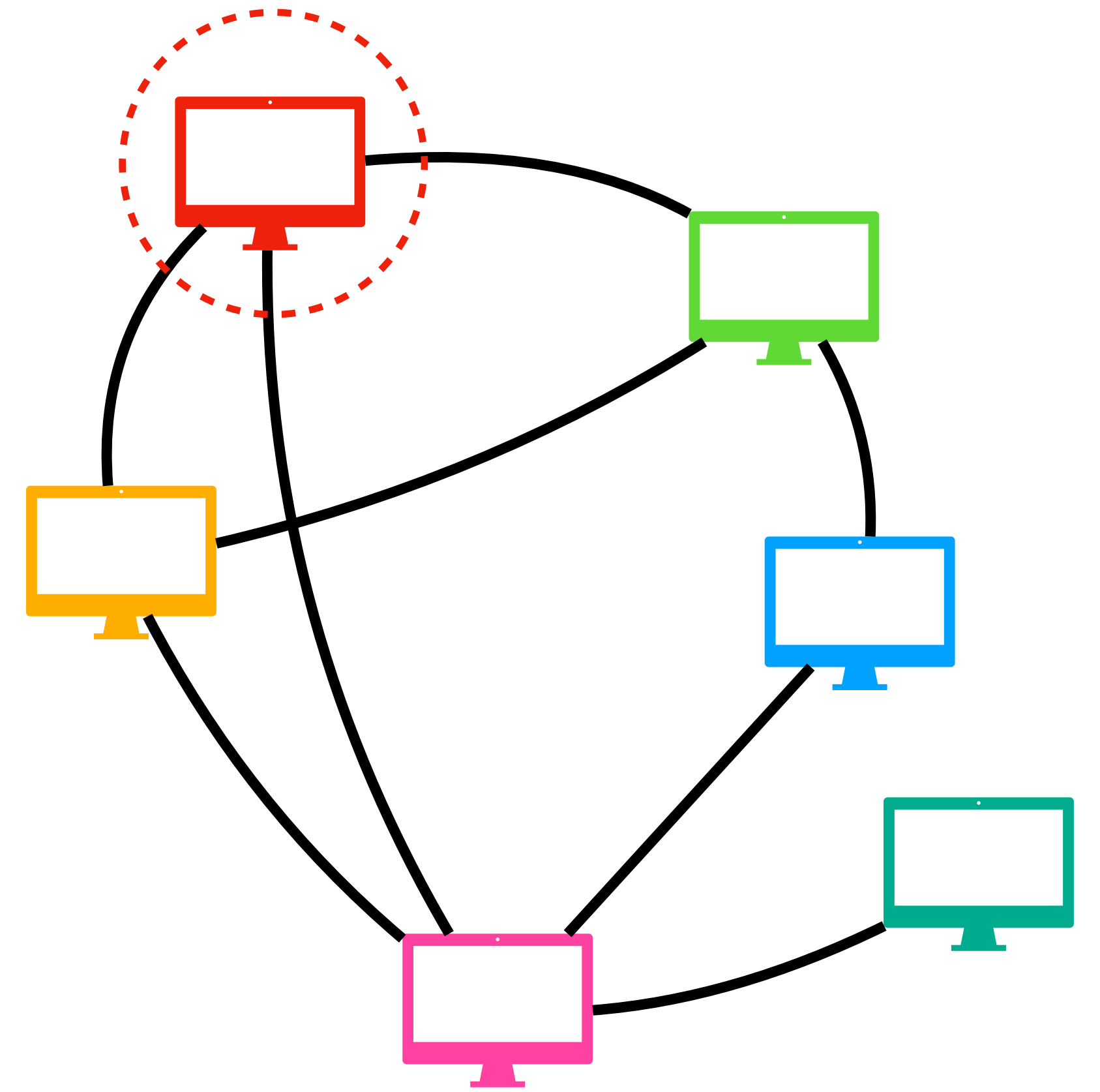
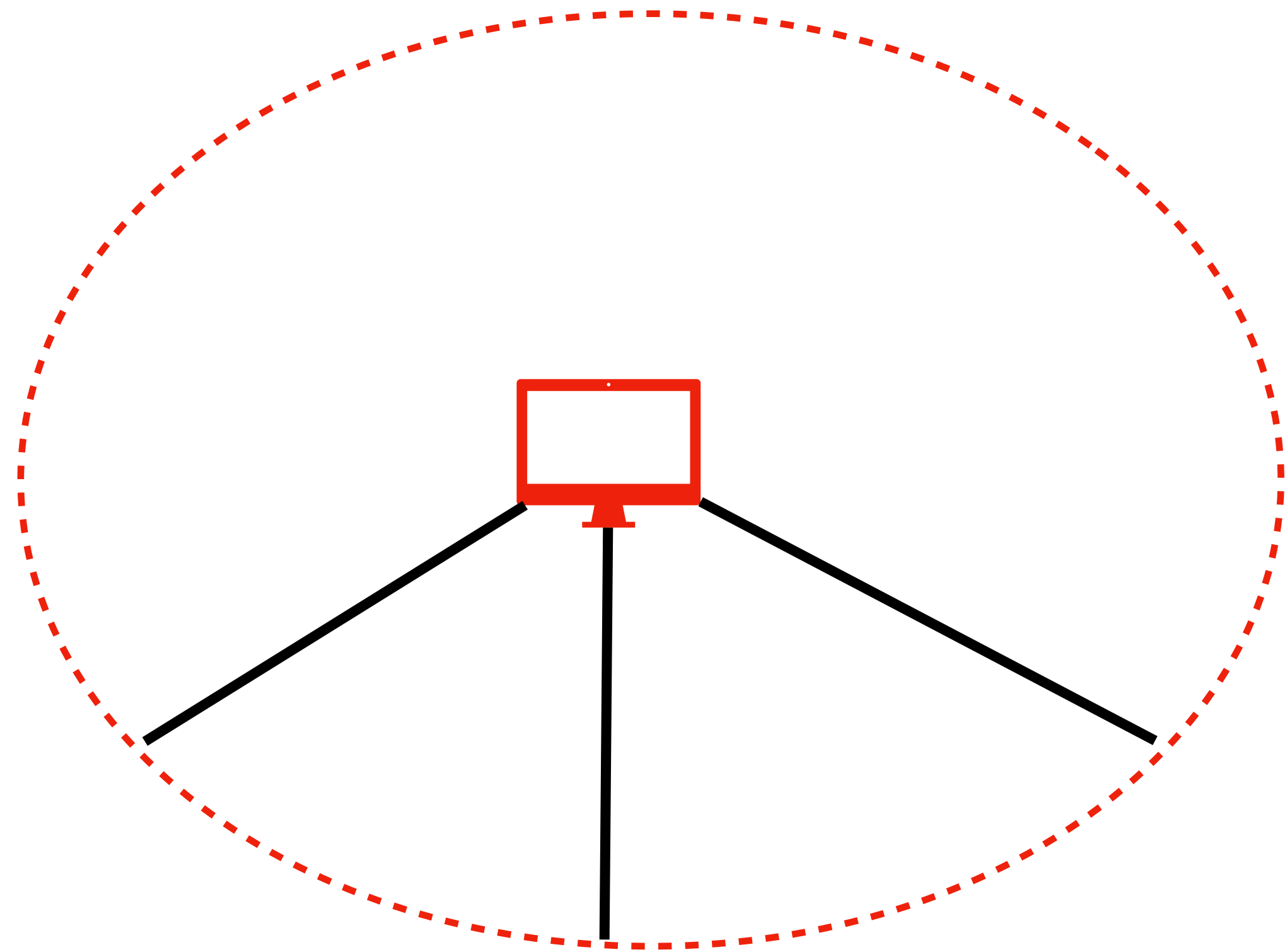
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- Nodes send $O(\log n)$ -bit messages per neighbor per round.



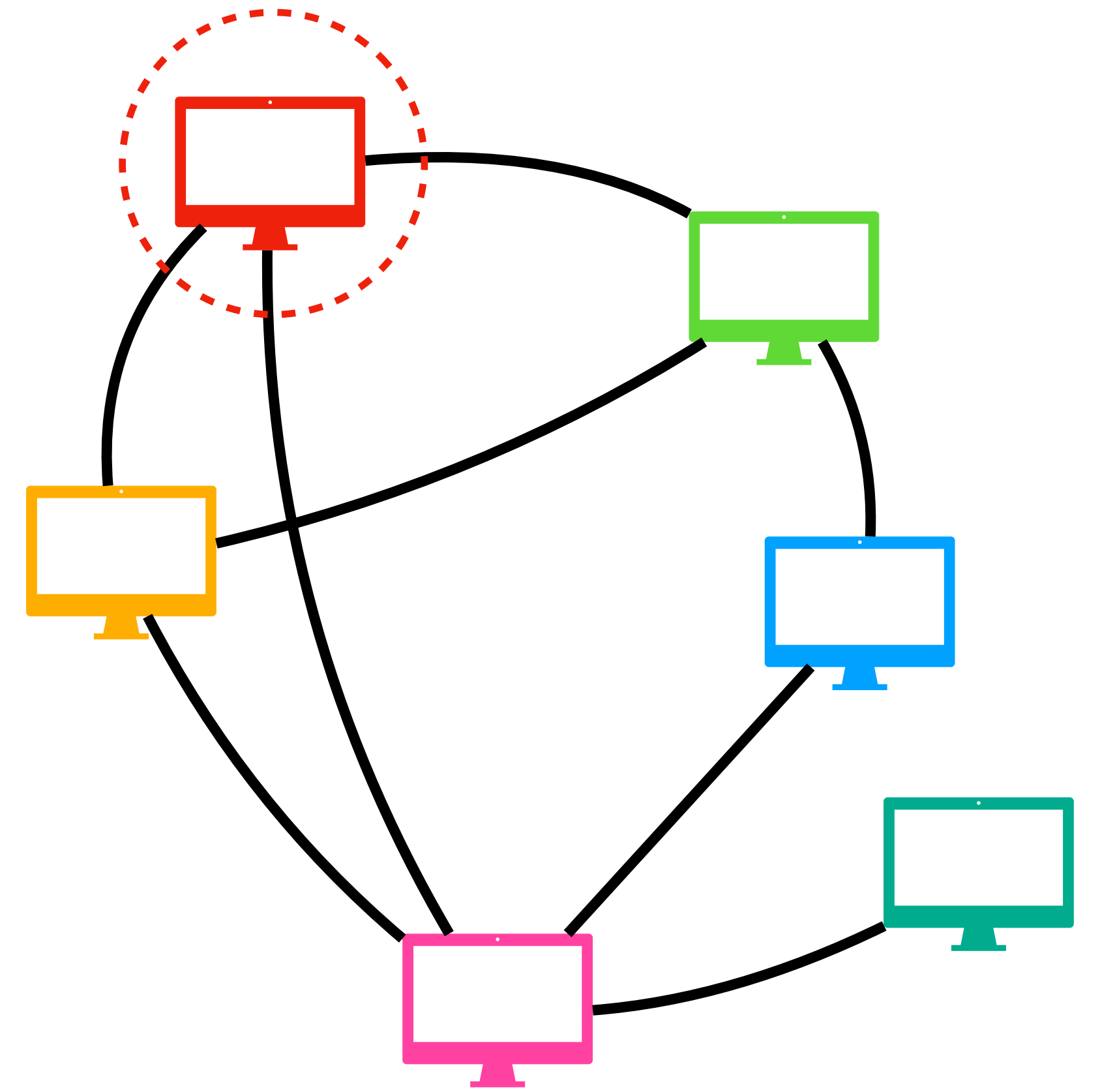
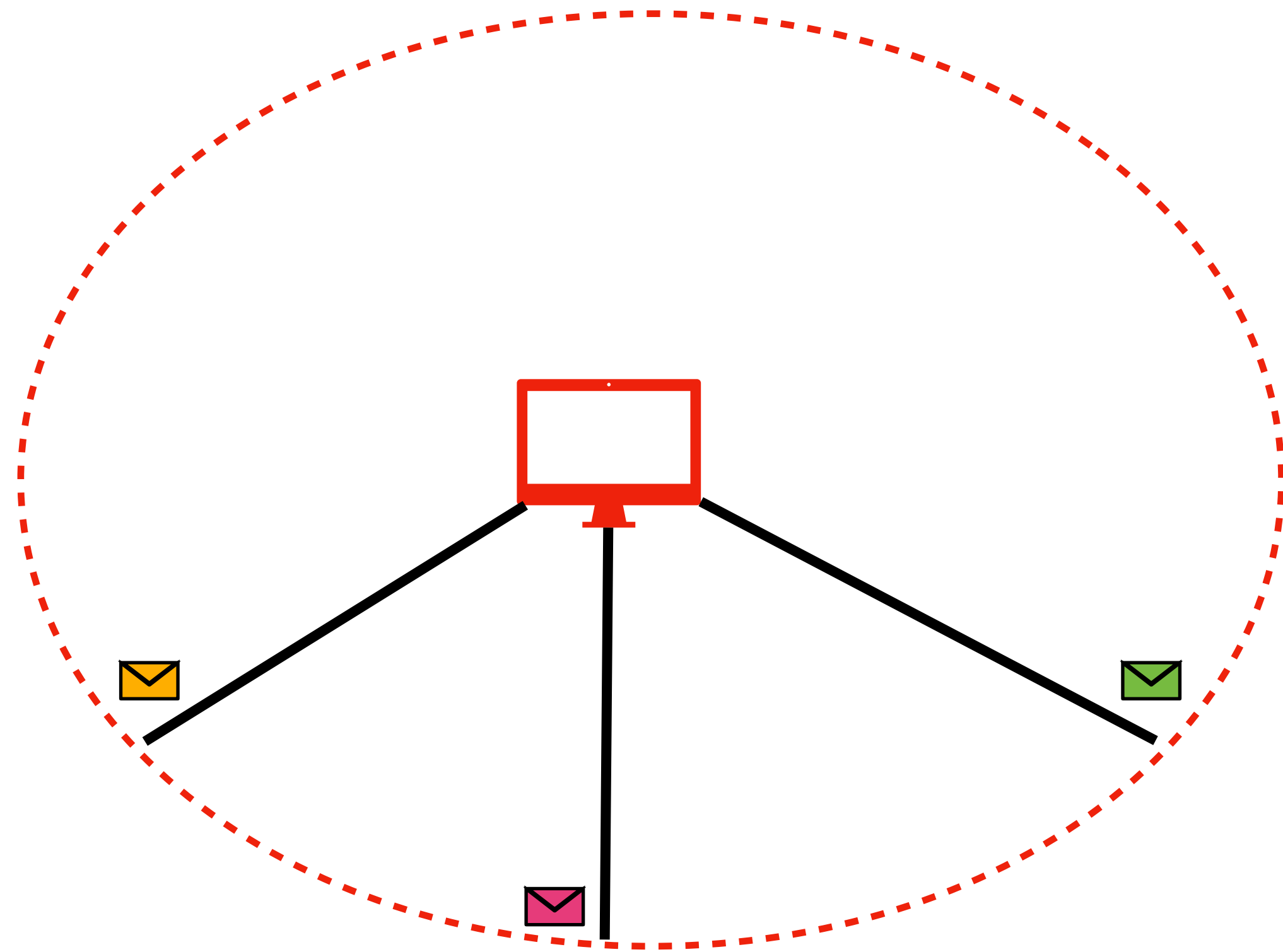
A Synchronous Round



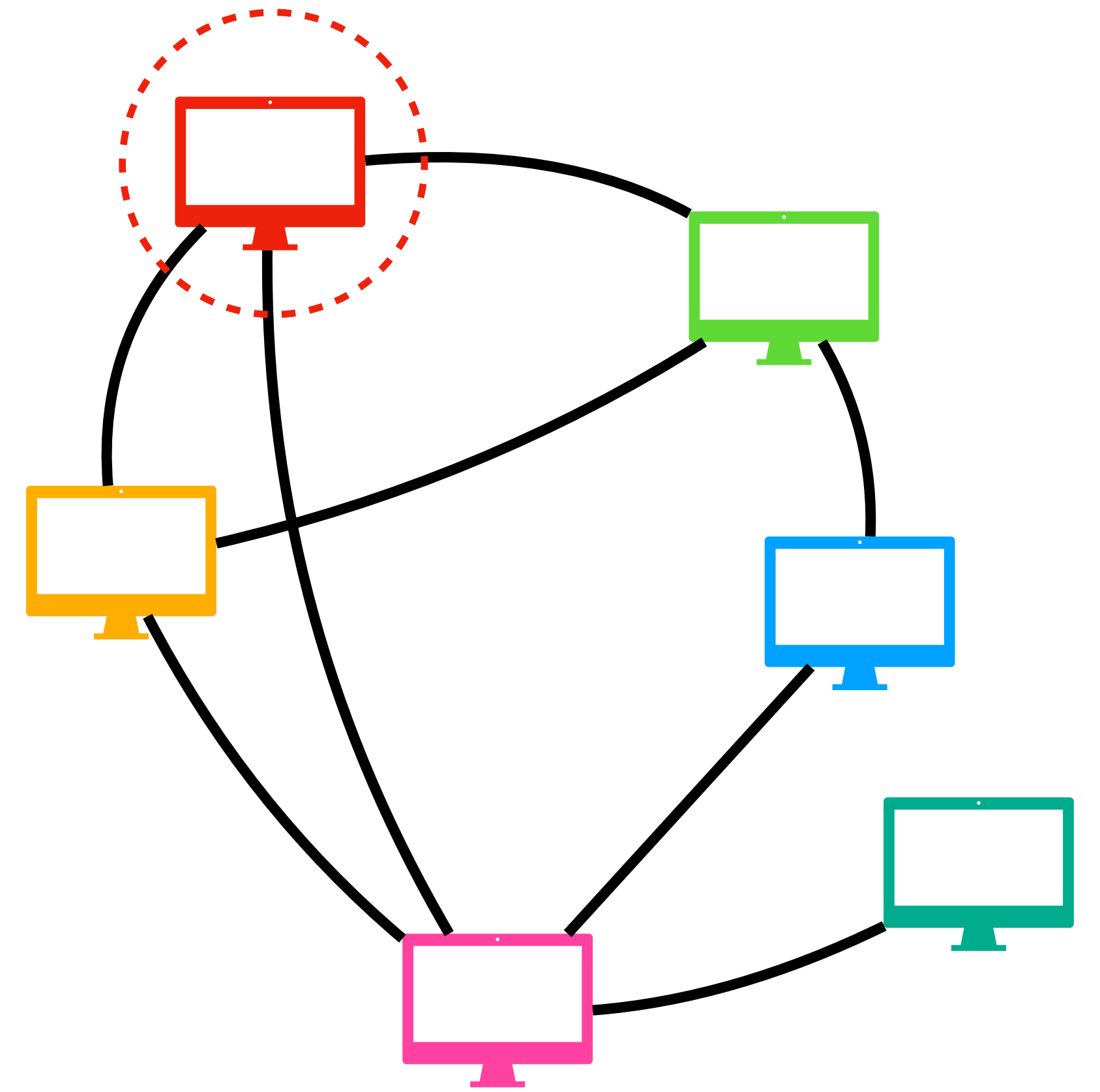
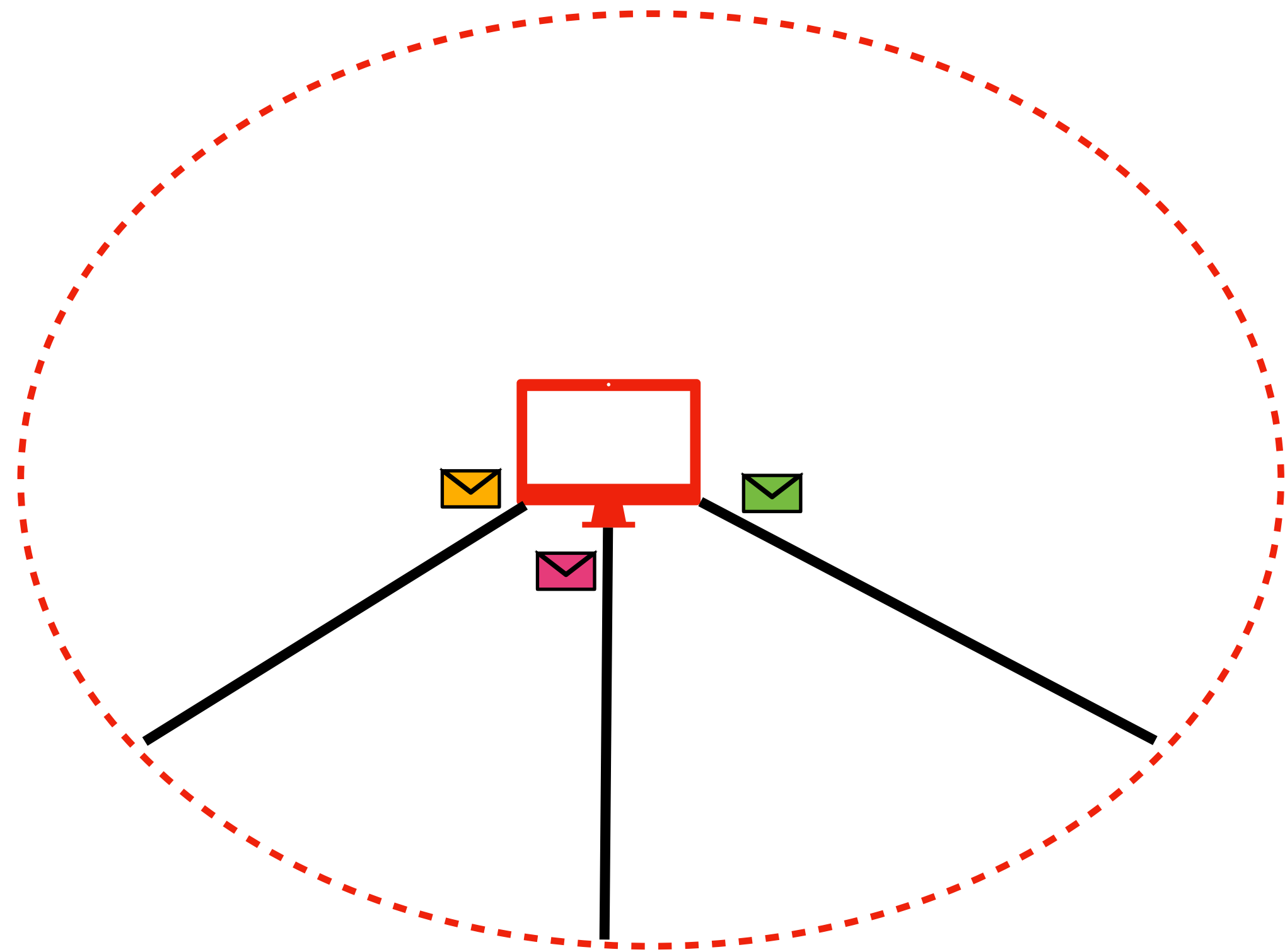
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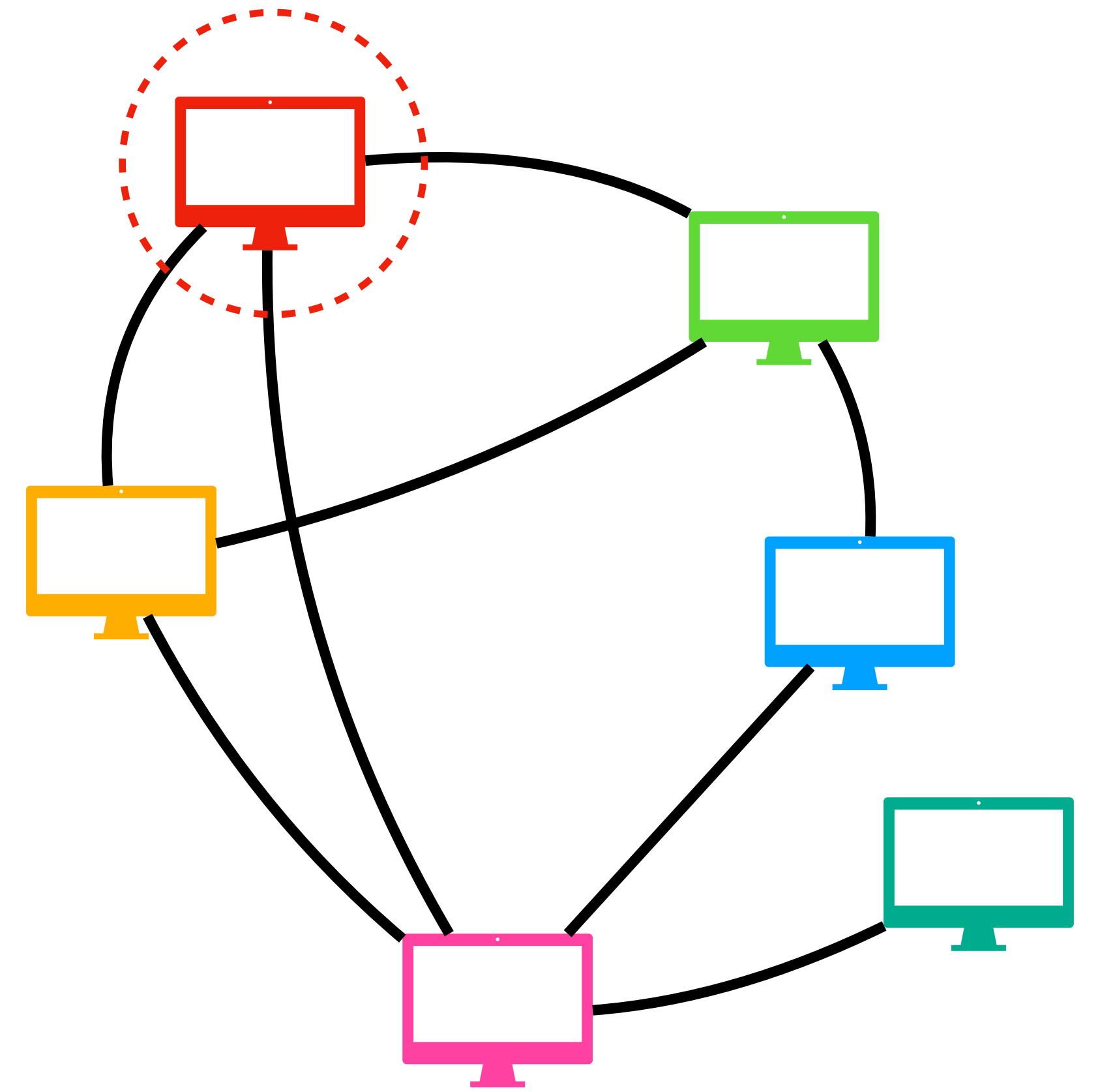
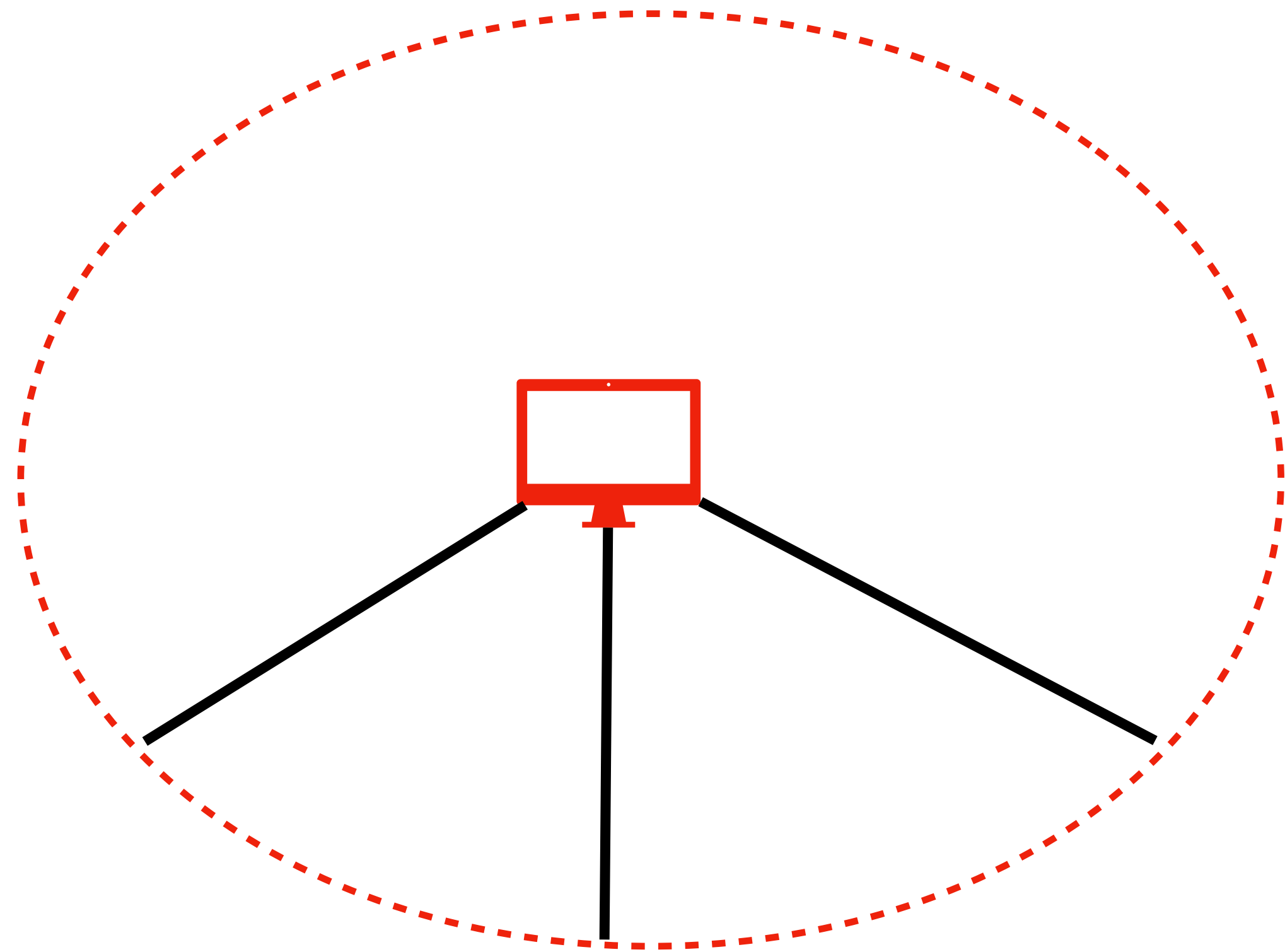
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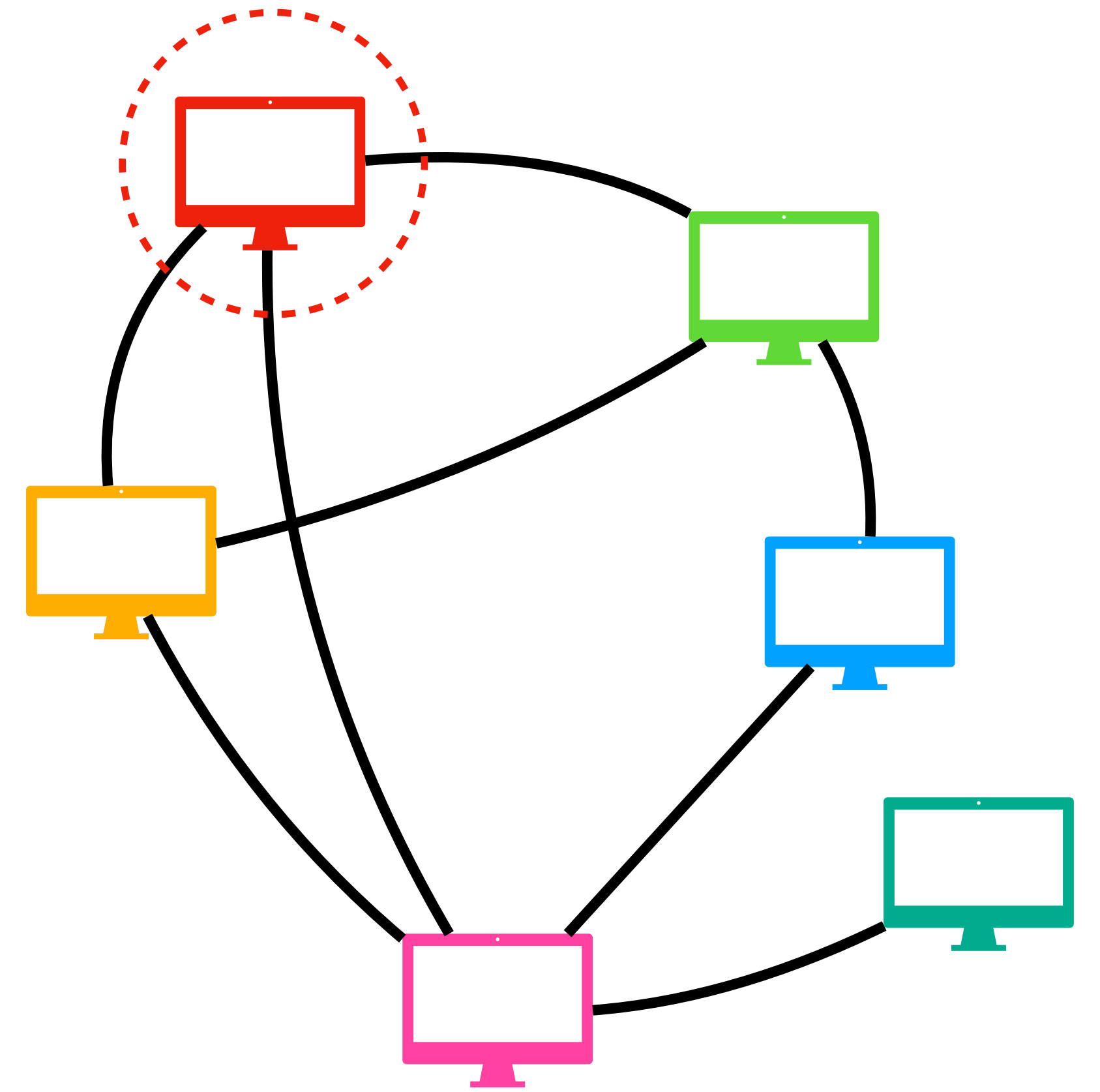
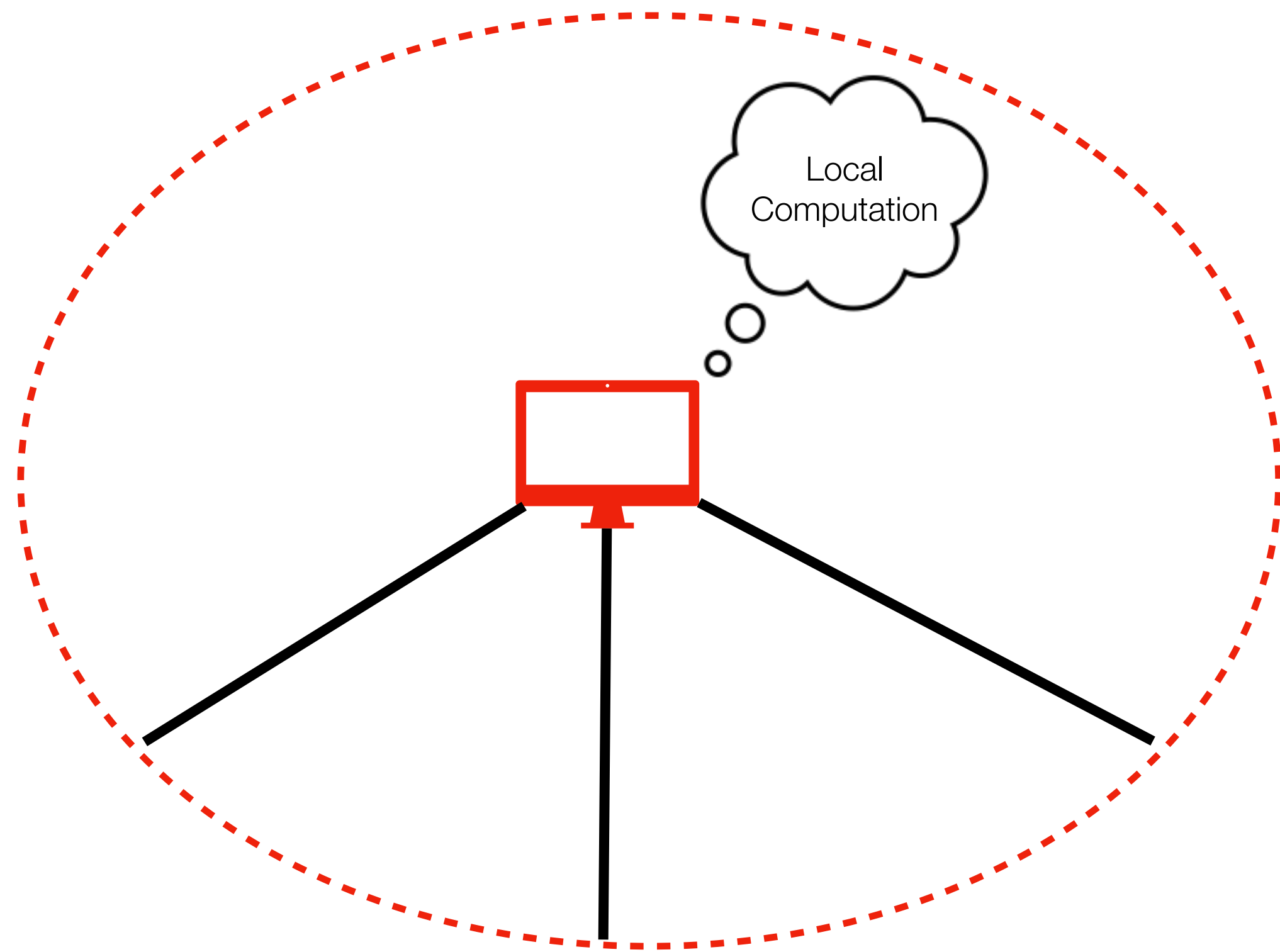
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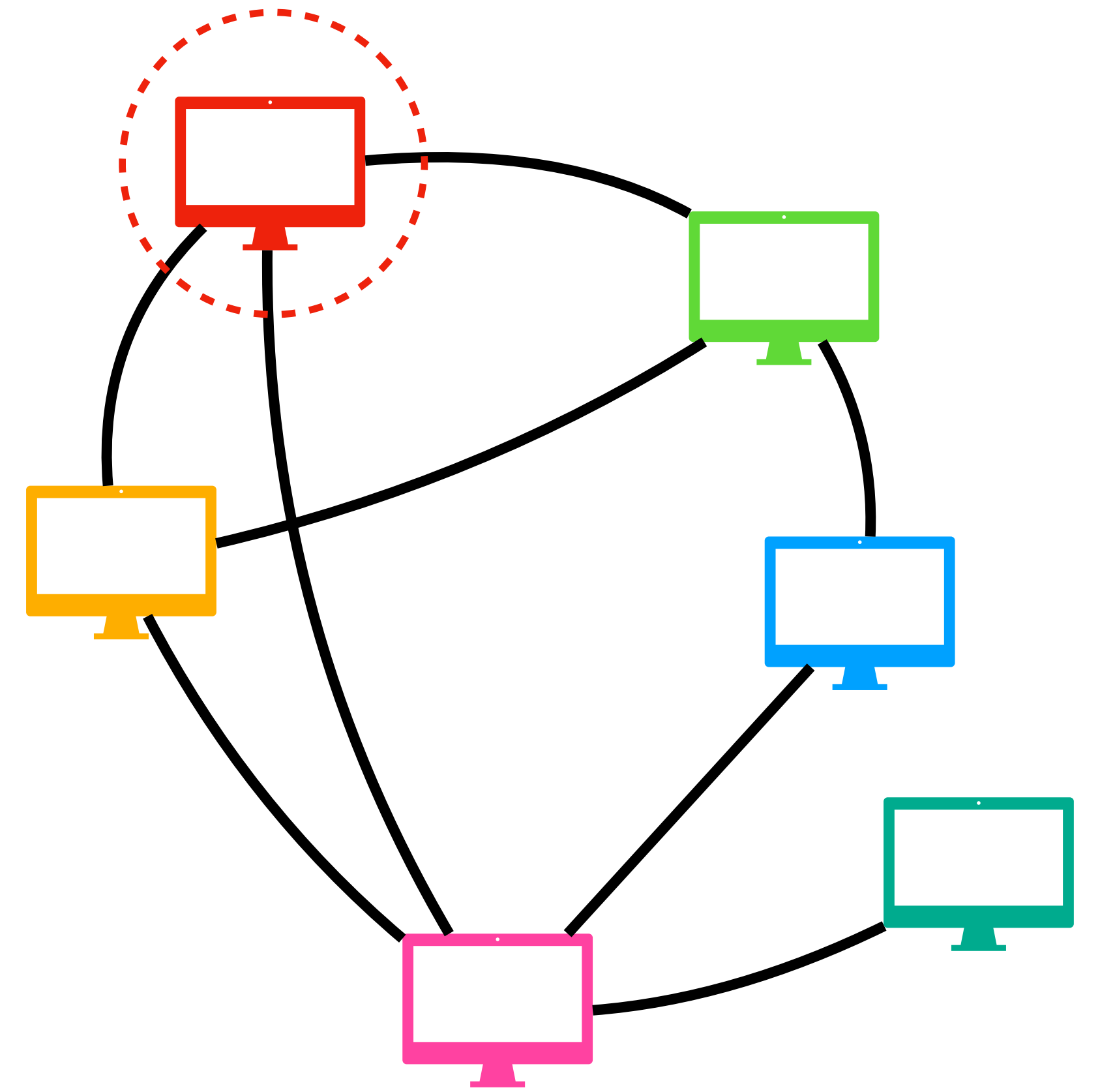
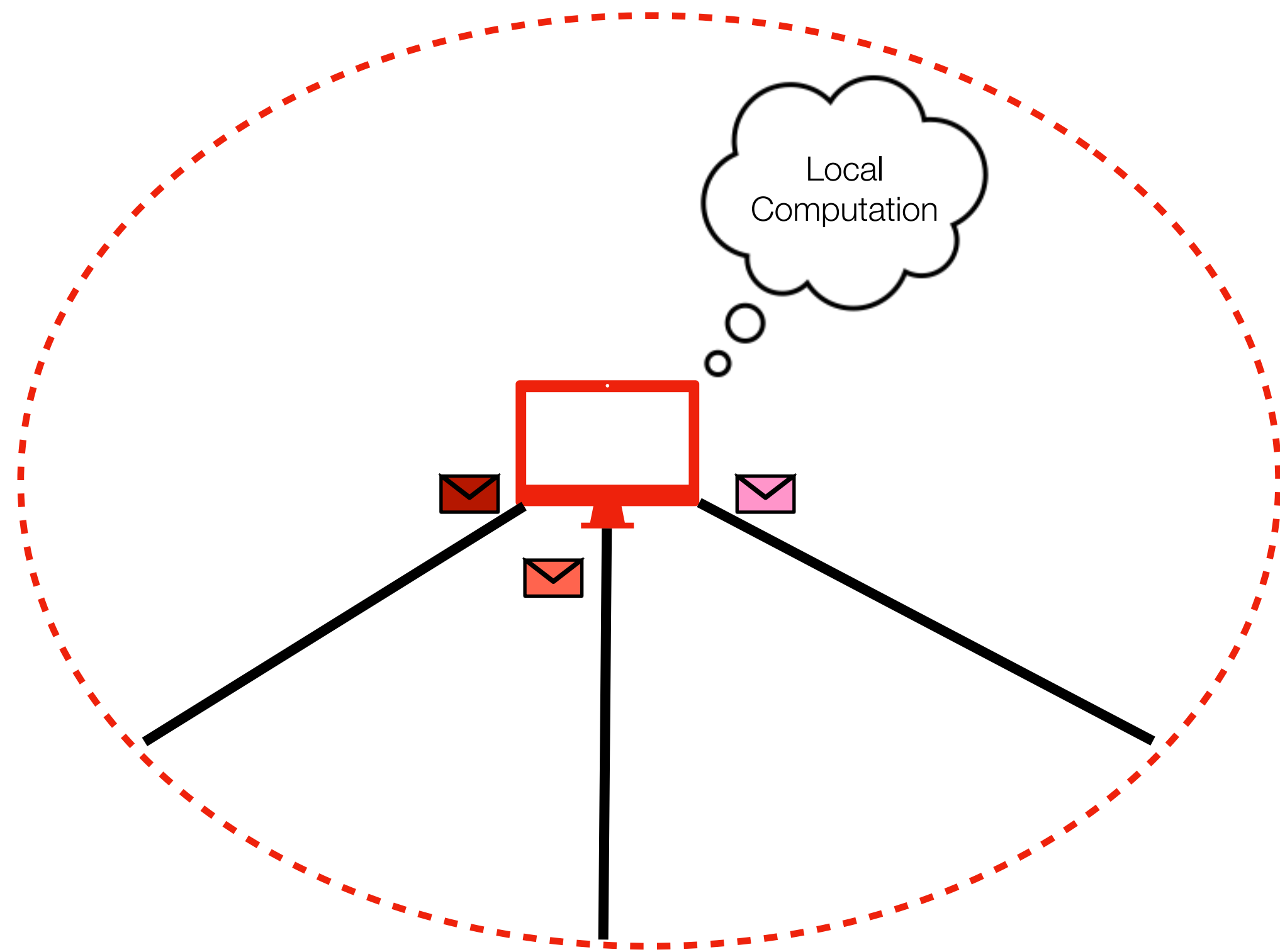
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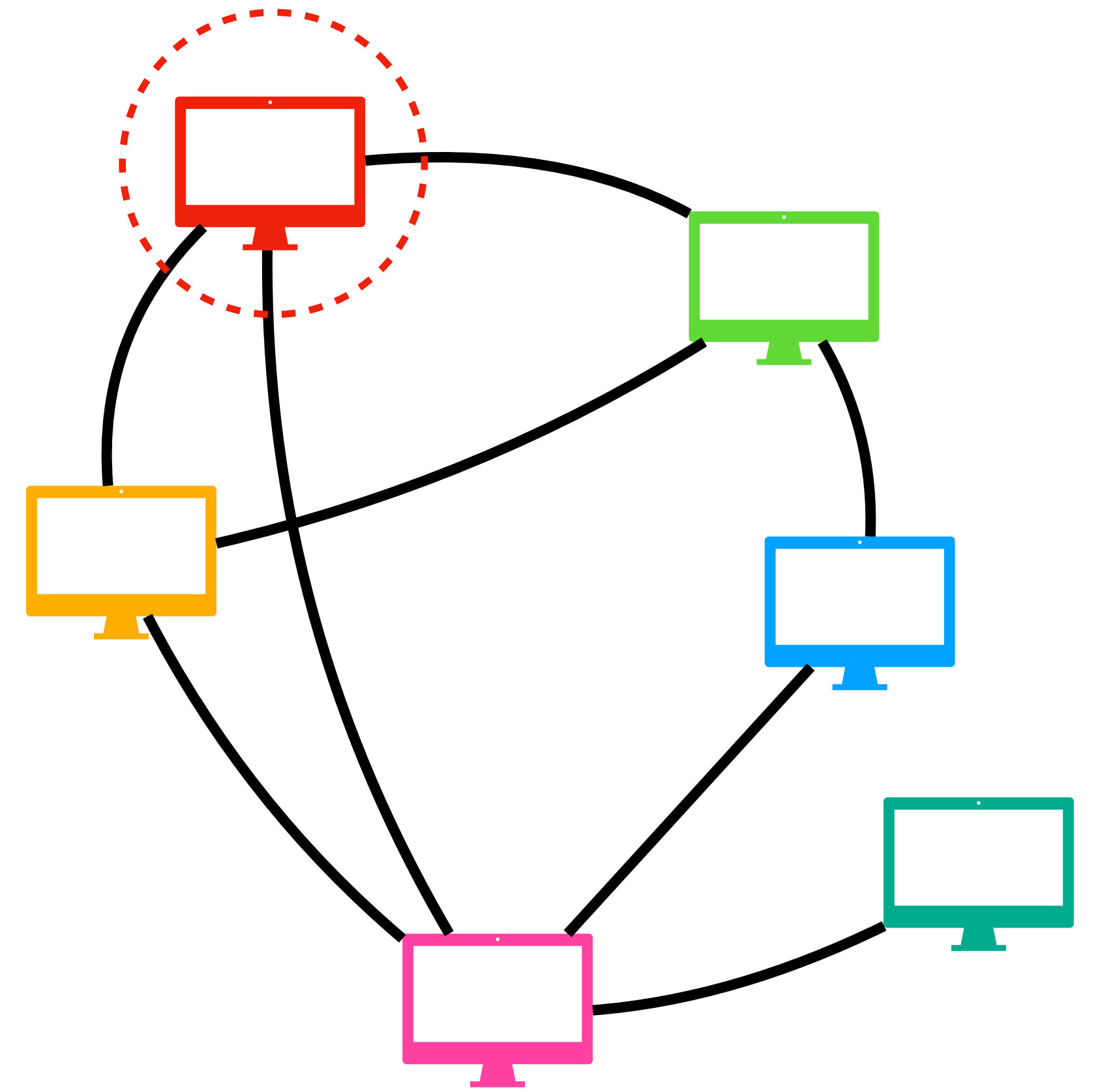
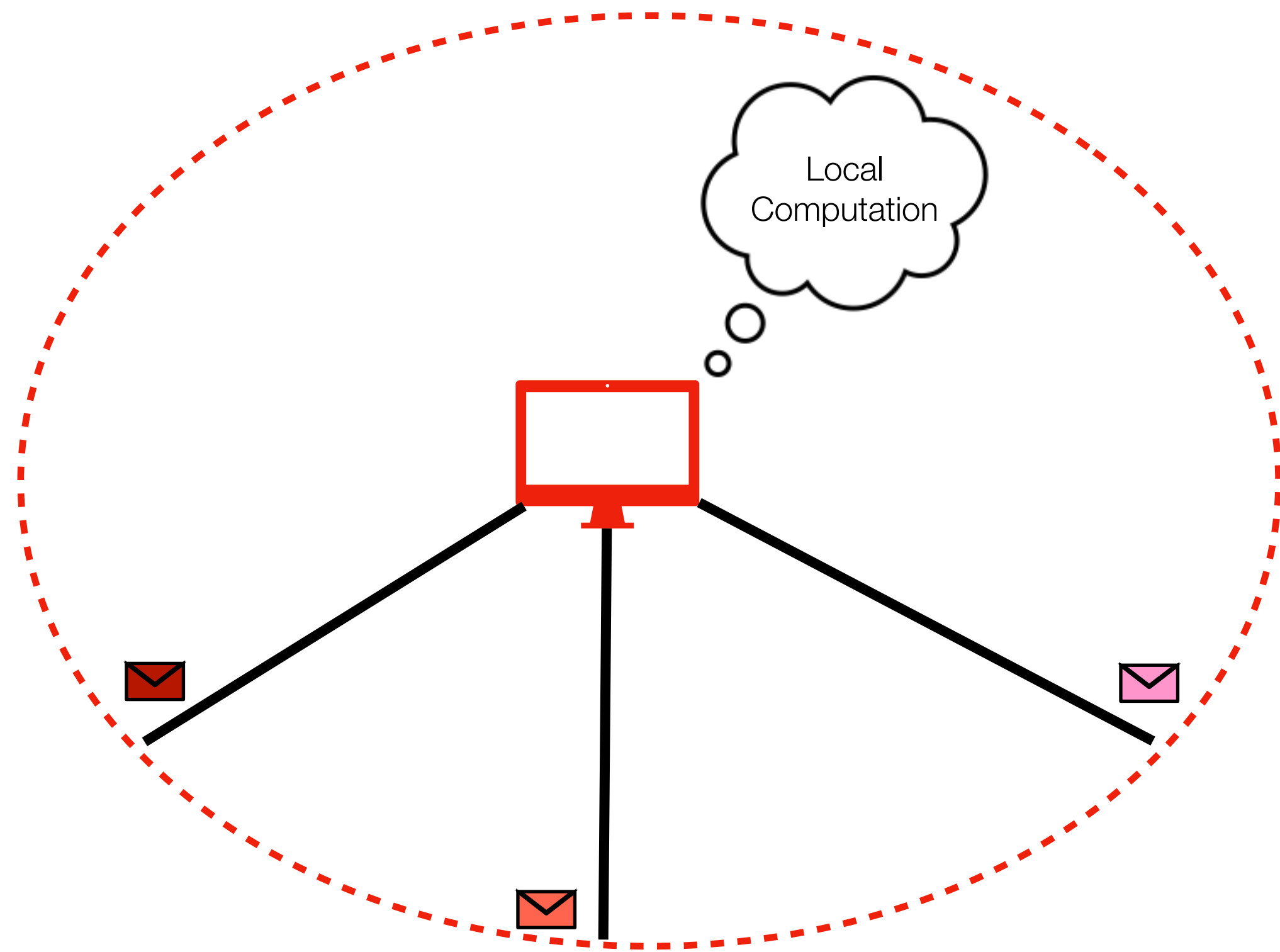
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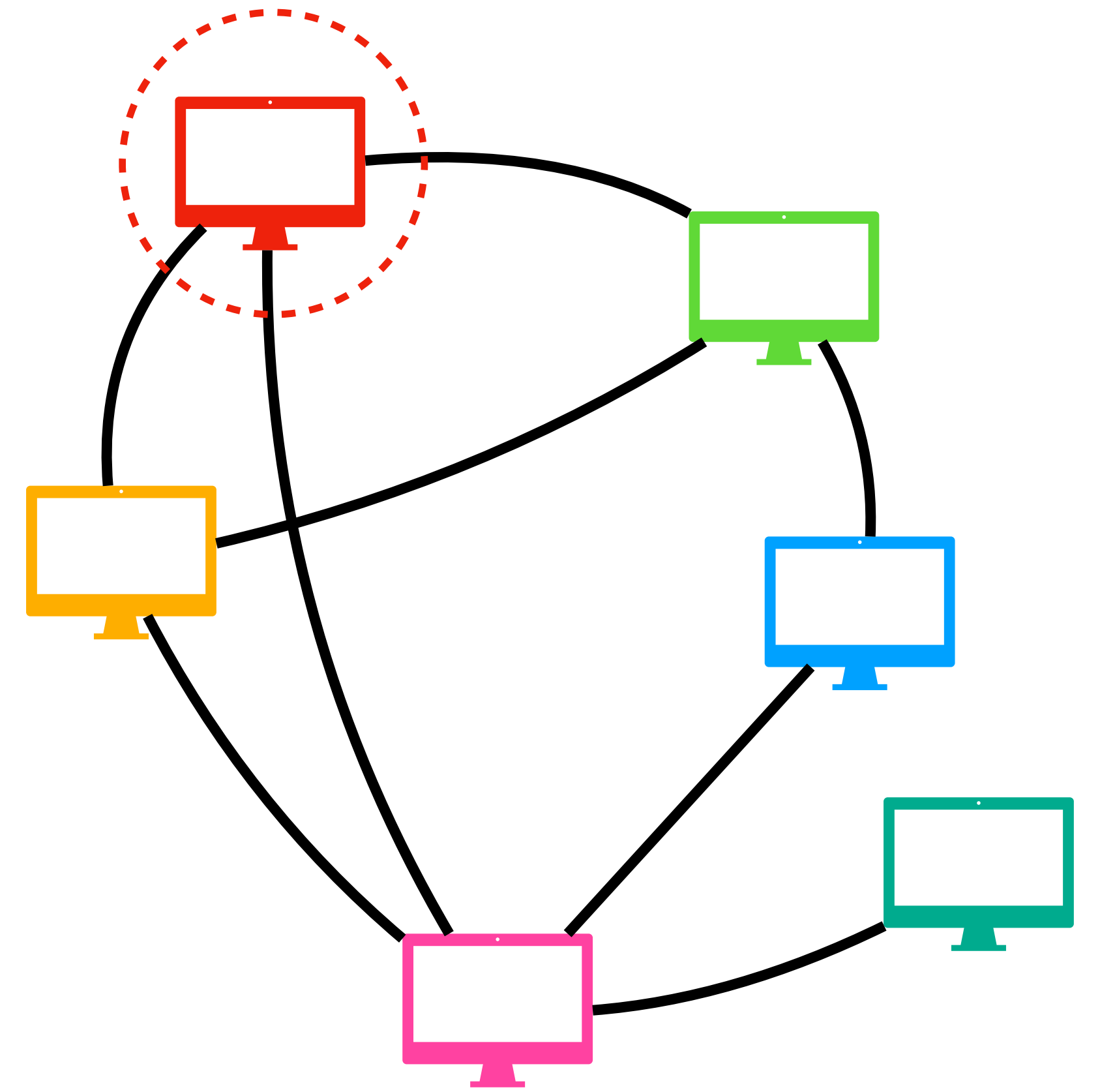
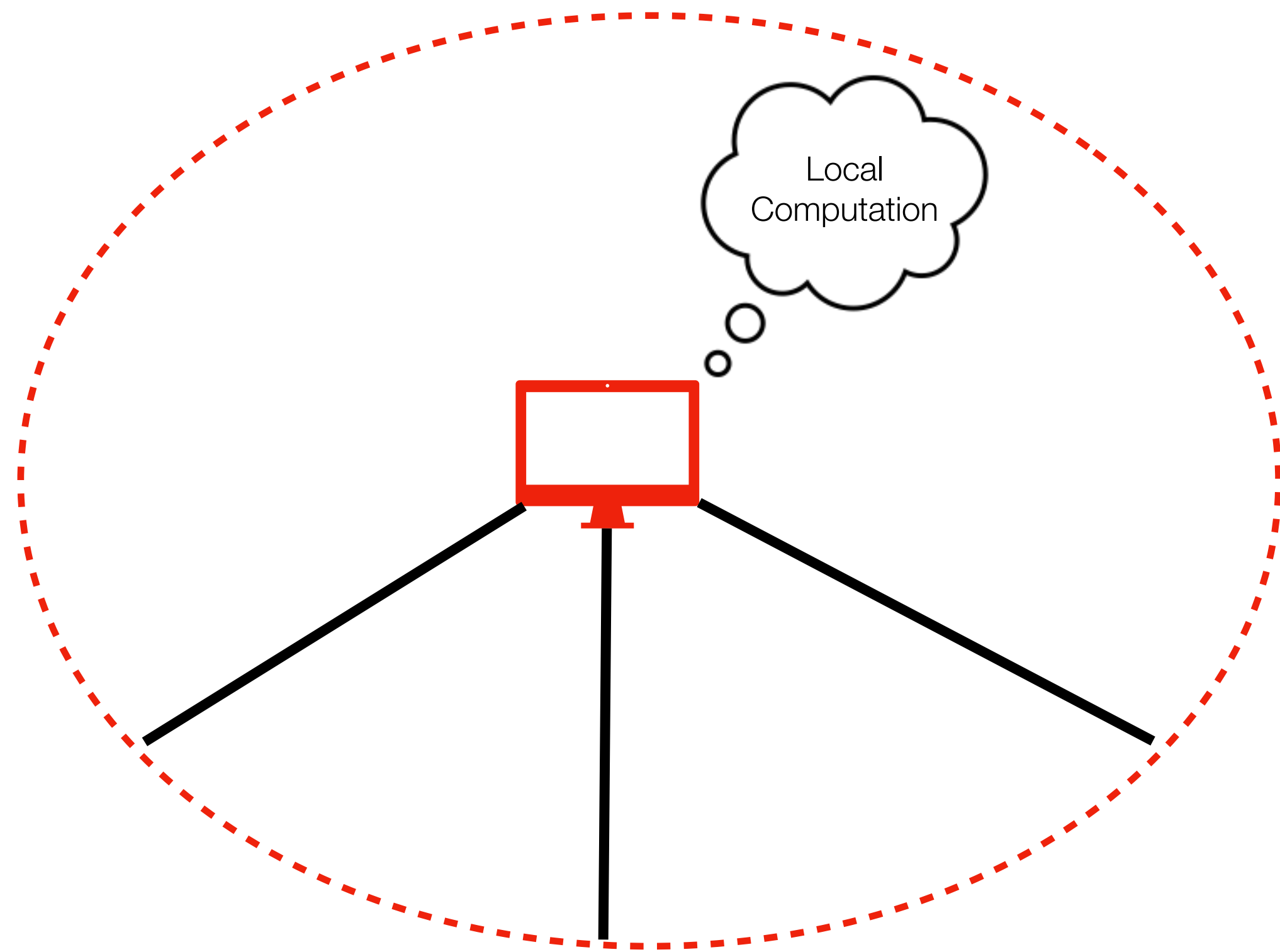
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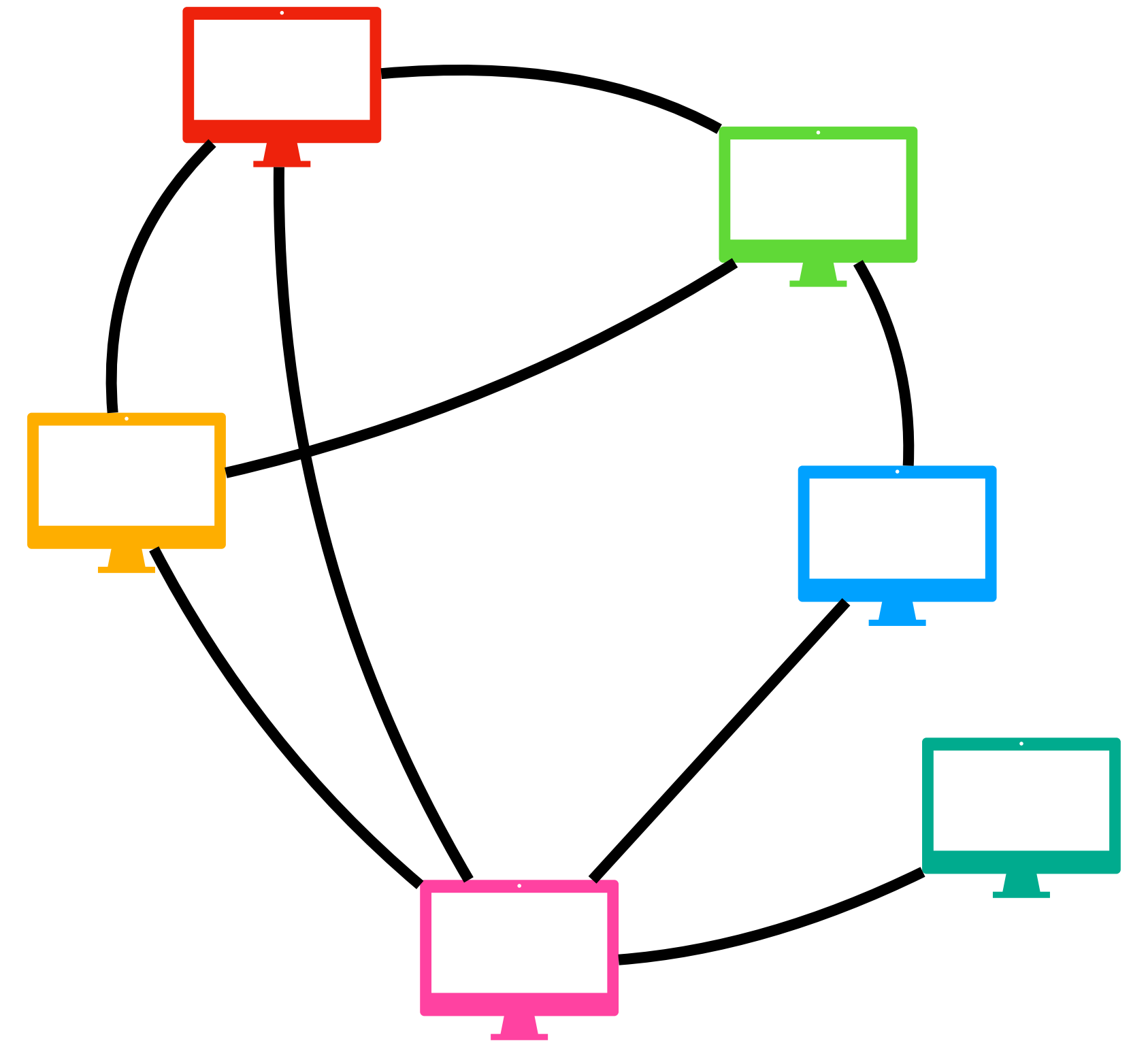


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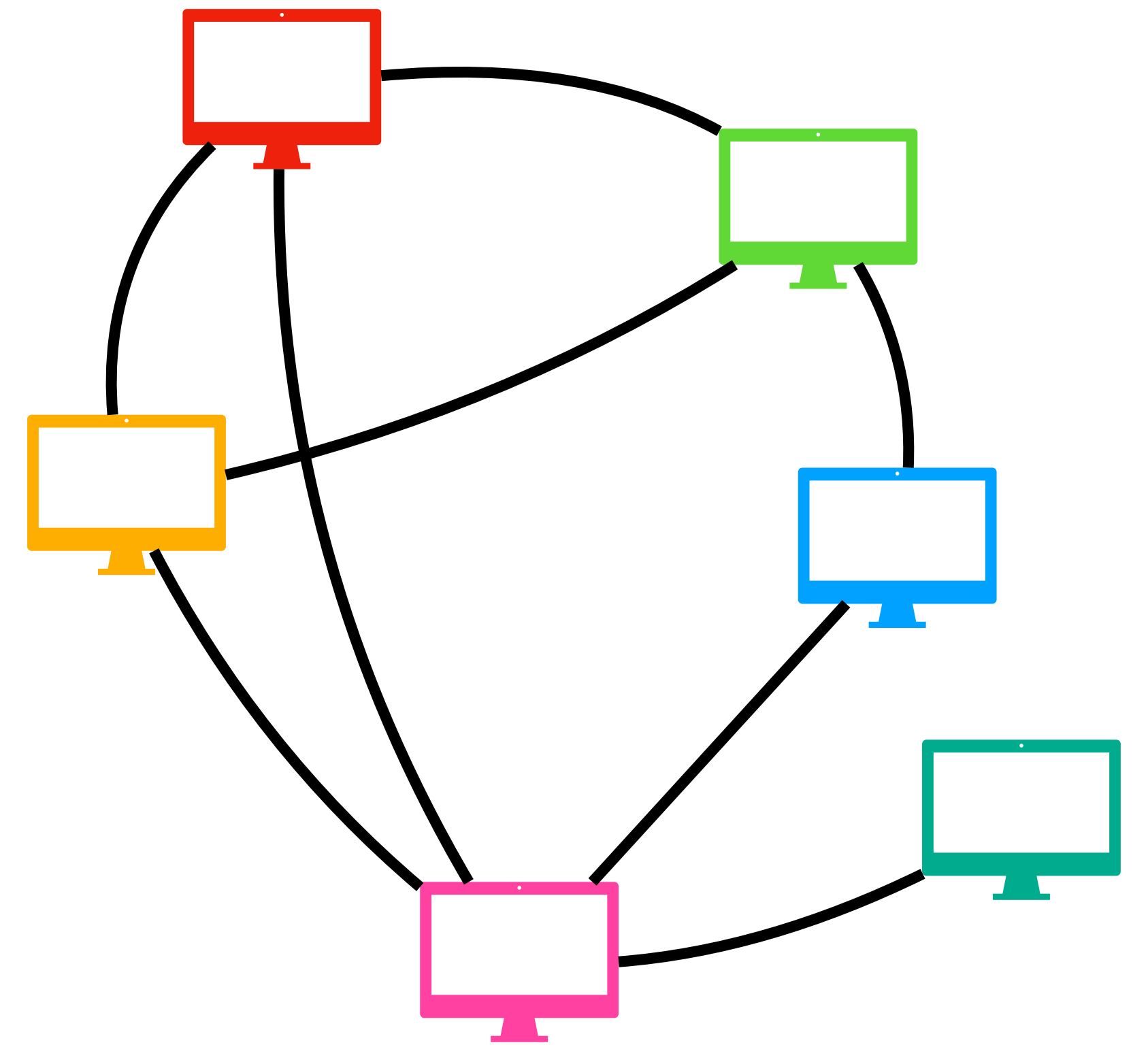


The CONGEST Model

- Other model assumptions:
 - The machines have unique ID's
 - Perfect Synchrony
 - No Faults
 - Lossless Message Passing
 - Infinite Local Computation Power

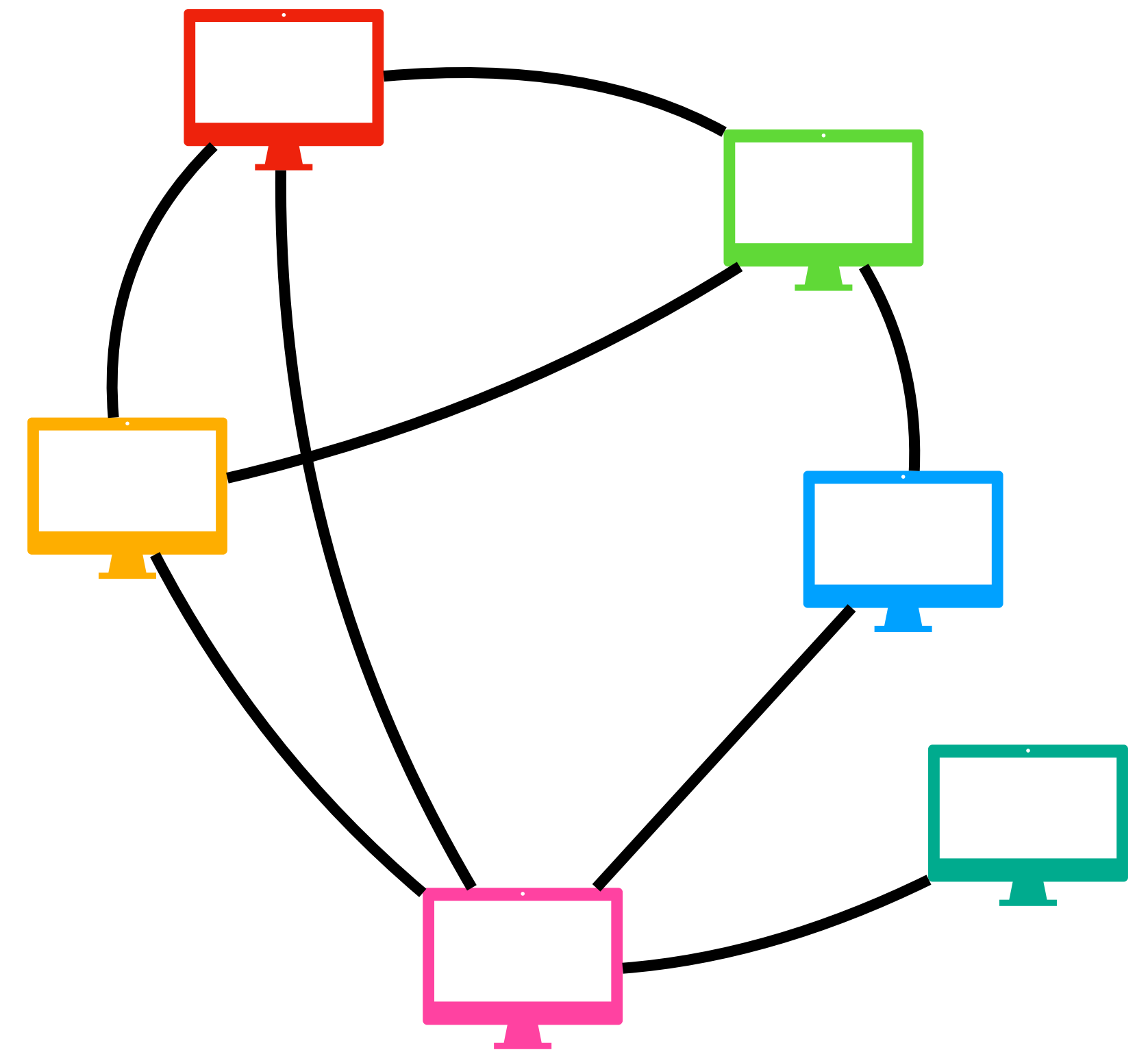


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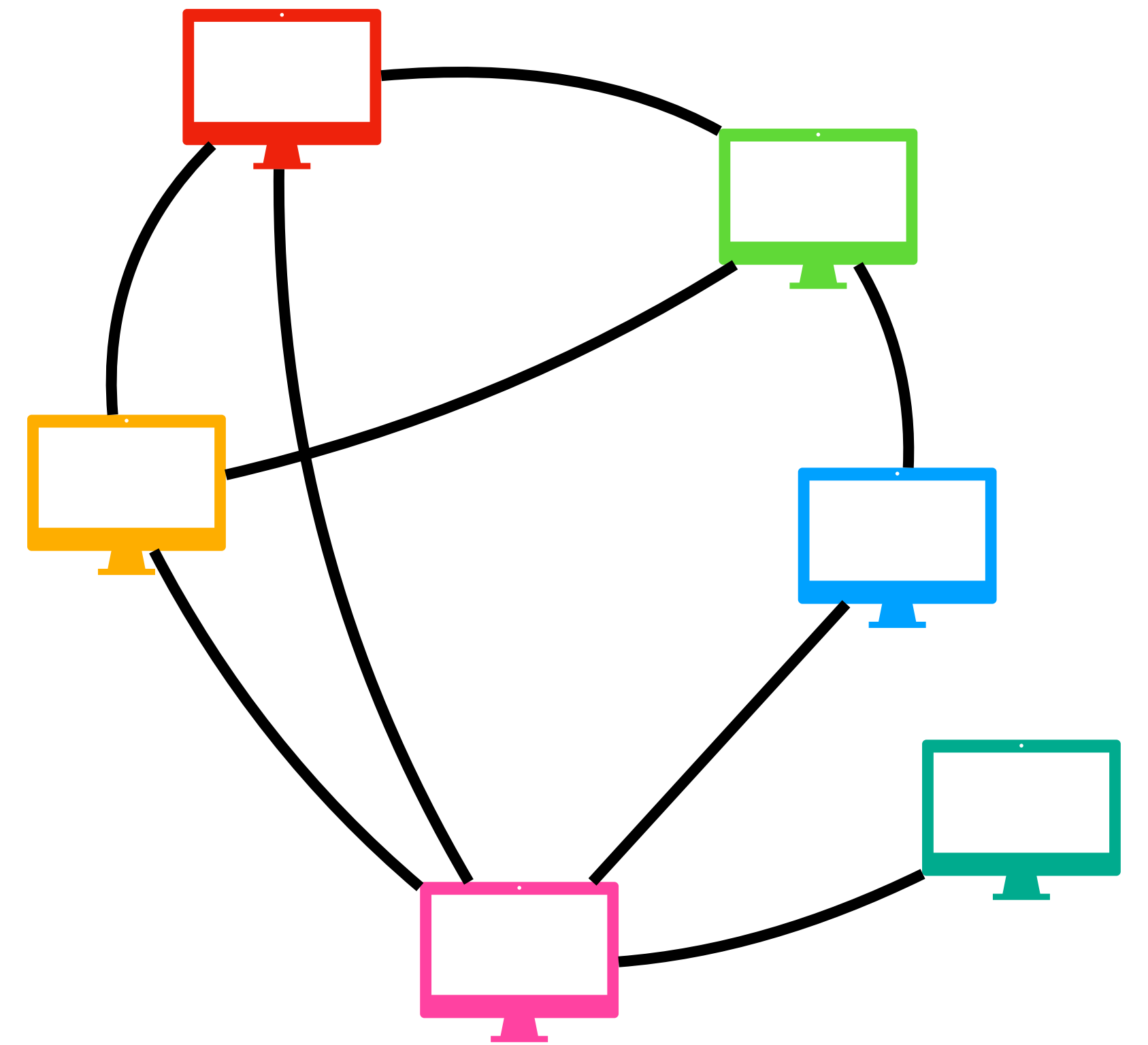
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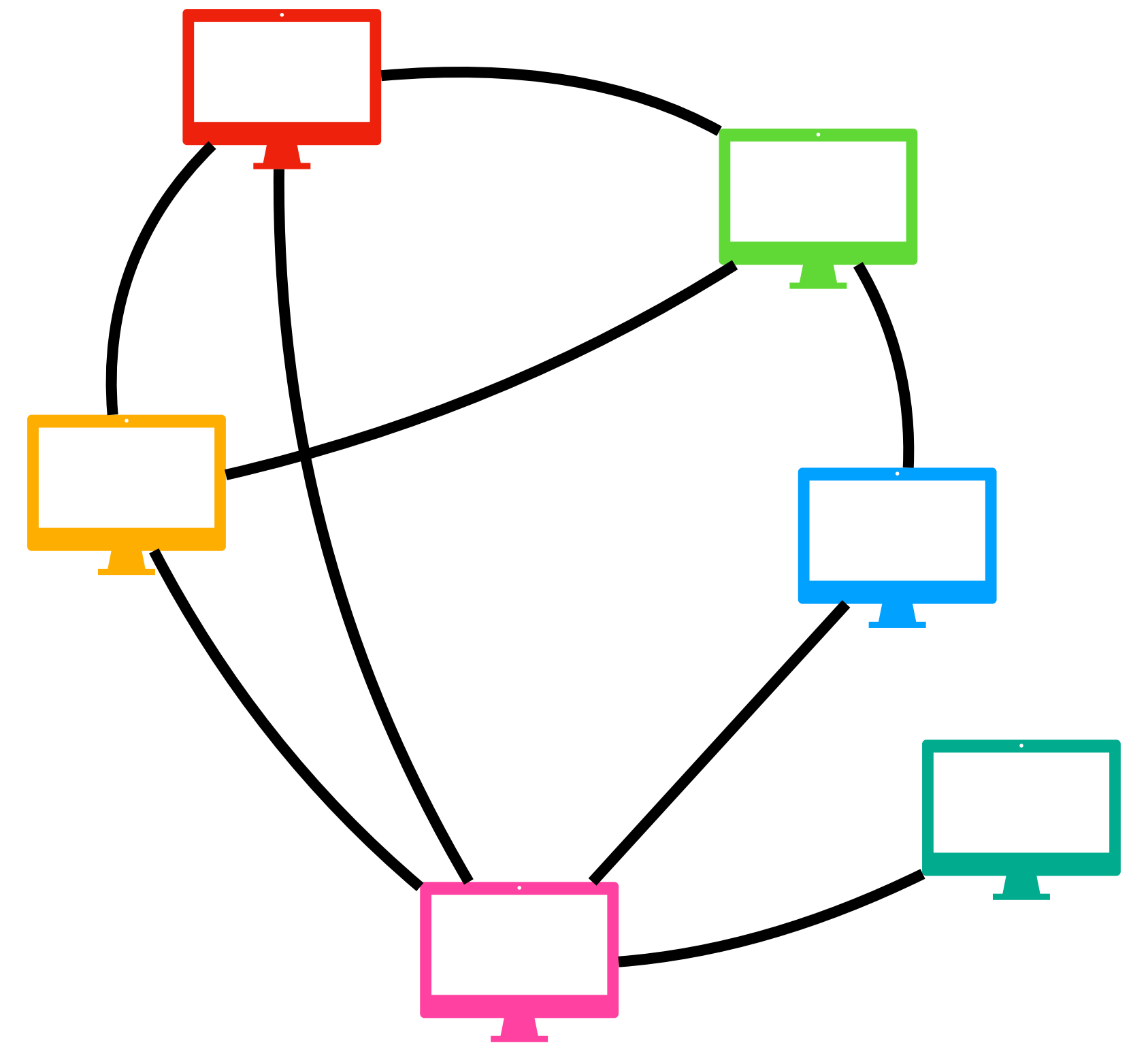
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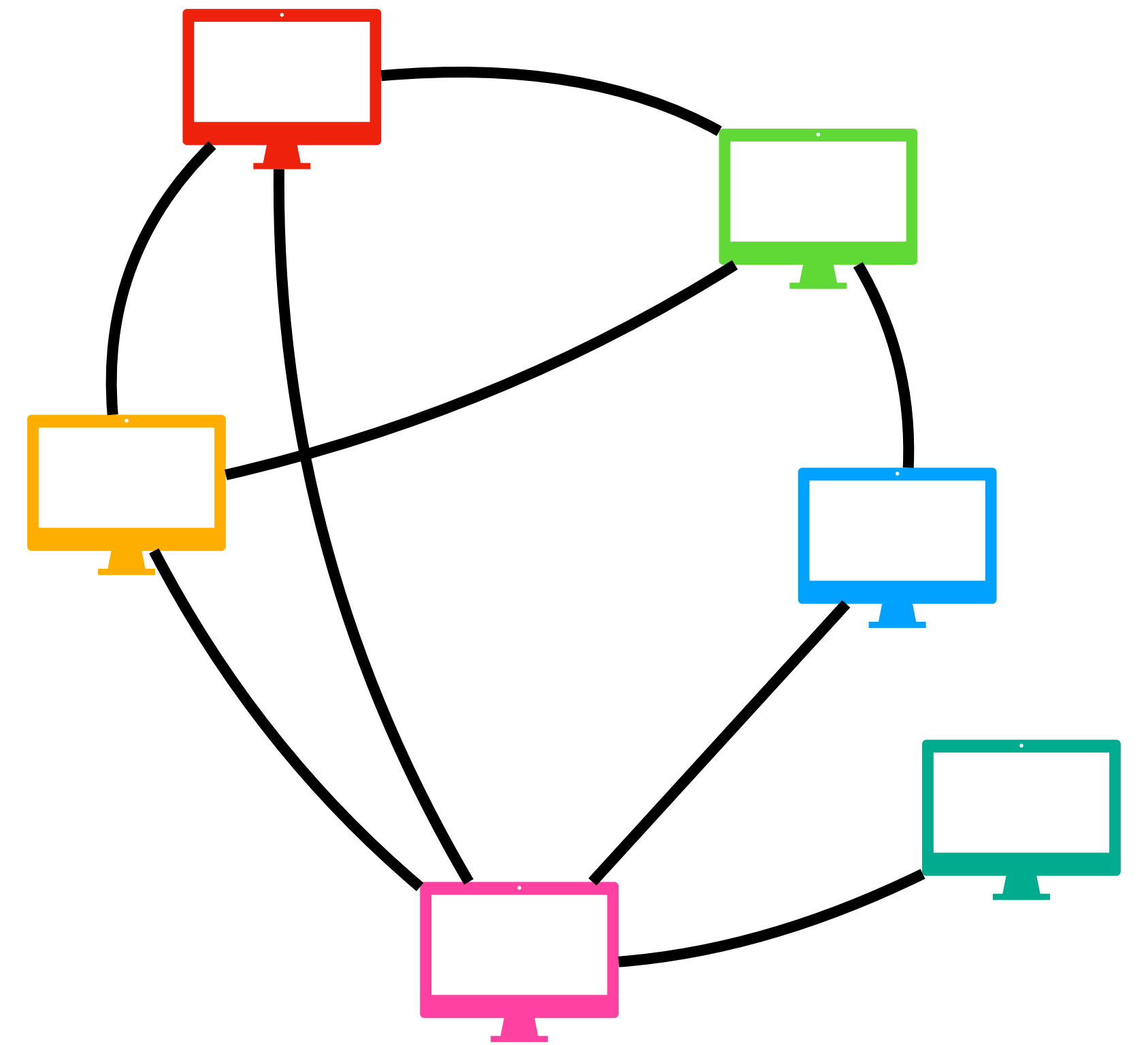


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- **Output:** each node will compute a part of the output, eg, pass/fail, its own color.
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- **Message Complexity:** total number of messages sent/received in the network.

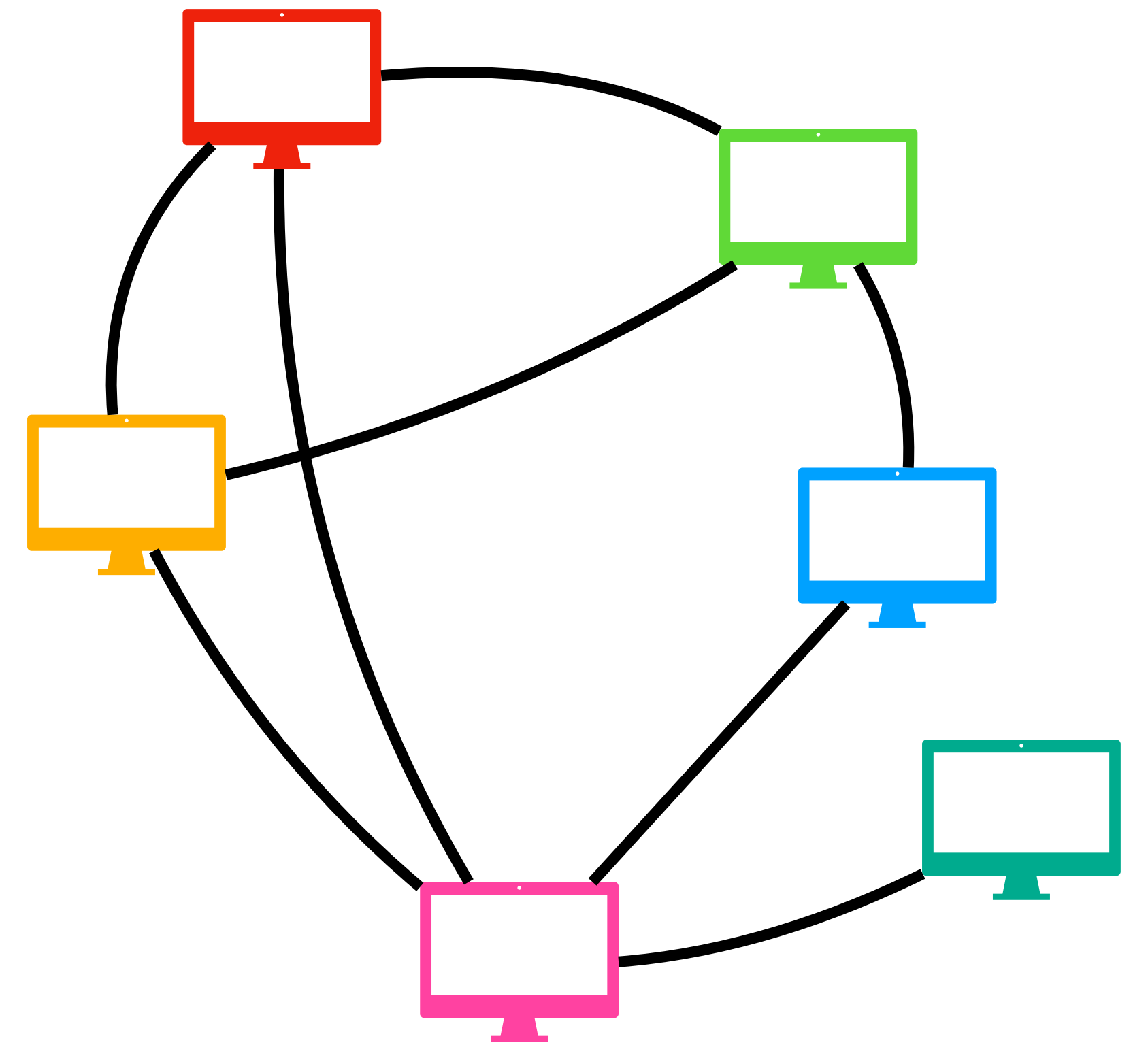


Why CONGEST?



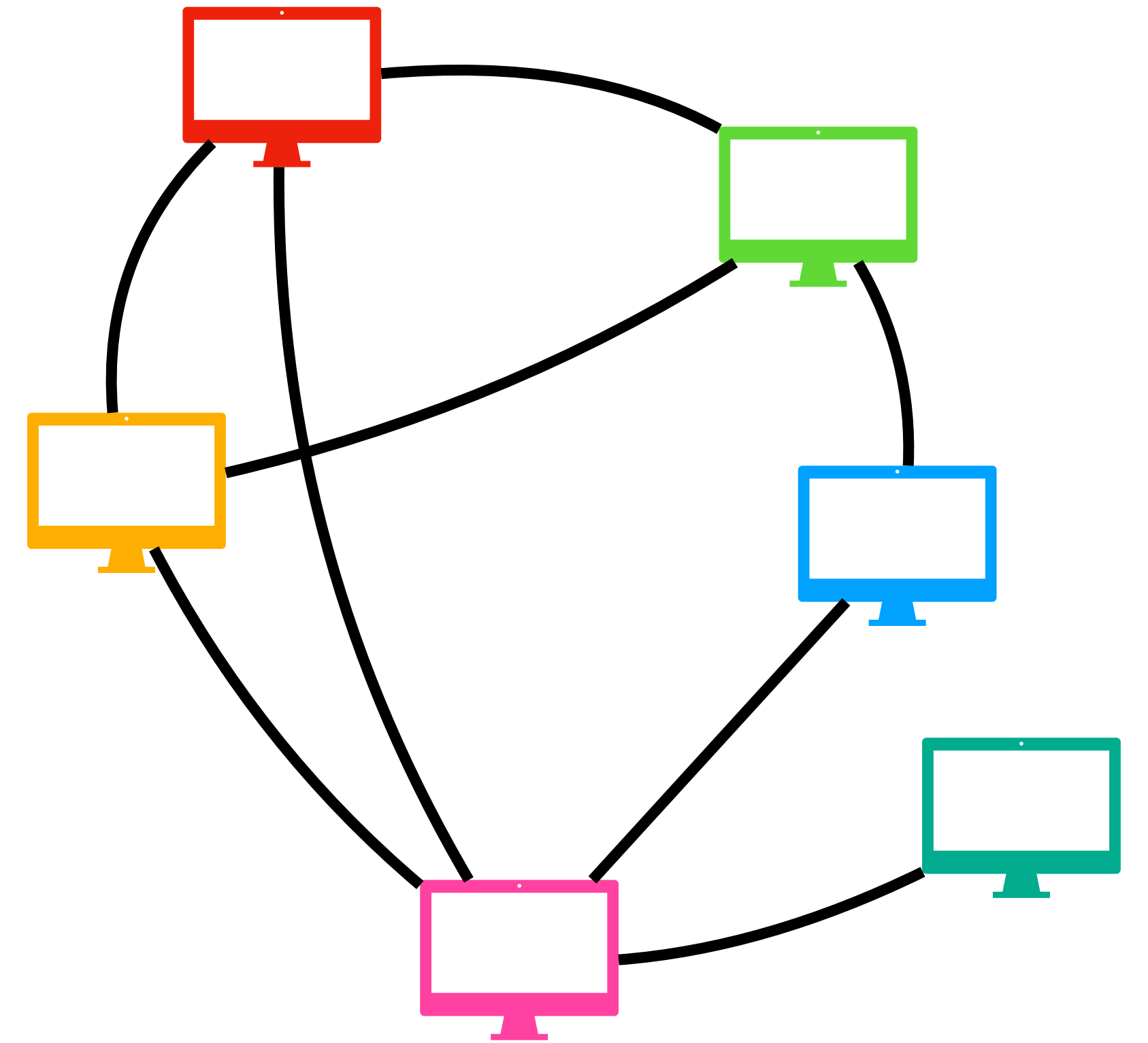
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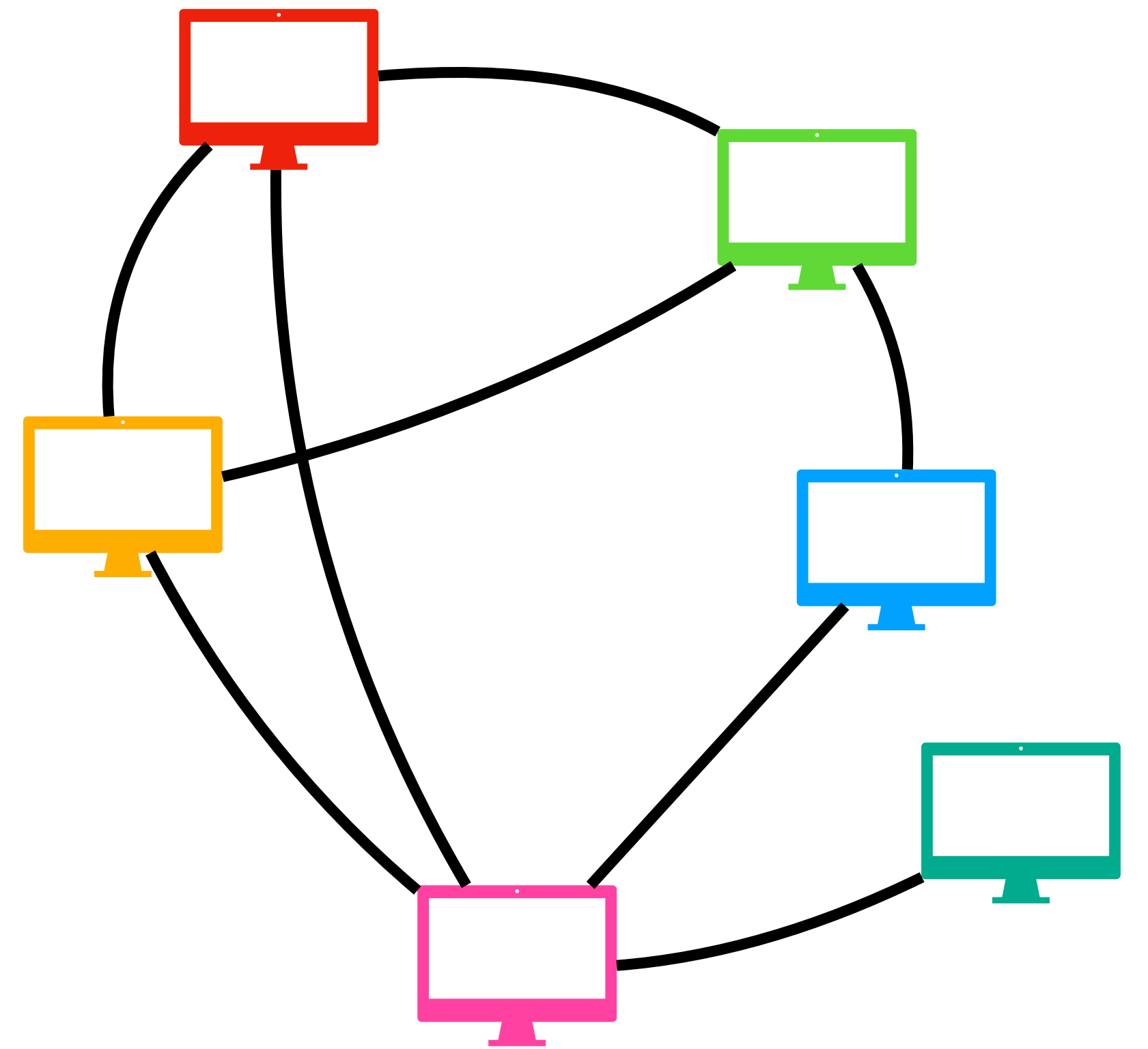
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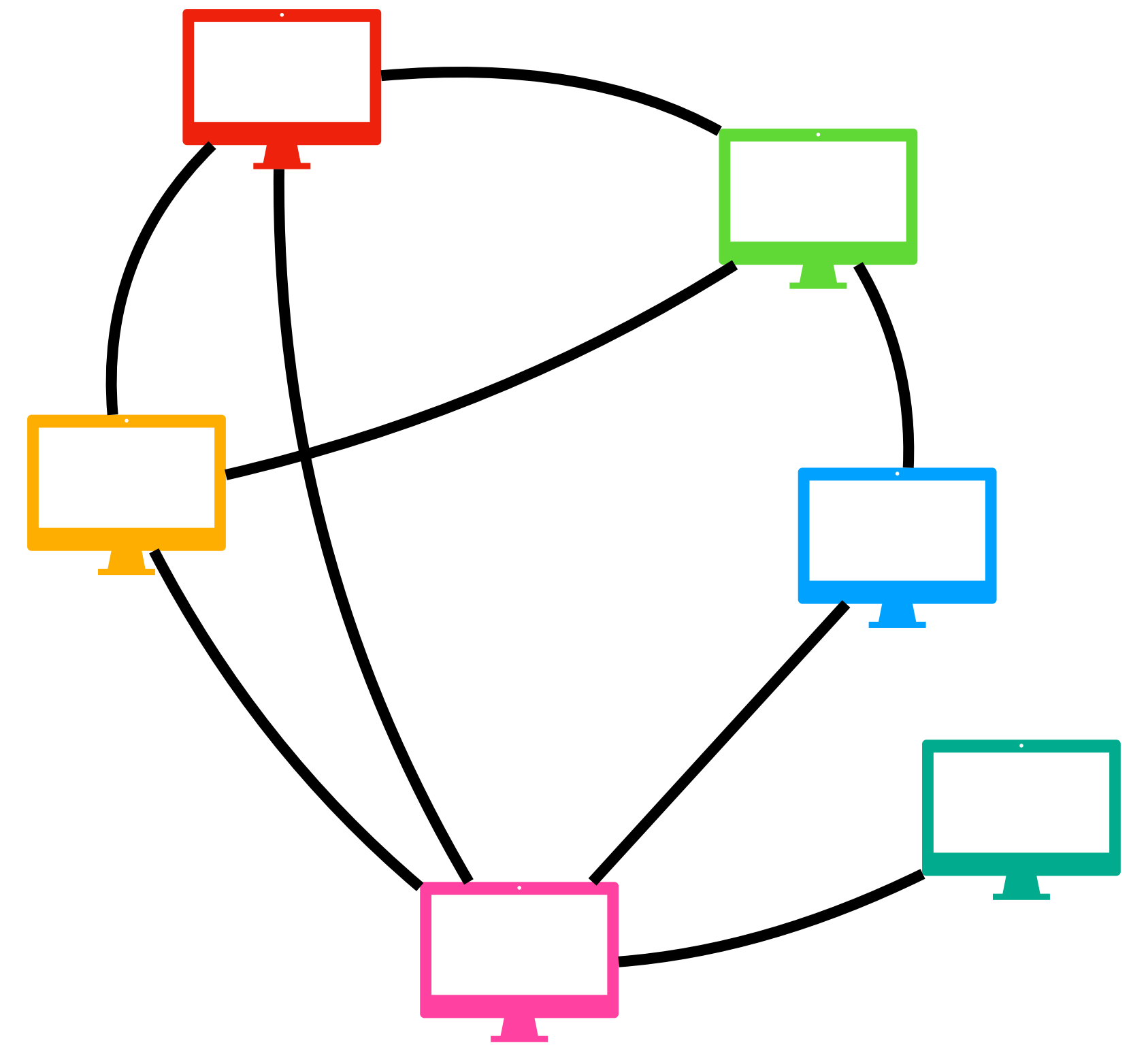
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- Captures two important aspects of distributed computing:
 - **Locality:** the information required is far away in the network.
 - **Congestion:** bandwidth constraints cause bottlenecks in the network.



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 - Need to send very large sized messages.
- Will not be the primary focus in this talk.

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- Flooding Algorithm:
 - Node u sends M to all its neighbors.
 - If v receives M for the first time, it sends M to all neighbors.

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- How do you formally prove that broadcast requires $\Omega(m)$ messages?

Initial Knowledge

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KT-0

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KT-1

Nodes know ID's of
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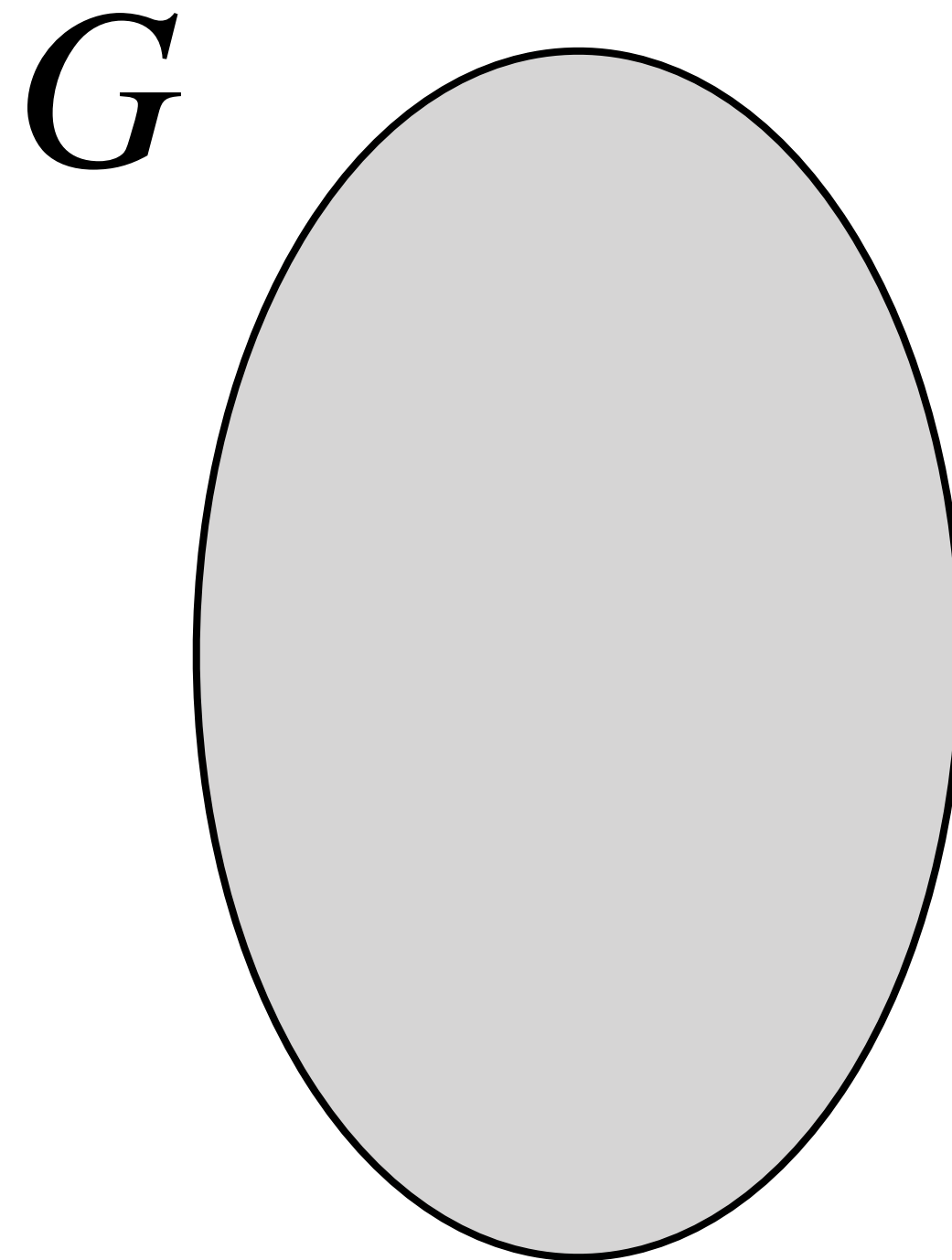
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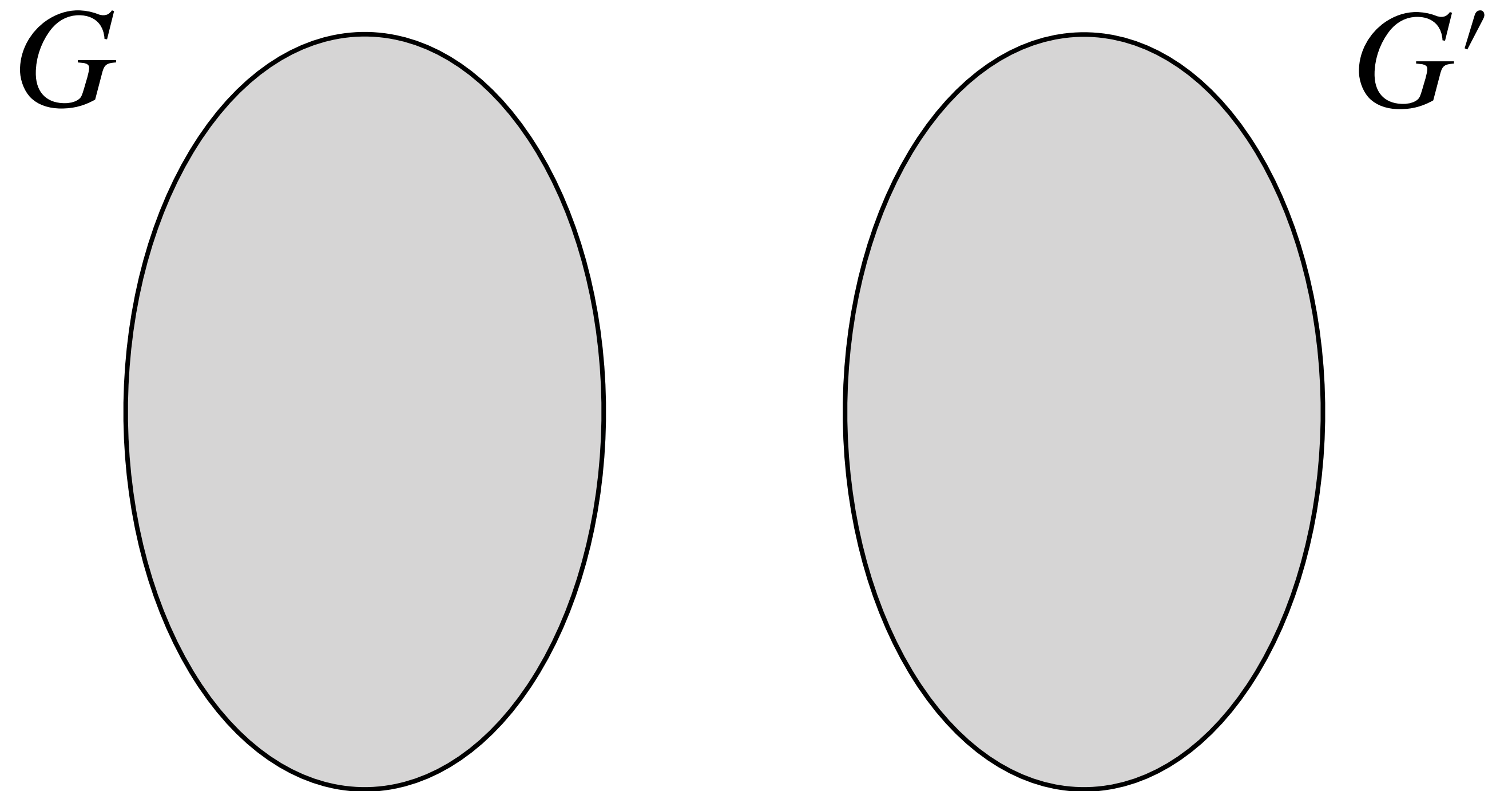
- Going from KT-0 to KT-1 requires only one round, but $O(m)$ messages.

KT-0 Indistinguishability

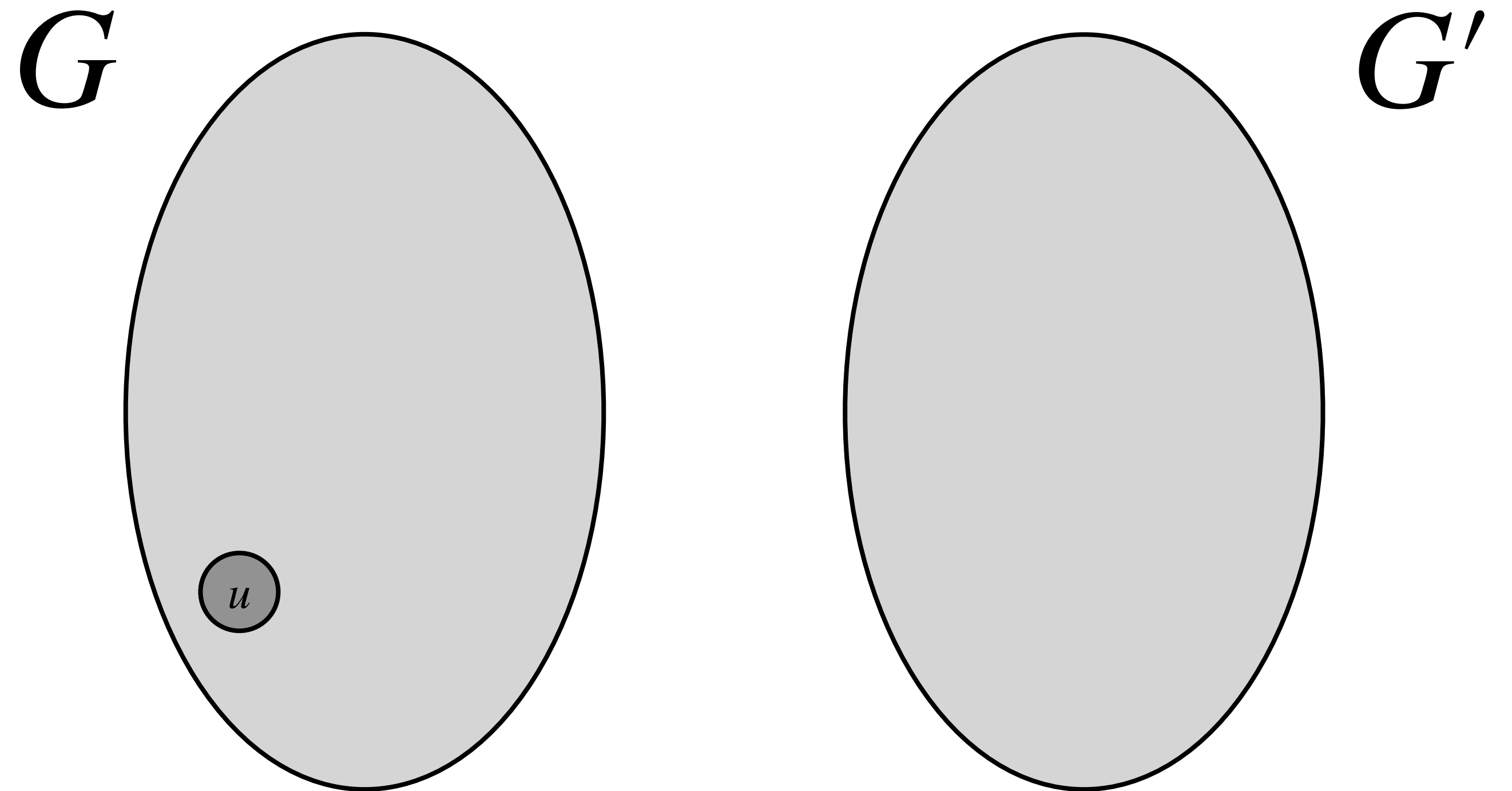
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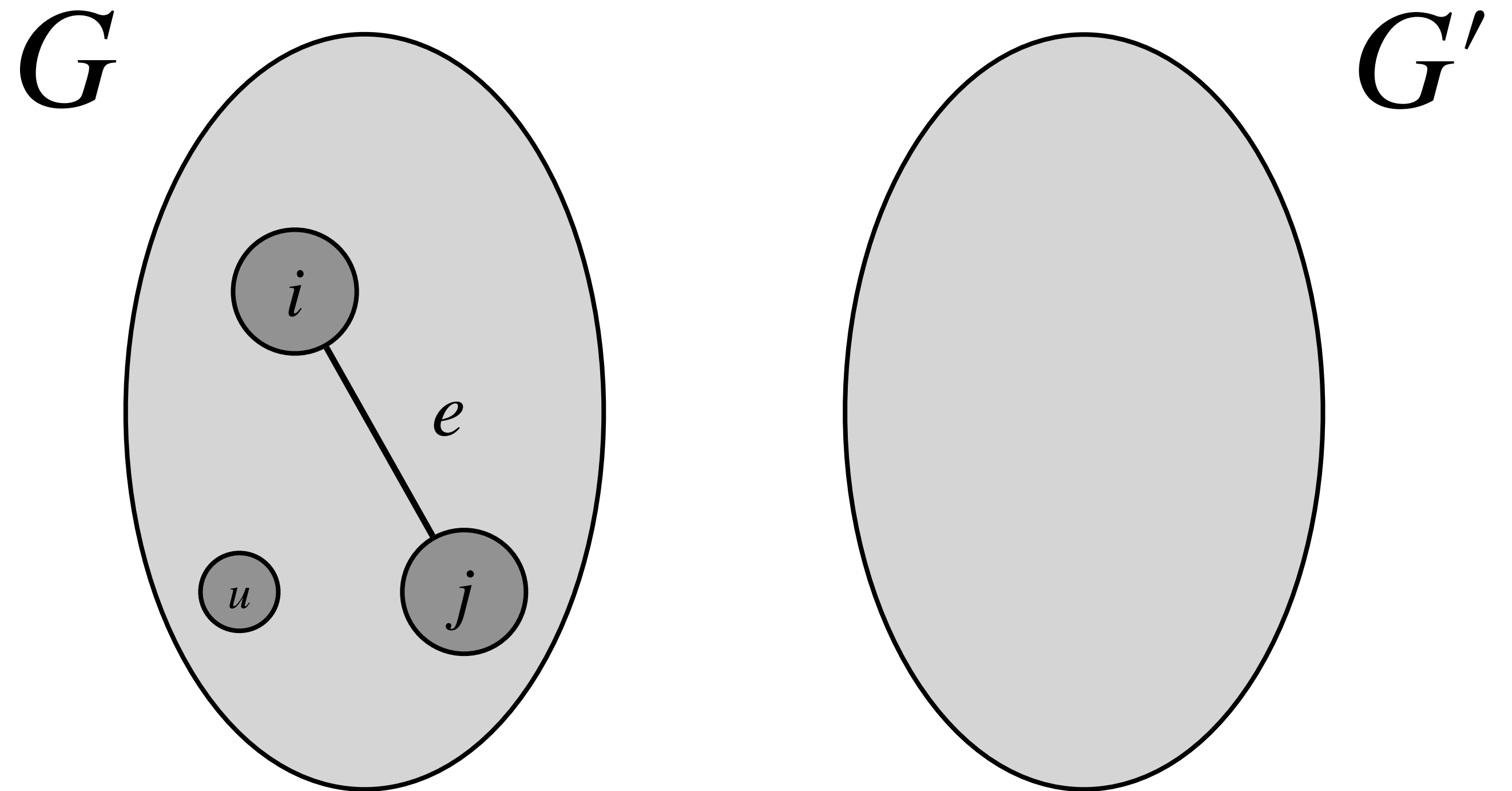
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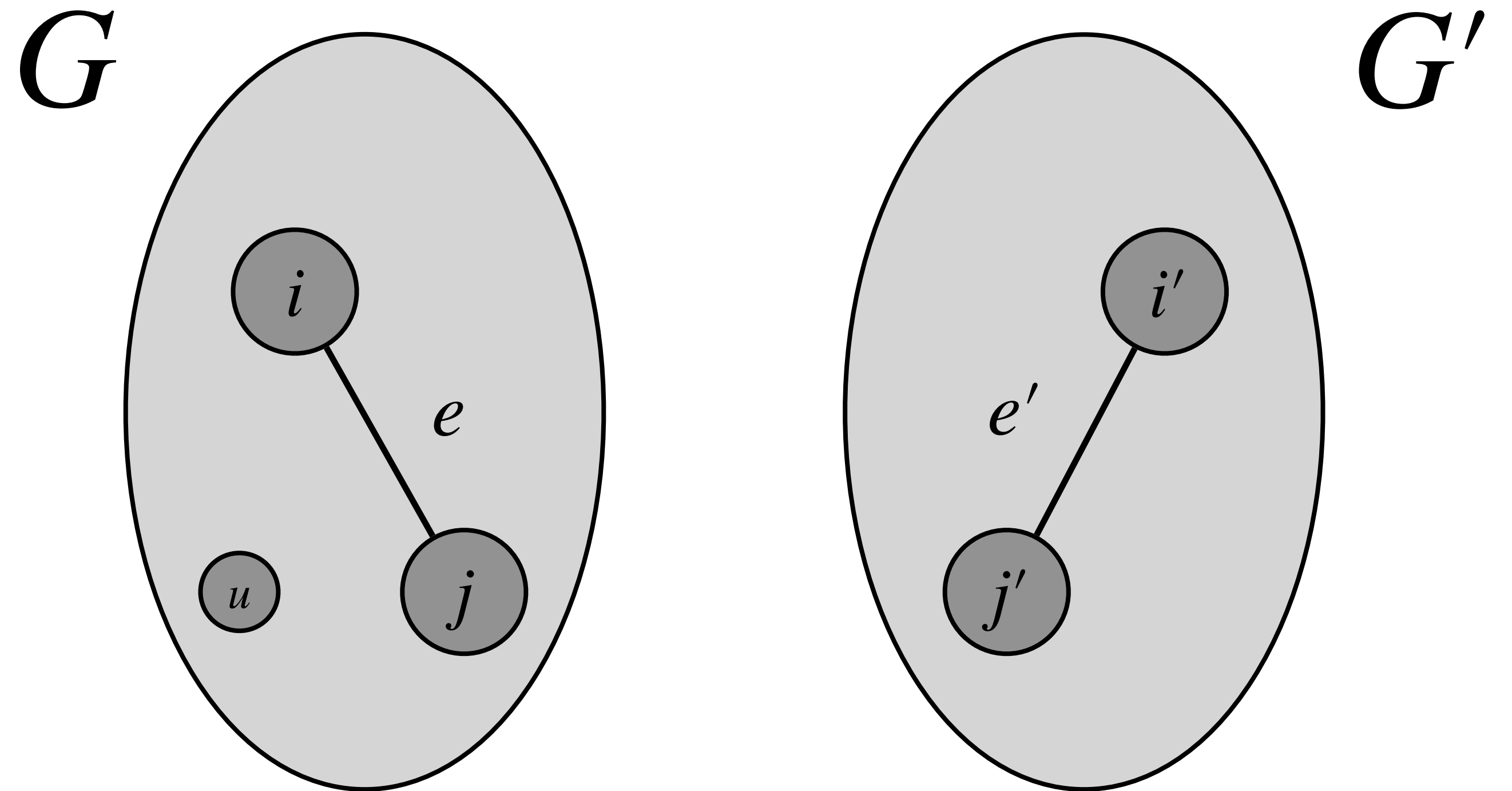
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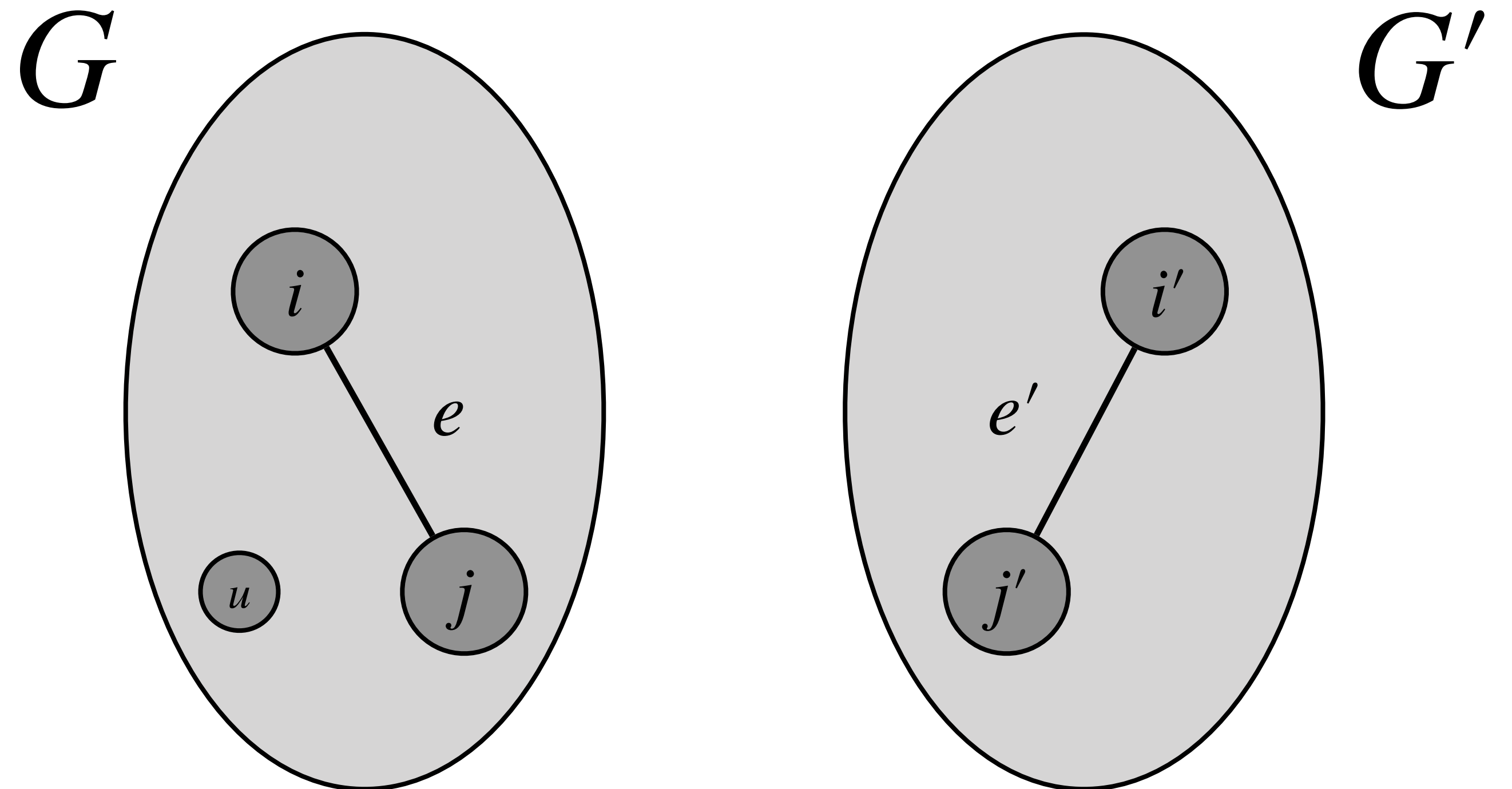


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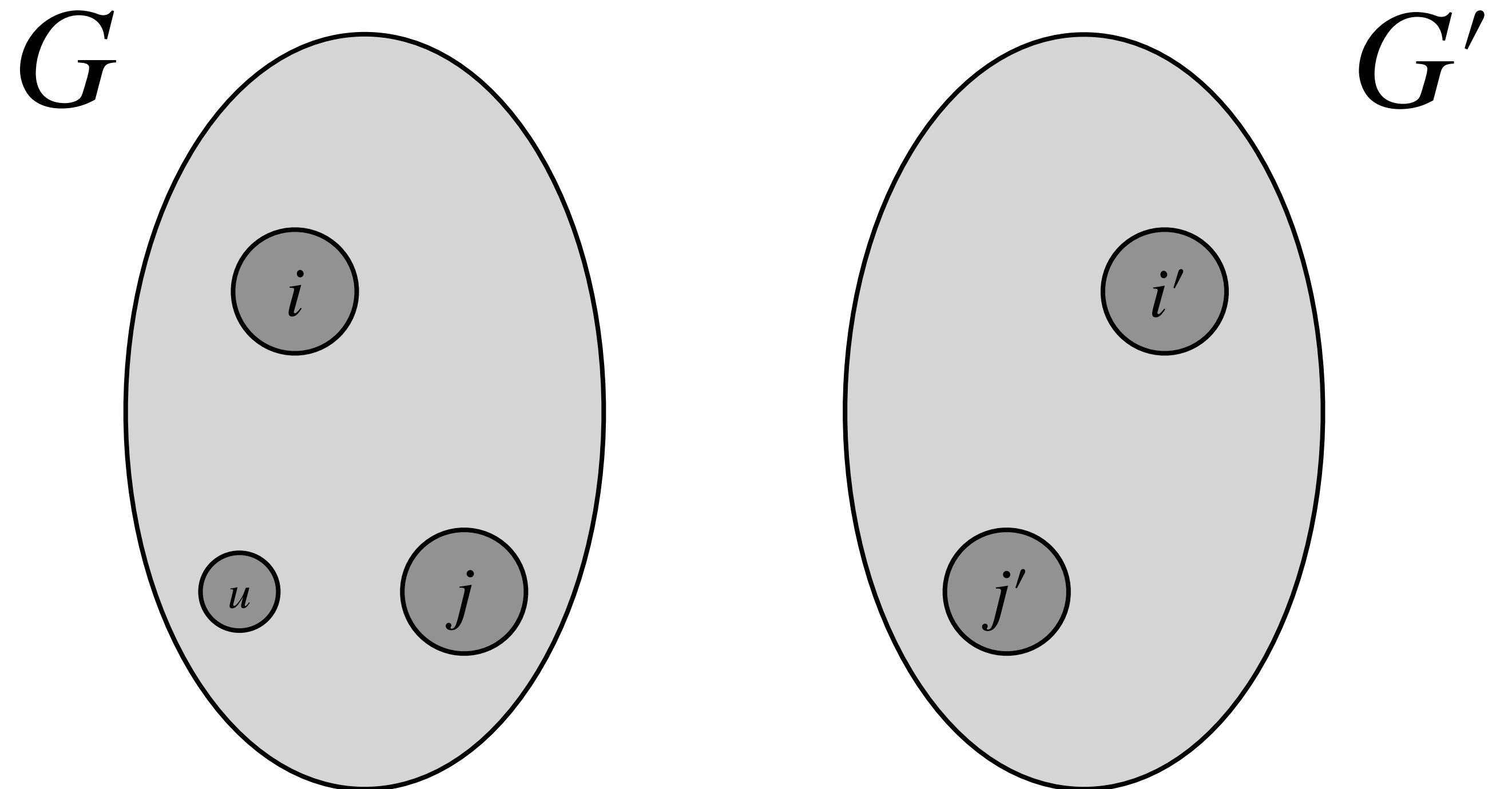
KT-0 Indistinguishability

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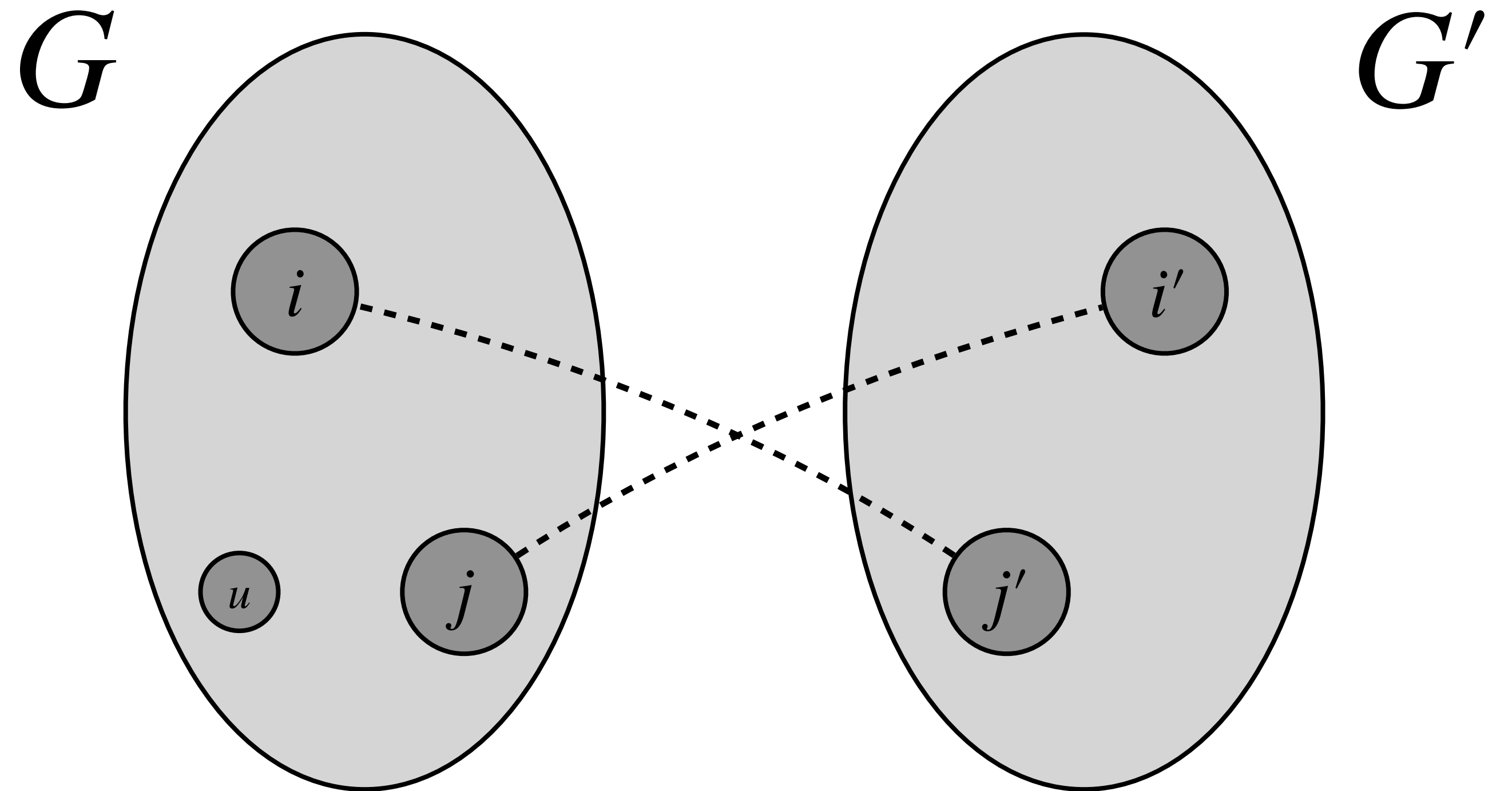
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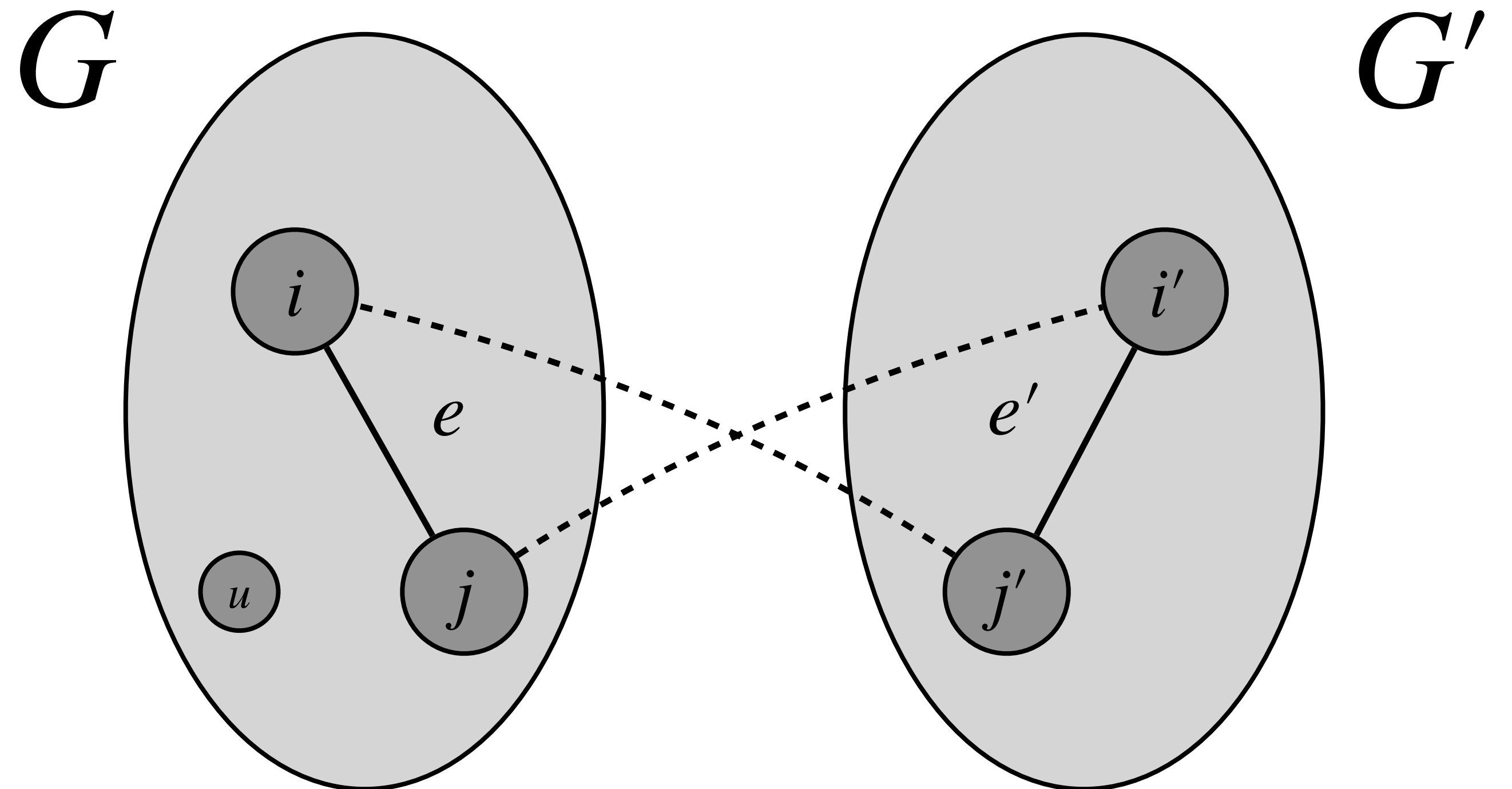
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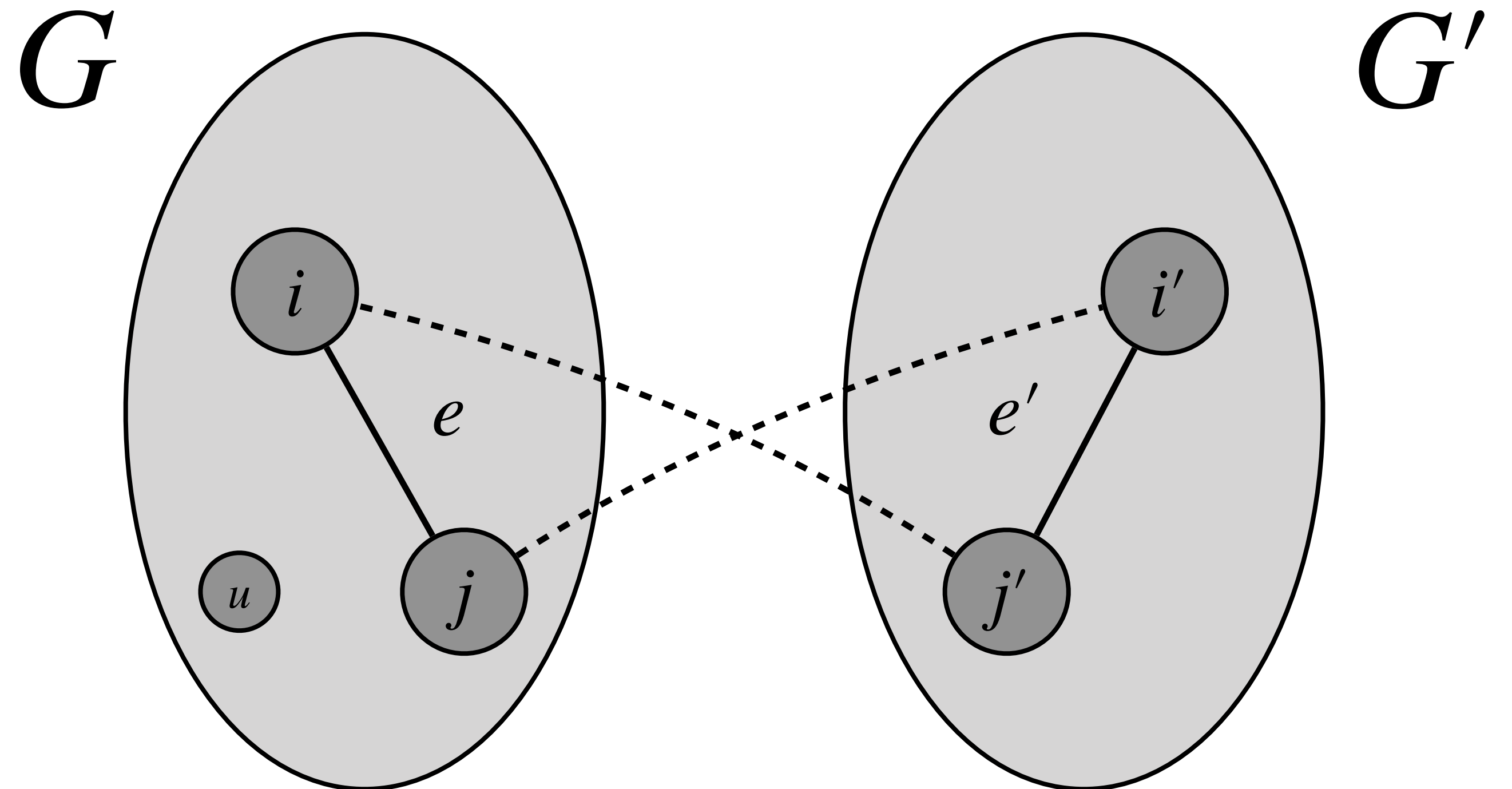
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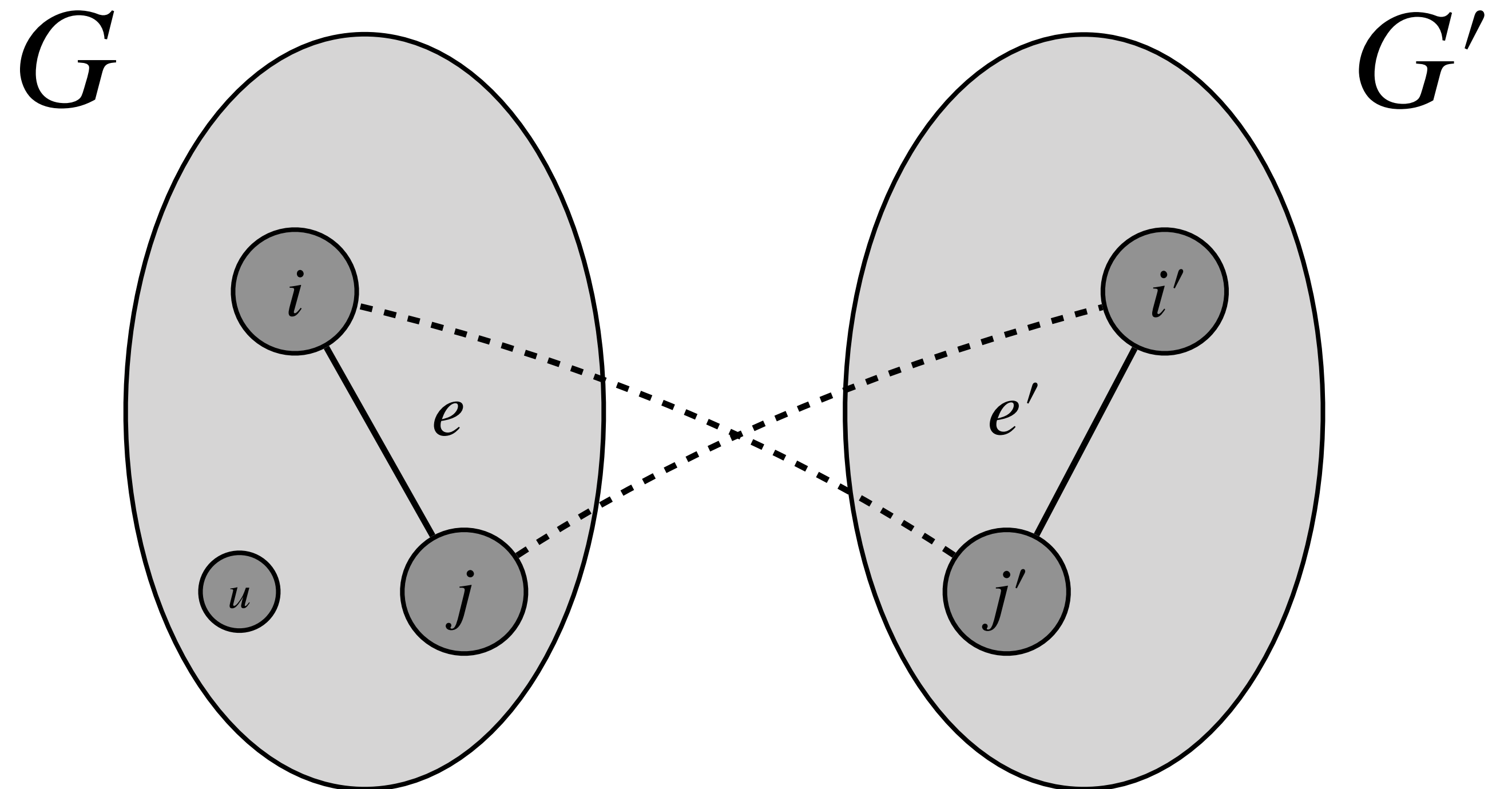
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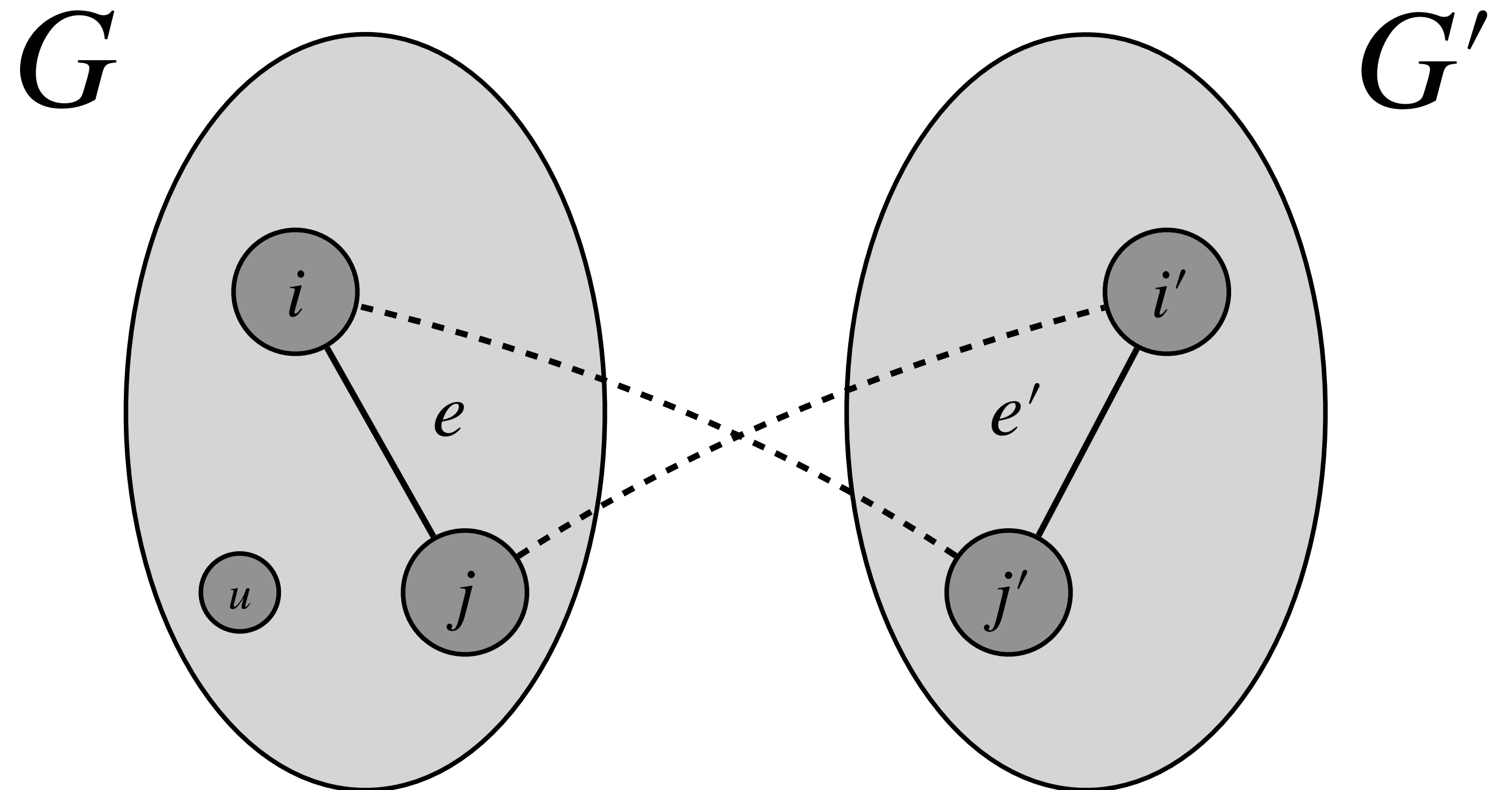
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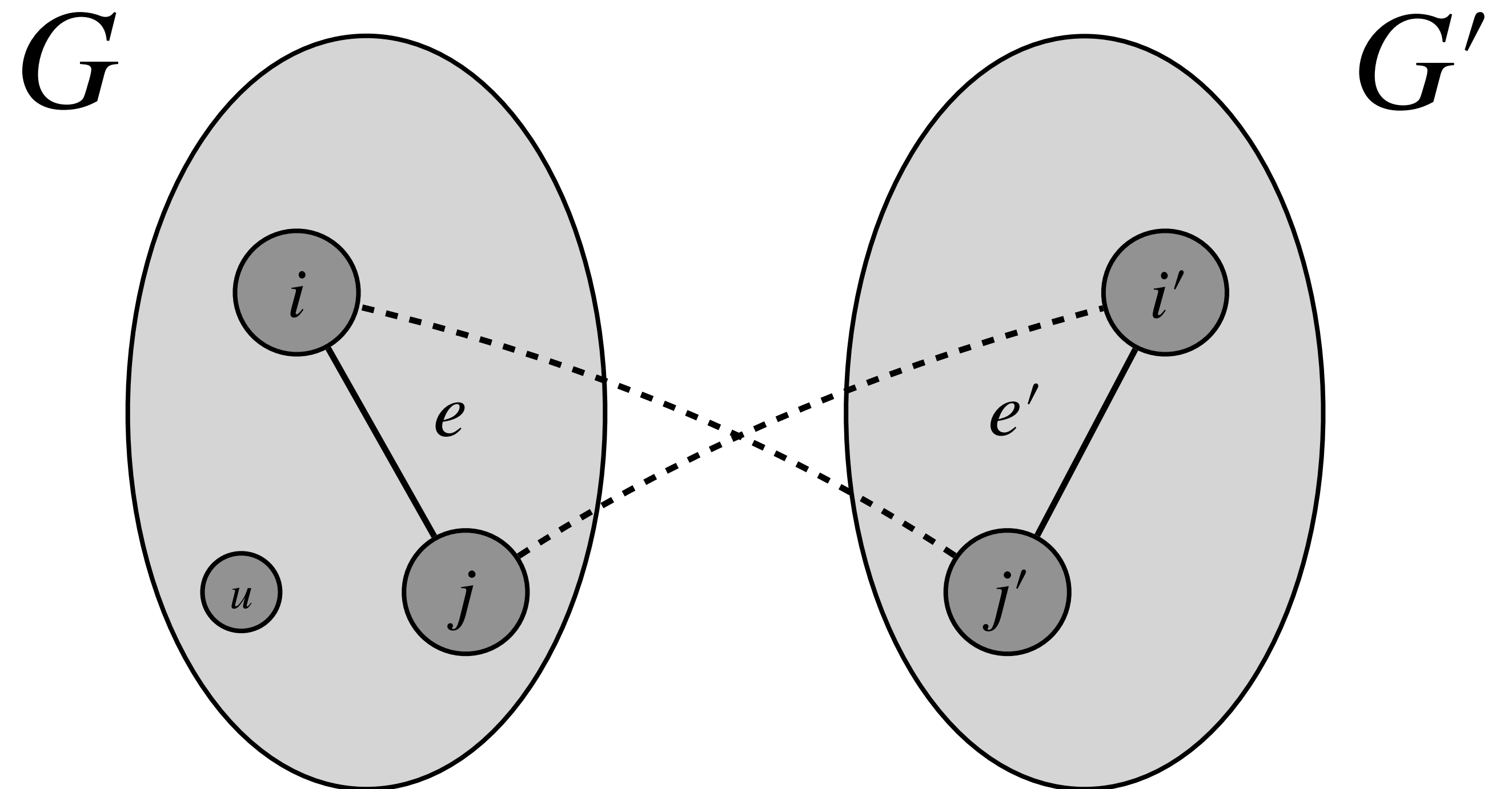


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- Even works with infinite bandwidth!

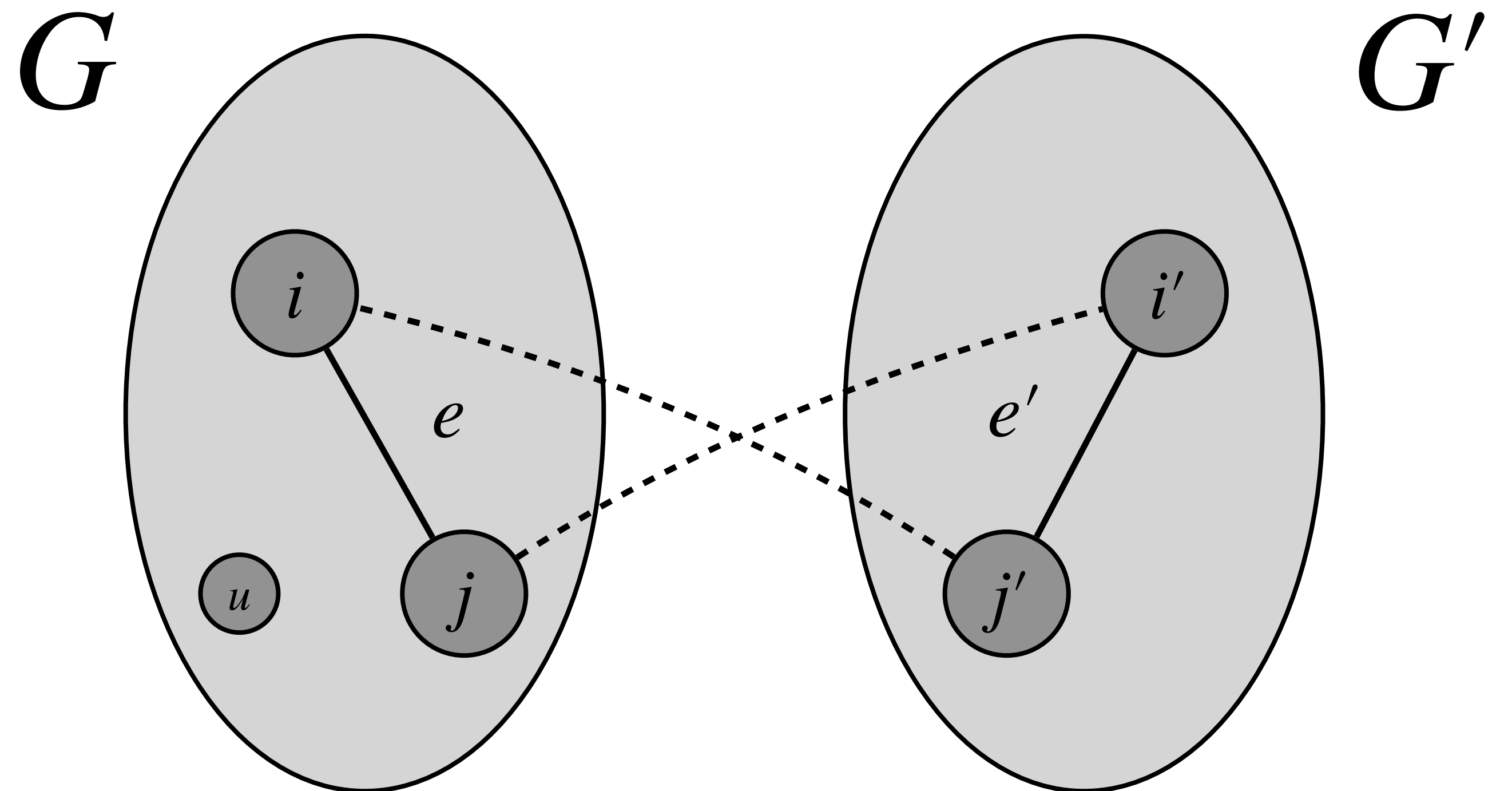


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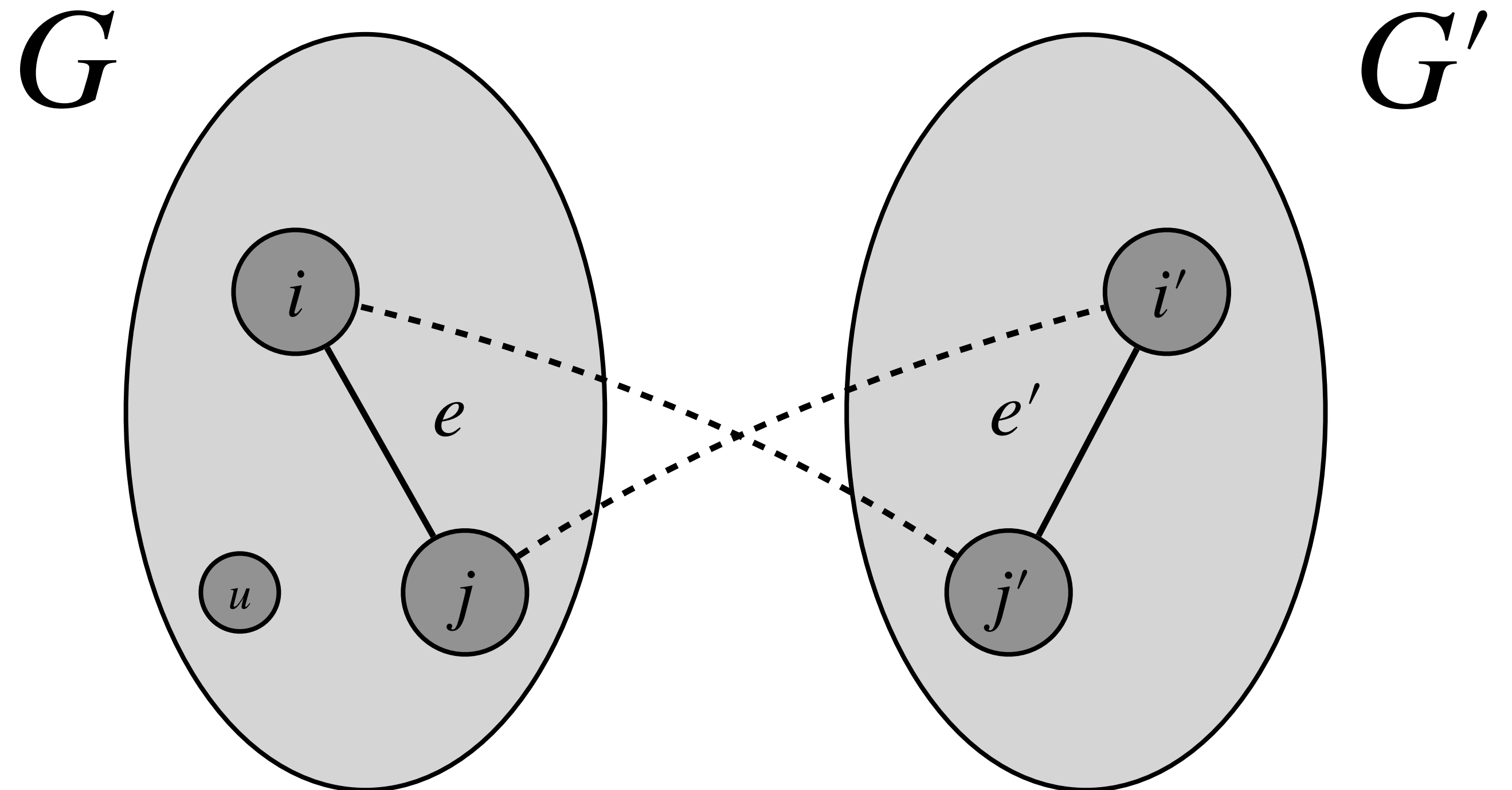
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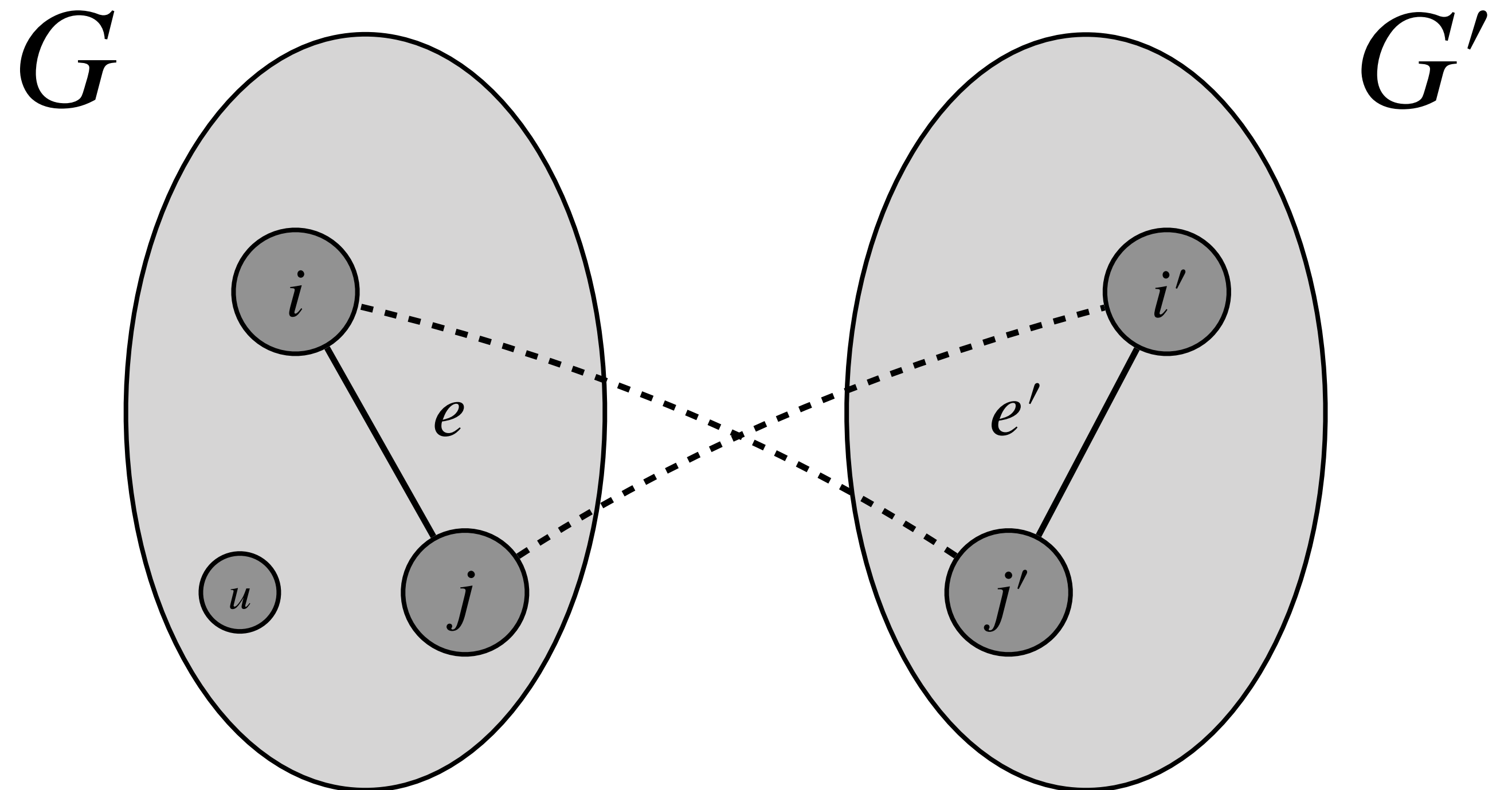
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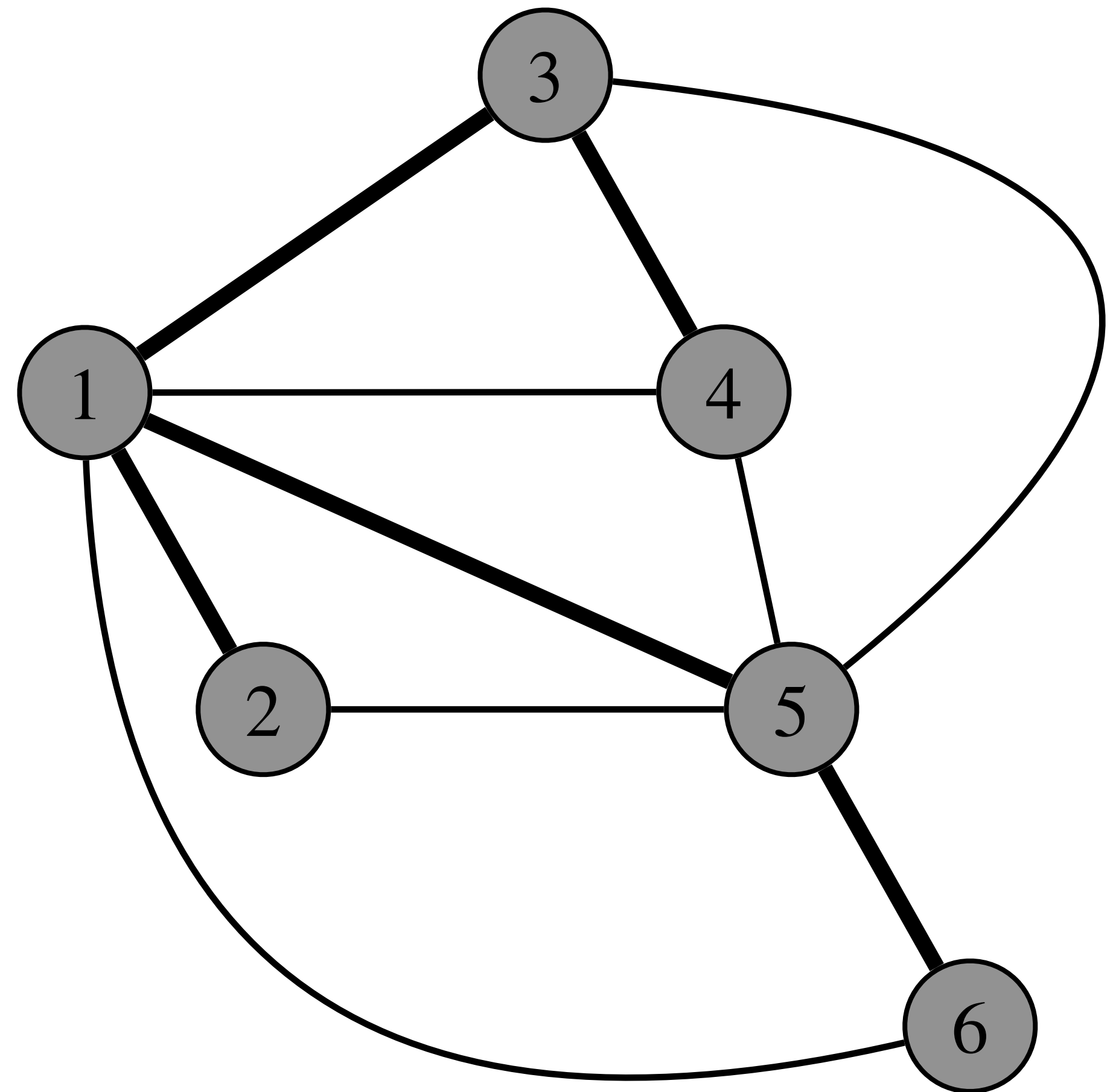


What about KT-1?

- Initial knowledge itself is different!
- Node i sees j in one graph and j' in the other.
- Is there any hope for an $\Omega(m)$ lower bound?

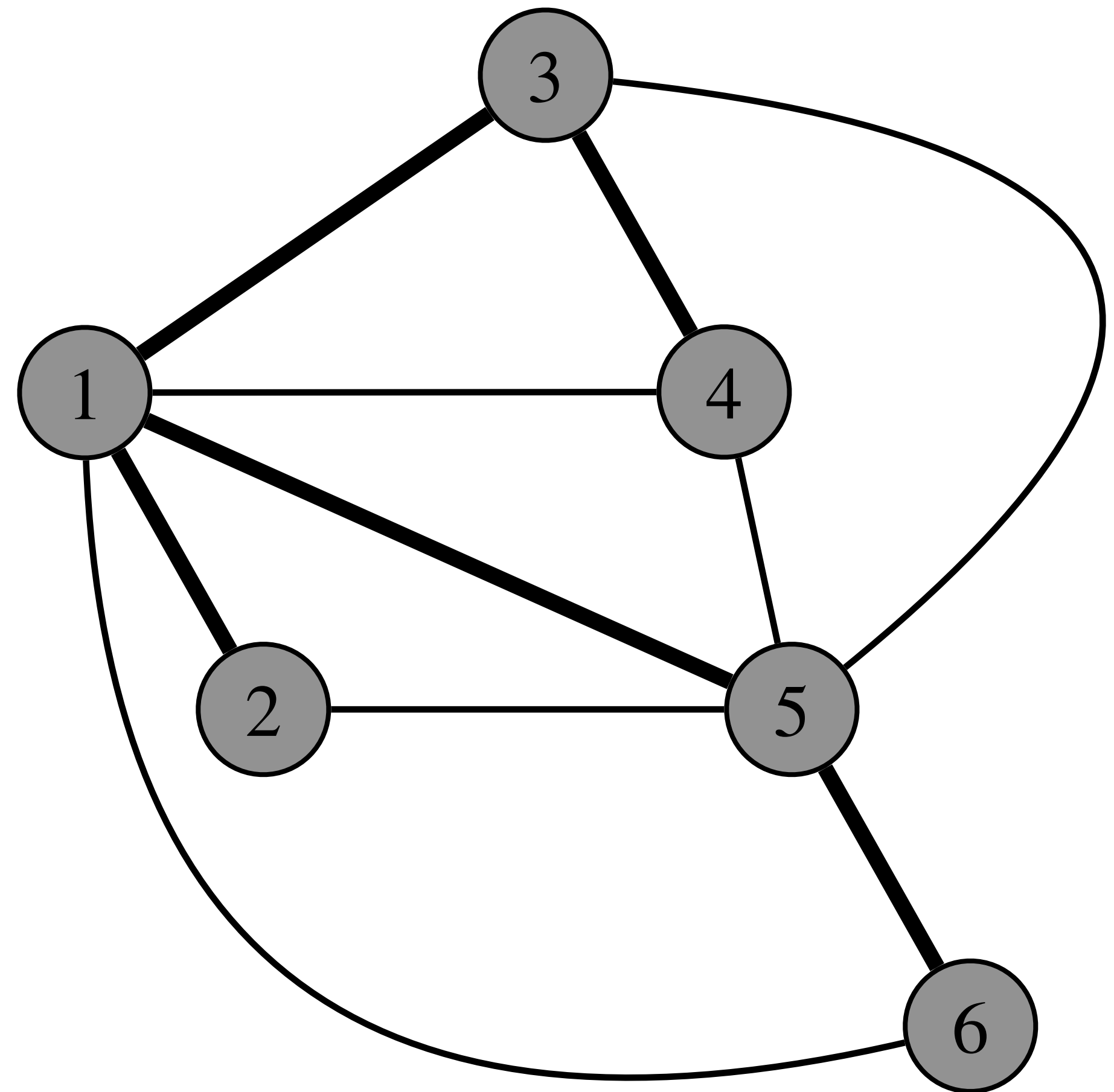


Message Efficient Broadcast



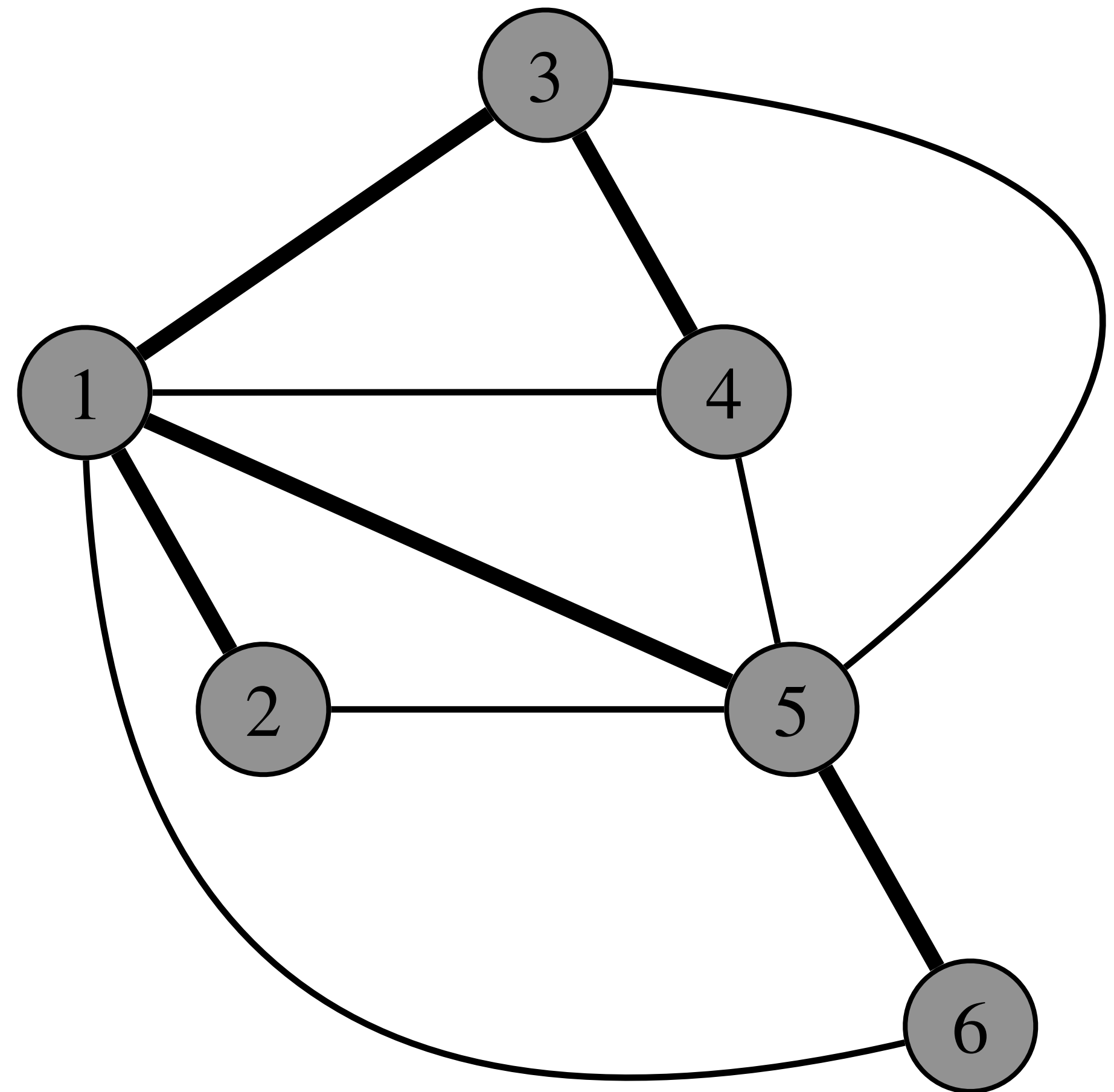
Message Efficient Broadcast

- We can compute a **spanning tree** with $\tilde{O}(n)$ rounds and $\tilde{O}(n)$ messages.



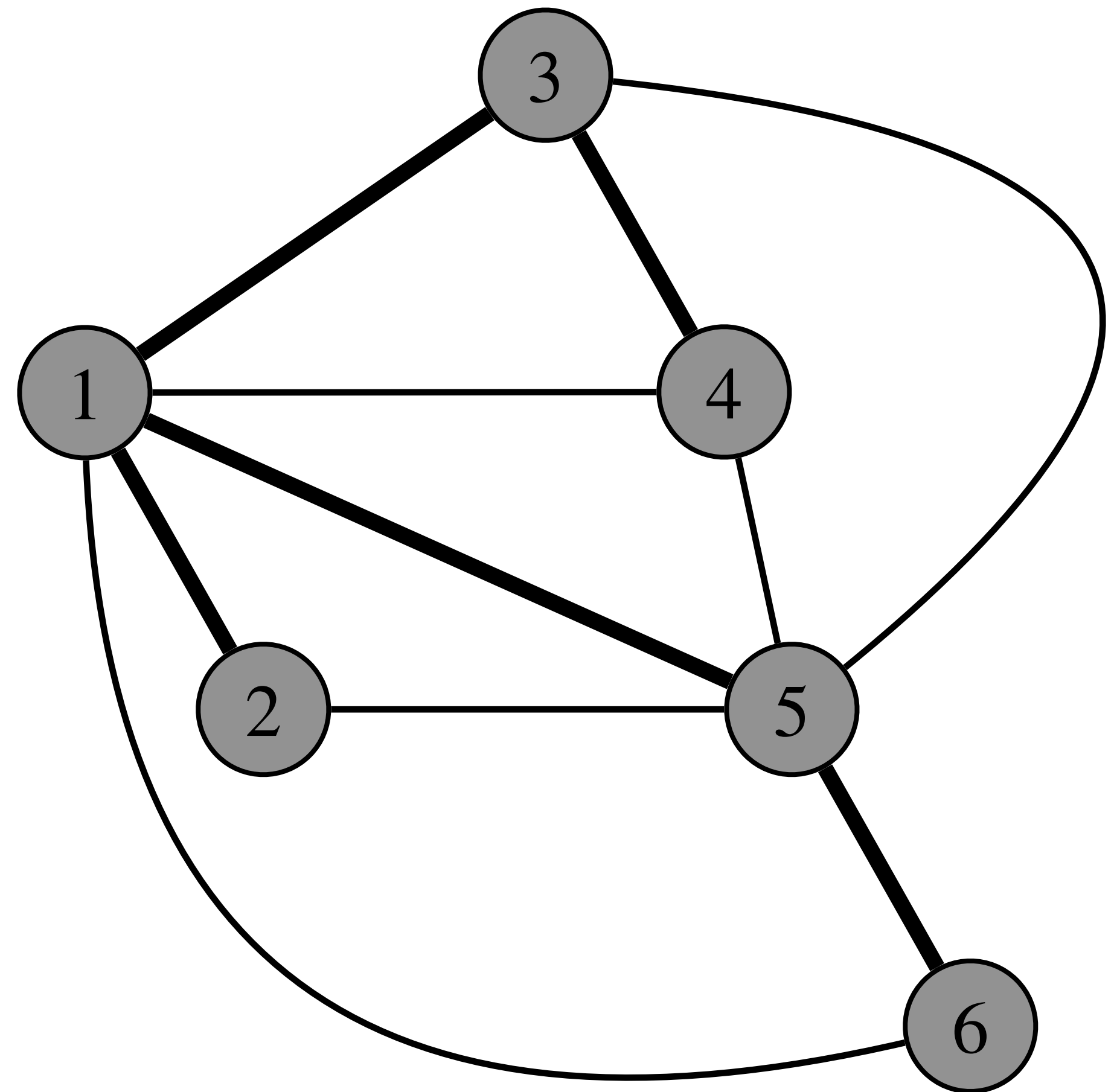
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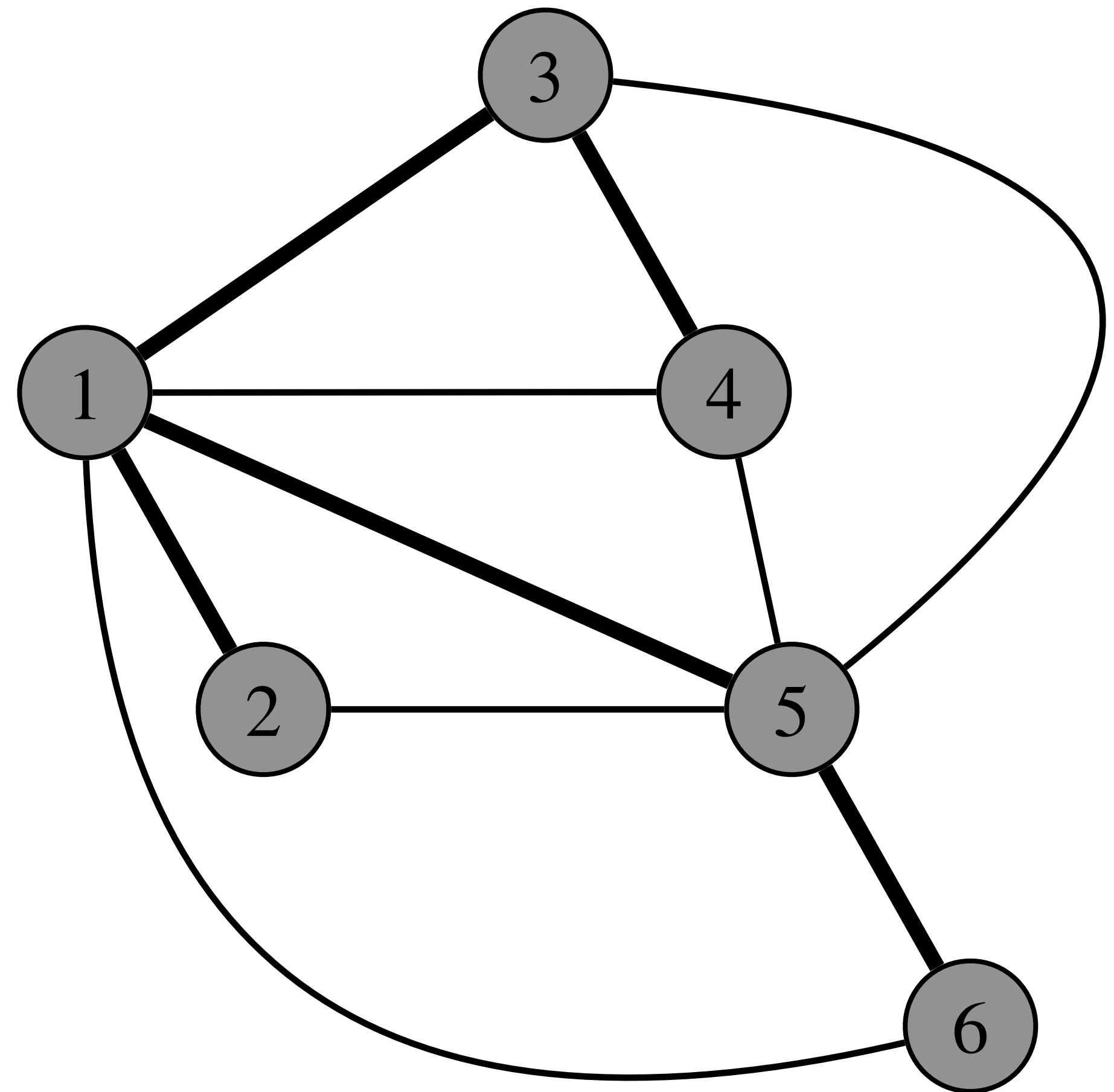
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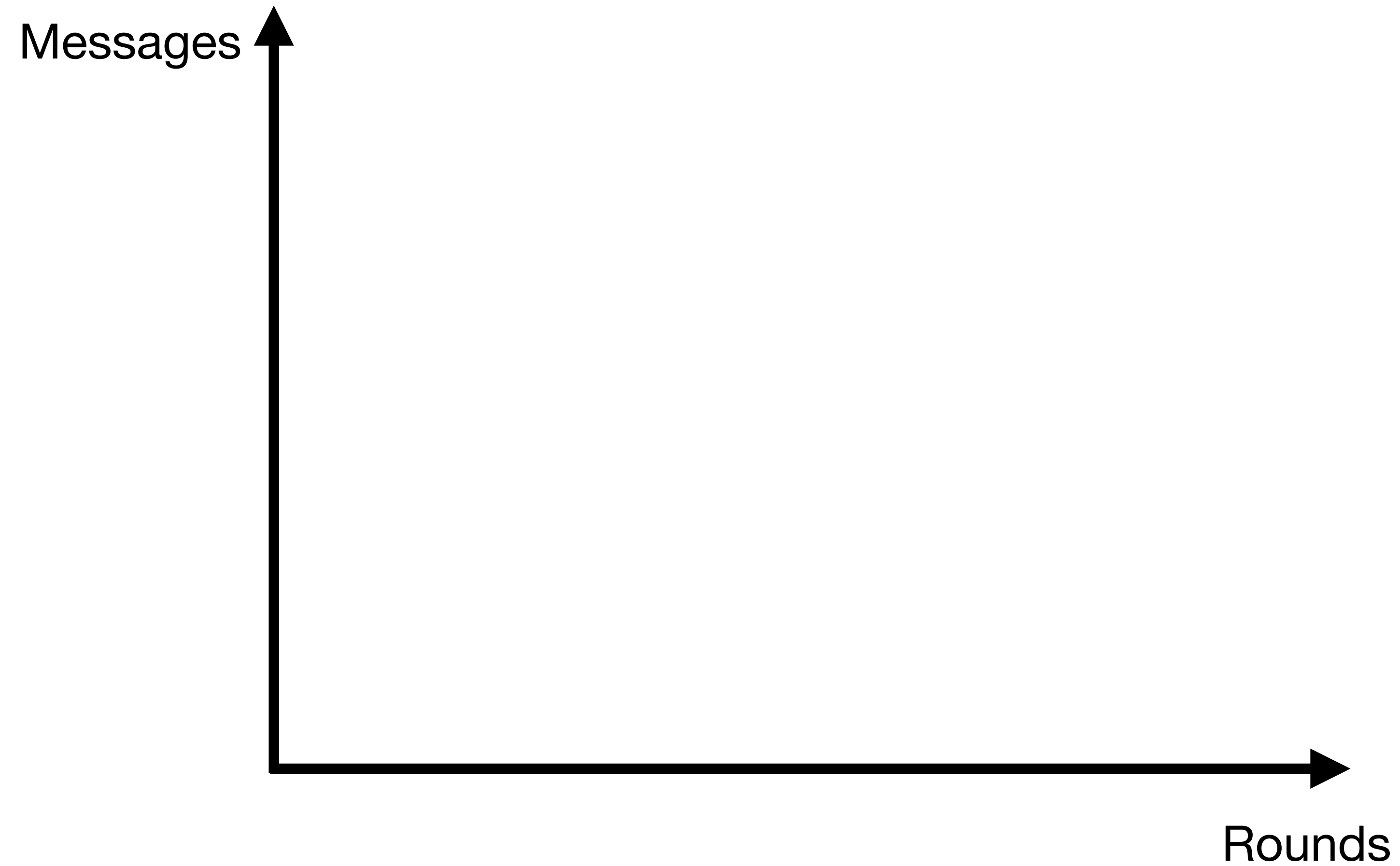


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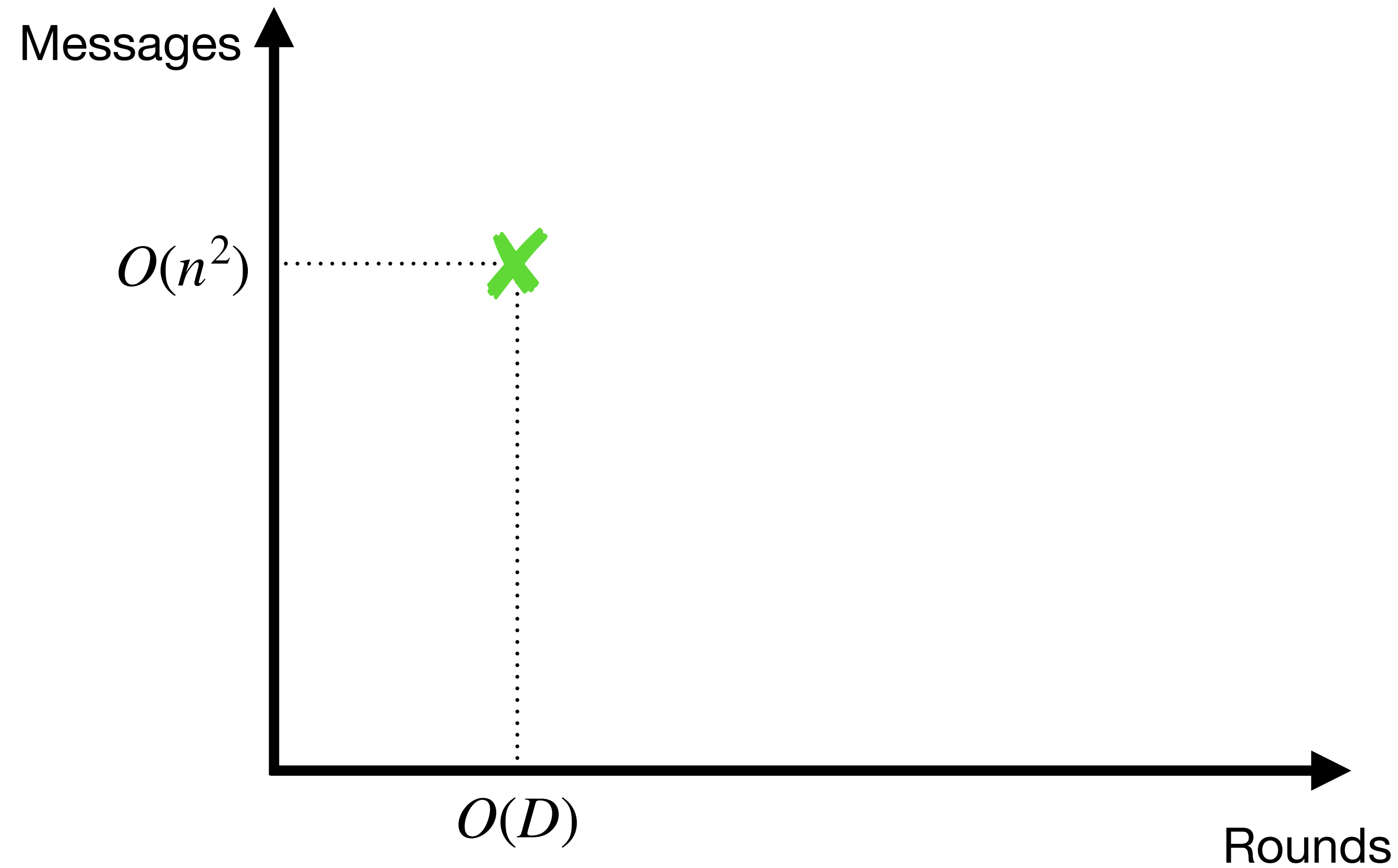
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- Broadcast by flooding on just the spanning tree edges.
- Message efficient but not round efficient.



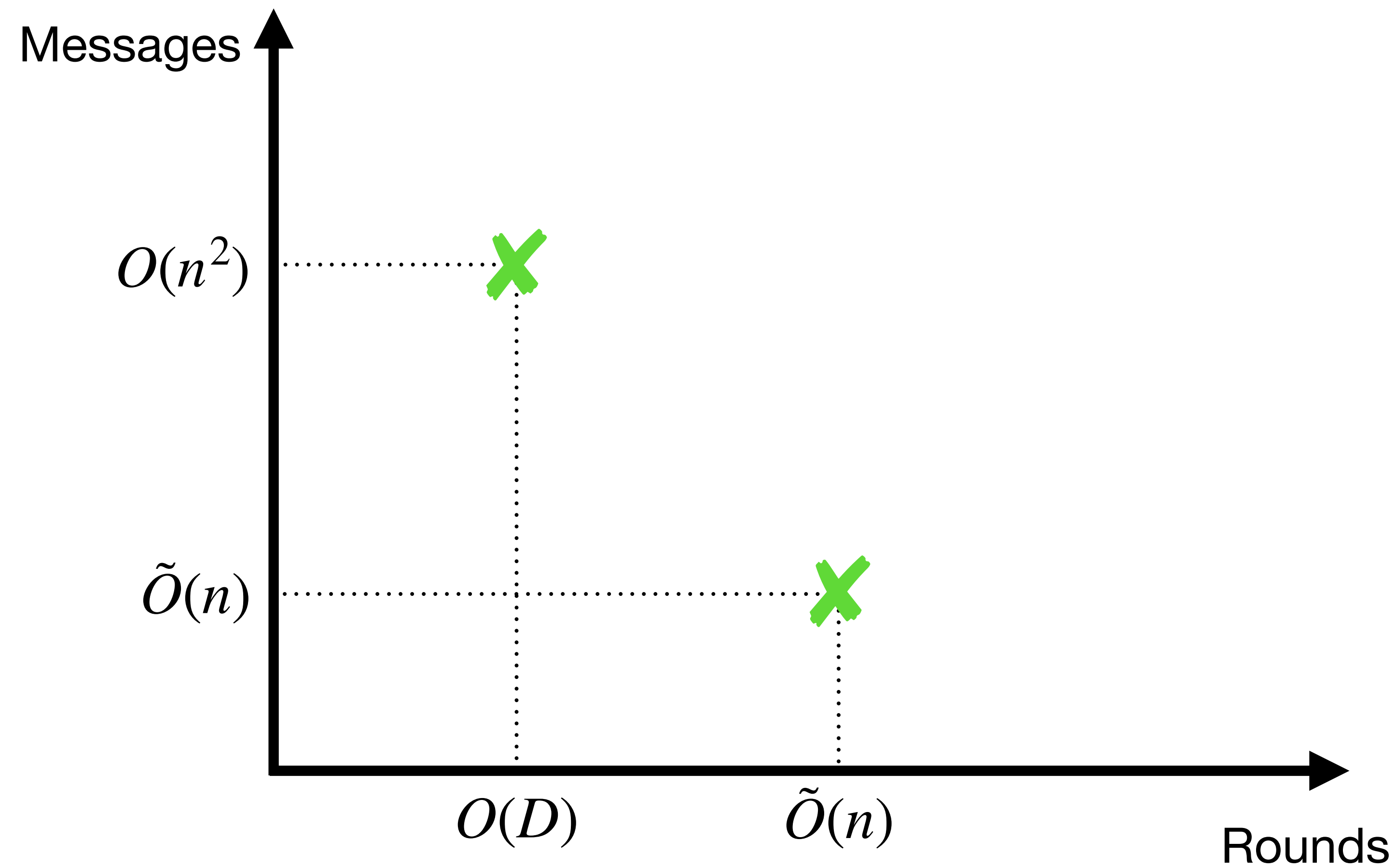
Rounds vs Messages



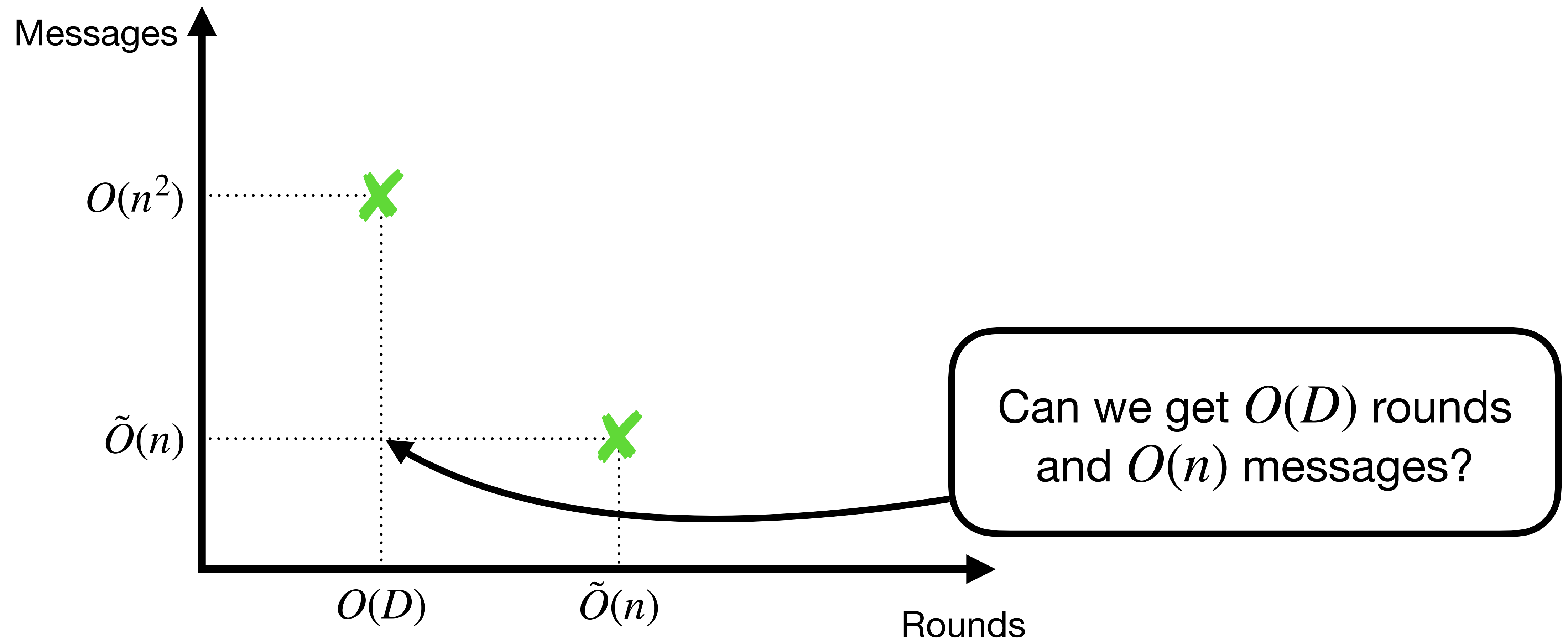
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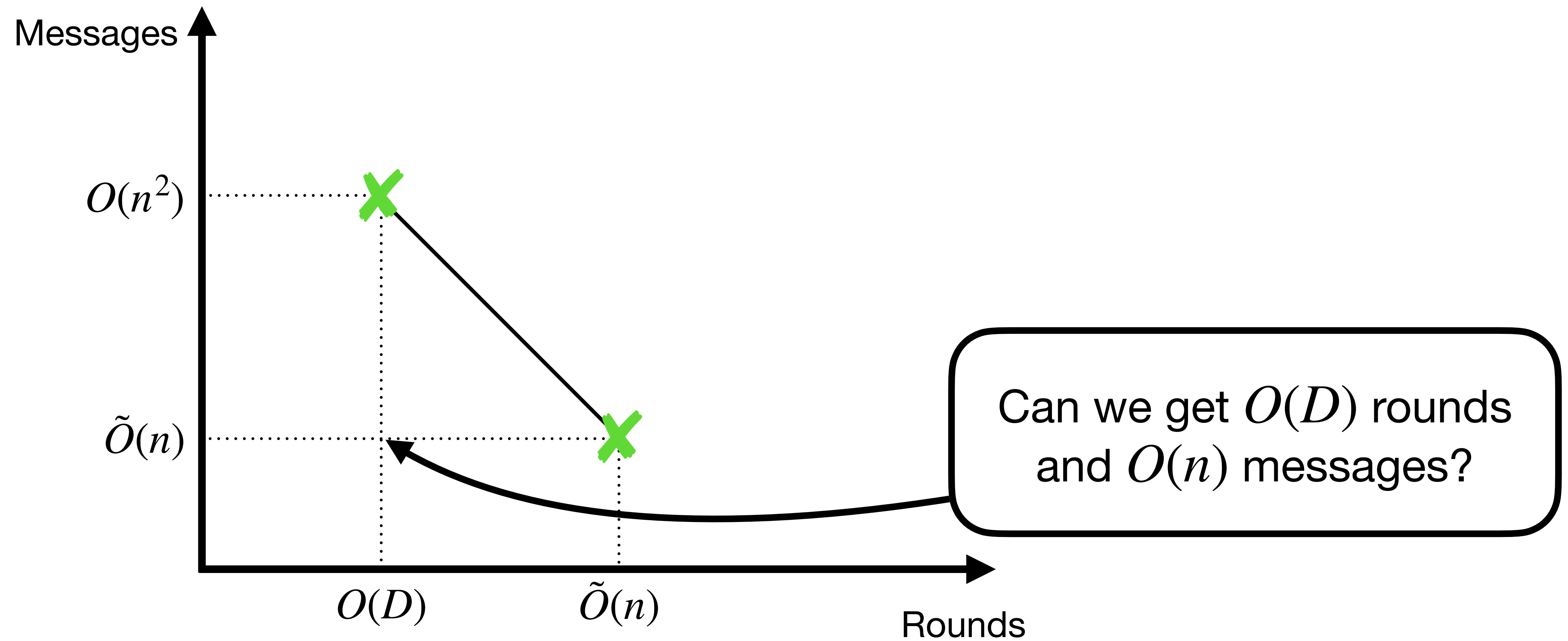
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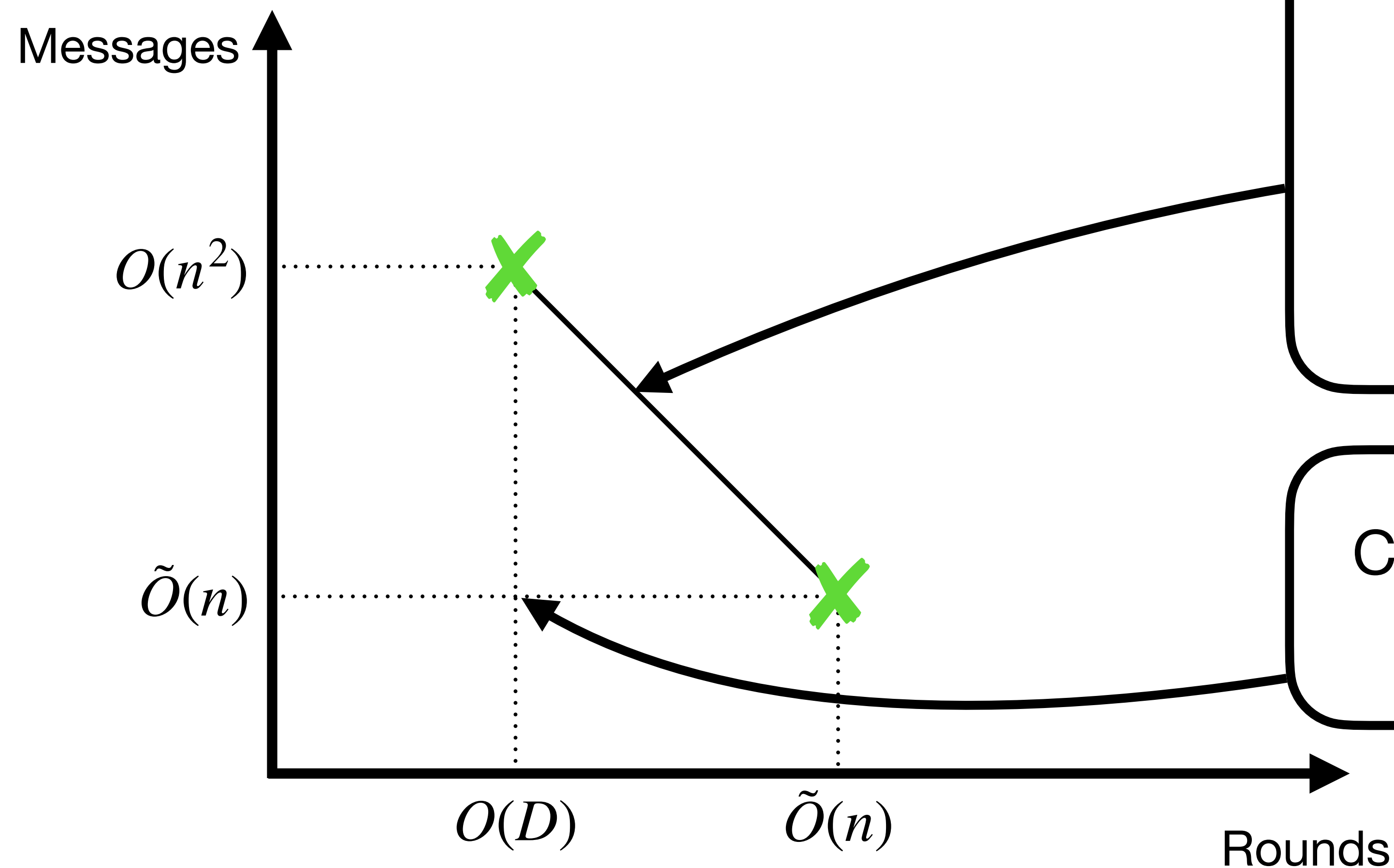
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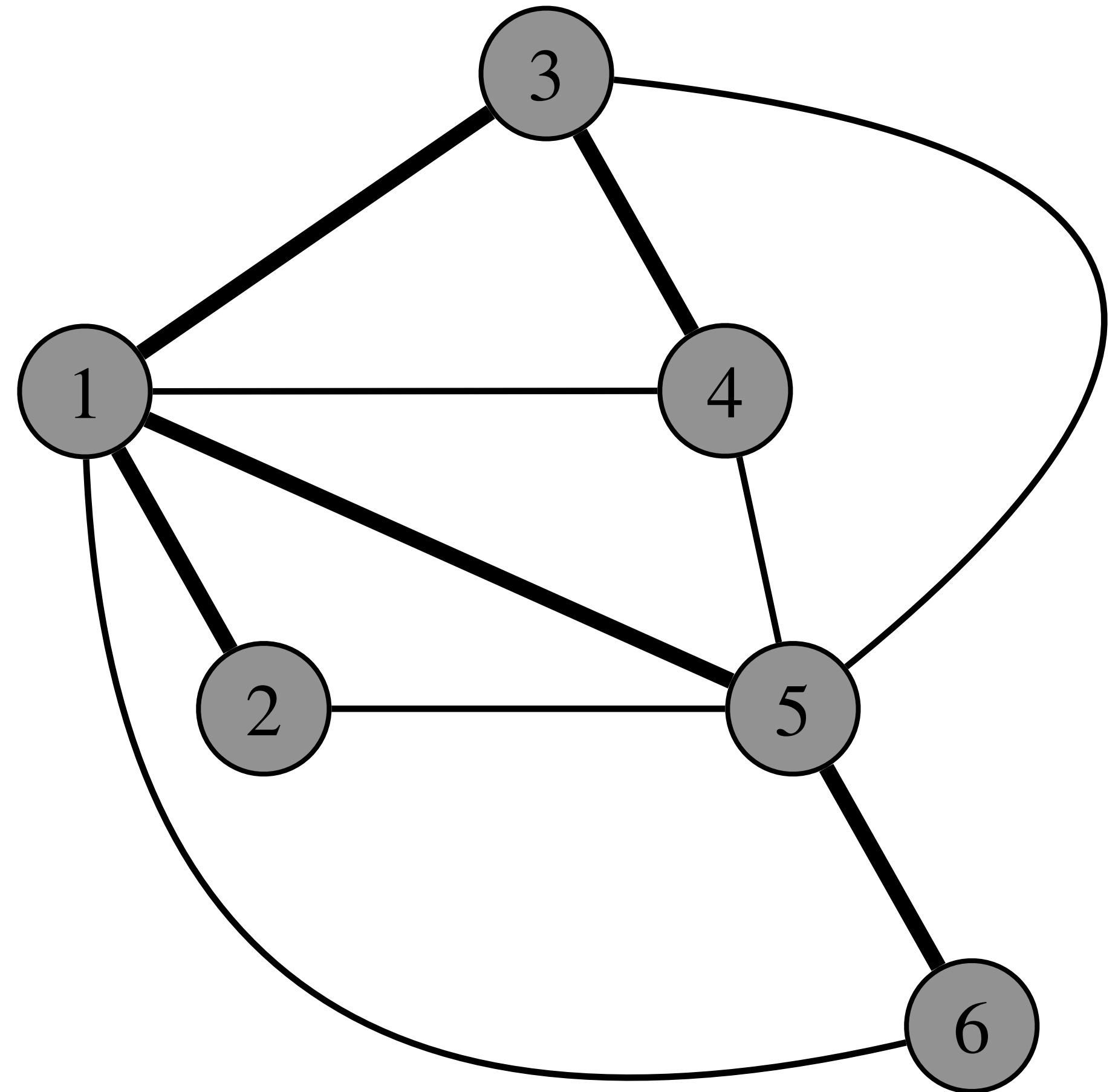
$\tilde{O}(D + n^{1-\delta})$ rounds

$\tilde{O}(n^{1+\delta})$ messages

for $0 < \delta < 1$ [GP18]

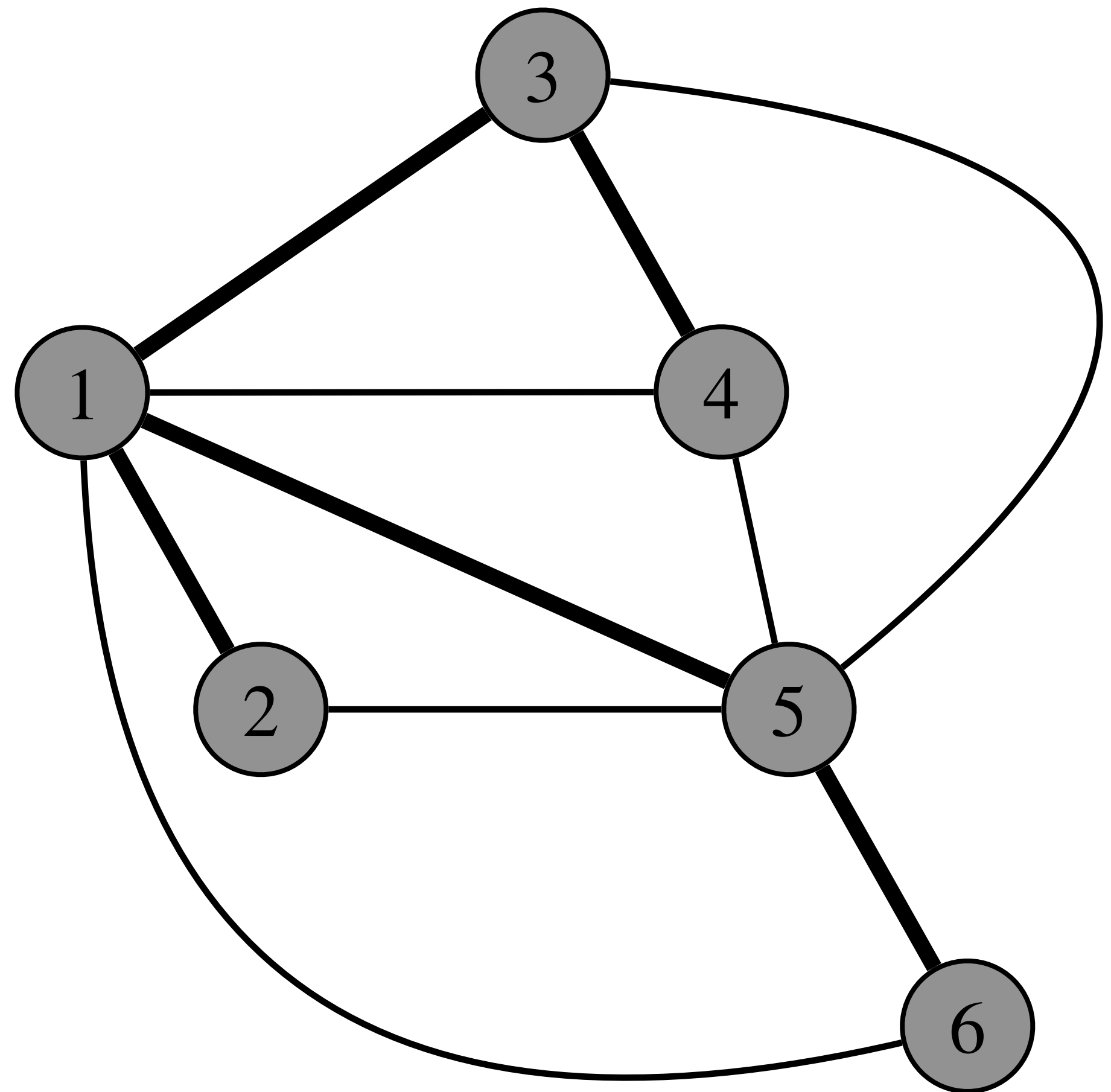
Can we get $O(D)$ rounds
and $O(n)$ messages?

Silence Conveys Information



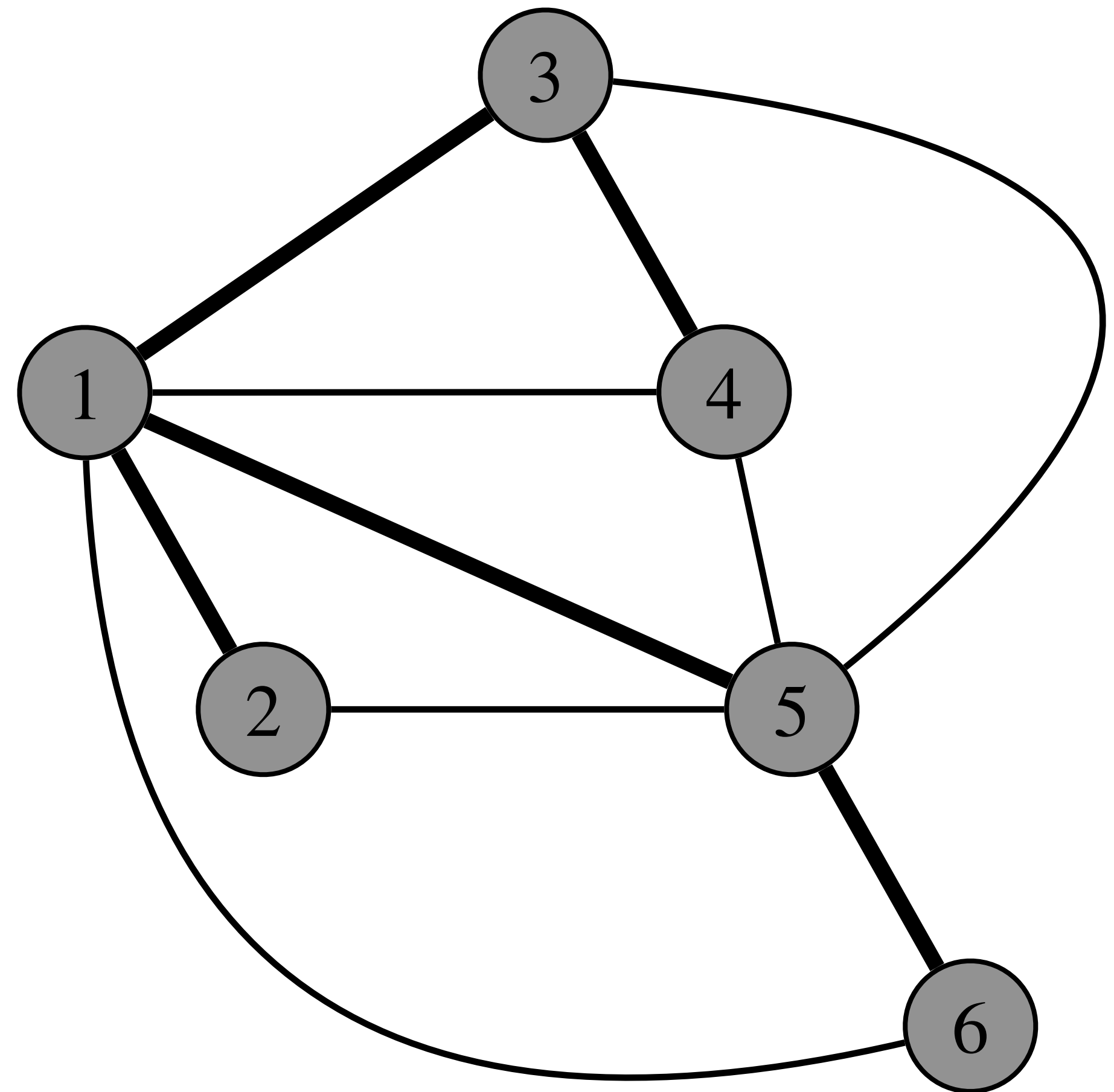
Silence Conveys Information

- We can compute a spanning tree using $\tilde{O}(n)$ messages.



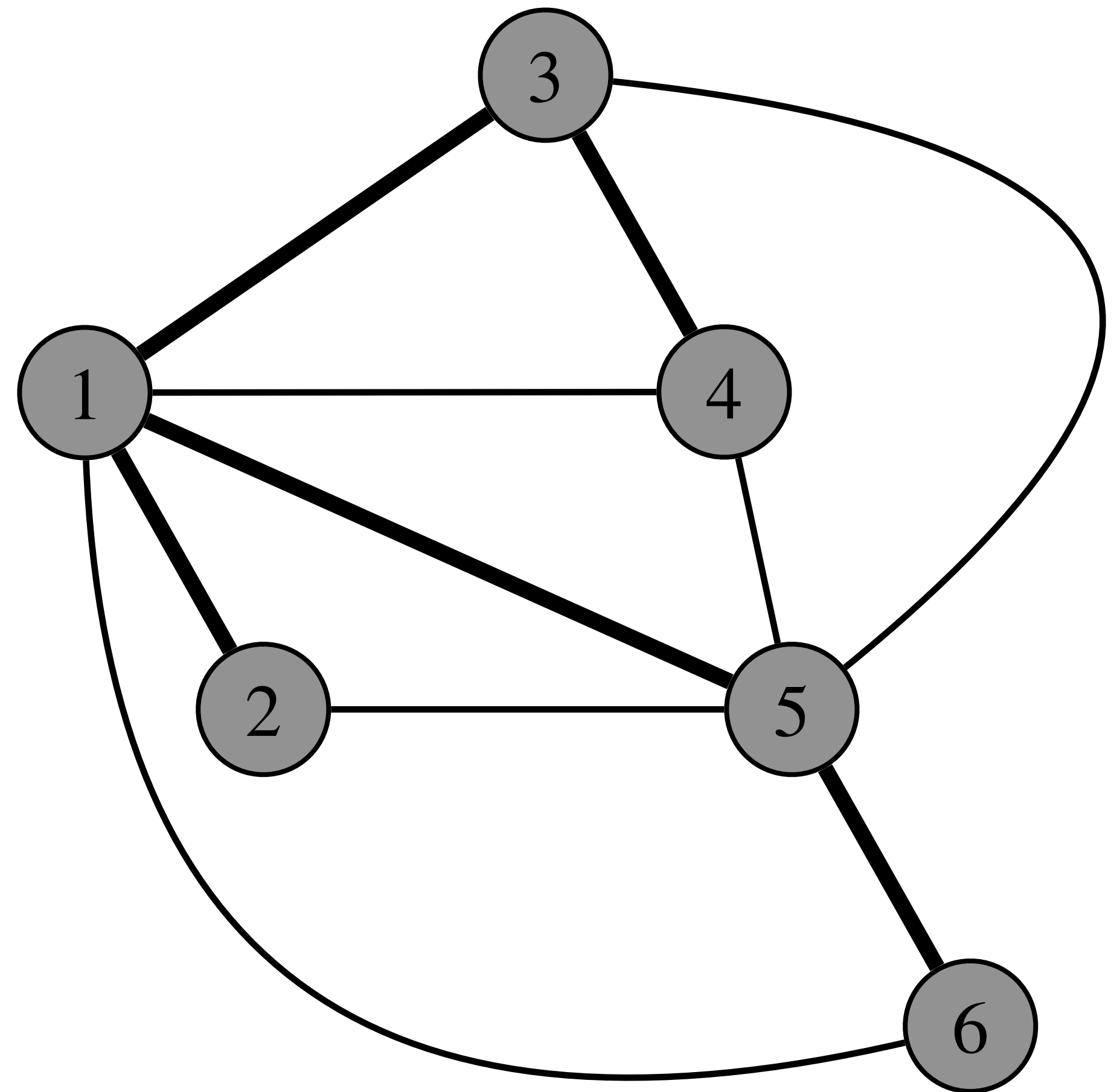
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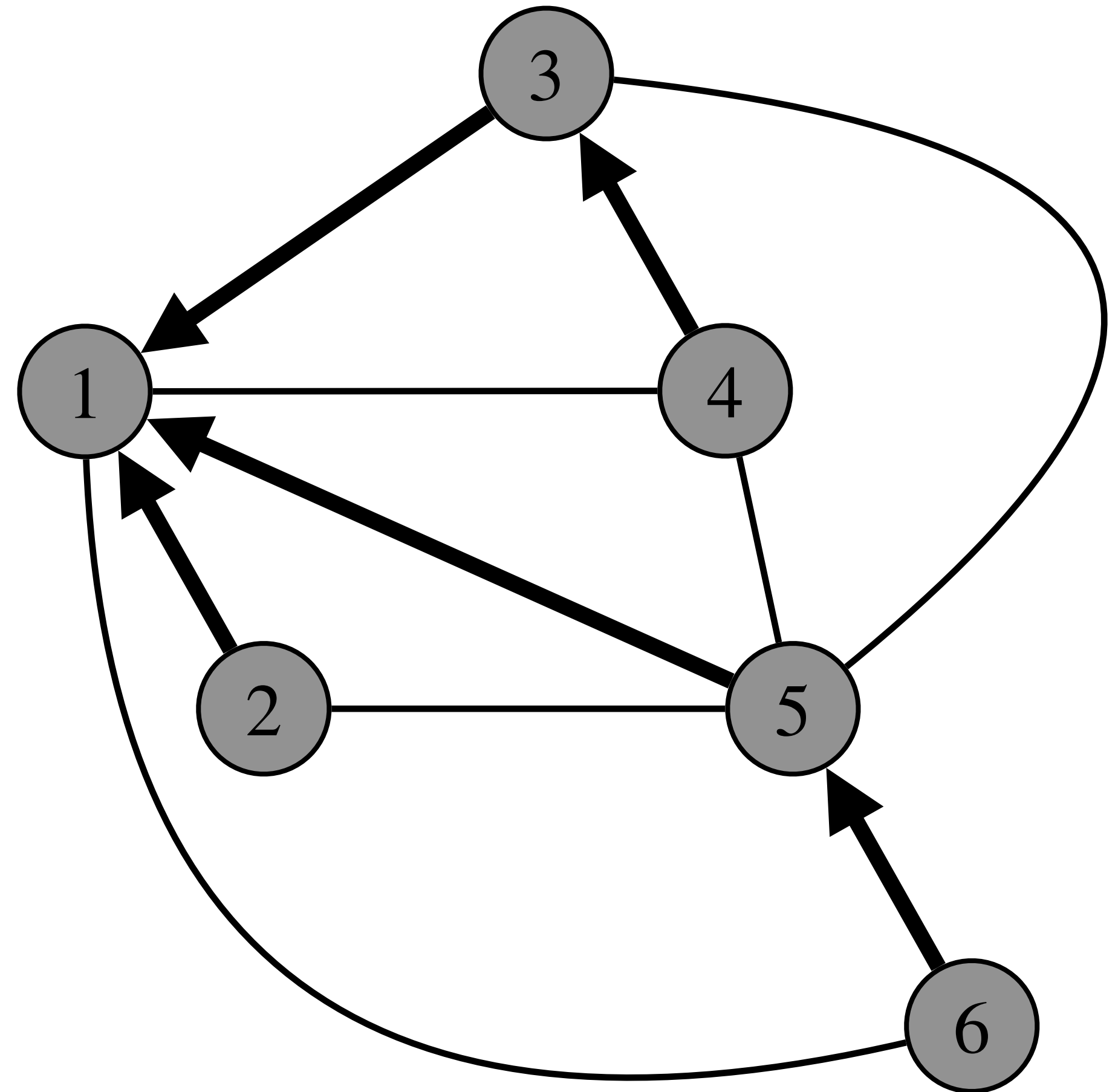


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- Trick: nodes use clock values to send topology information up the spanning tree.



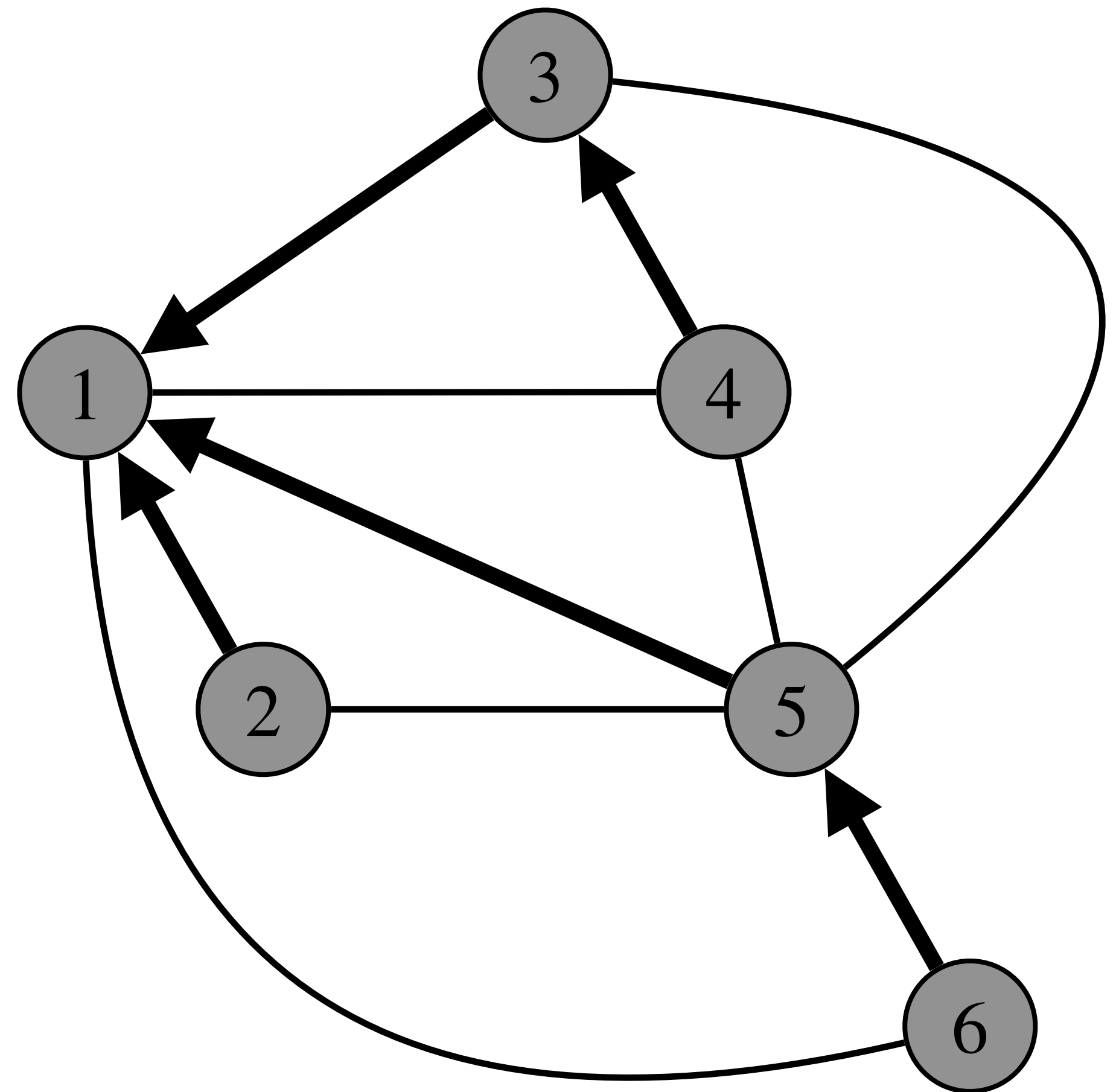
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List $\ell = 2^{\binom{n}{2}}$ graphs on n nodes.

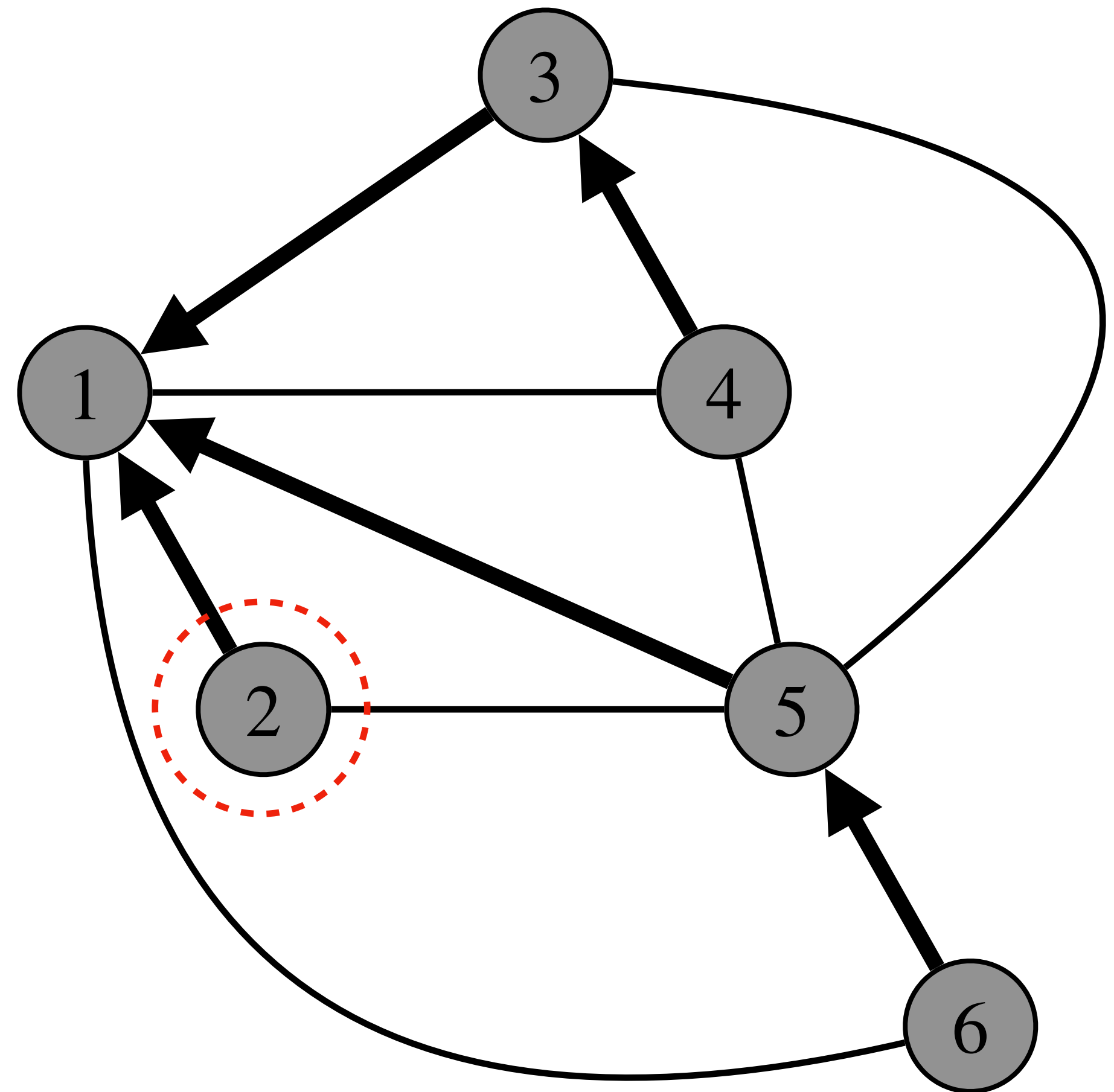
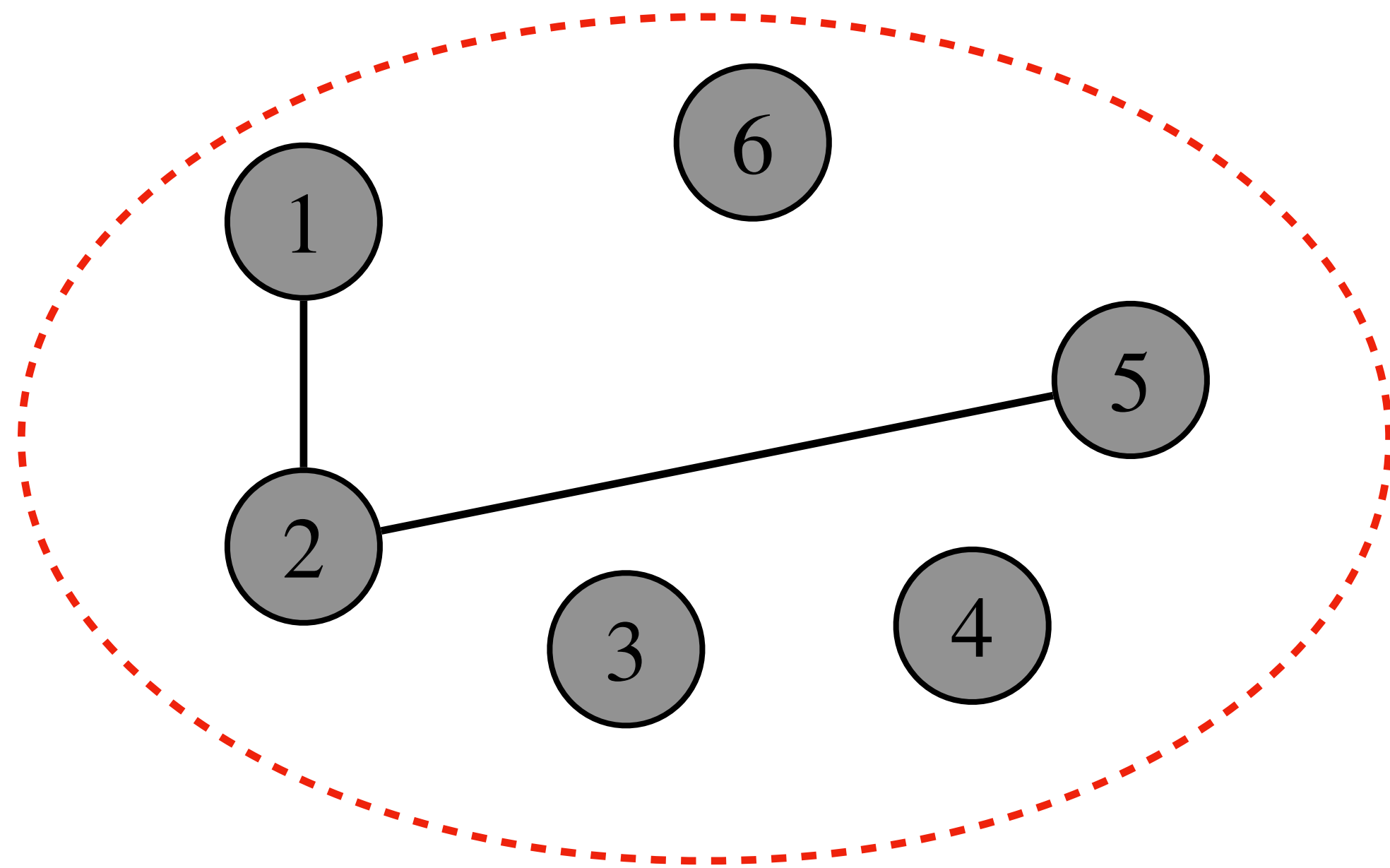
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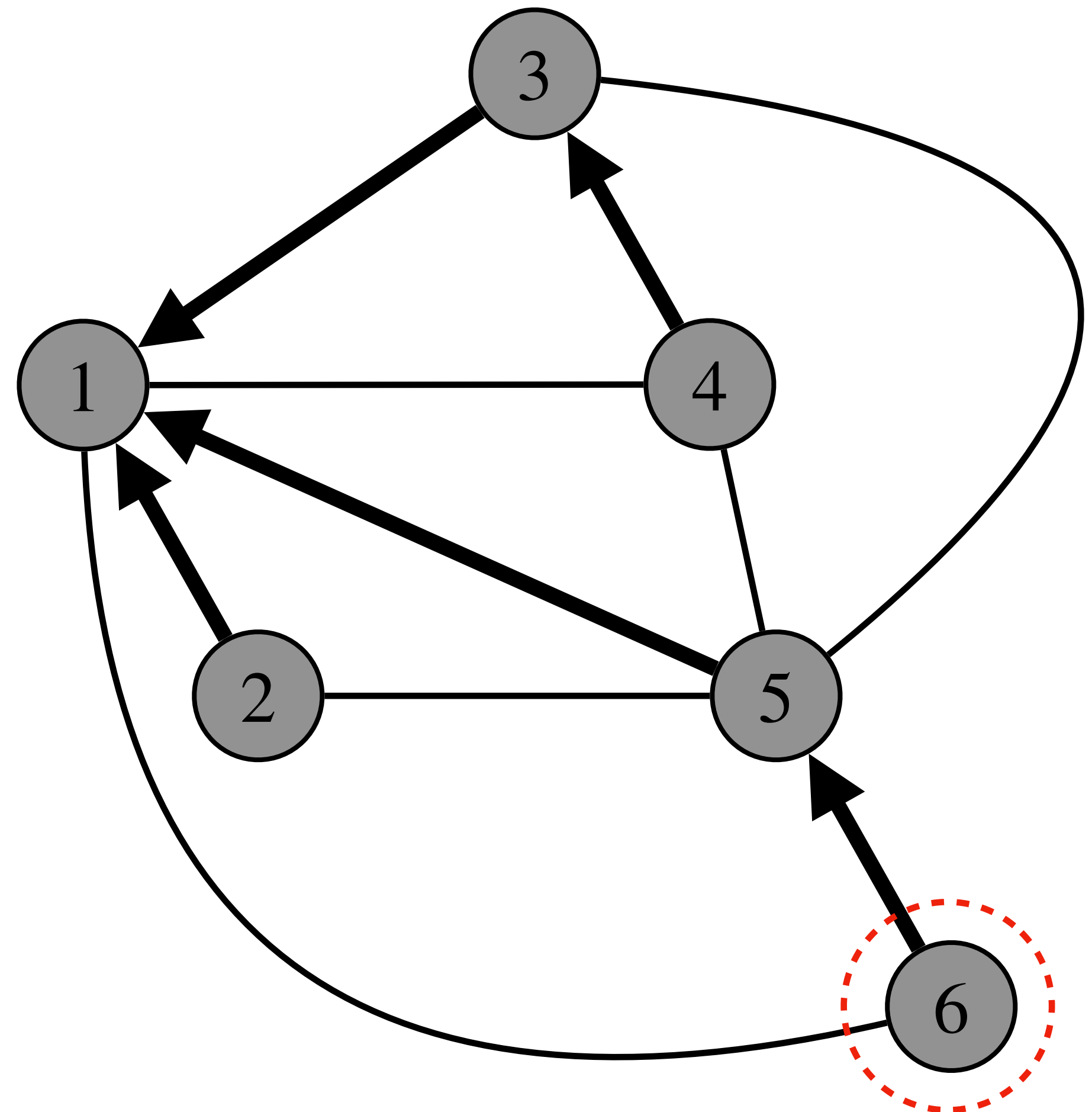
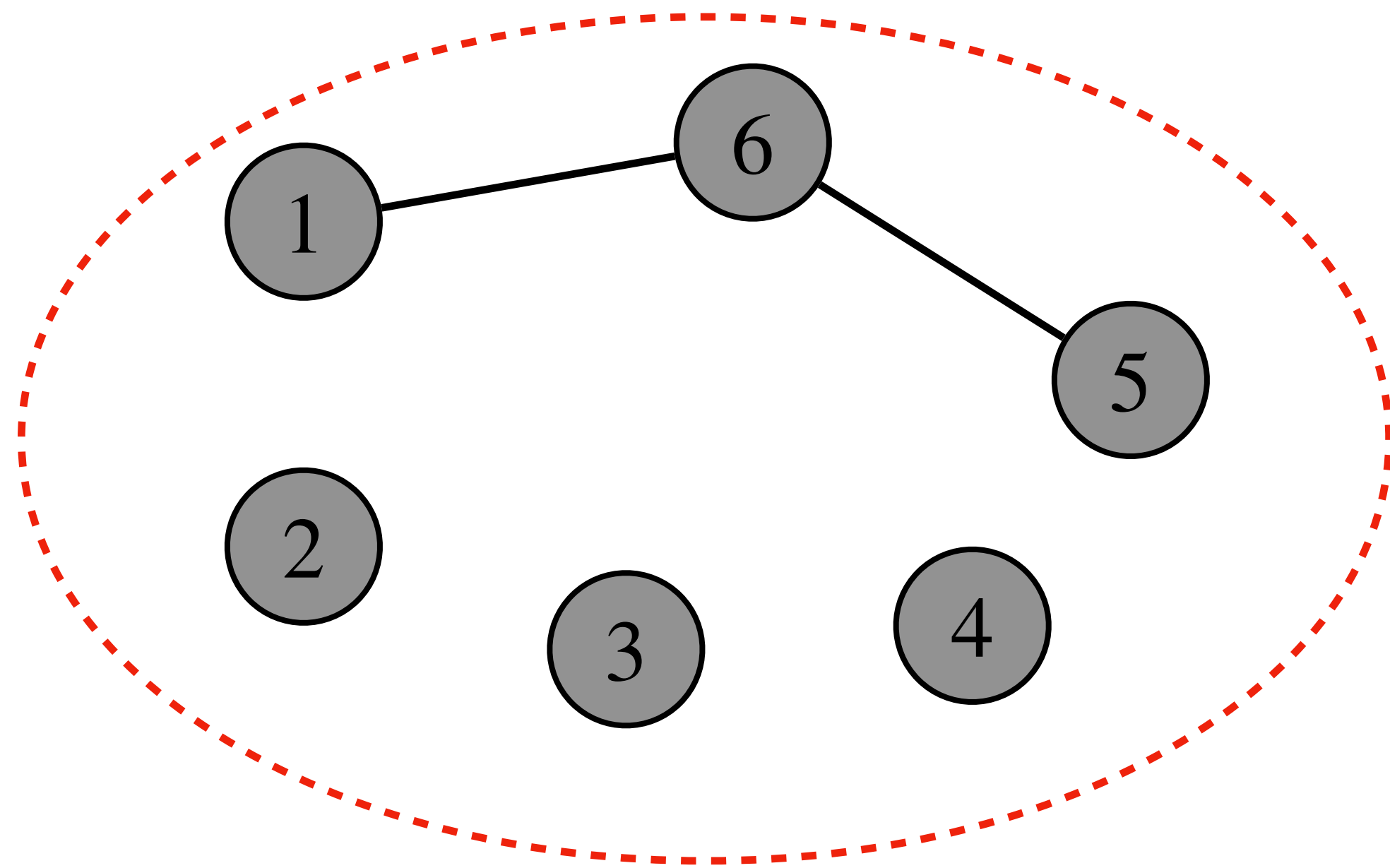
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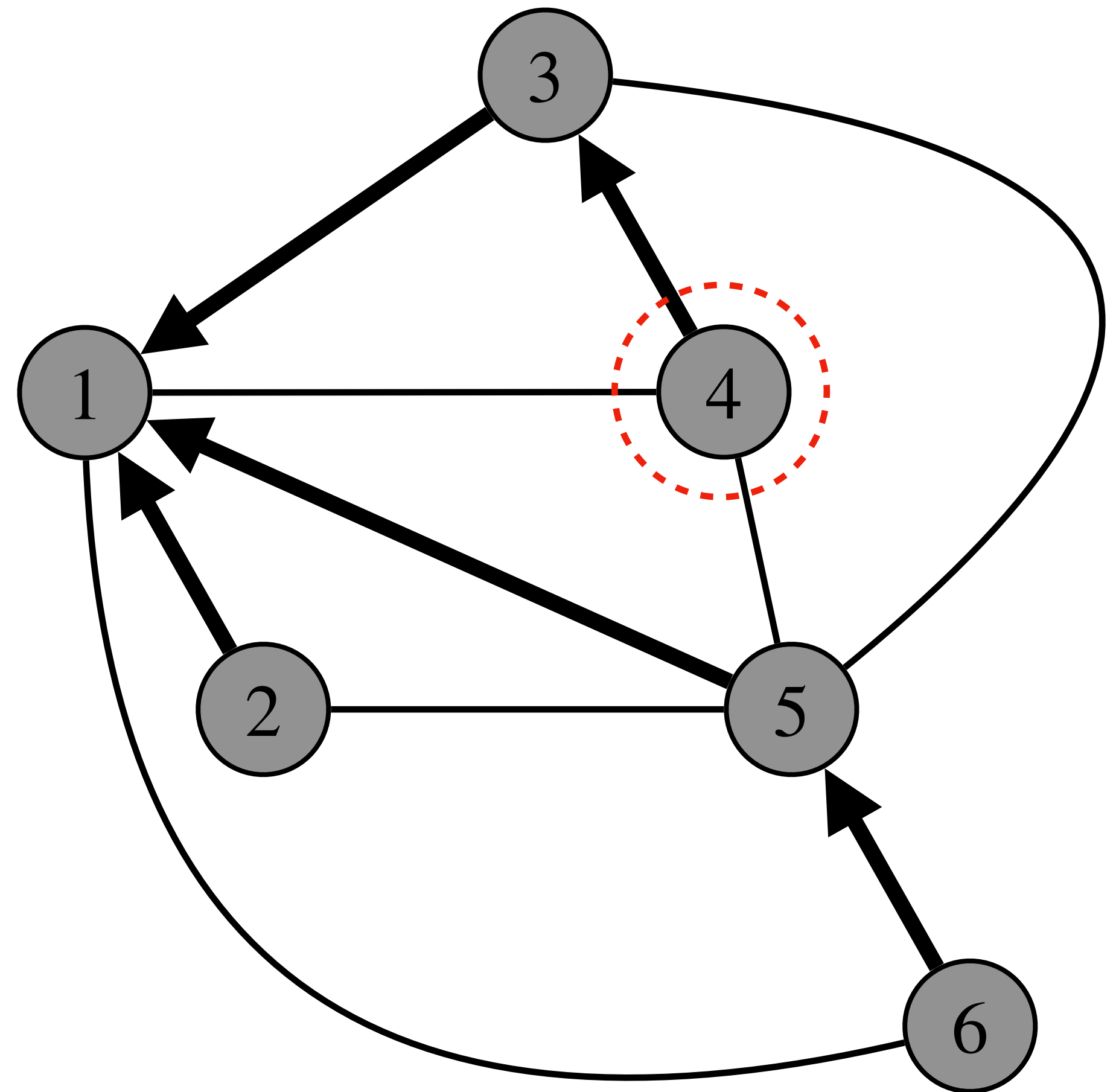
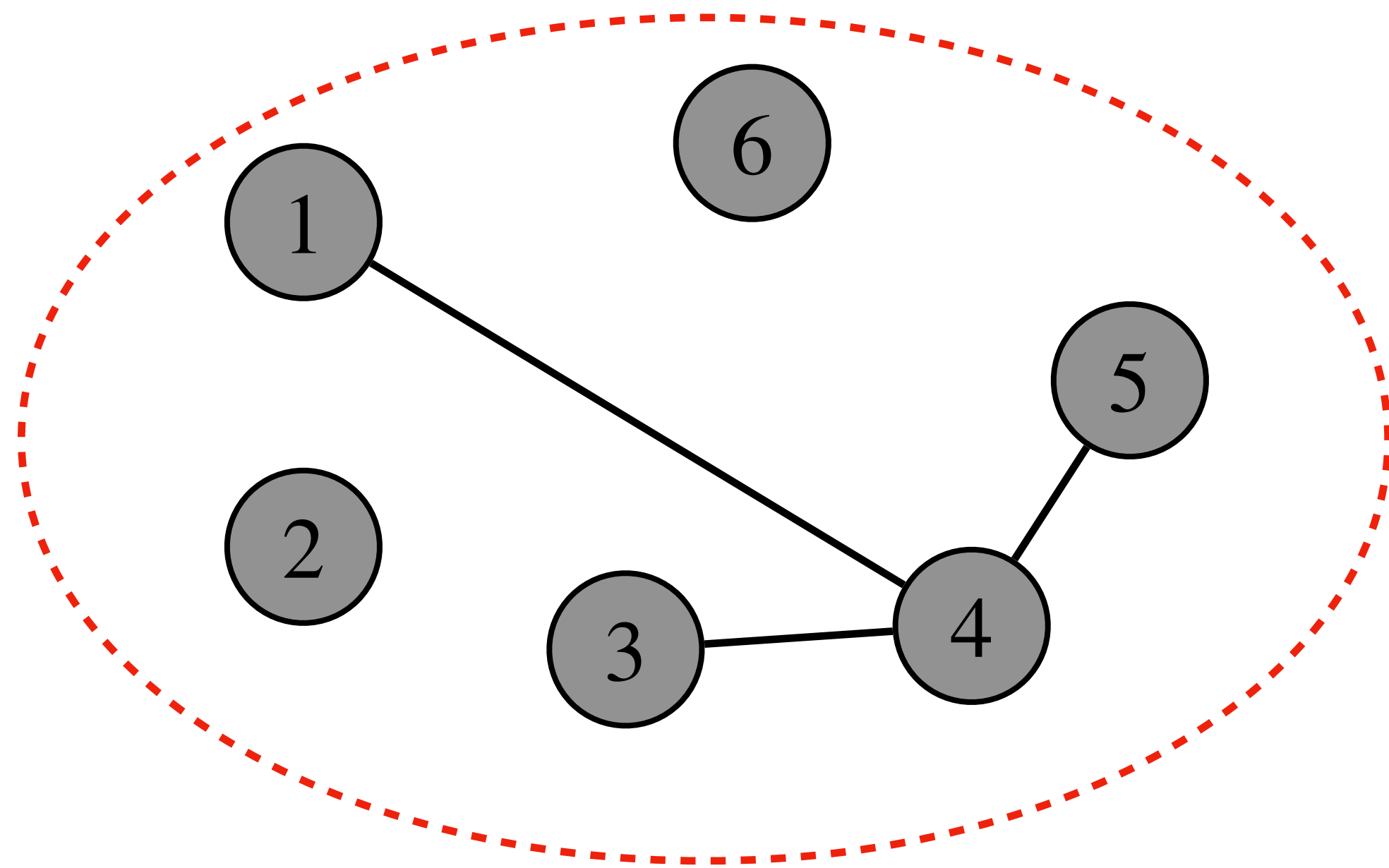
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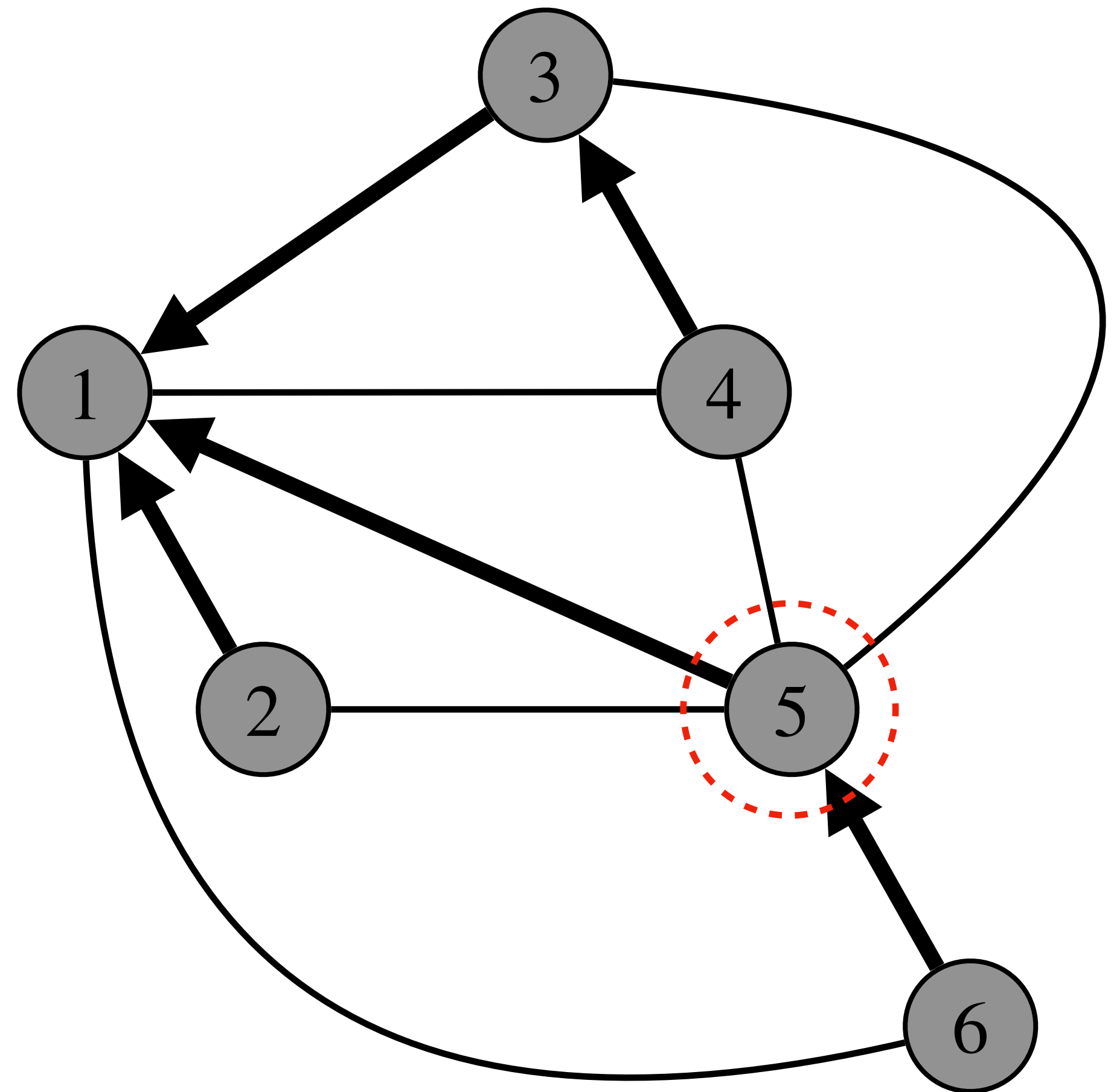
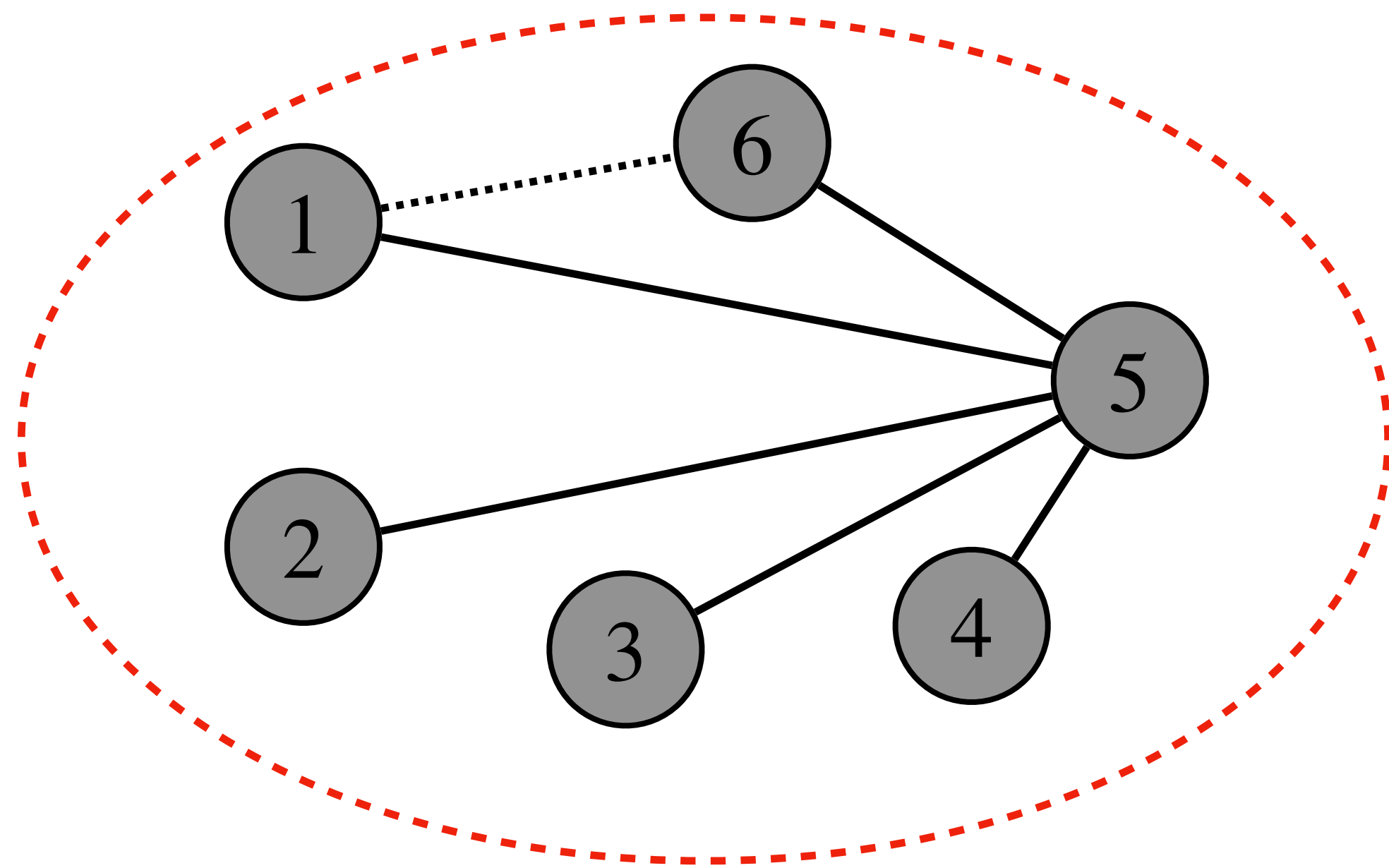
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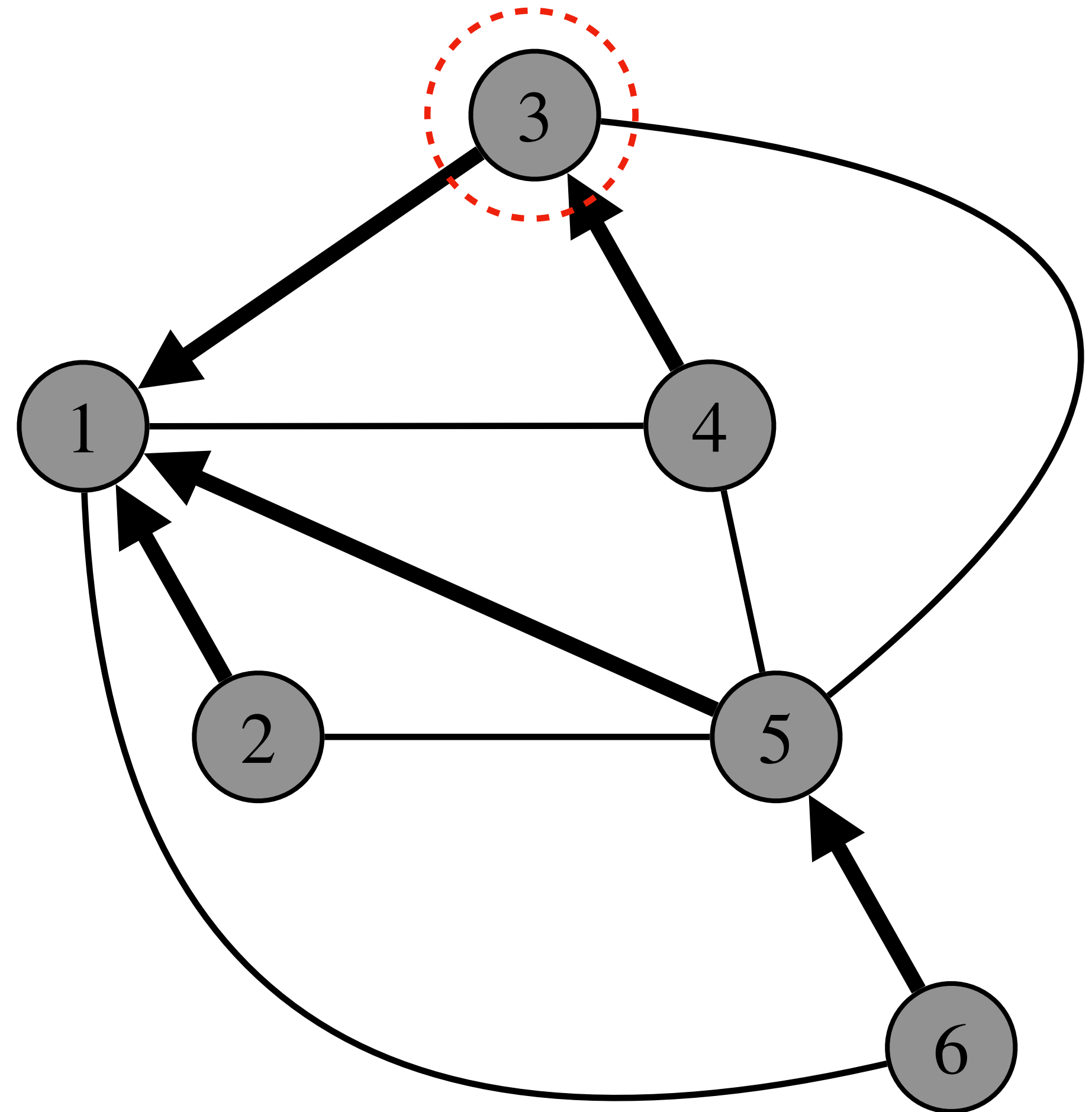
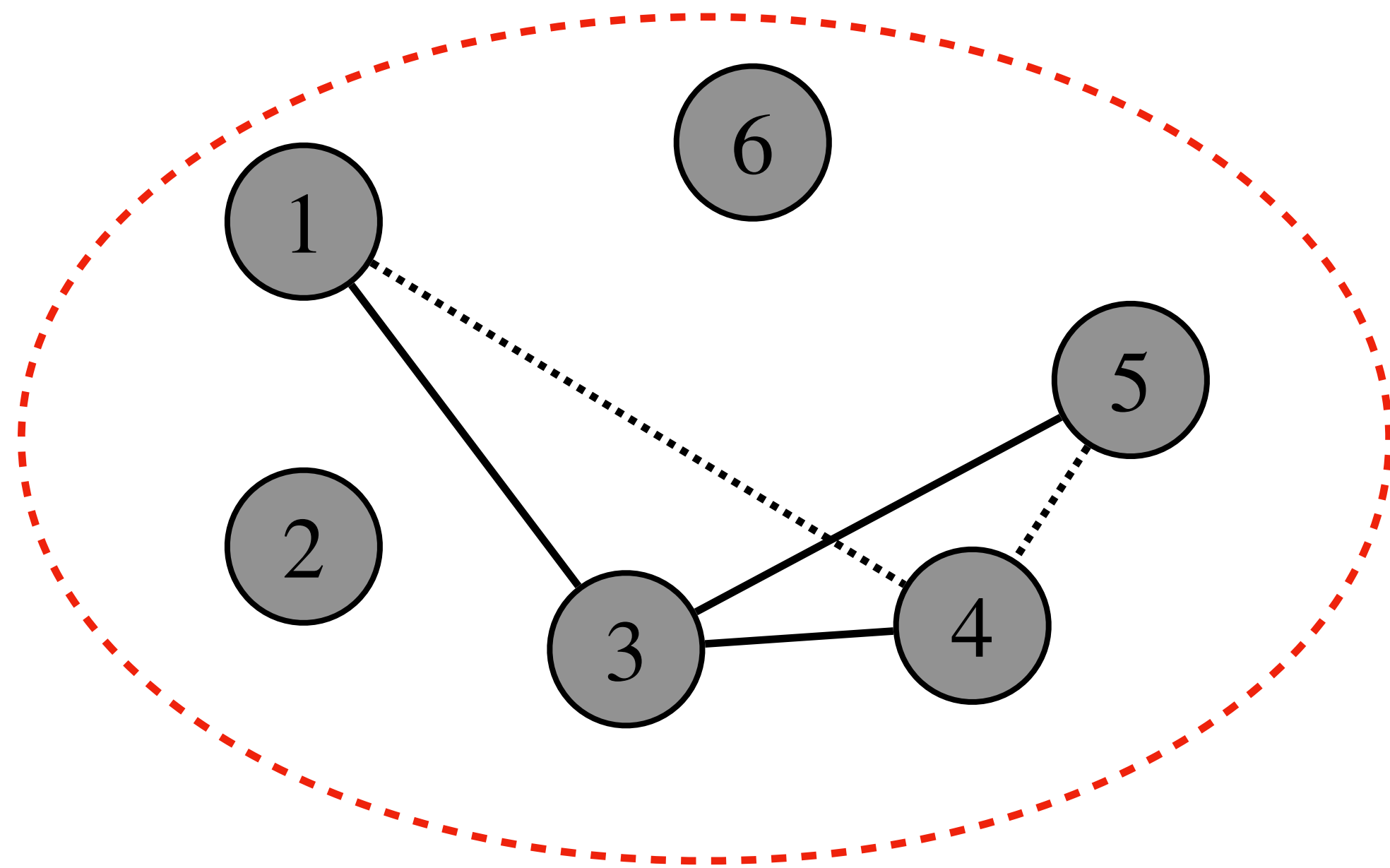
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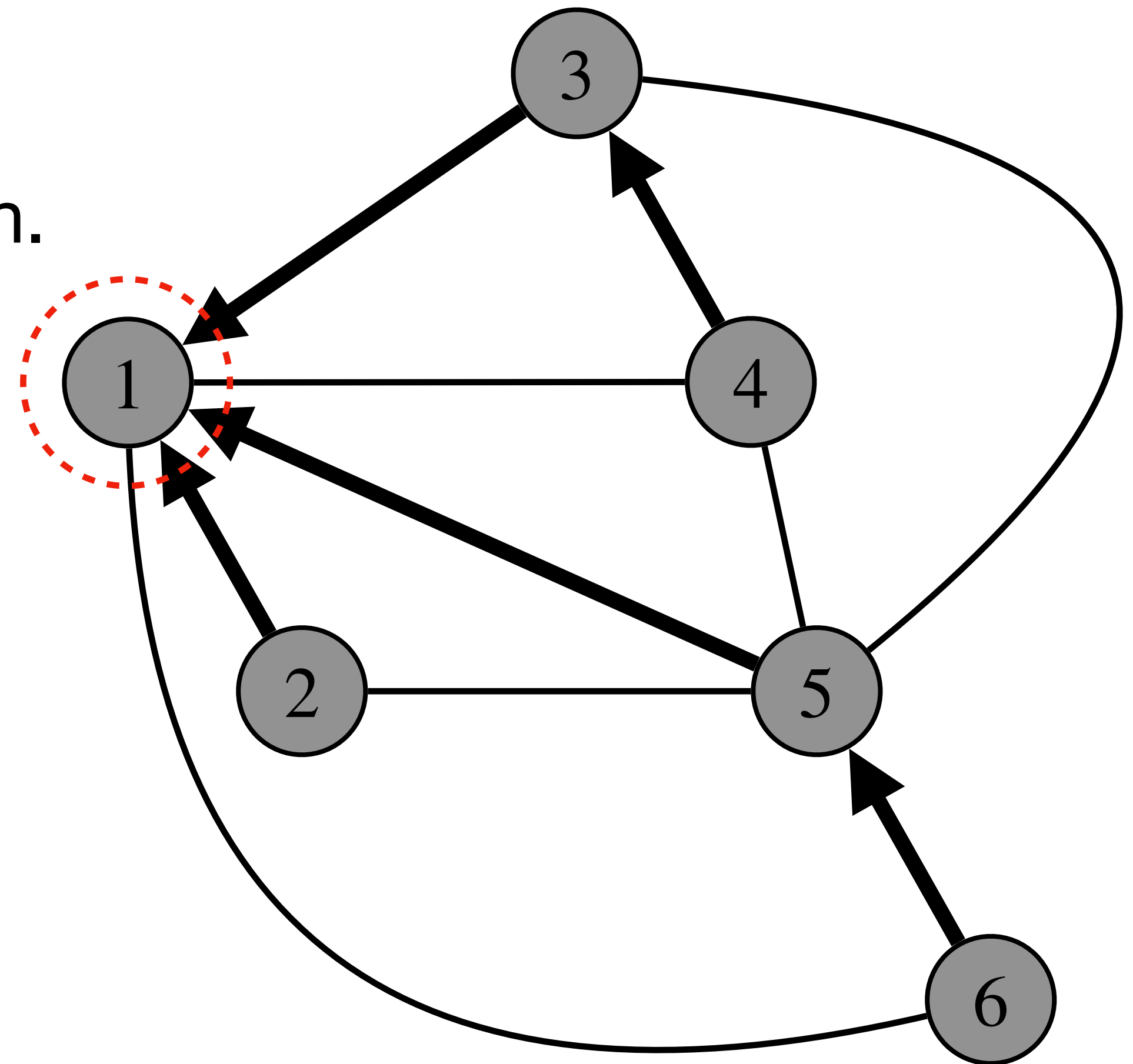
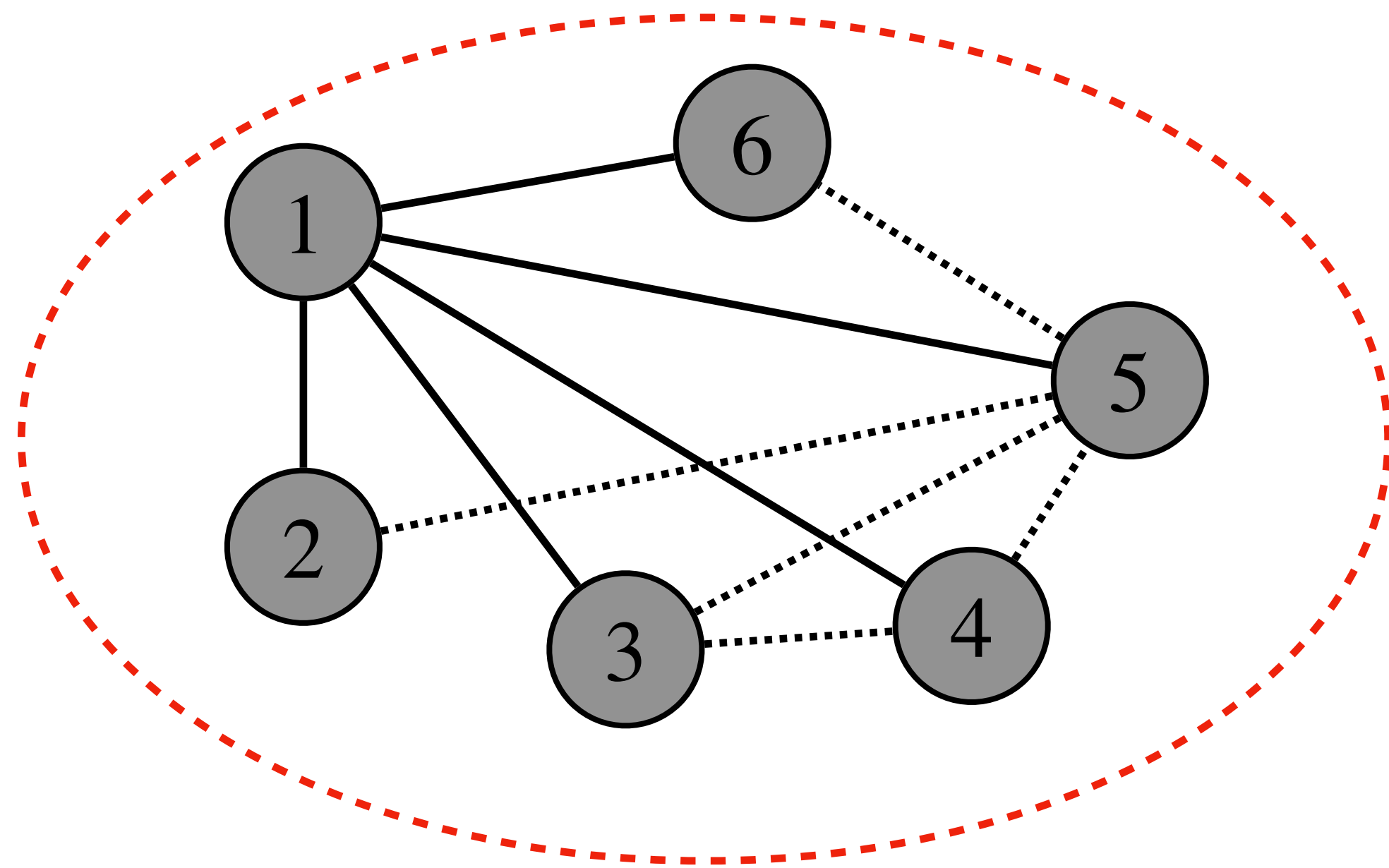
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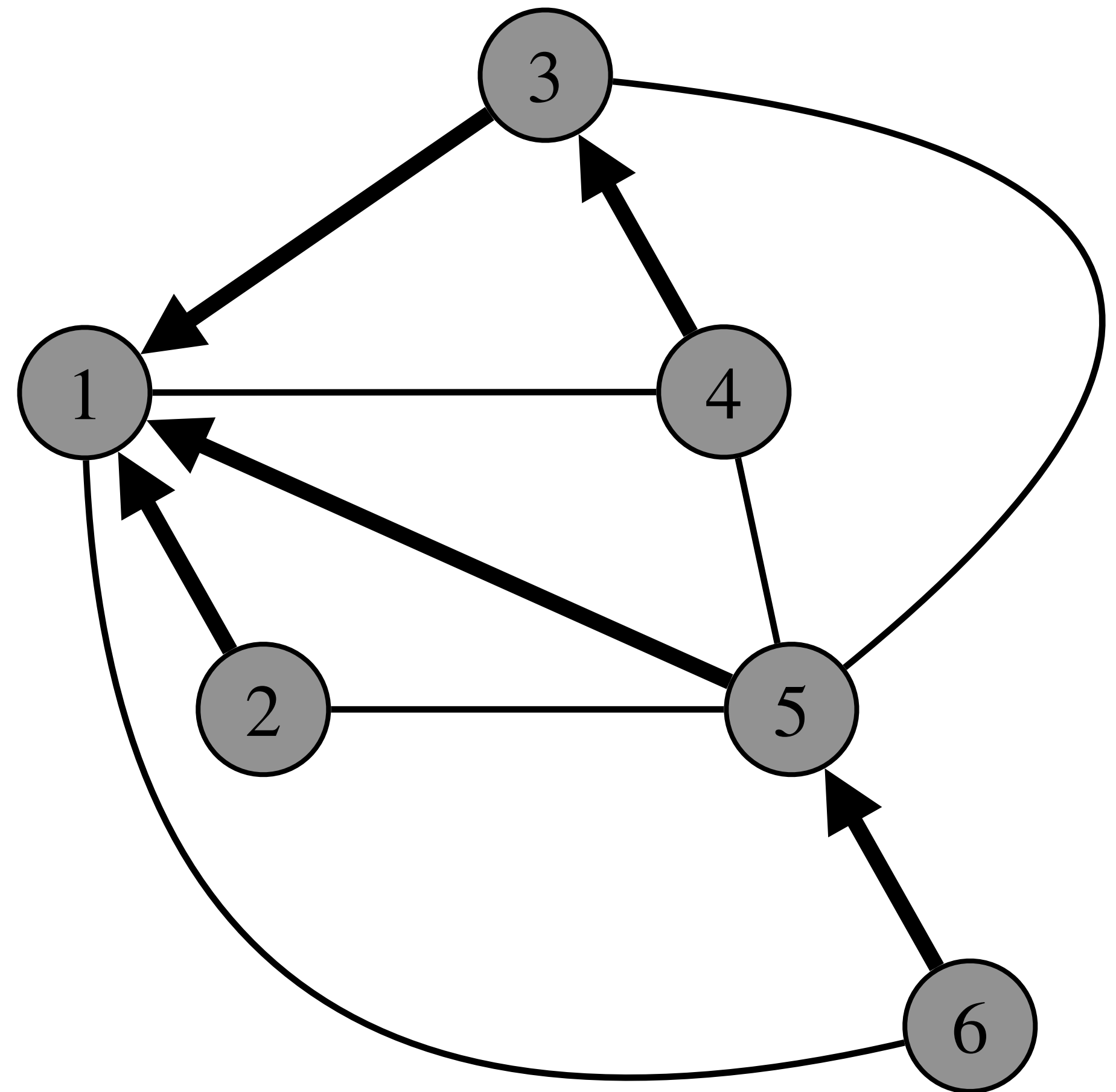
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- Under what conditions can we hope for message lower bounds?

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- Restrict to algorithms that use few rounds (maybe $\text{poly}(n)$ or $\log n$ rounds)
 - Can be achieved by communication complexity reductions.

To $\Omega(m)$ and Beyond



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- For comparison based KT-1 algorithms, $\Omega(m)$ message lower bound for:
 - $(\Delta + 1)$ -coloring.
 - Maximal Independent Set.

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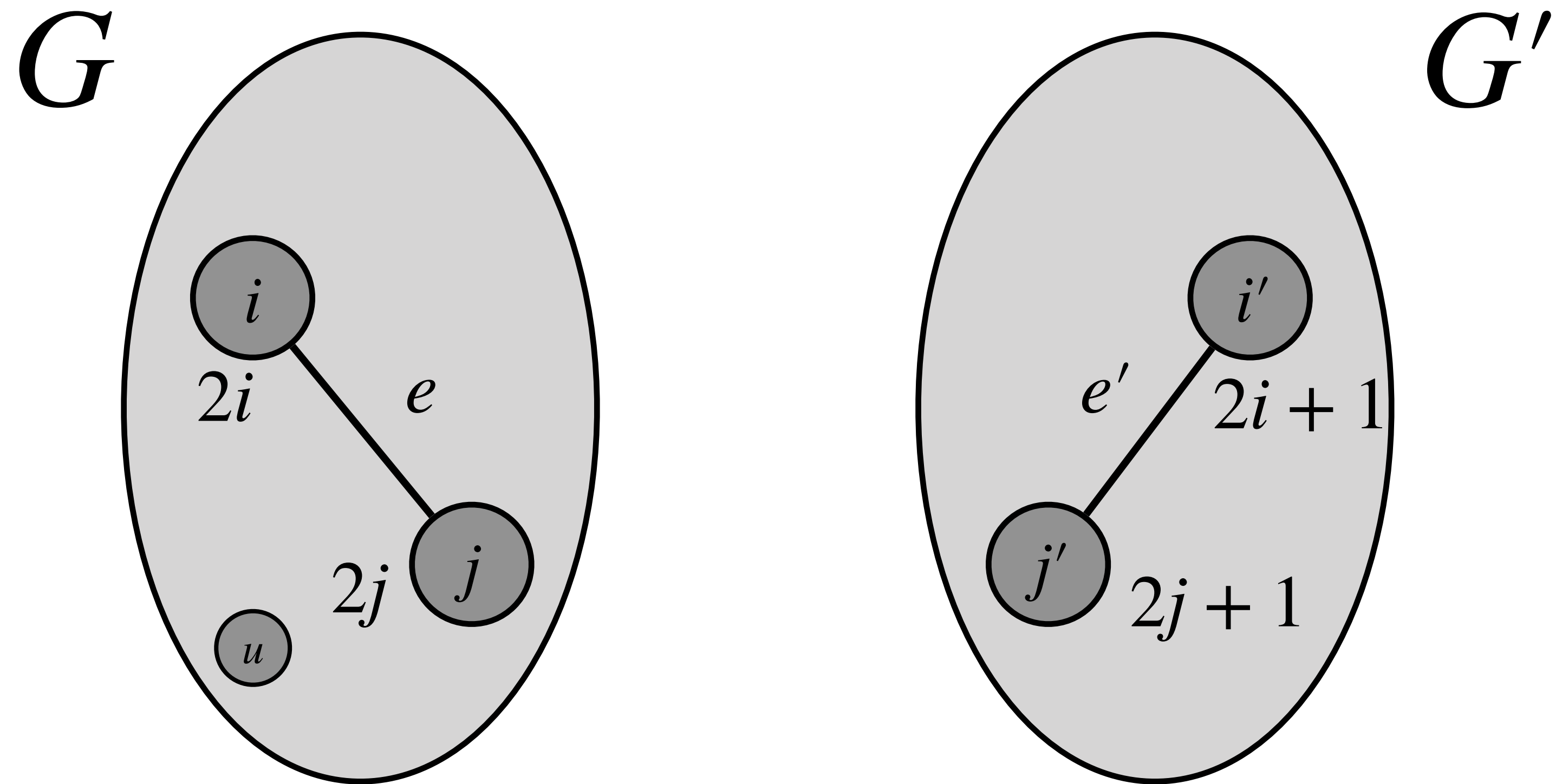
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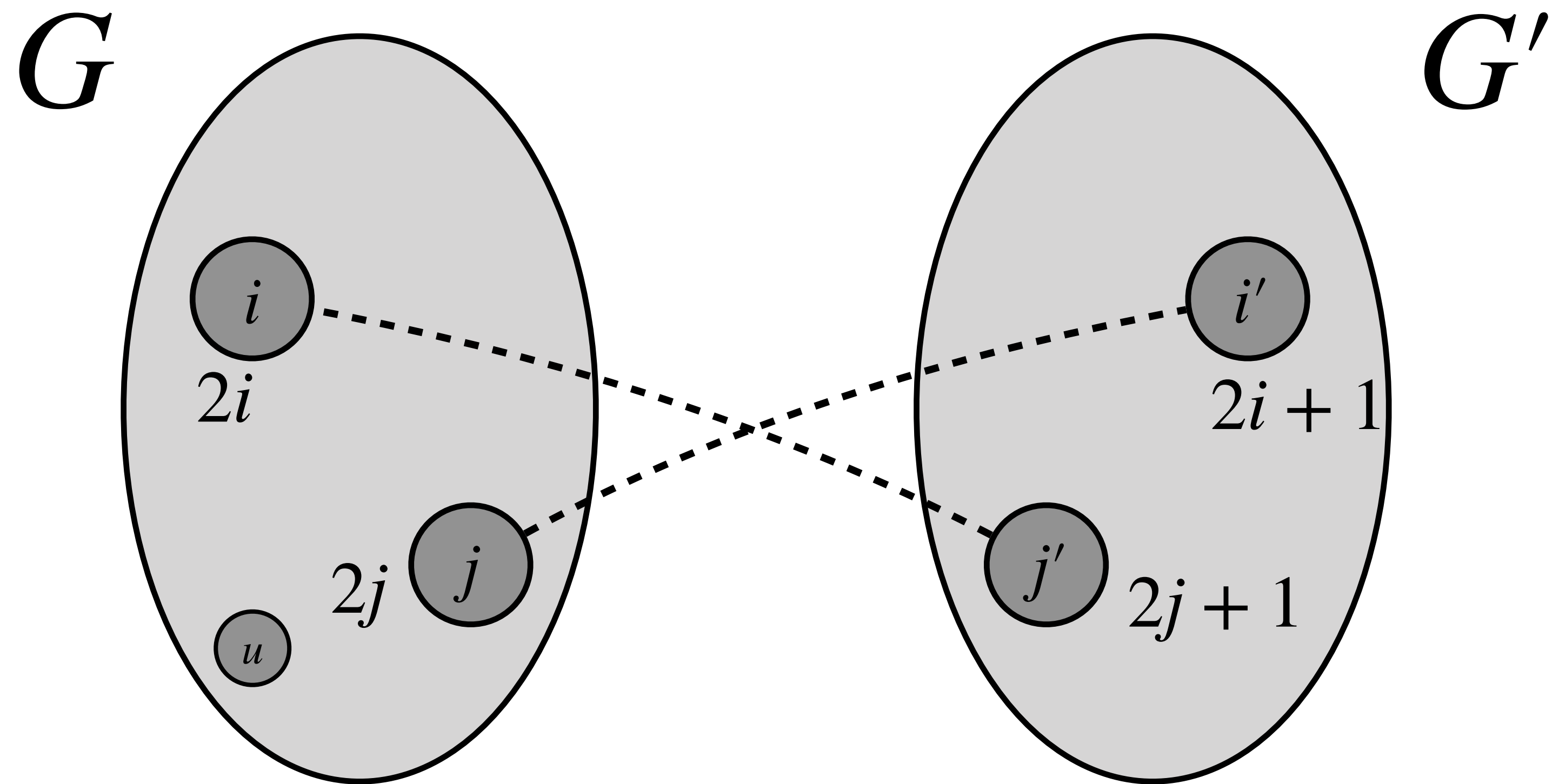
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Comparison Based Broadcast

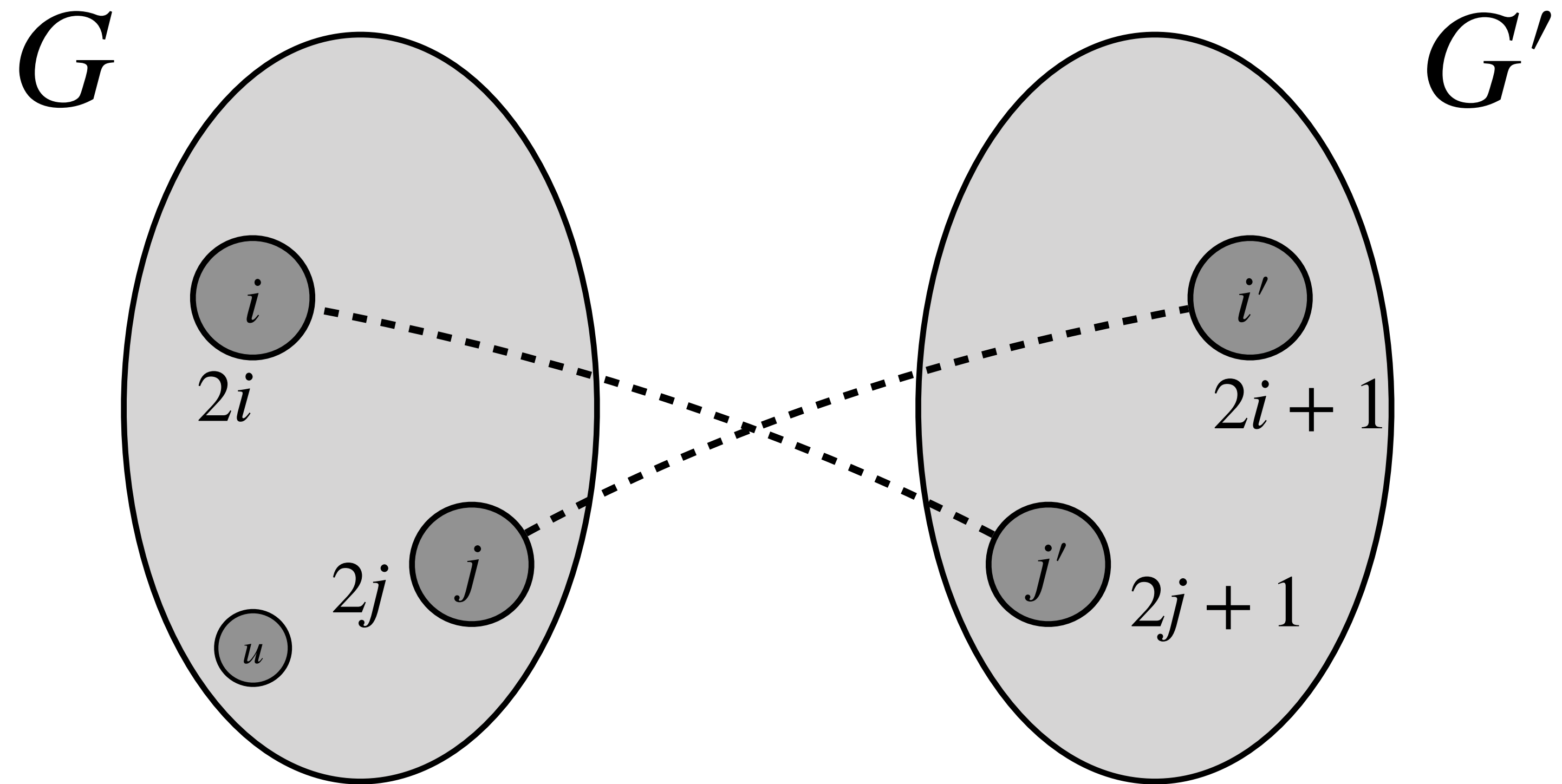


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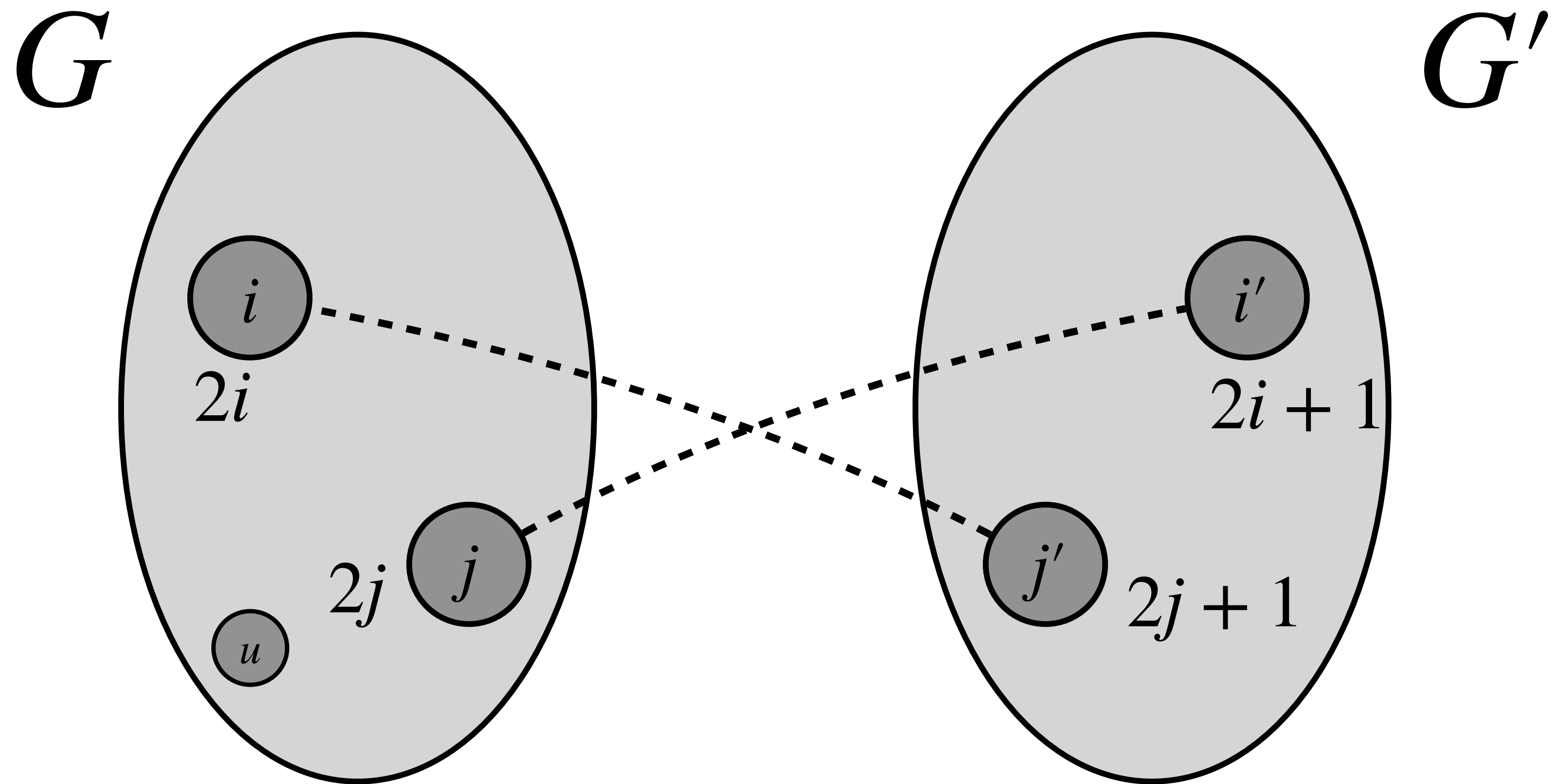
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- Initial knowledge is different!



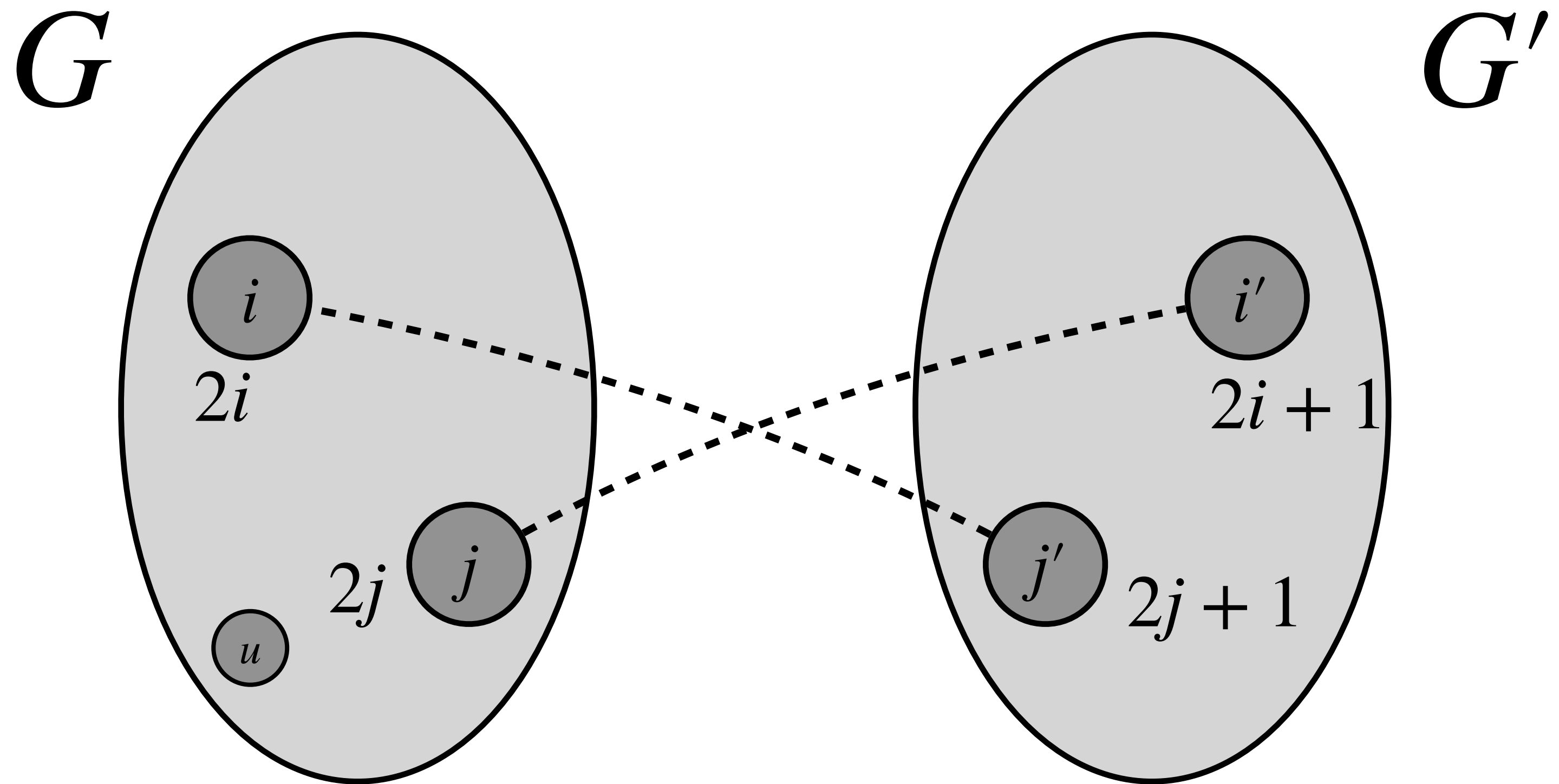
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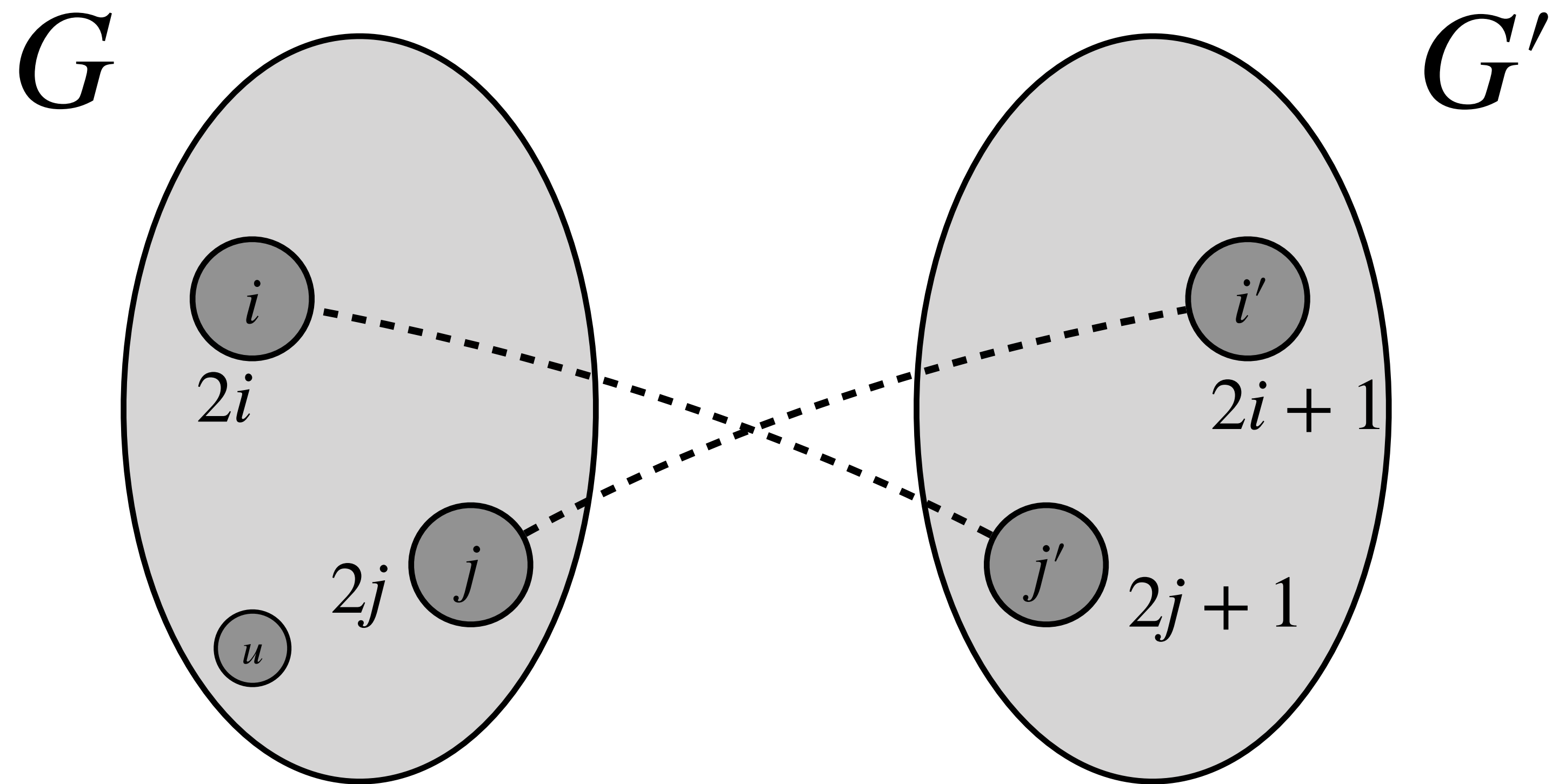
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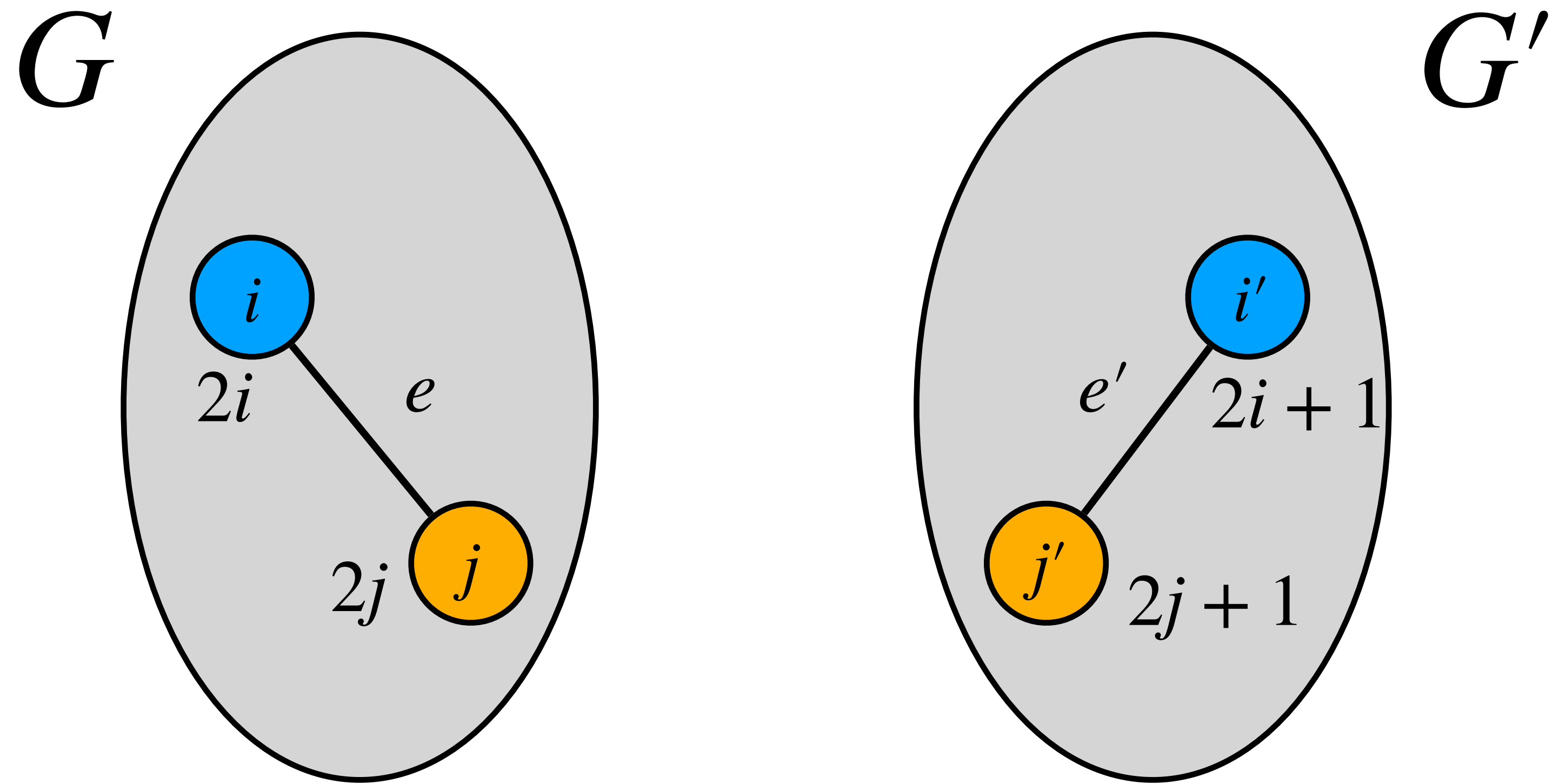


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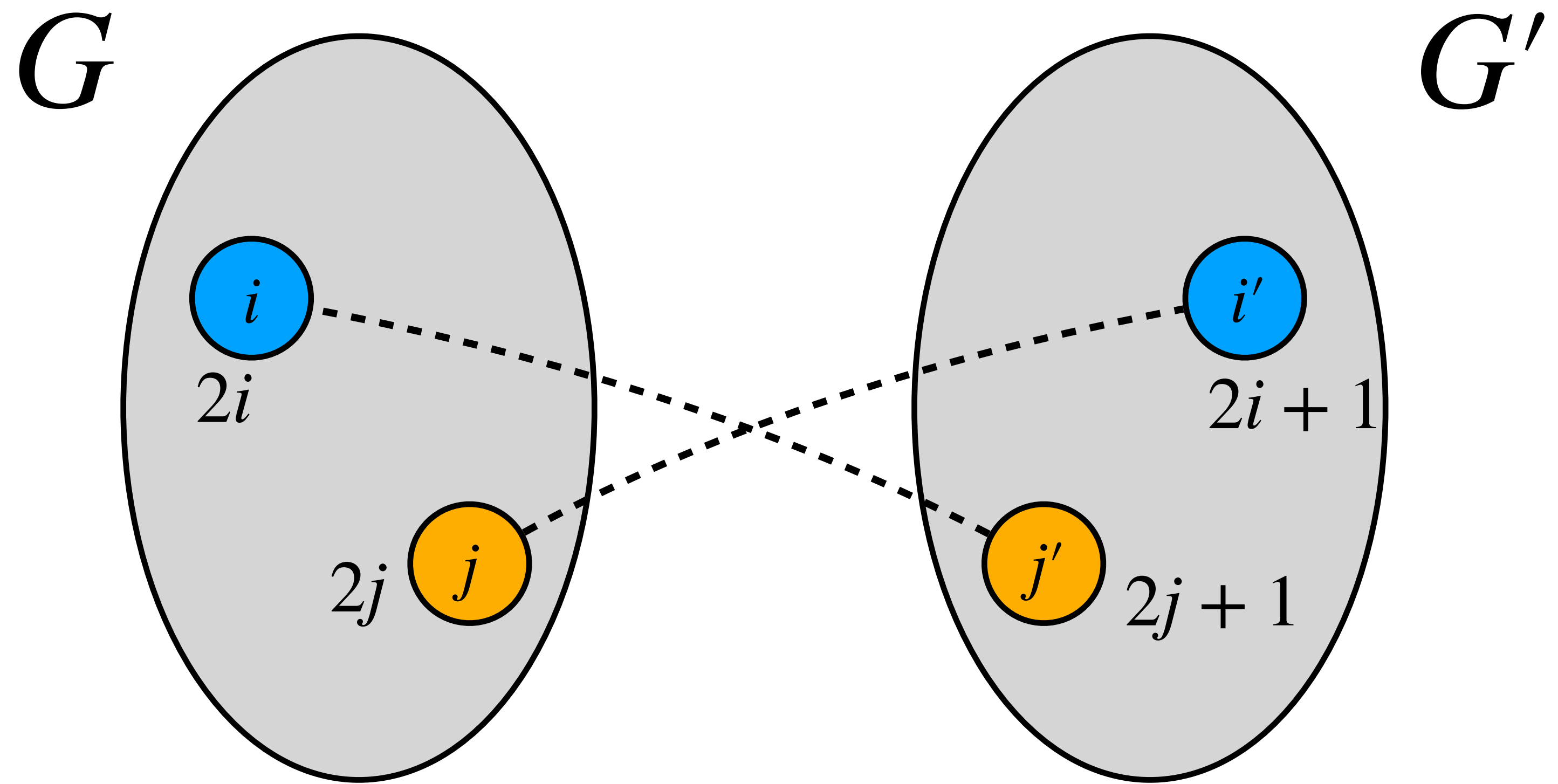
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- So we can get an $\Omega(m)$ message lower bound.



Extending to Coloring

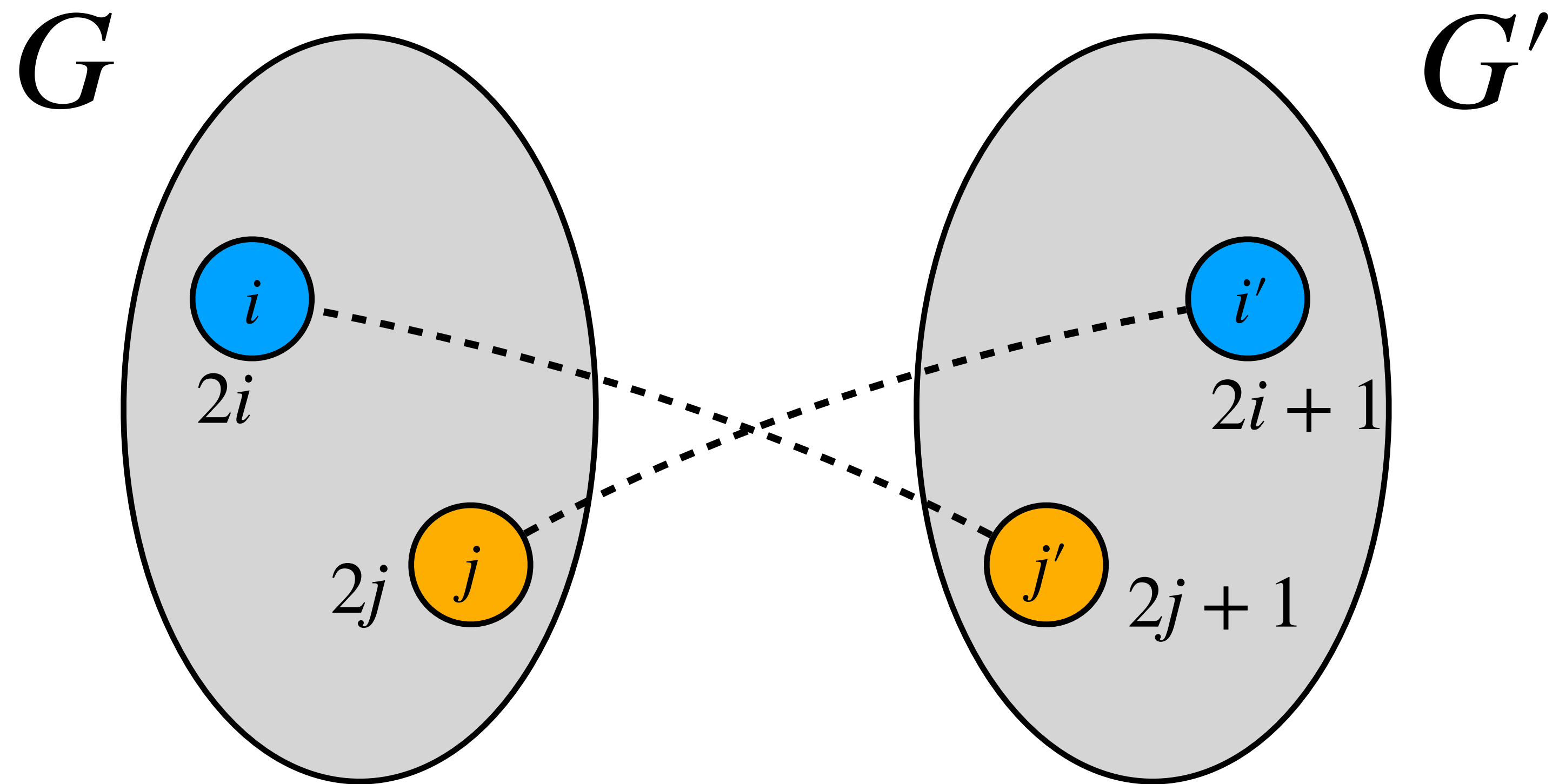


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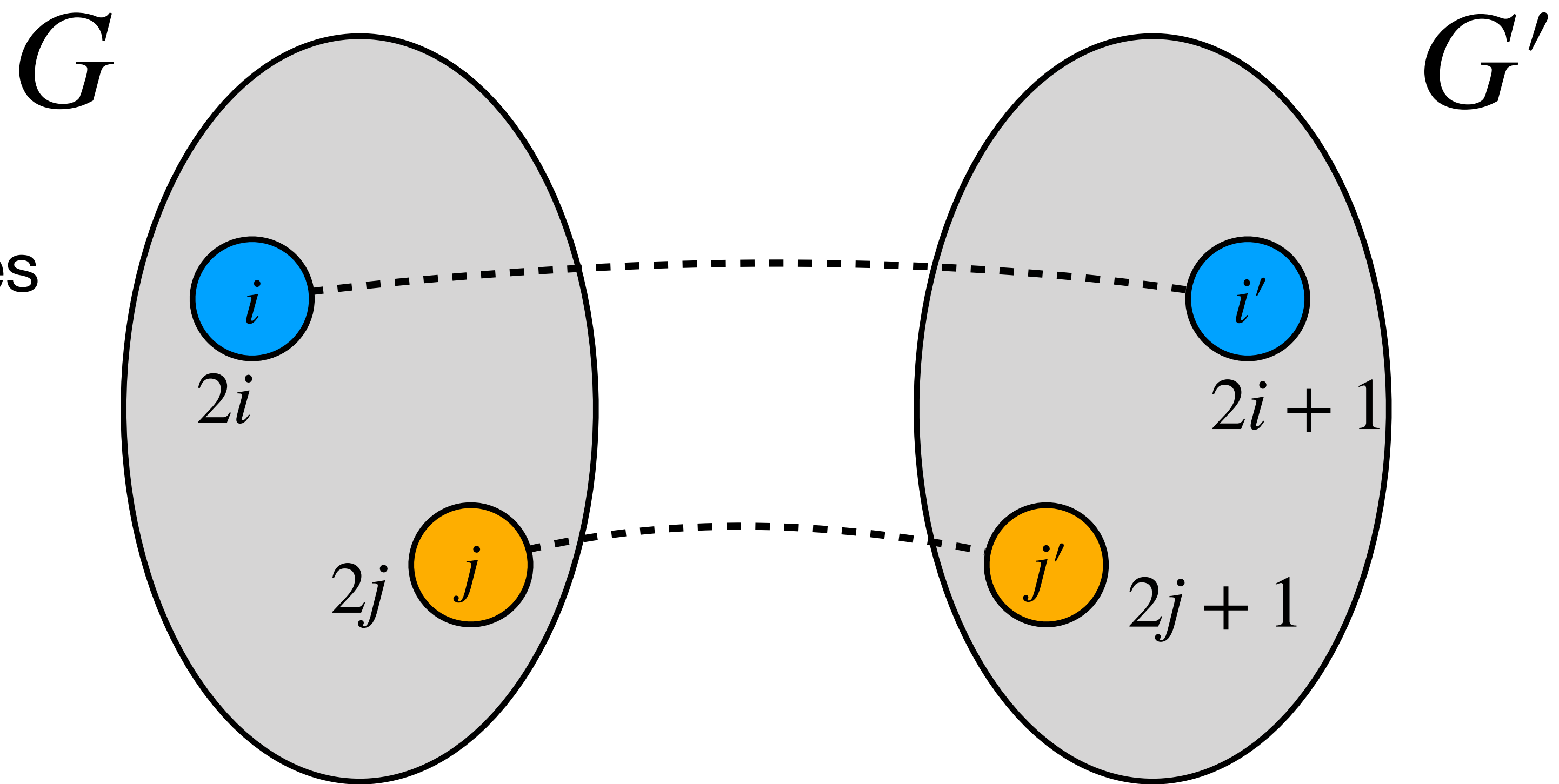
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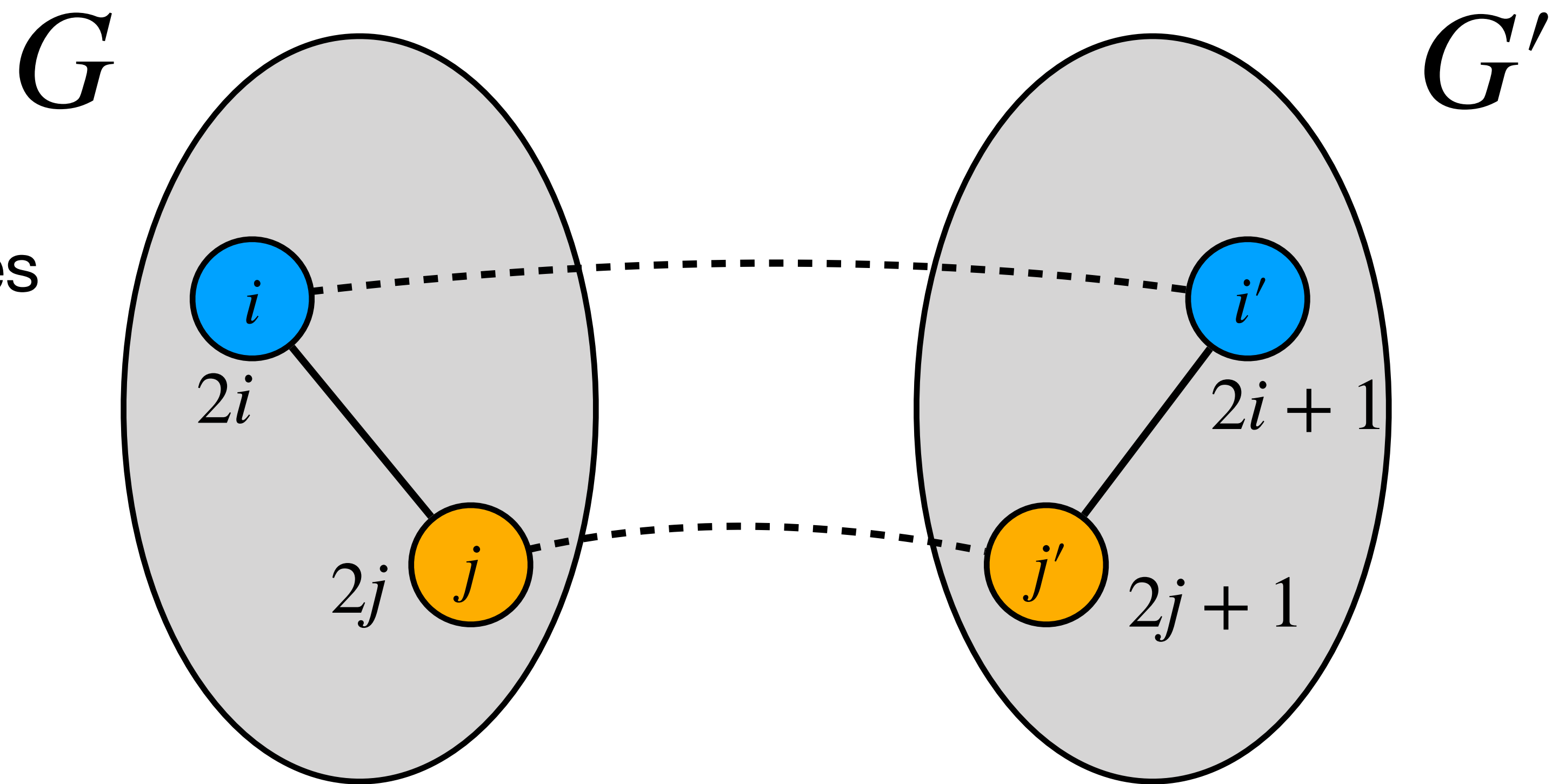
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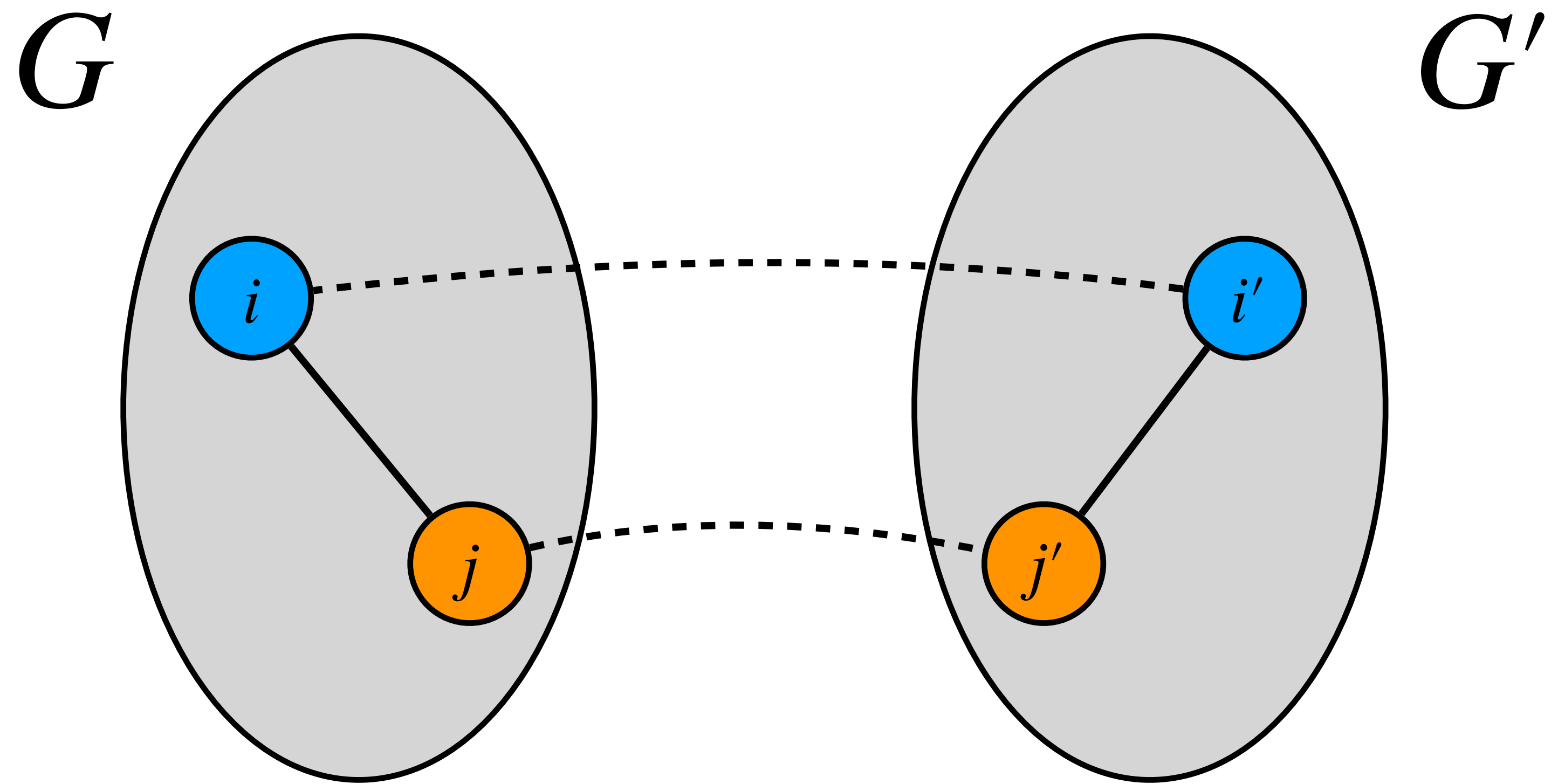


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- But $2i + 1$ can be way out of order compared to $2j...$

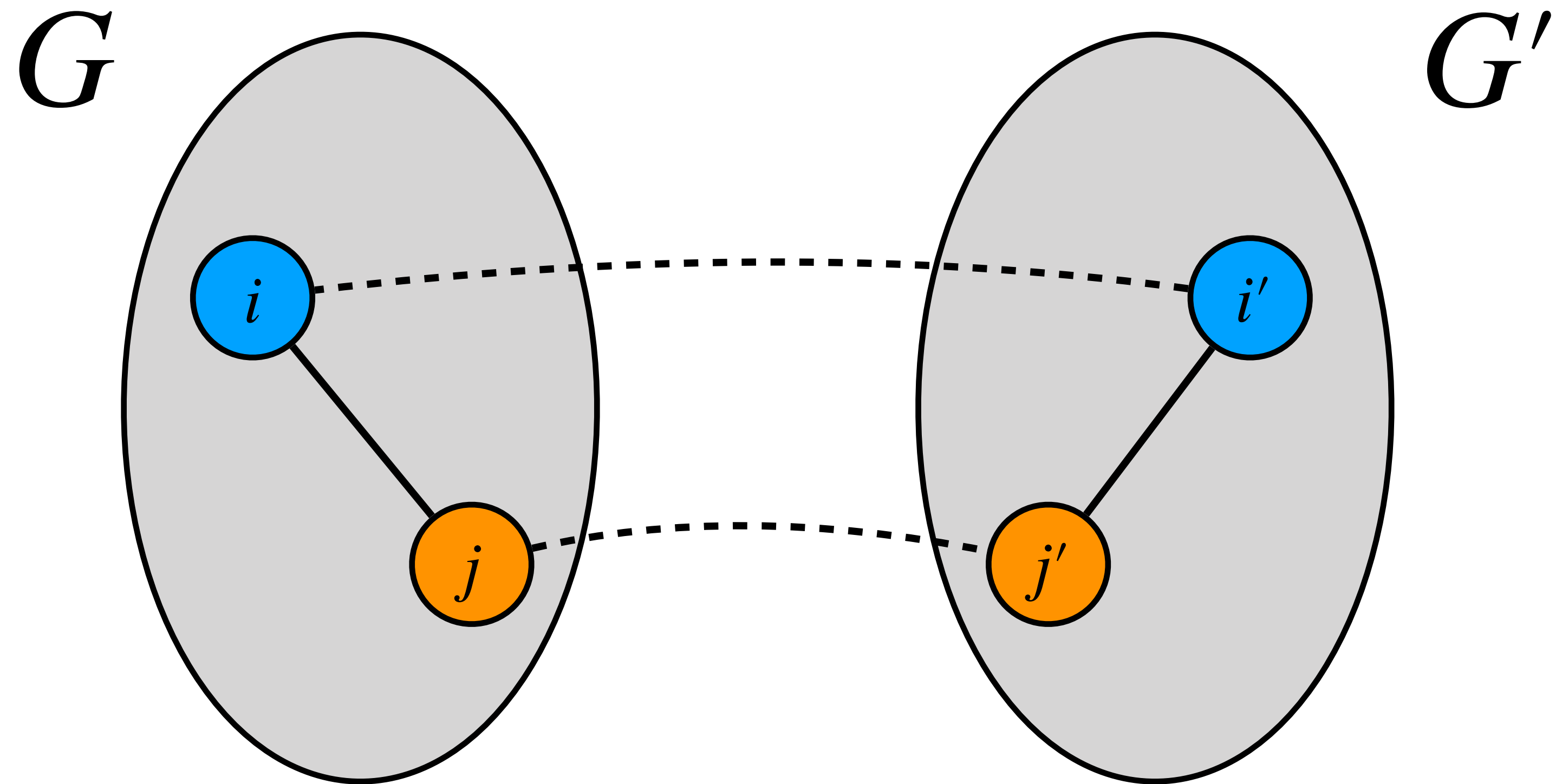


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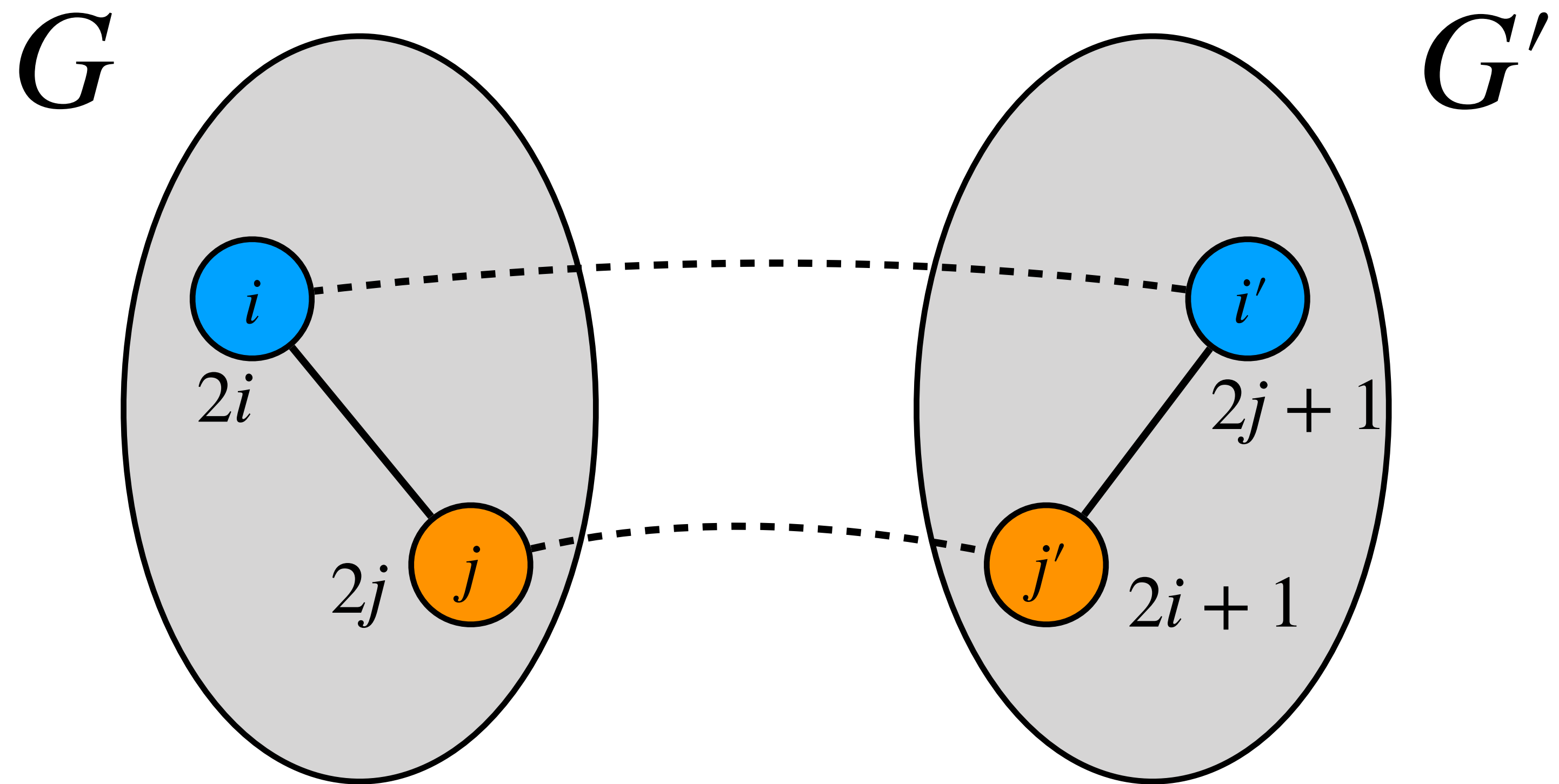
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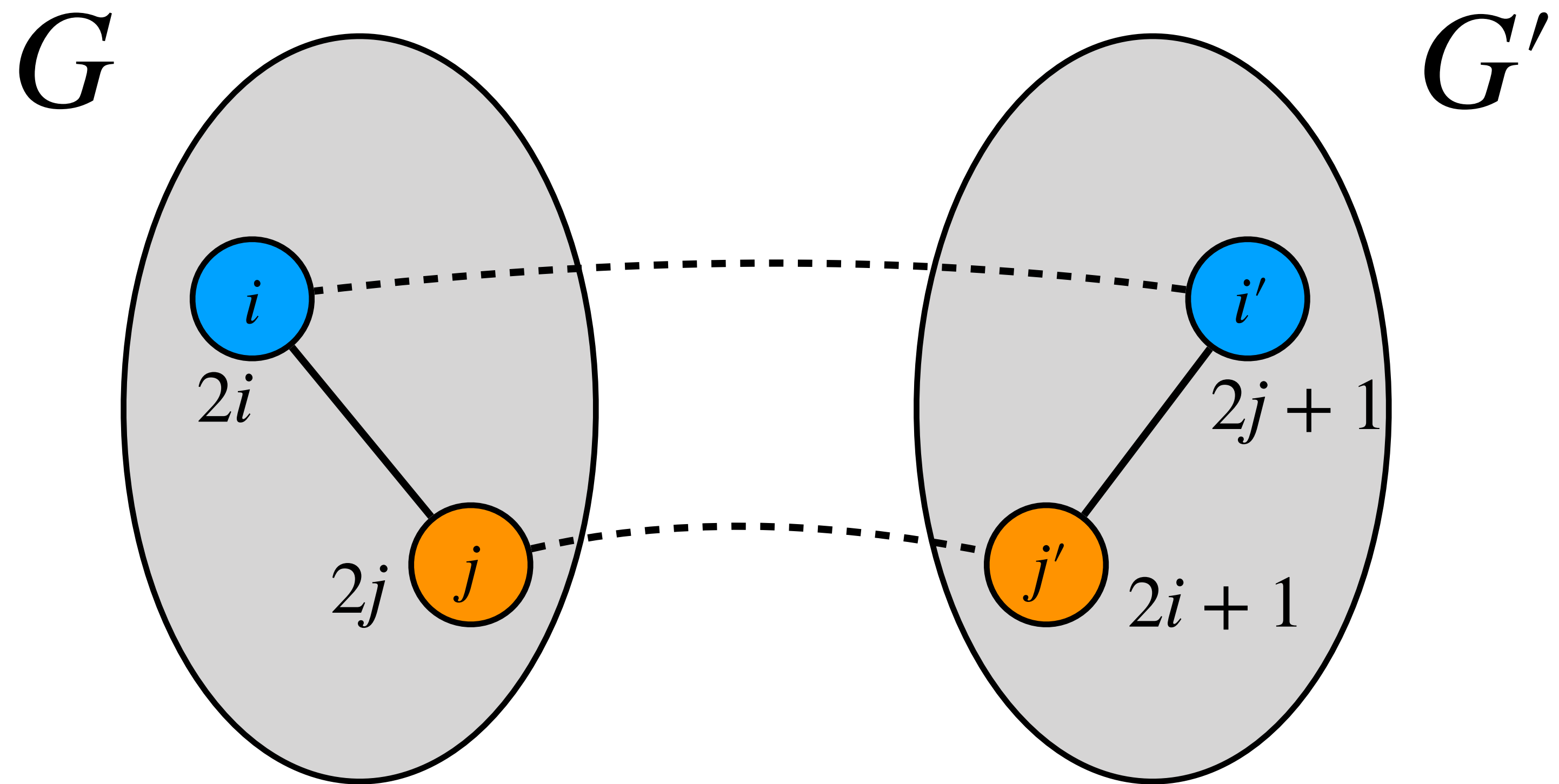
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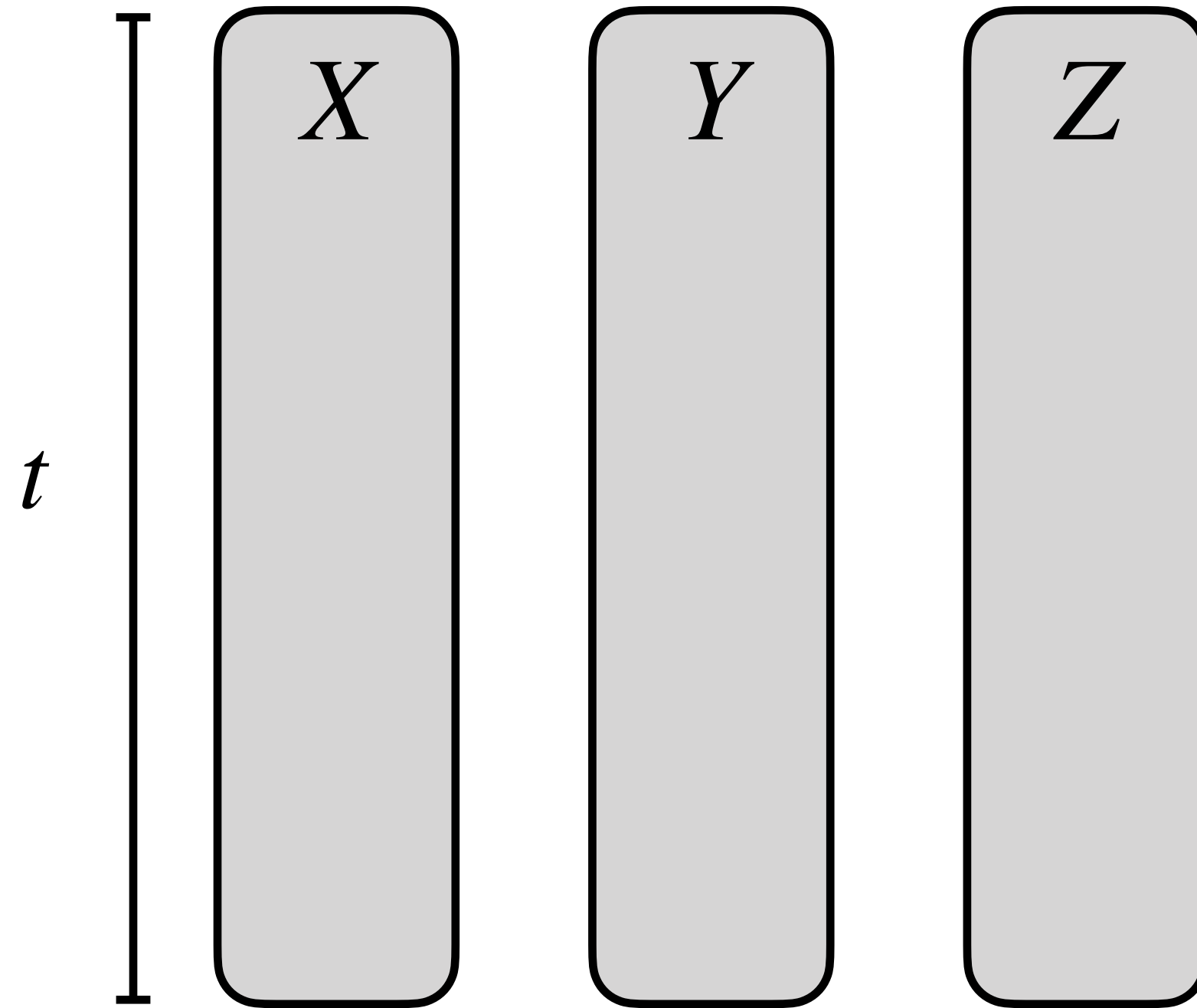
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- Is it always possible?

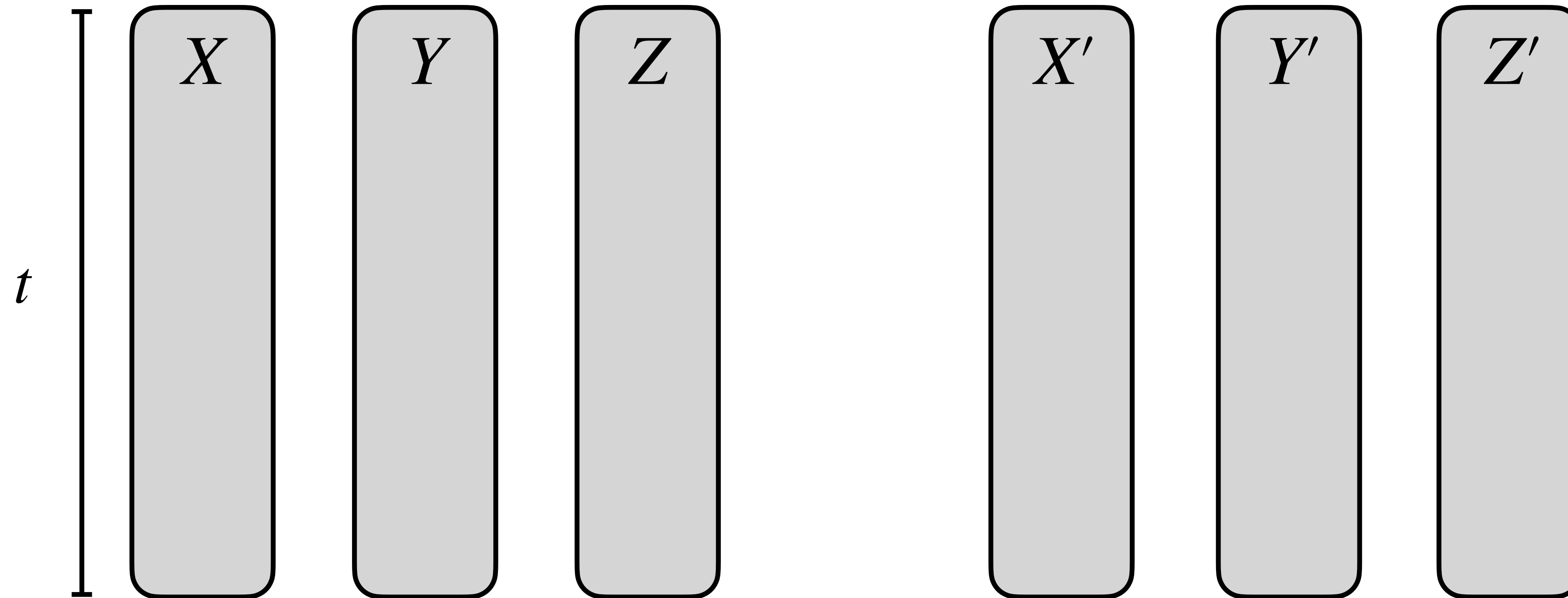


ID Assignments

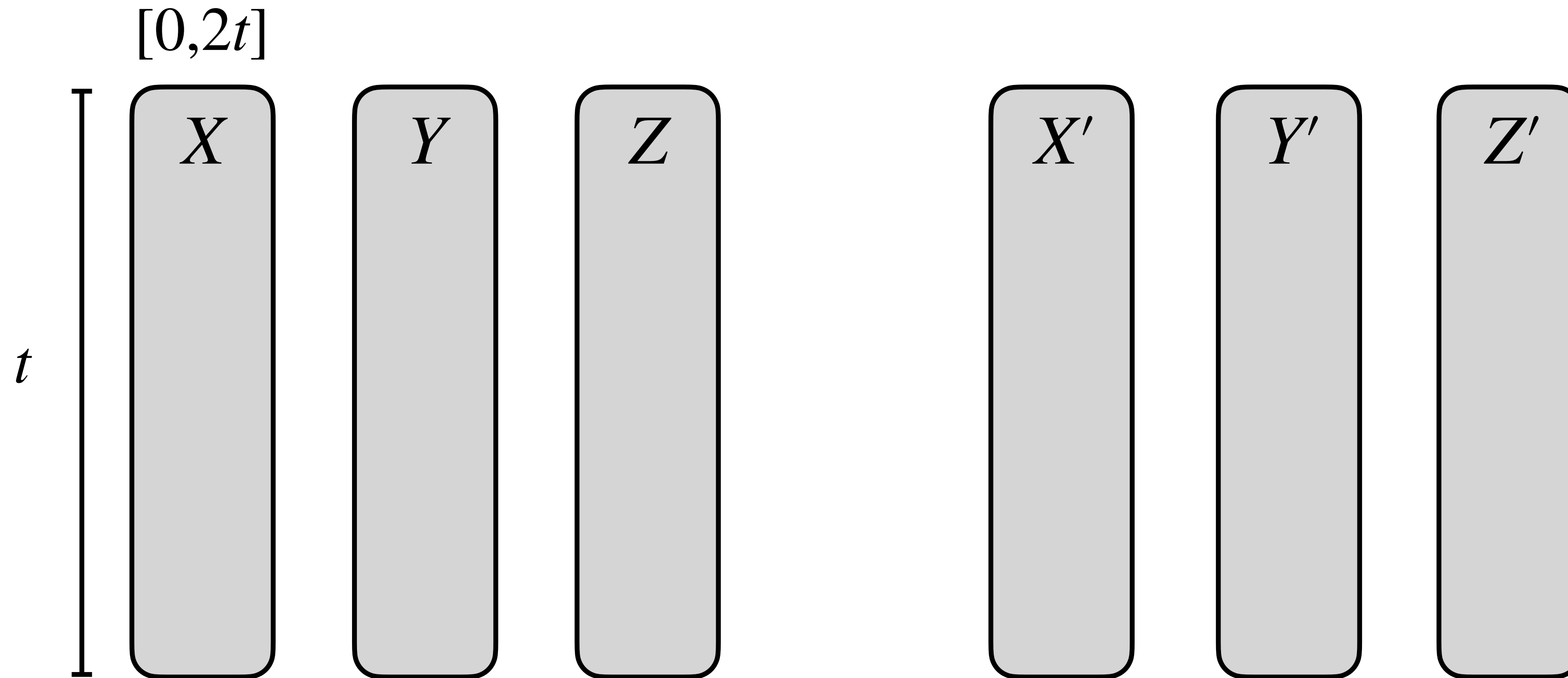
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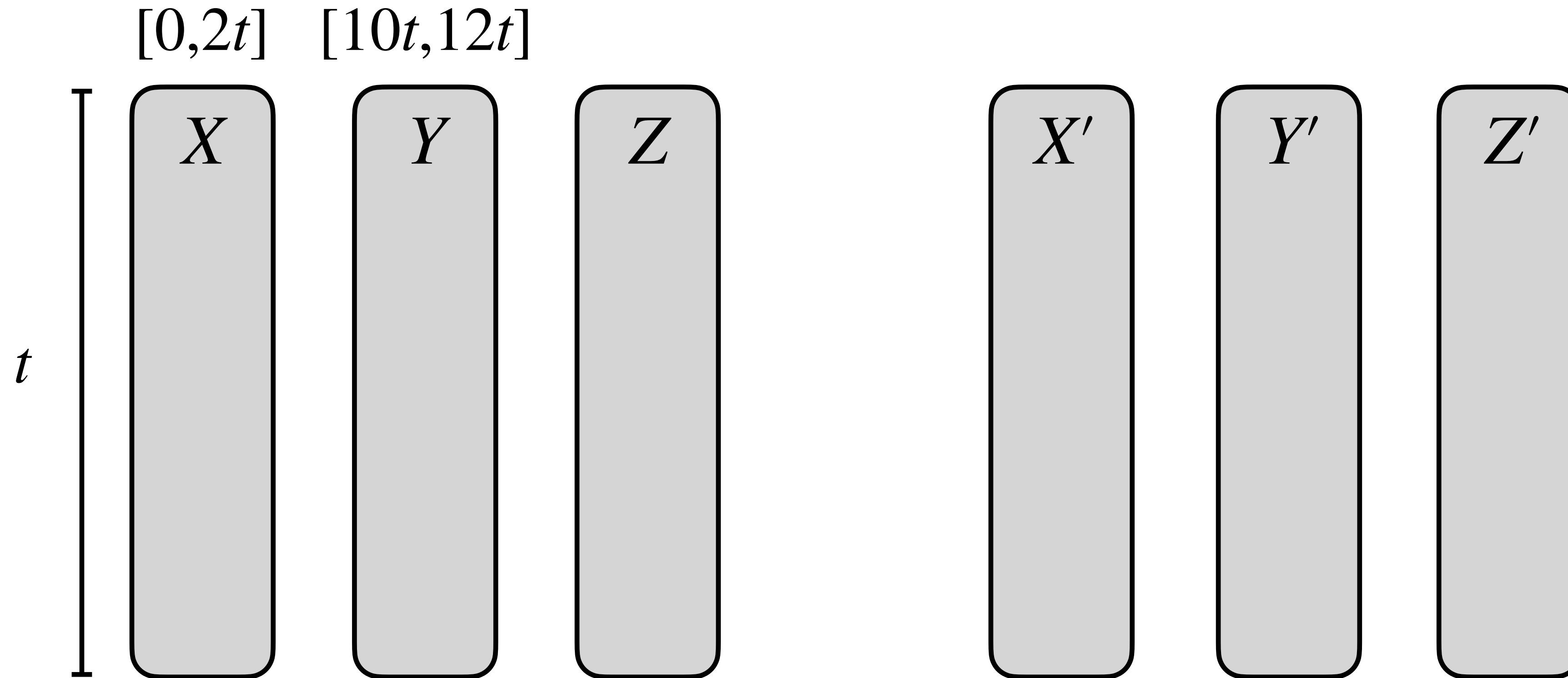
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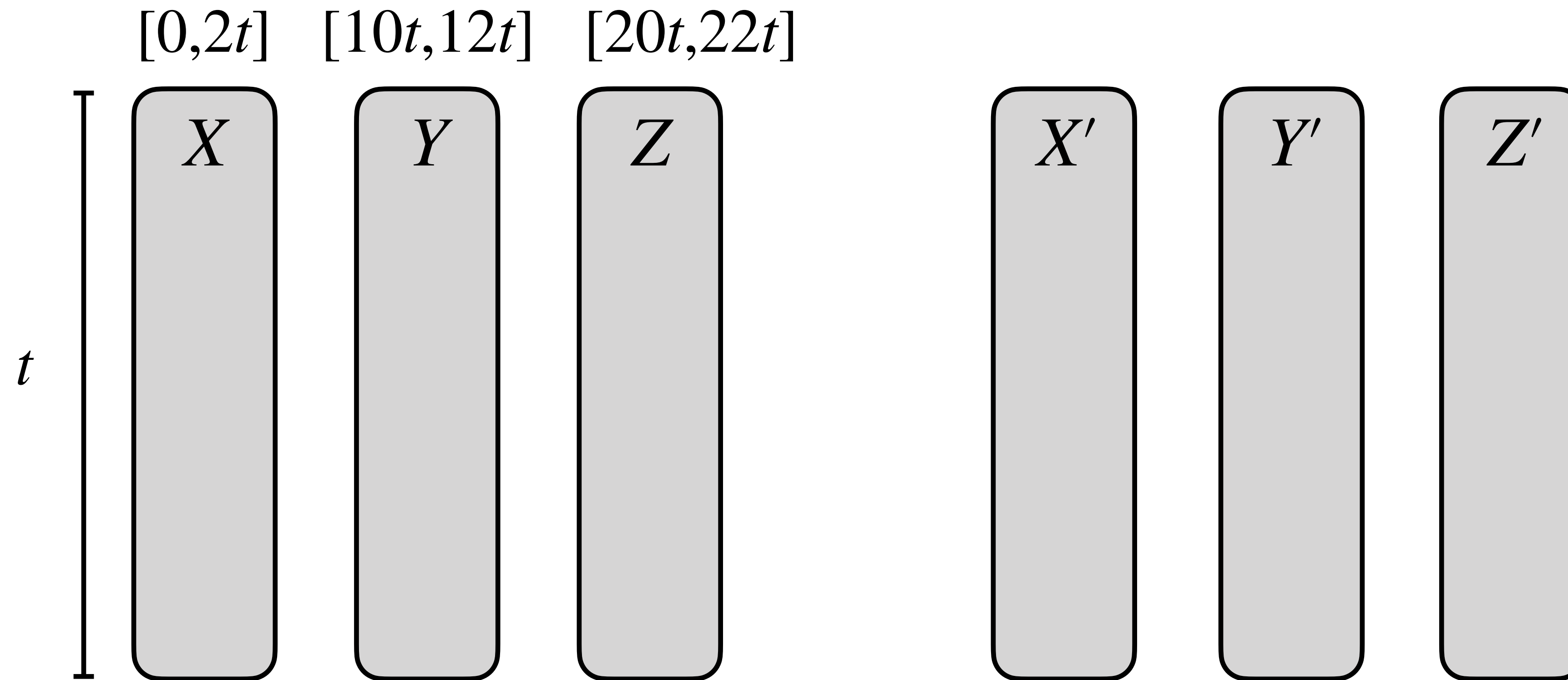
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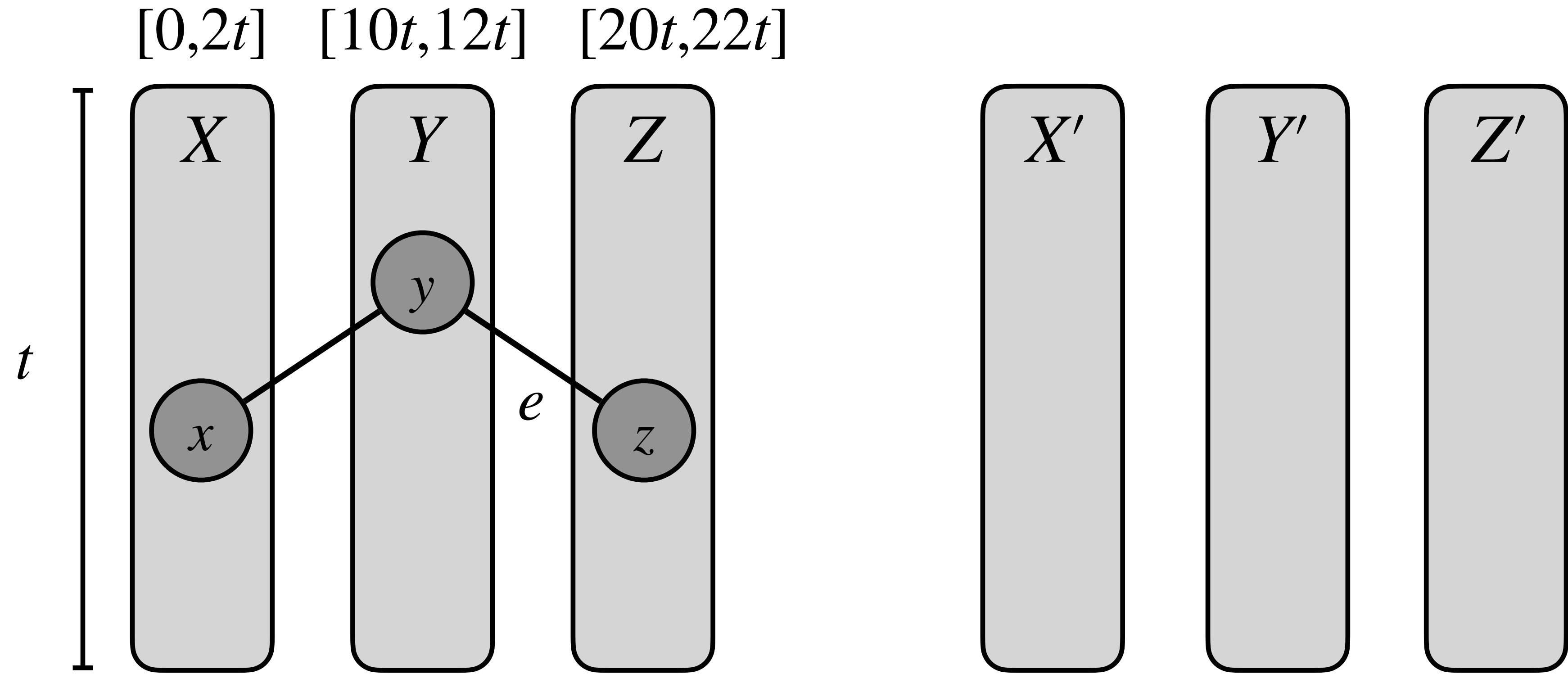
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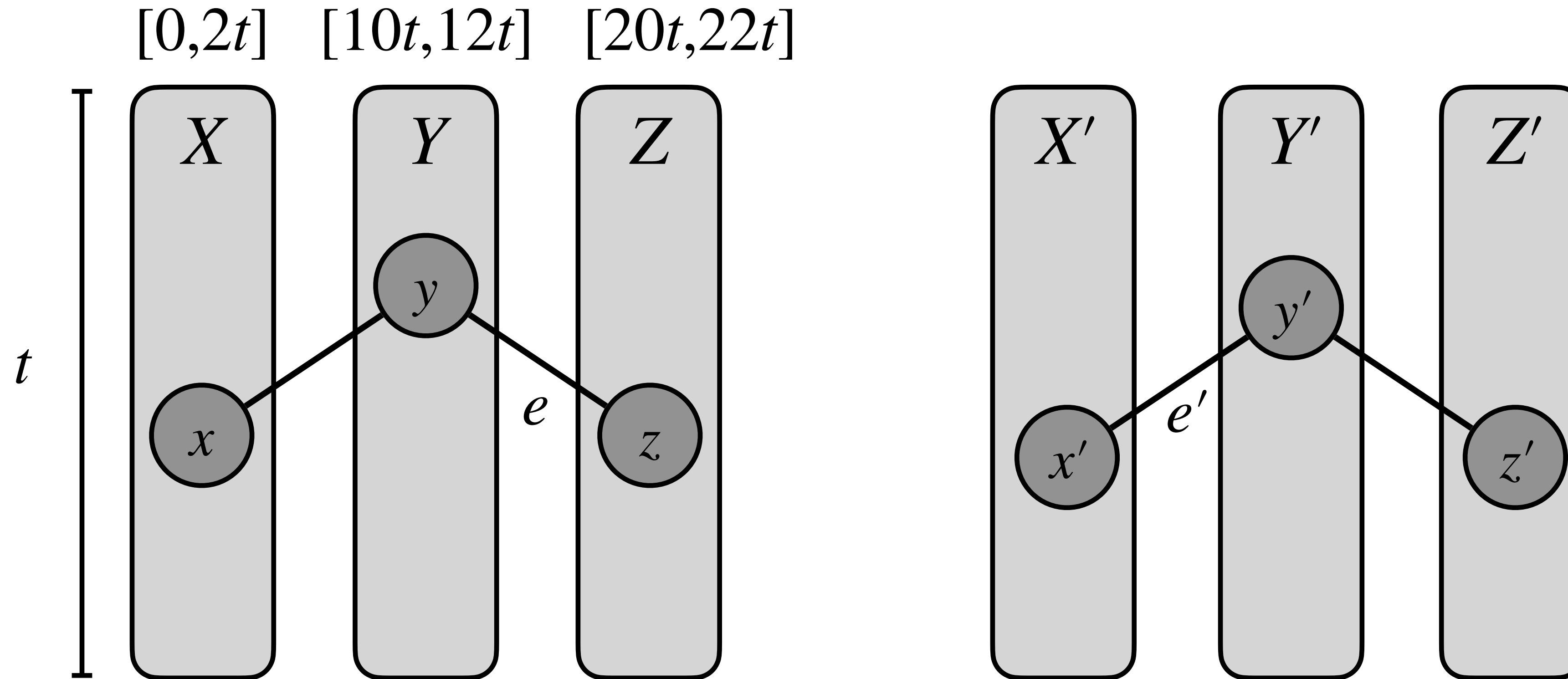
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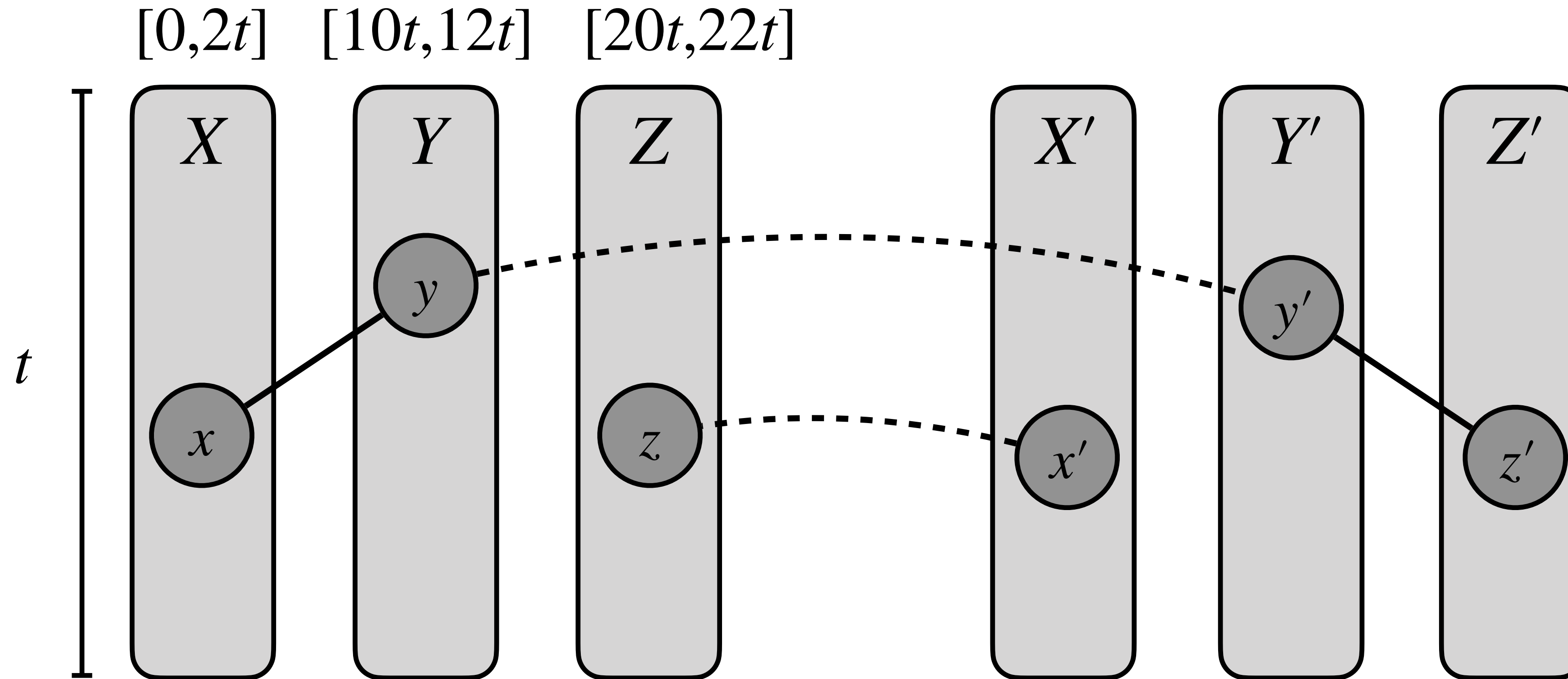
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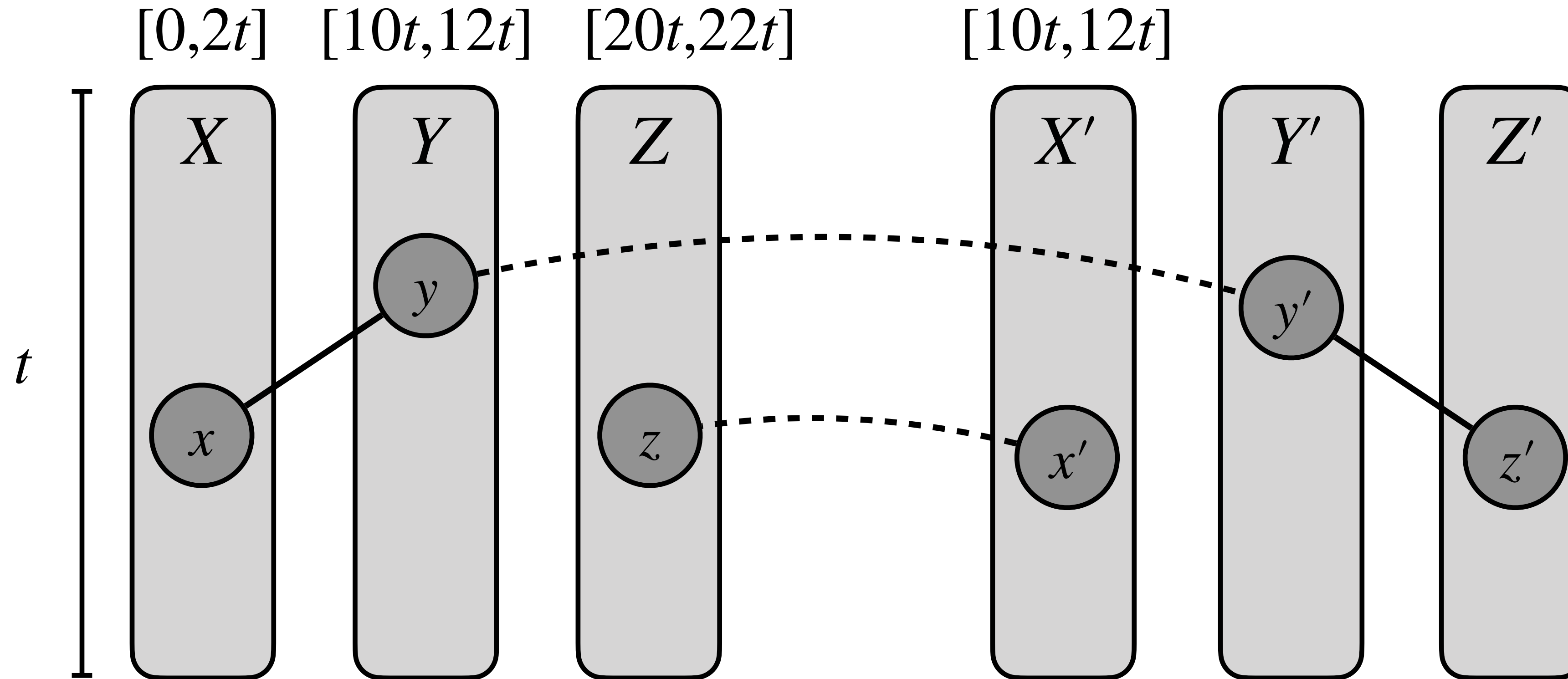
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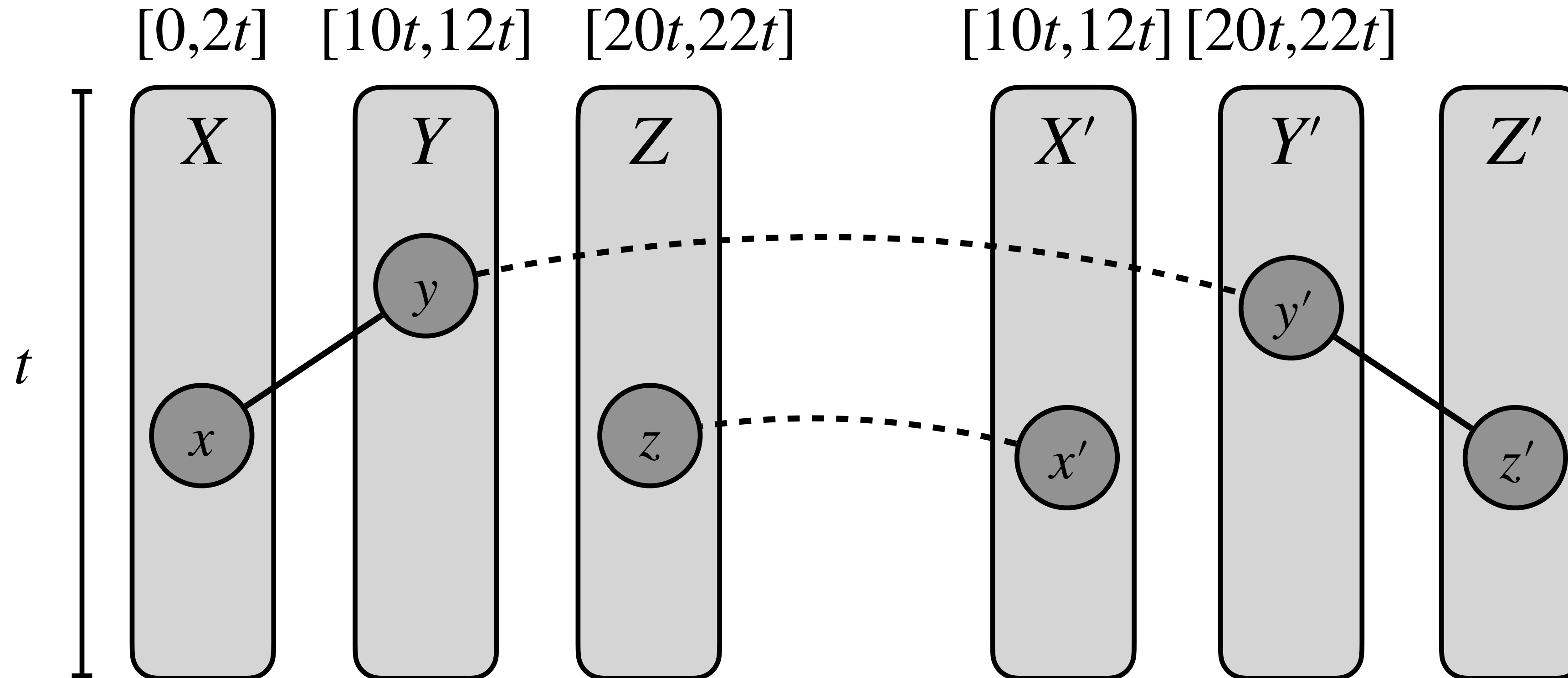


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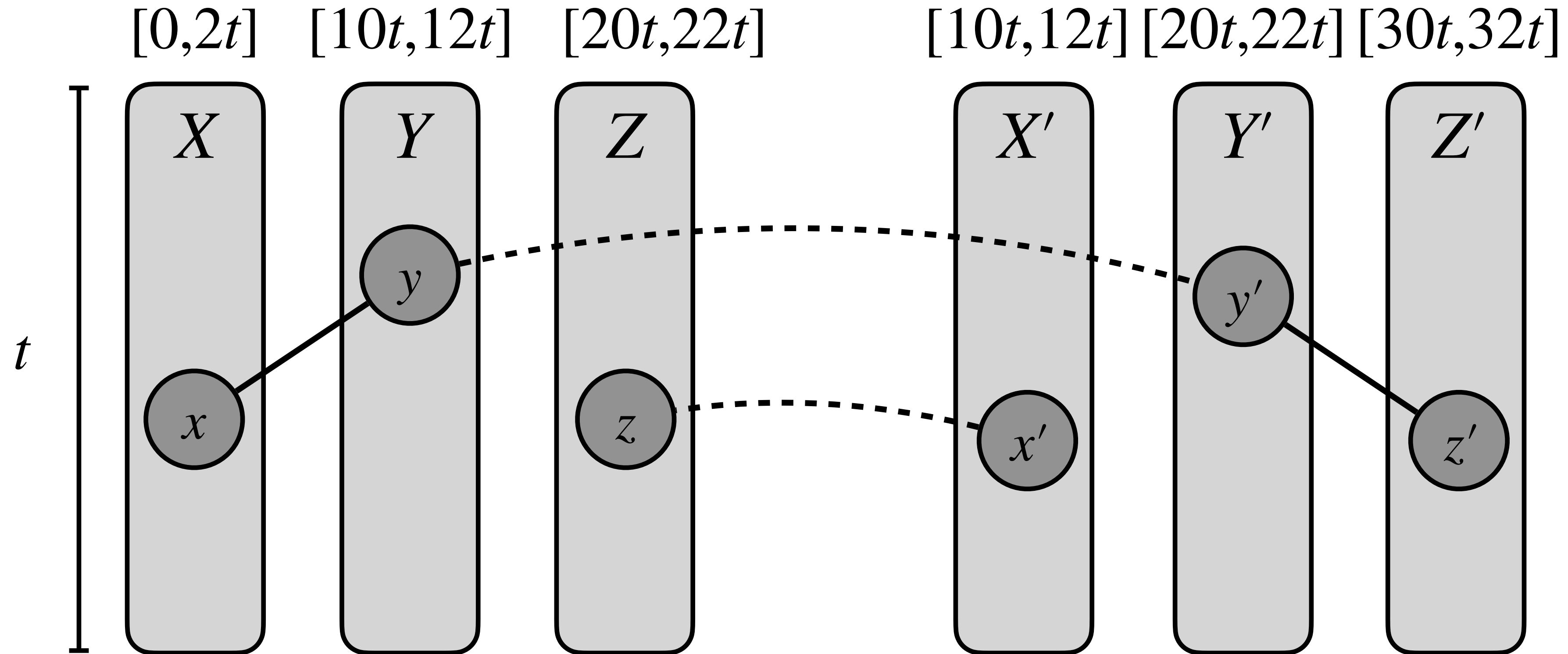
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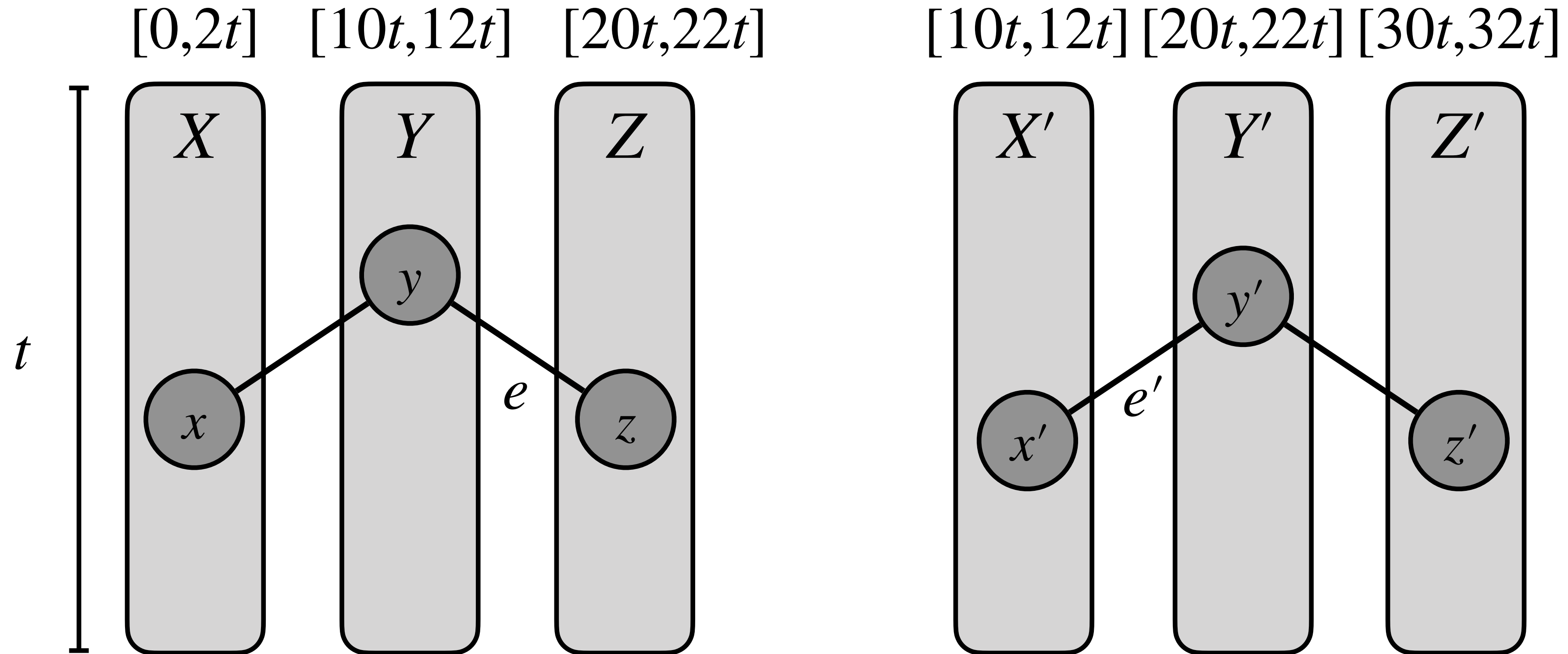
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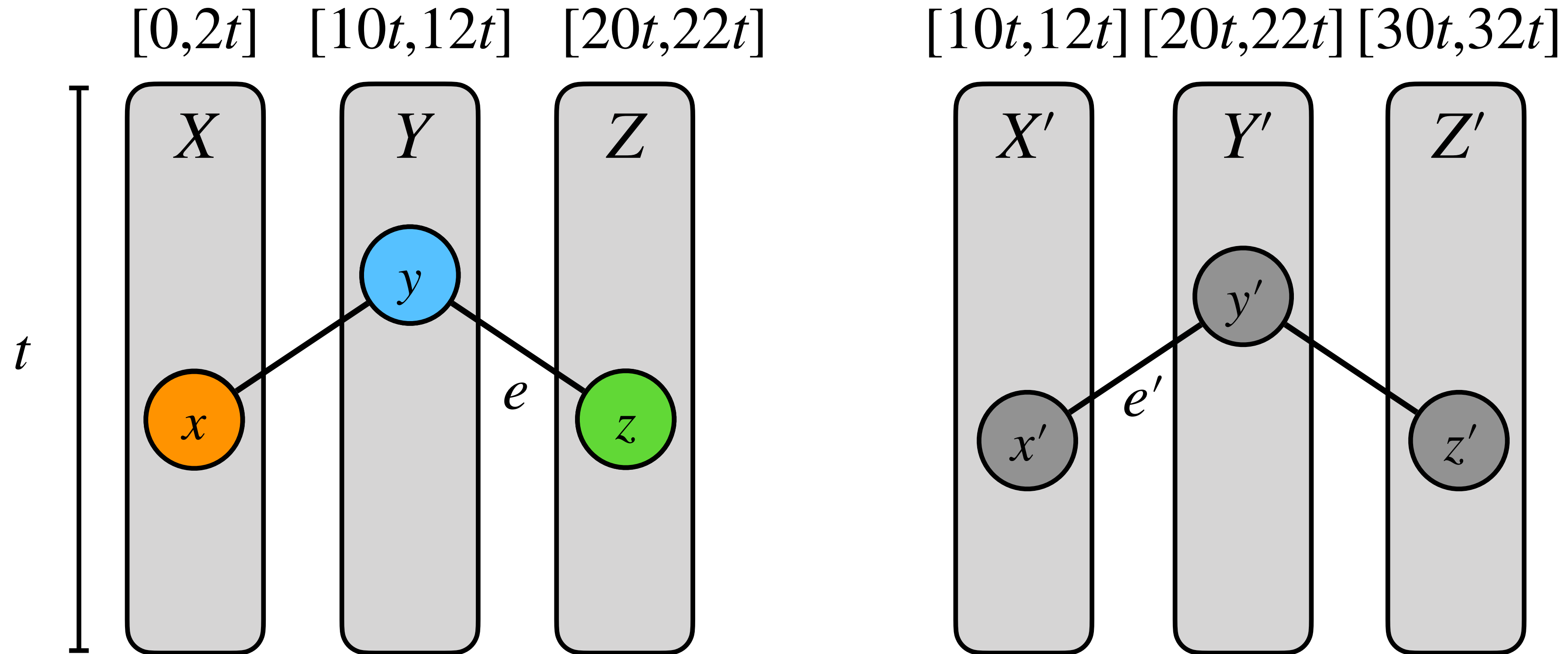
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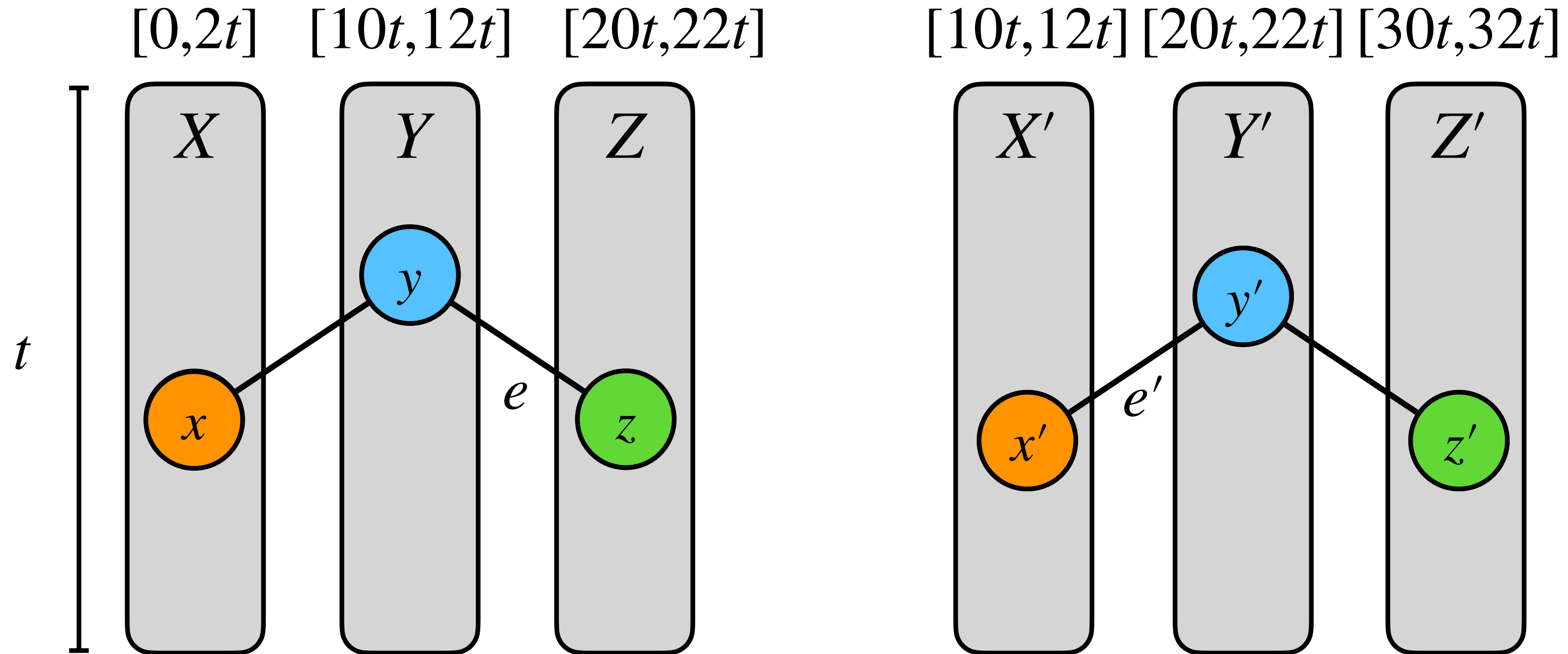
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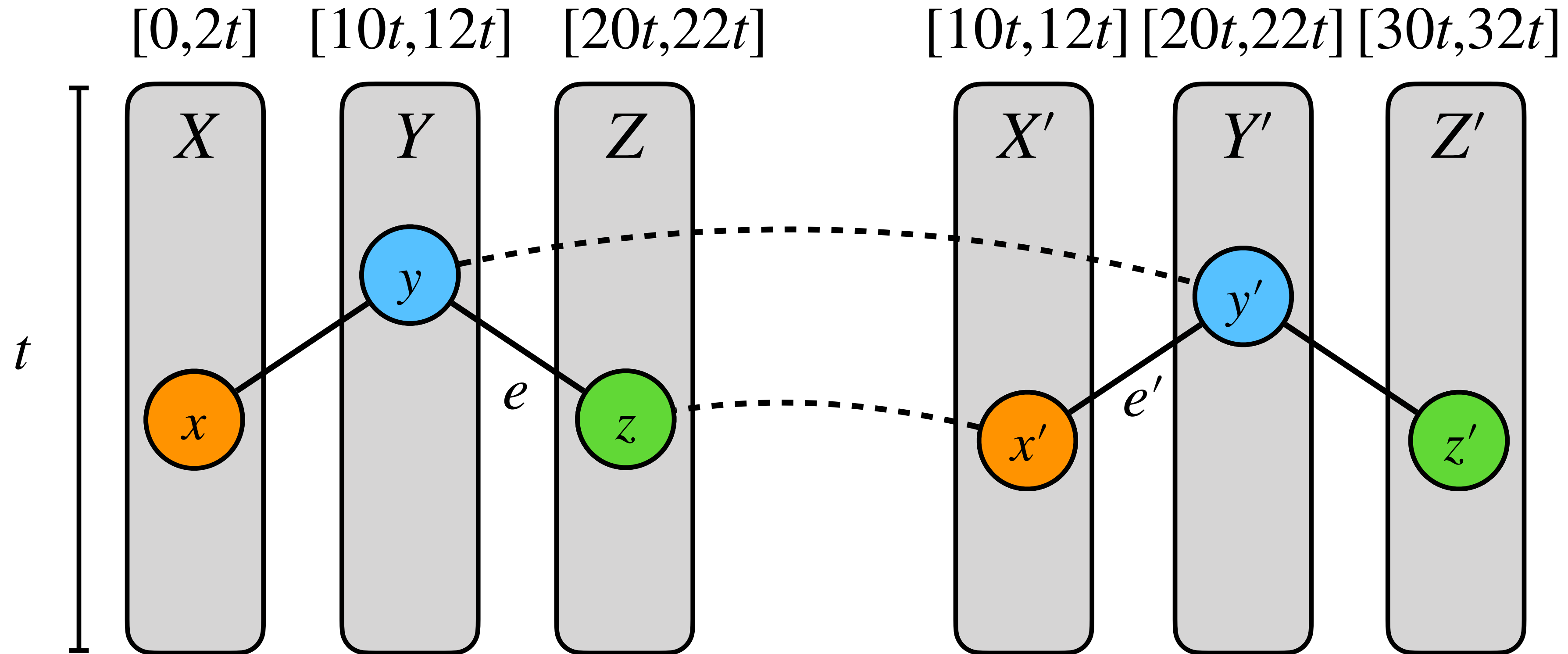
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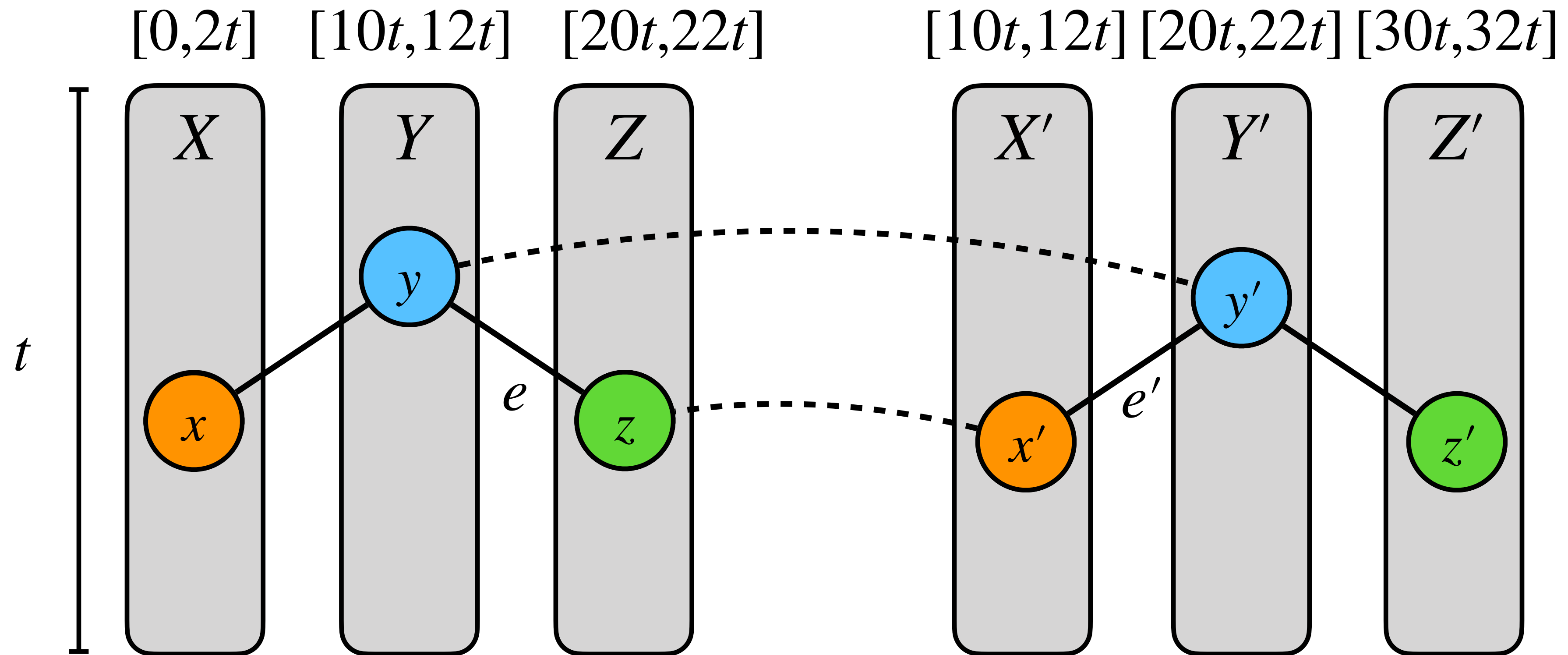
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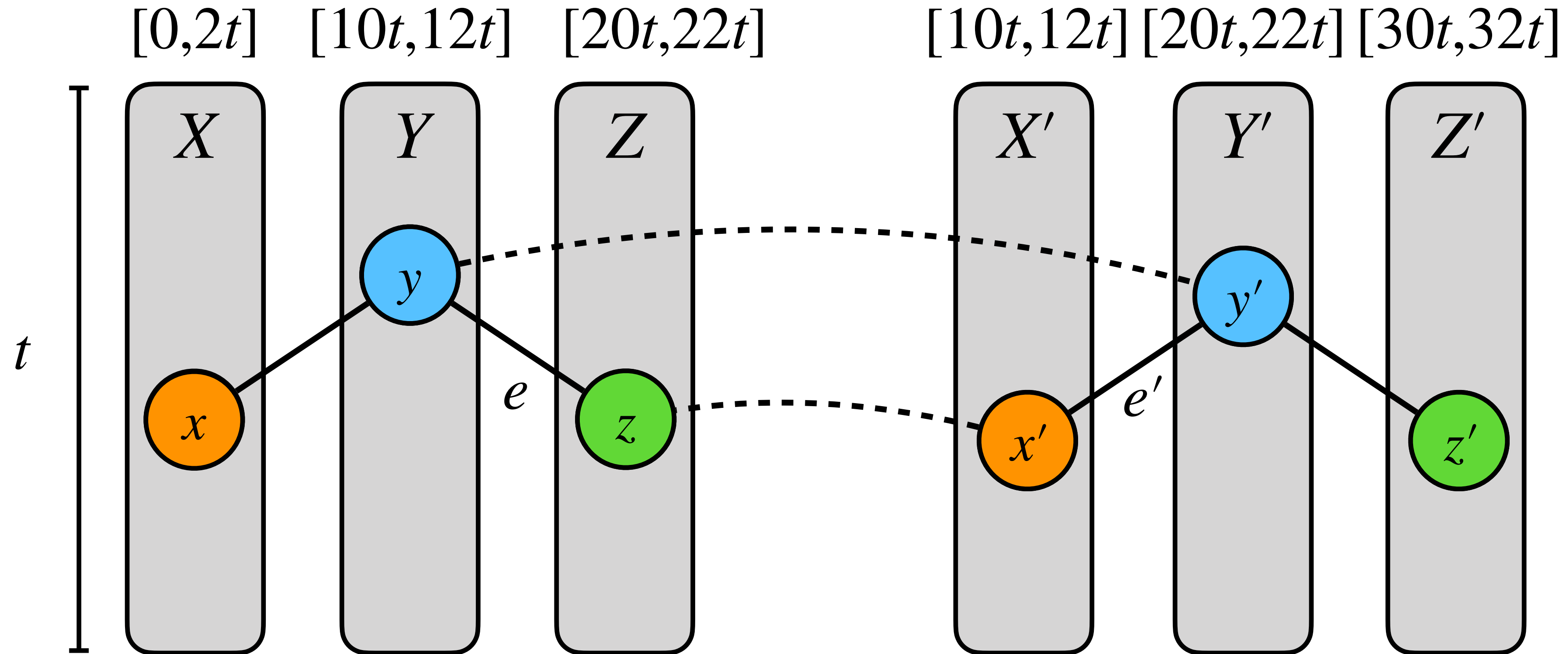


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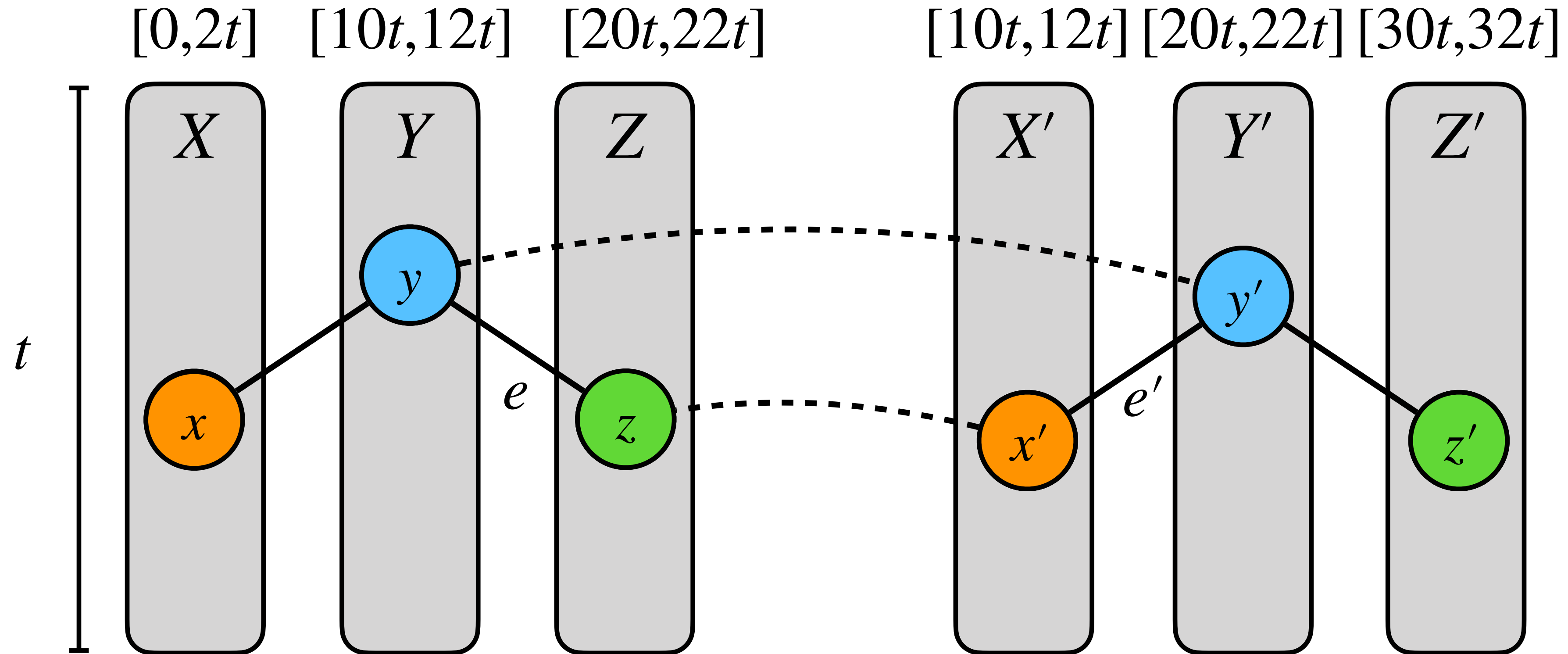


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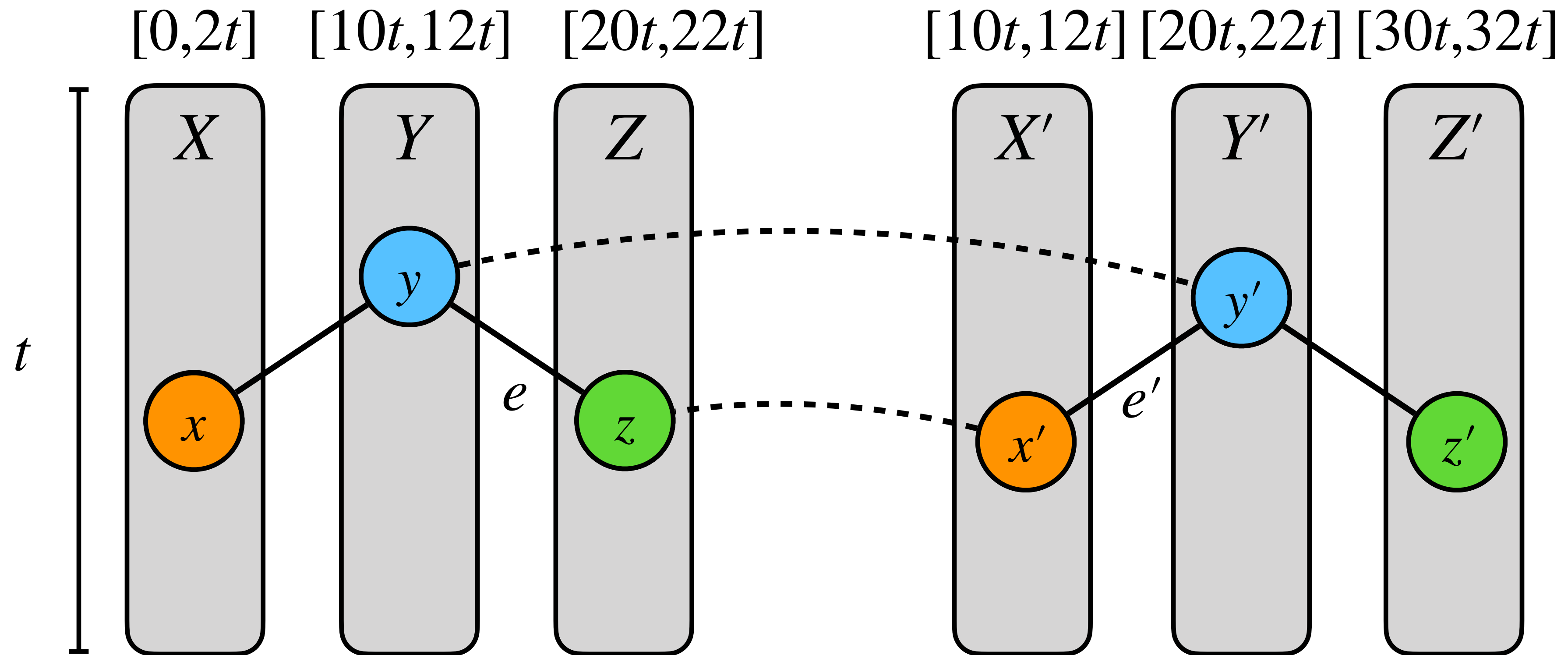
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ID Assignments



KT-1 Coloring Algorithms



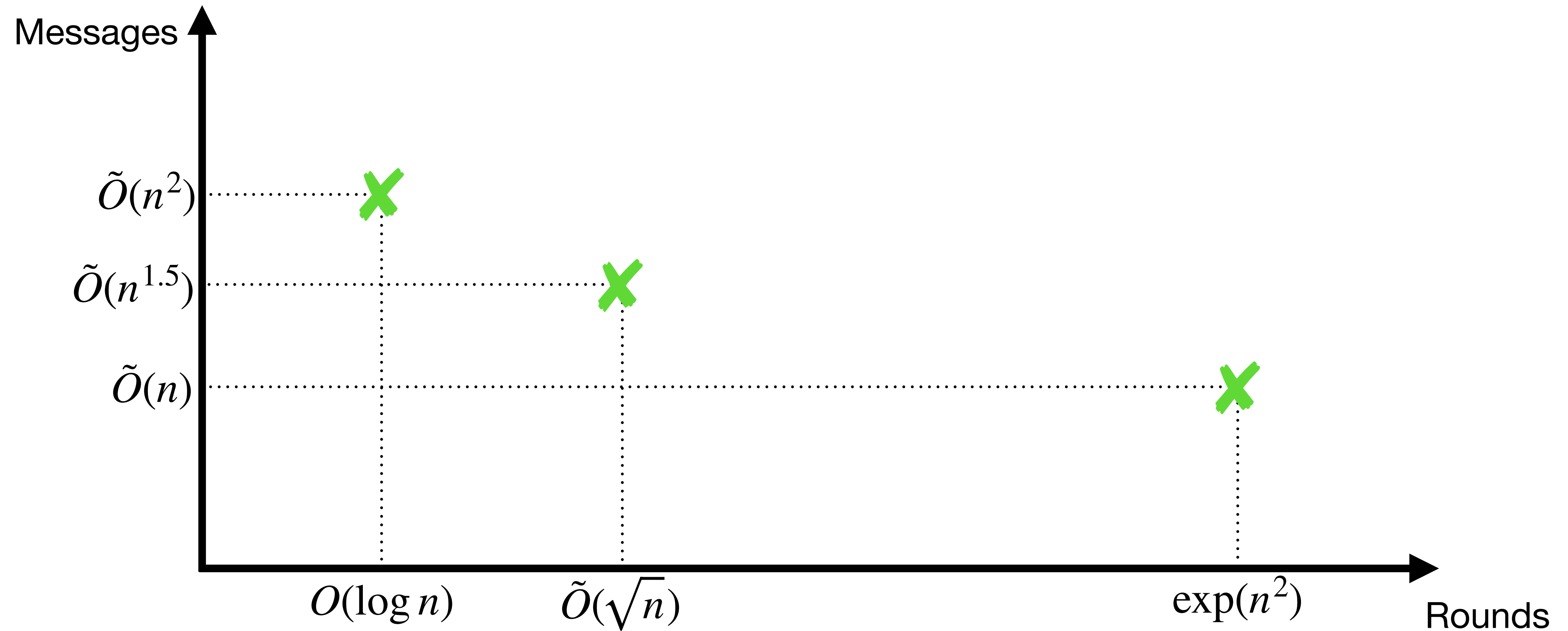
KT-1 Coloring Algorithms



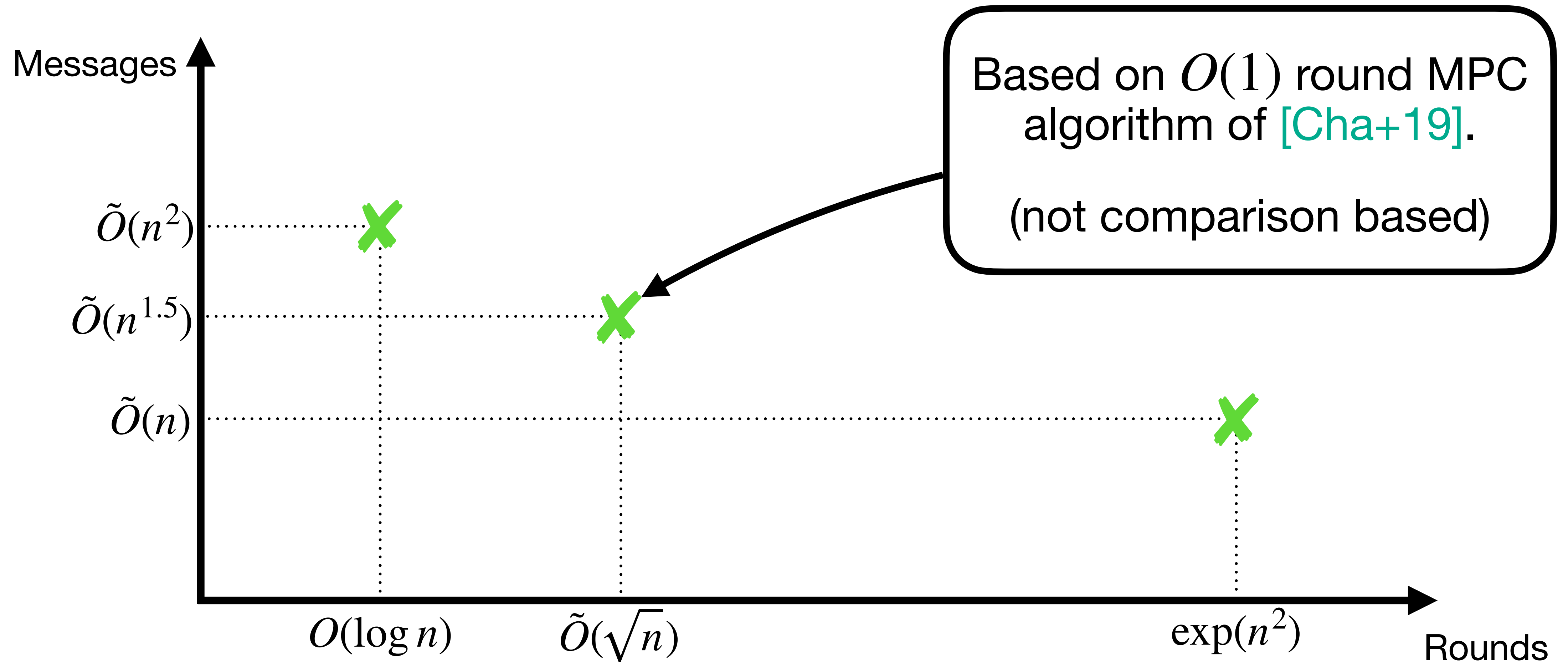
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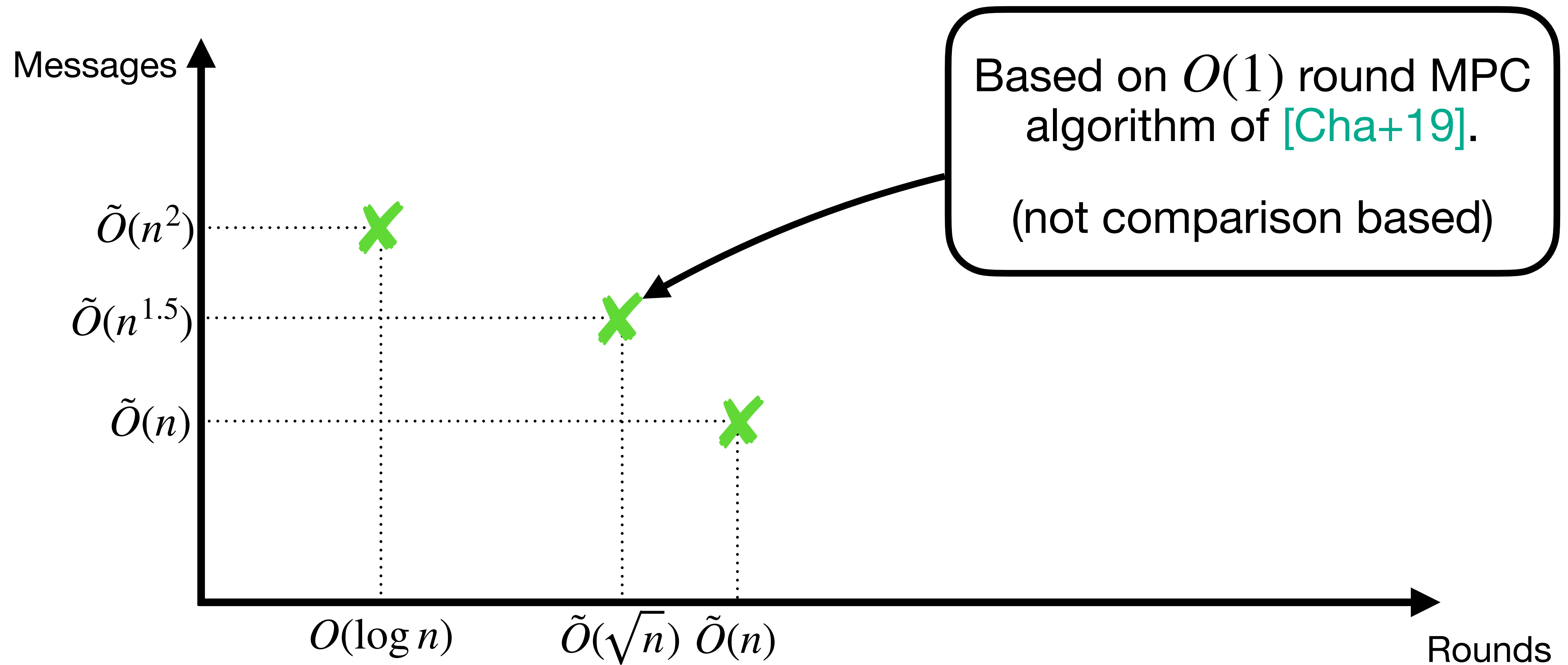
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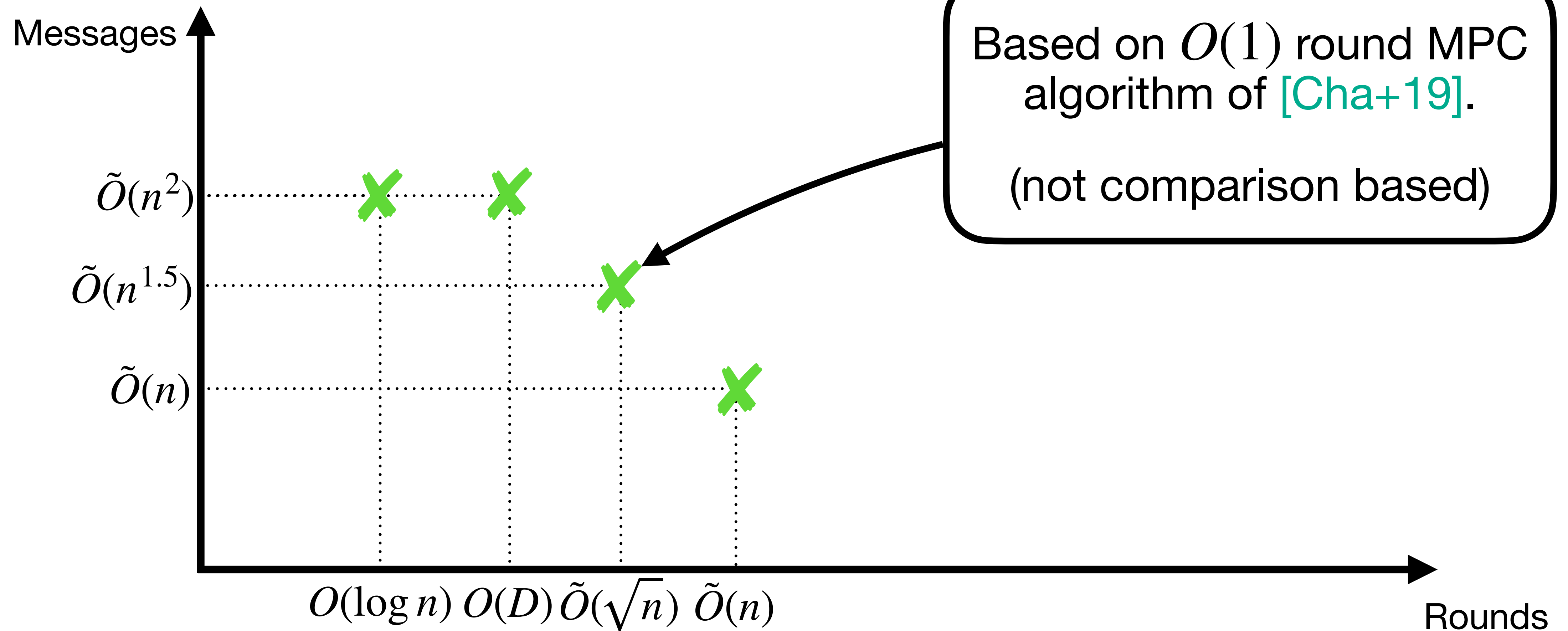
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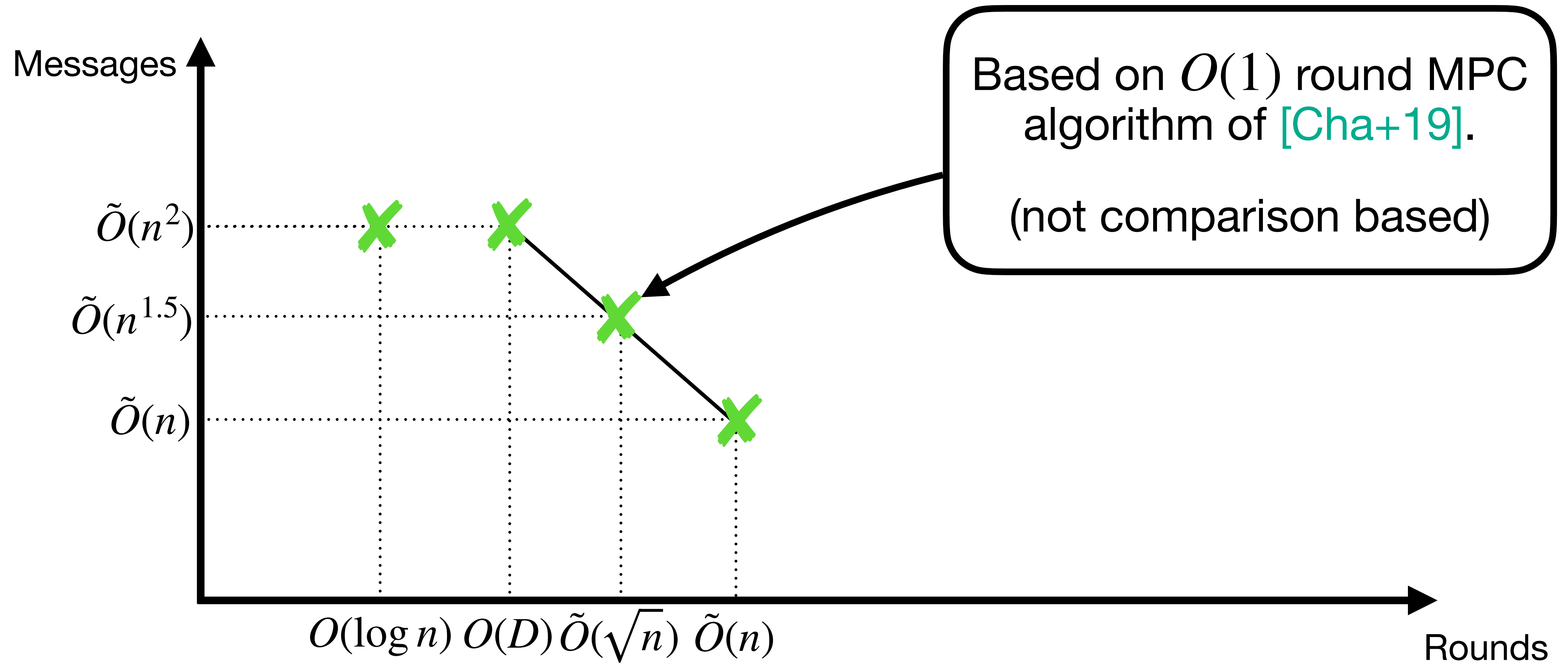
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Open Questions

- Can we get singularly optimal algorithms for local symmetry breaking problems like MIS, $(\Delta + 1)$ -coloring, Maximal Matching?
 - Such algorithms are known for problems like leader election.
- Can we rule out singularly optimal algorithms in KT-1 CONGEST?
- Can we design an algorithm for MIS in KT-1 CONGEST that uses $\text{poly}(n)$ rounds and $o(m)$ messages?

To $\Omega(m)$ and Beyond



- For comparison based KT-1 algorithms, $\Omega(m)$ message lower bound for:

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[PPP+21] Pai, Pandurangan, Pemmaraju, Robinson. PODC 2021

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 - $SD(x, y) = \text{False}$ if $x_i = y_i = 1$.

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$y \in \{0,1\}^k$

Lower Bound for MVC

- Based on the 2-party communication complexity reduction framework of [CKP17].
- Typically reduce from Set Disjointness.
 - $SD(x, y) = \text{False}$ if $x_i = y_i = 1$.
 - $SD(x, y) = \text{True}$ otherwise

Alice

$x \in \{0,1\}^k$

Bob

$y \in \{0,1\}^k$

Lower Bound for MVC

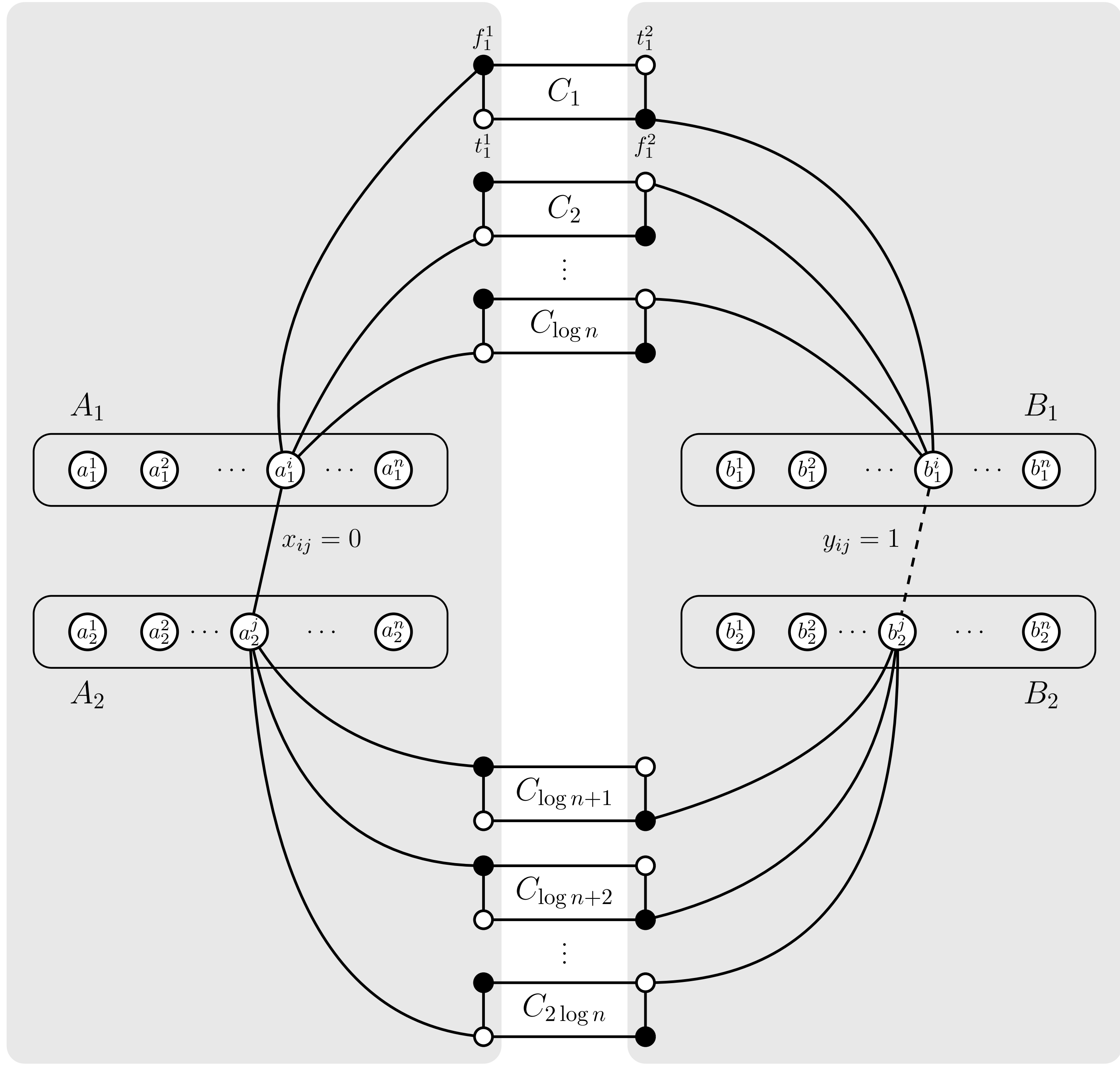
- Based on the 2-party communication complexity reduction framework of [CKP17].
- Typically reduce from Set Disjointness.
 - $SD(x, y) = \text{False}$ if $x_i = y_i = 1$.
 - $SD(x, y) = \text{True}$ otherwise
- Alice and Bob need to exchange $\Omega(k)$ bits to compute $SD(x, y)$.

Alice

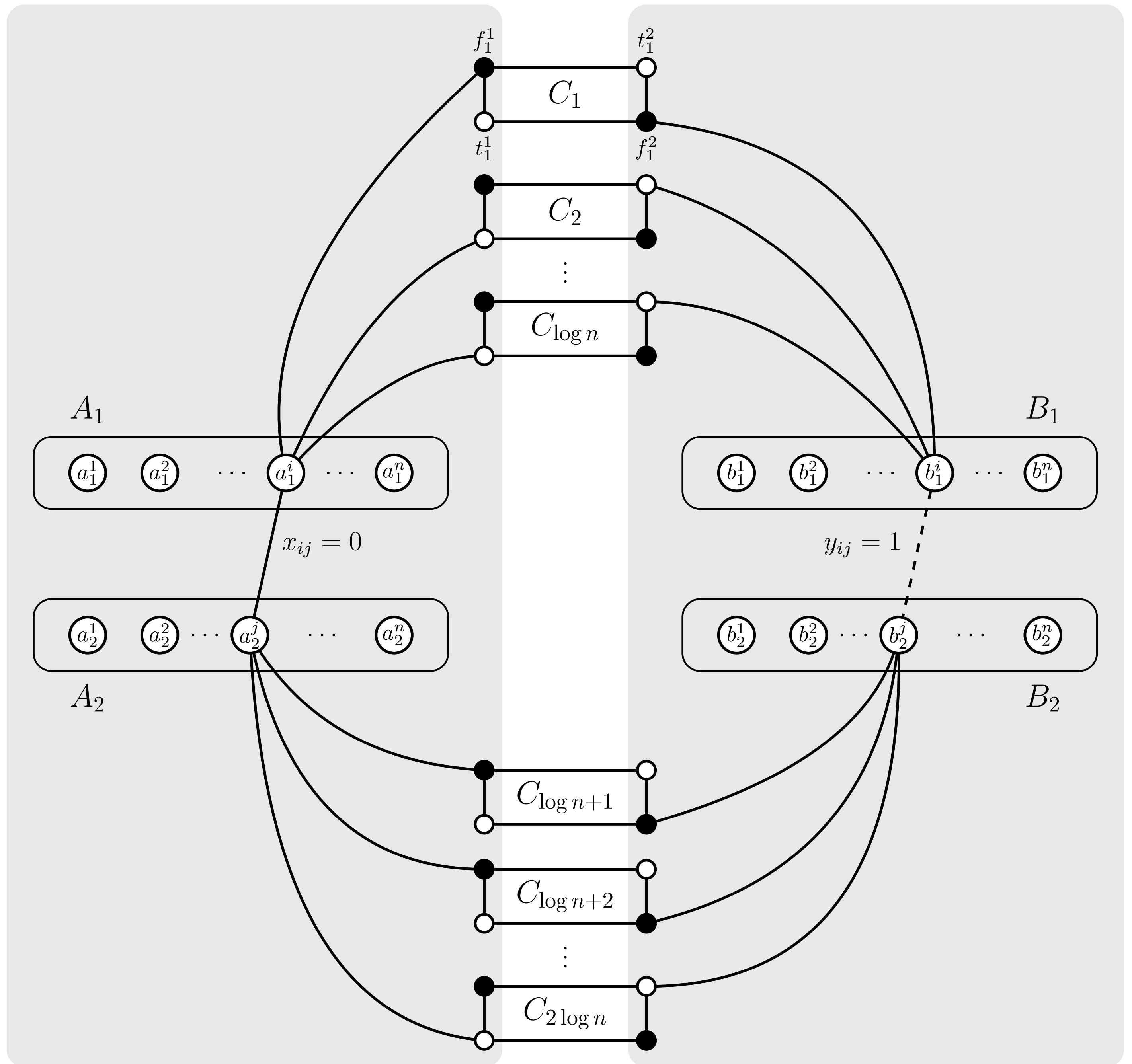
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Bob

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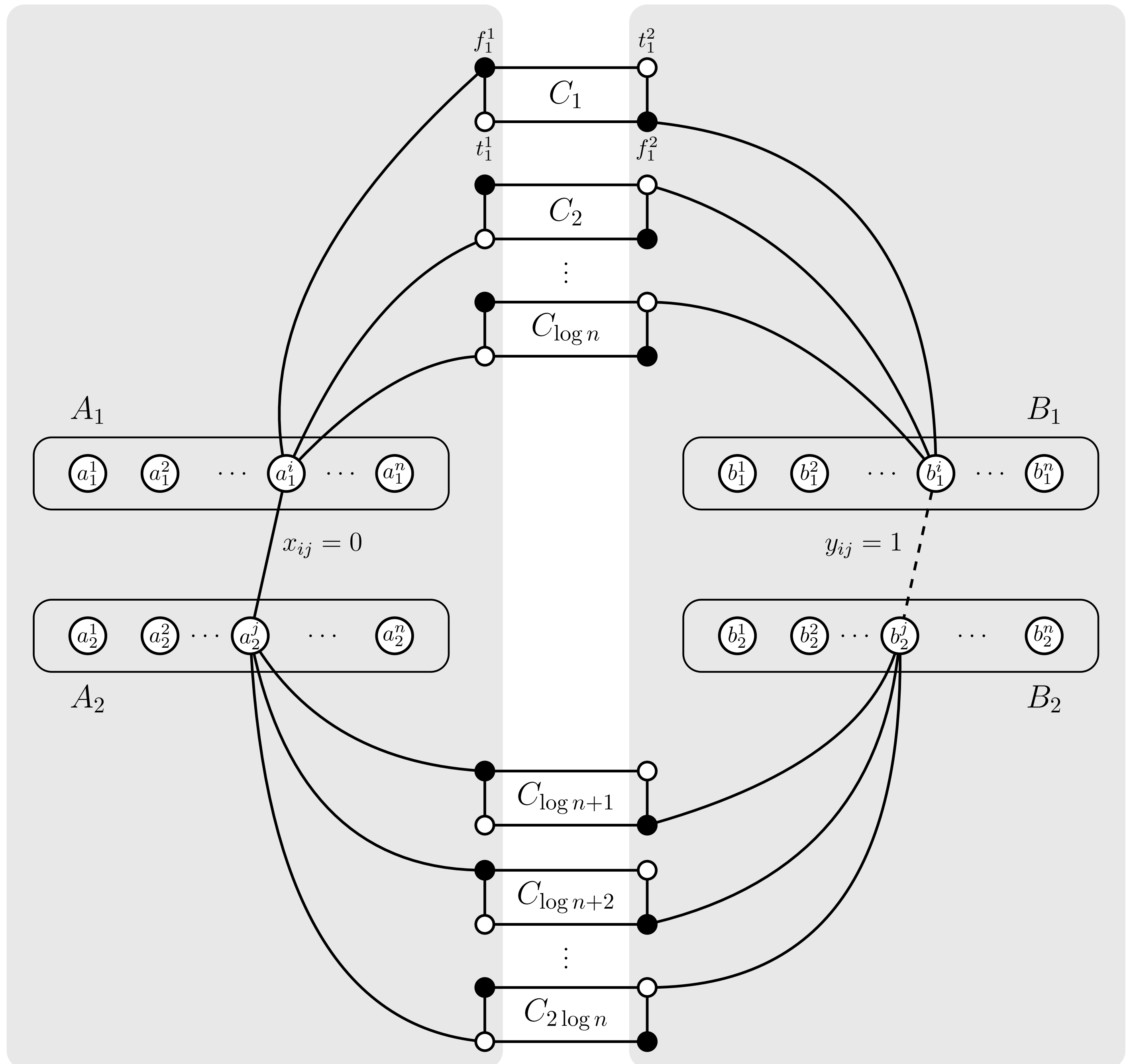


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Round Lower Bound

Alice

Bob

$x \in \{0,1\}^{n^2}$

$y \in \{0,1\}^{n^2}$

Round Lower Bound

- Alice and Bob first construct $G_{x,y}$

Alice

Bob

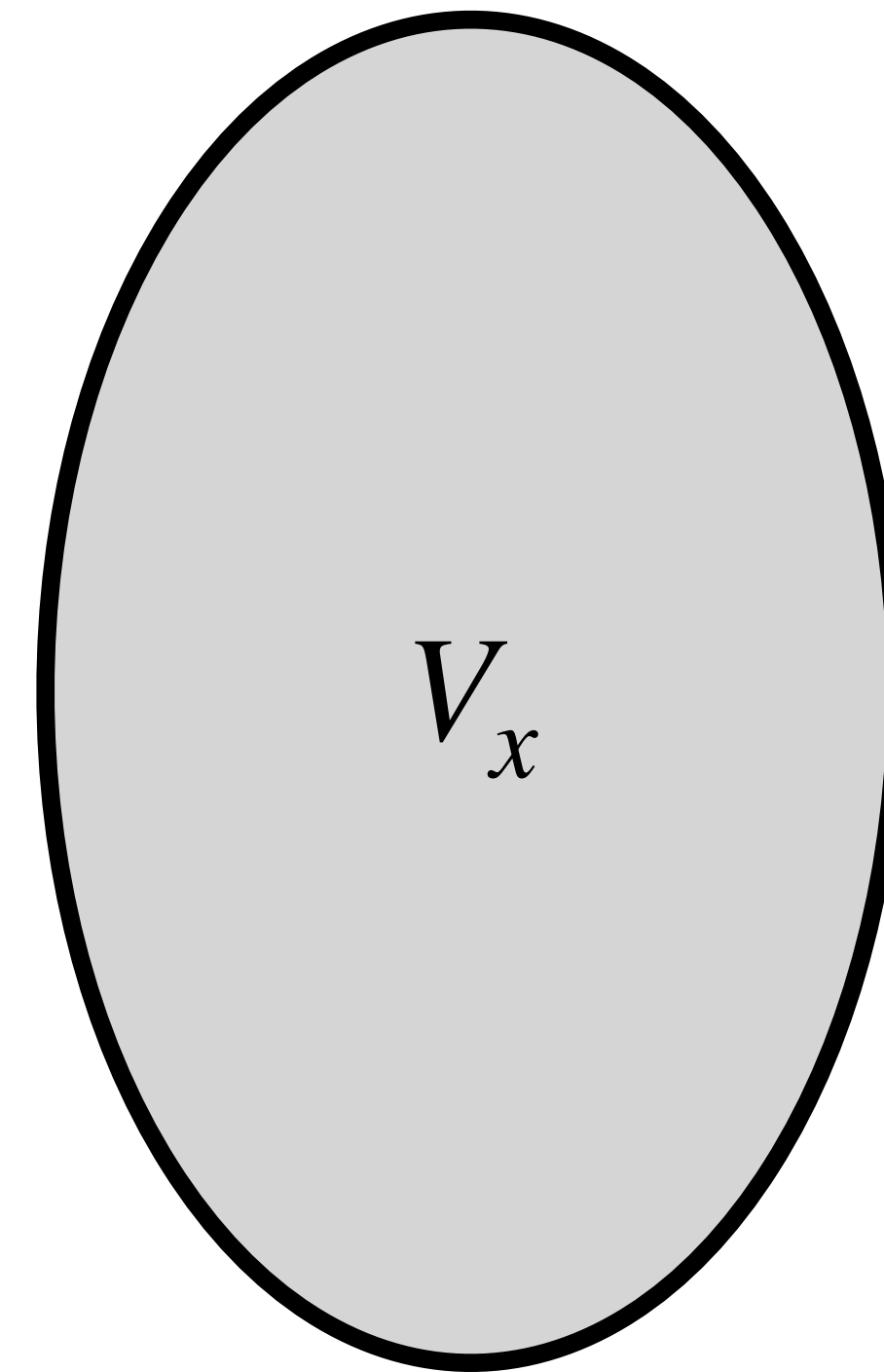
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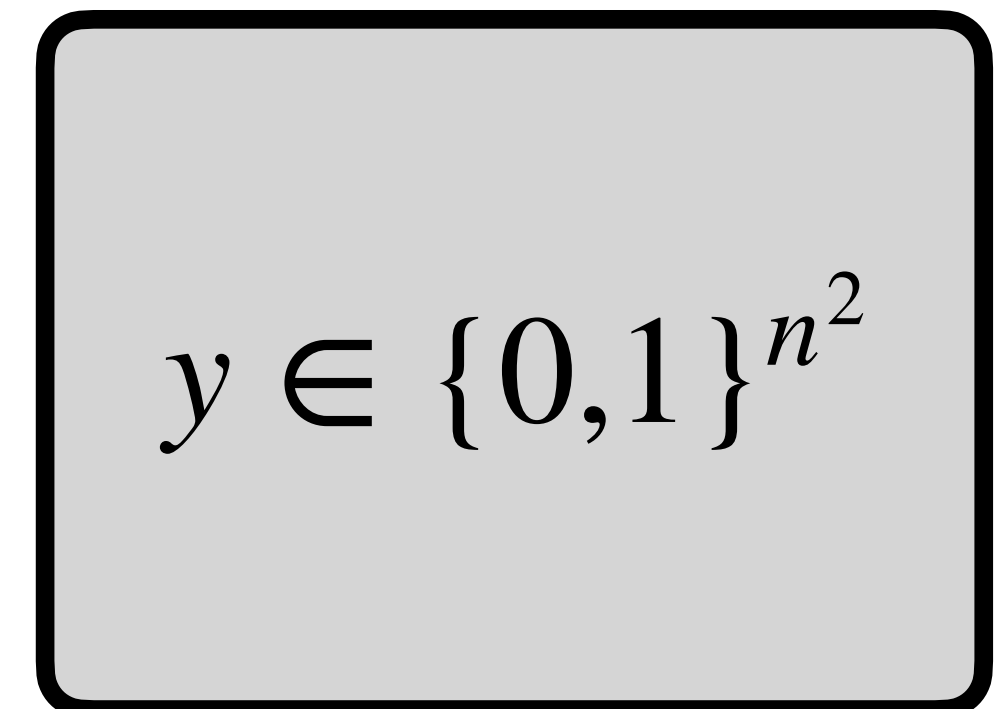
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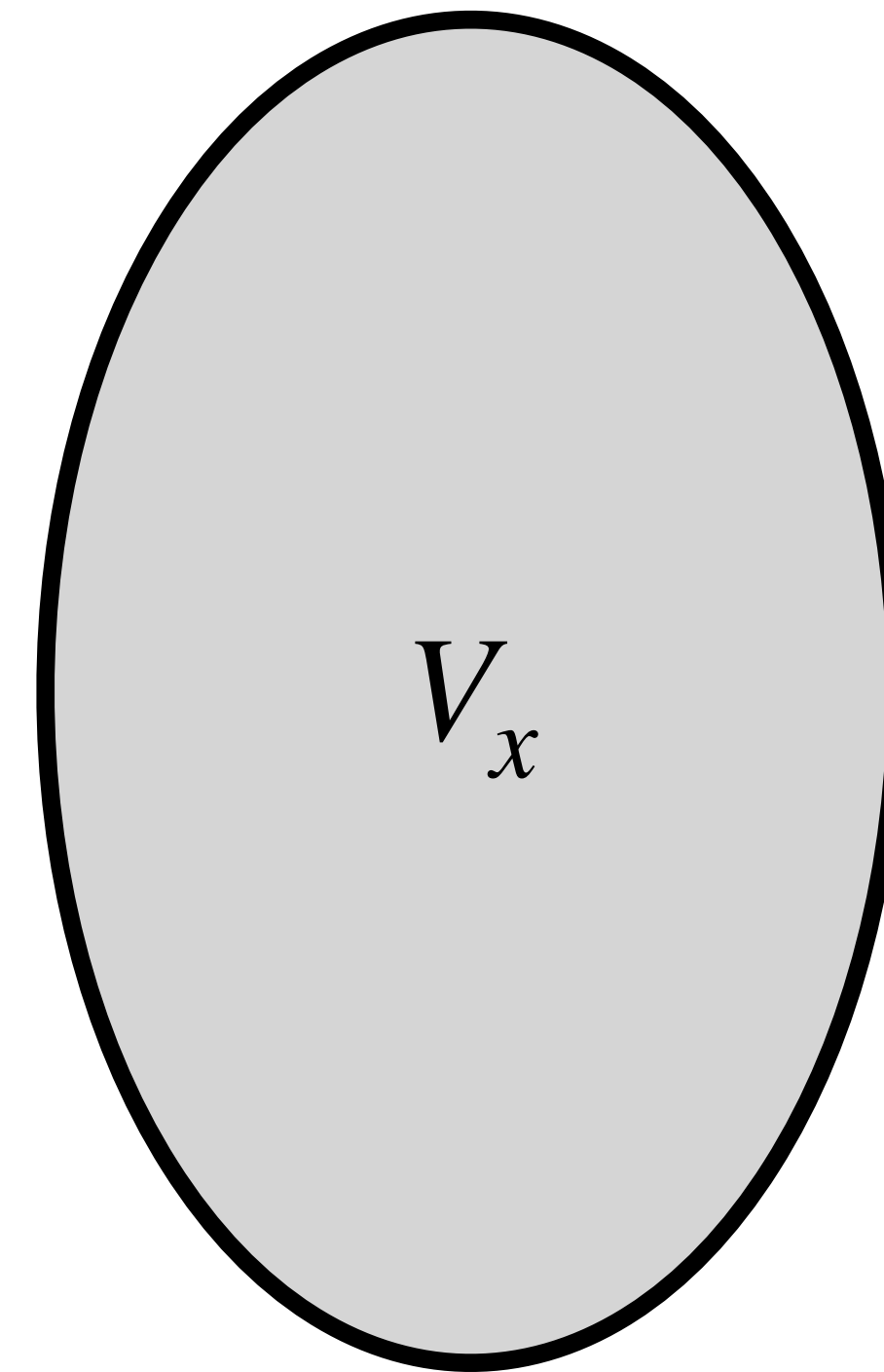
Bob



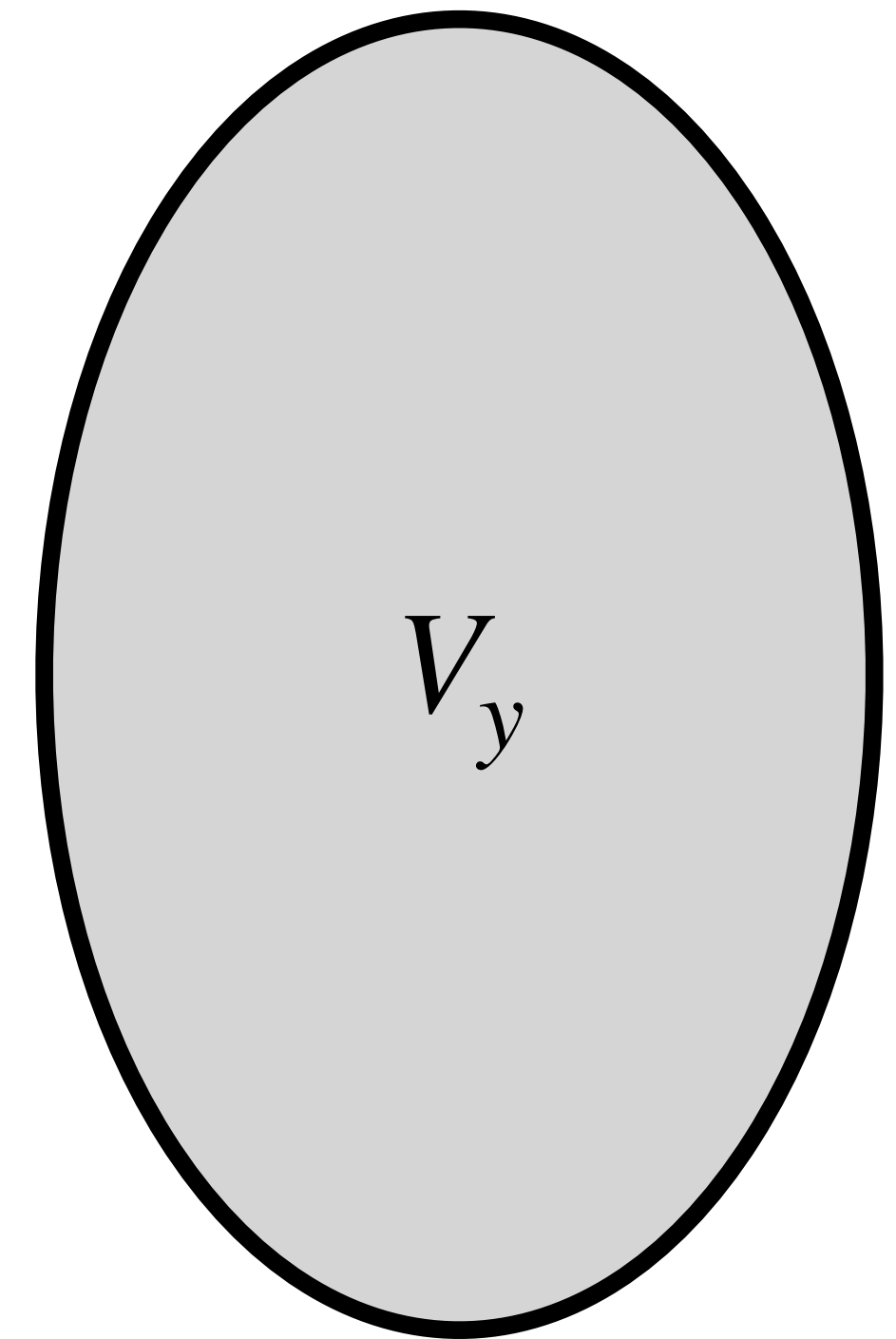
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Alice

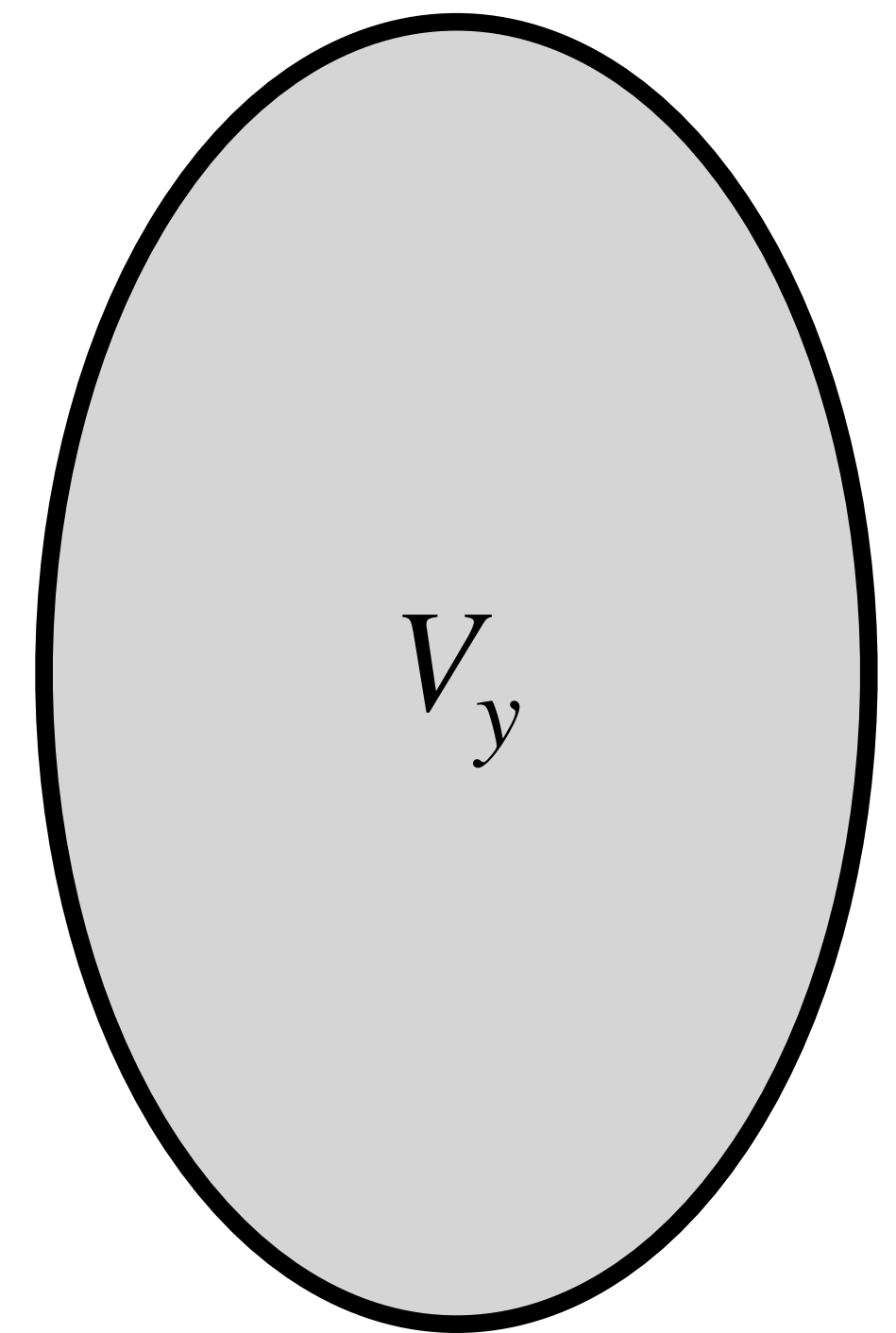
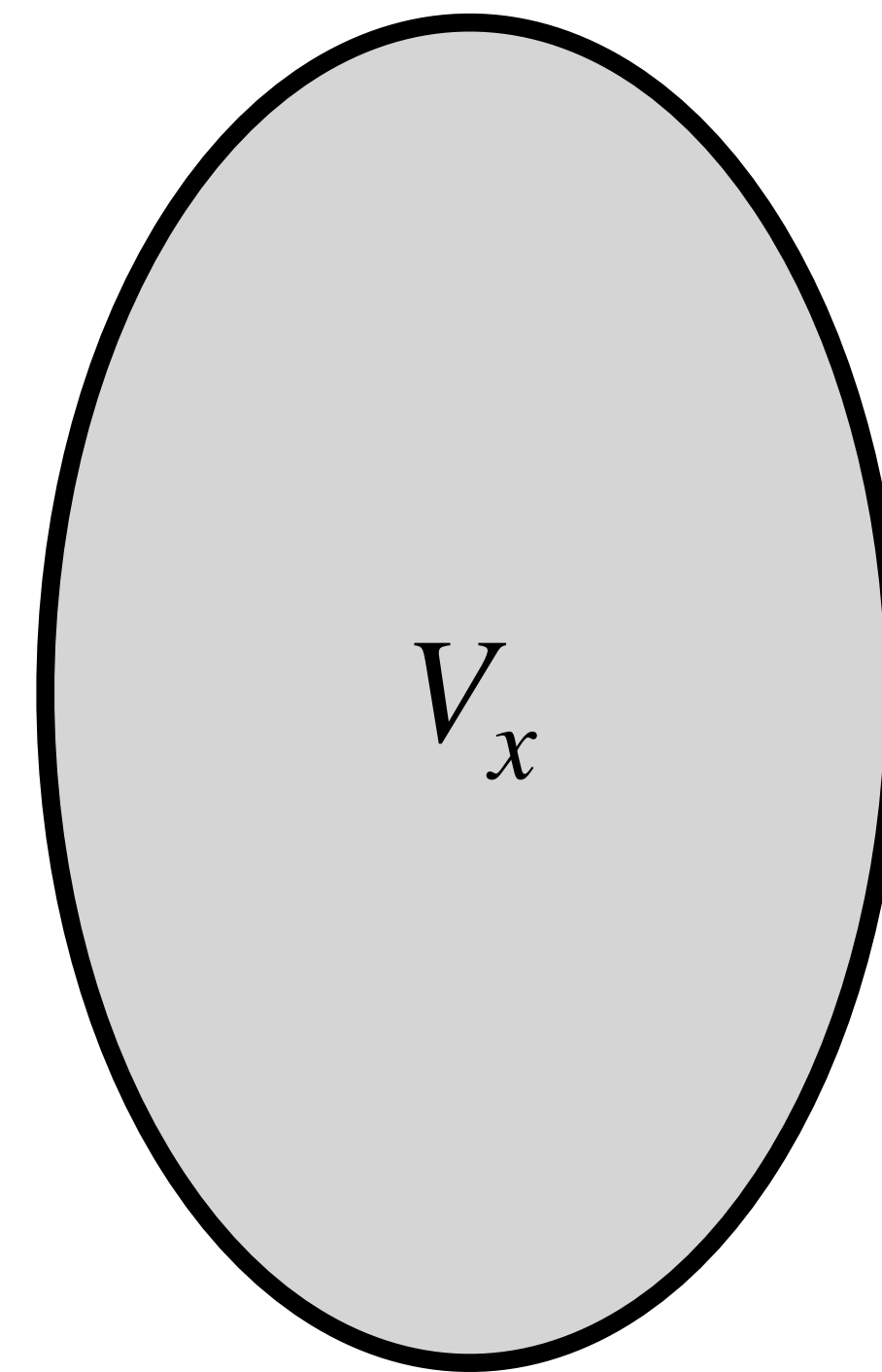


Bob



Round Lower Bound

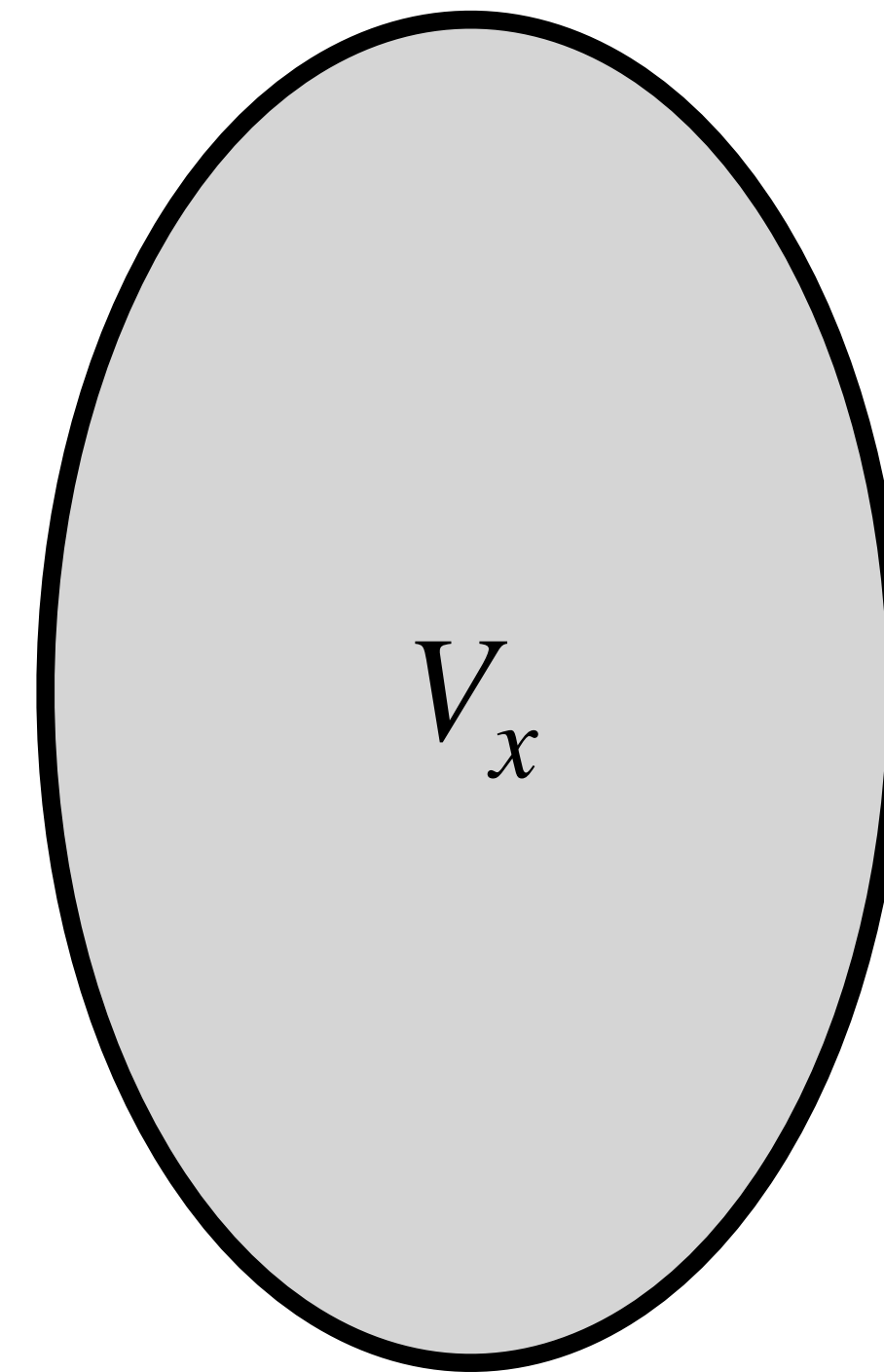
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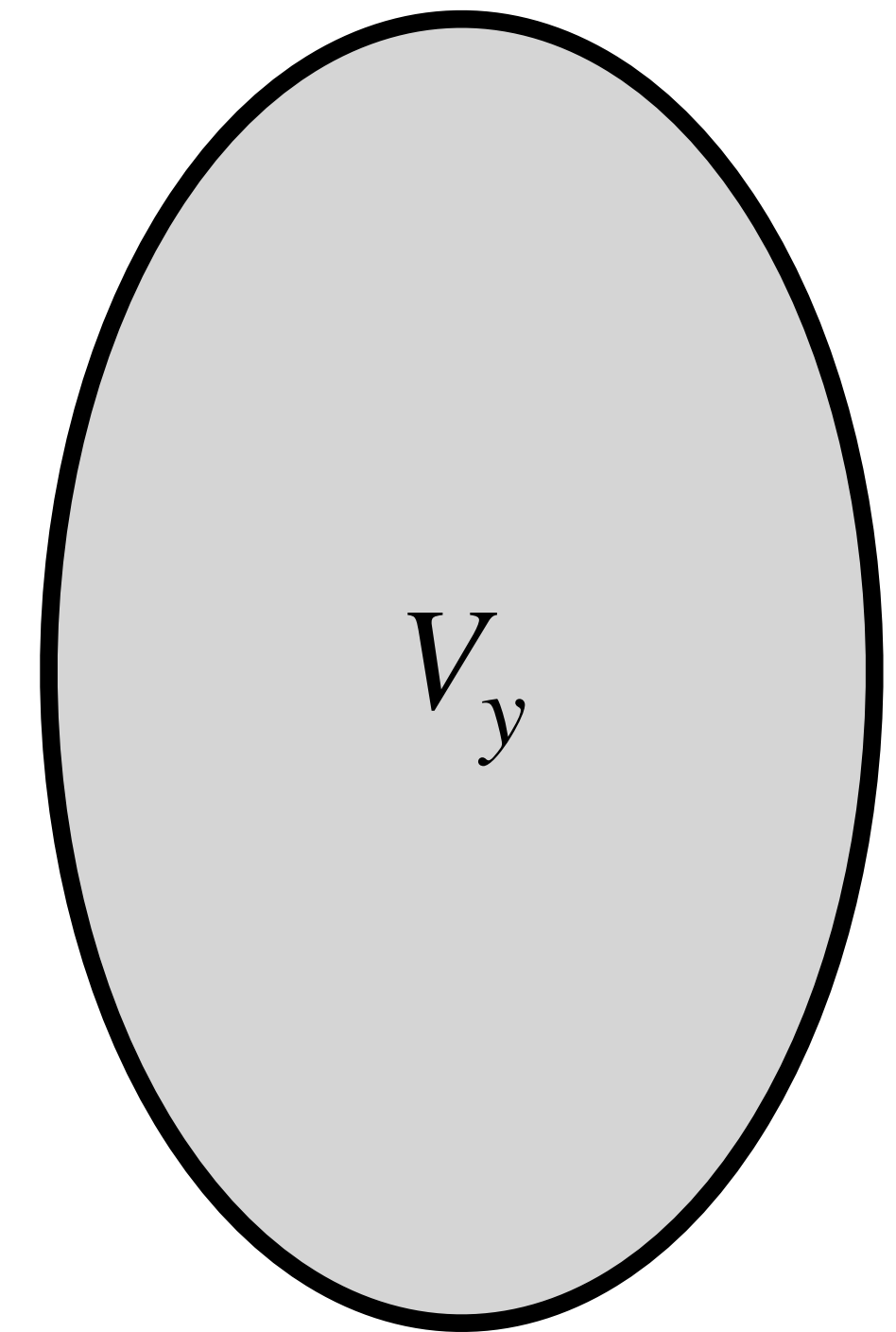
Round Lower Bound

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 - Each round requires Alice and Bob to exchange $O(\log^2 n)$ bits.

Alice



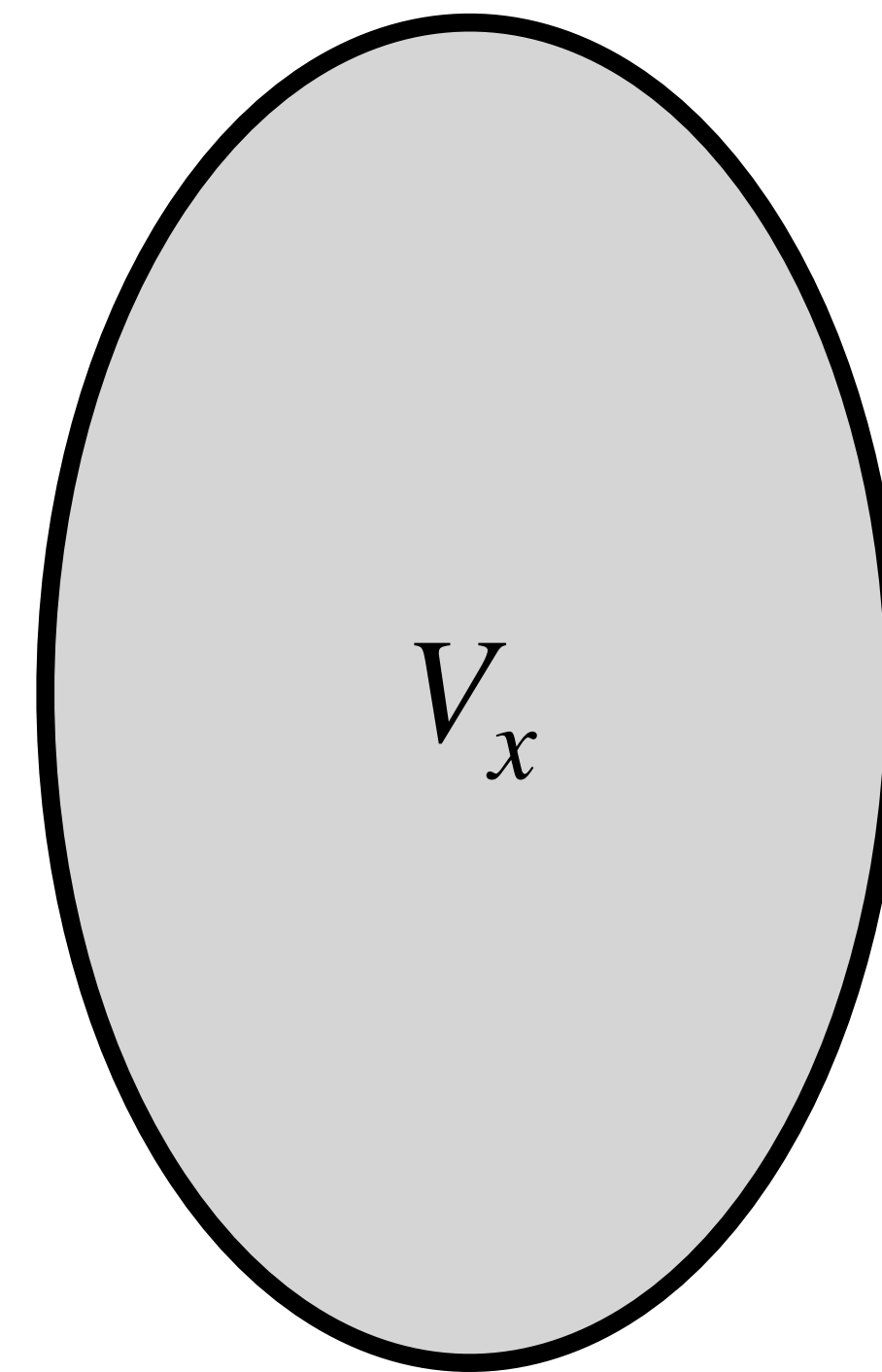
Bob



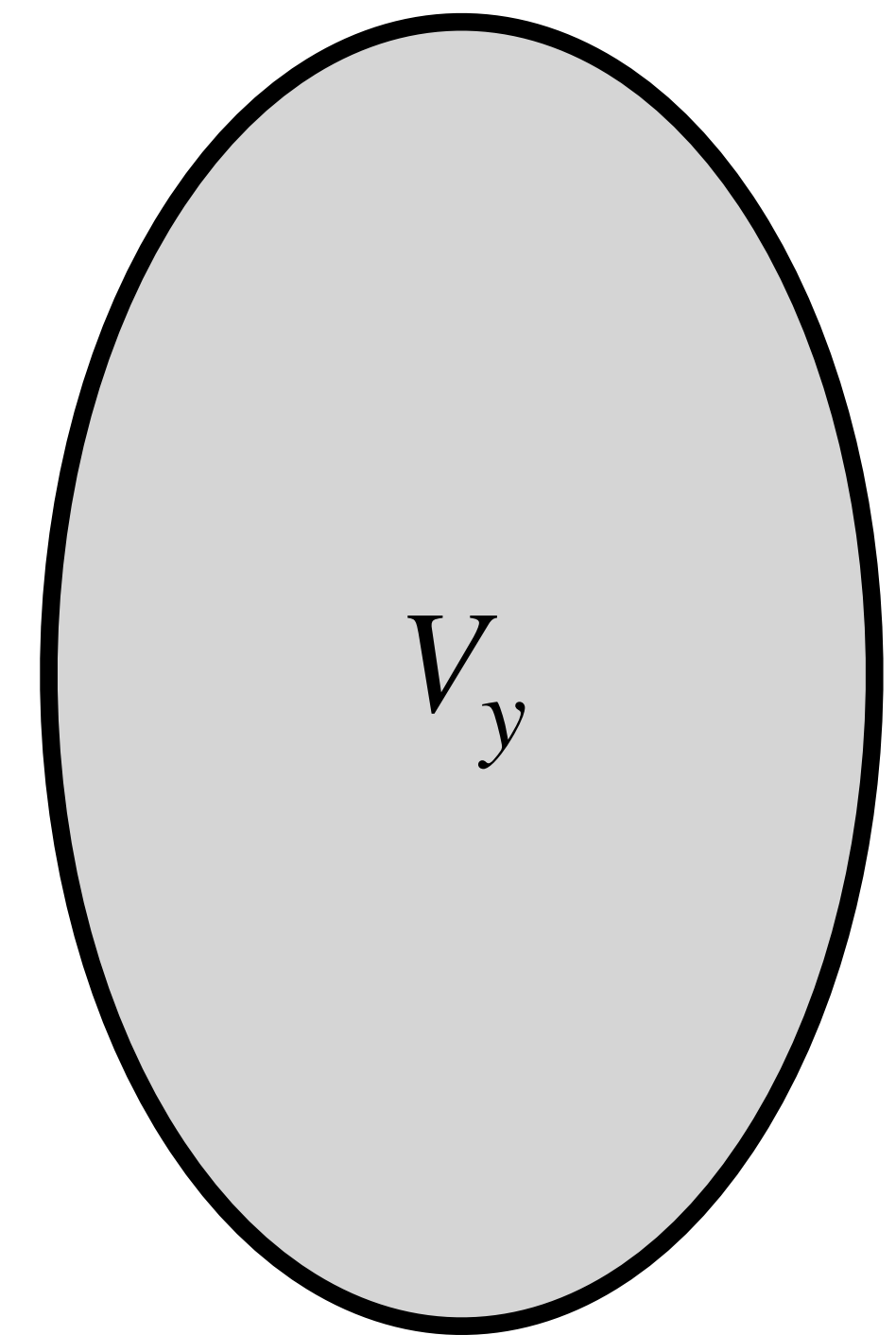
Round Lower Bound

- Alice and Bob first construct $G_{x,y}$
- Then simulate an r -round CONGEST algorithm that computes size of MVC.
 - Each round requires Alice and Bob to exchange $O(\log^2 n)$ bits.
- By the SD lower bound we must have $r \cdot \log^2 n \geq n^2$.

Alice

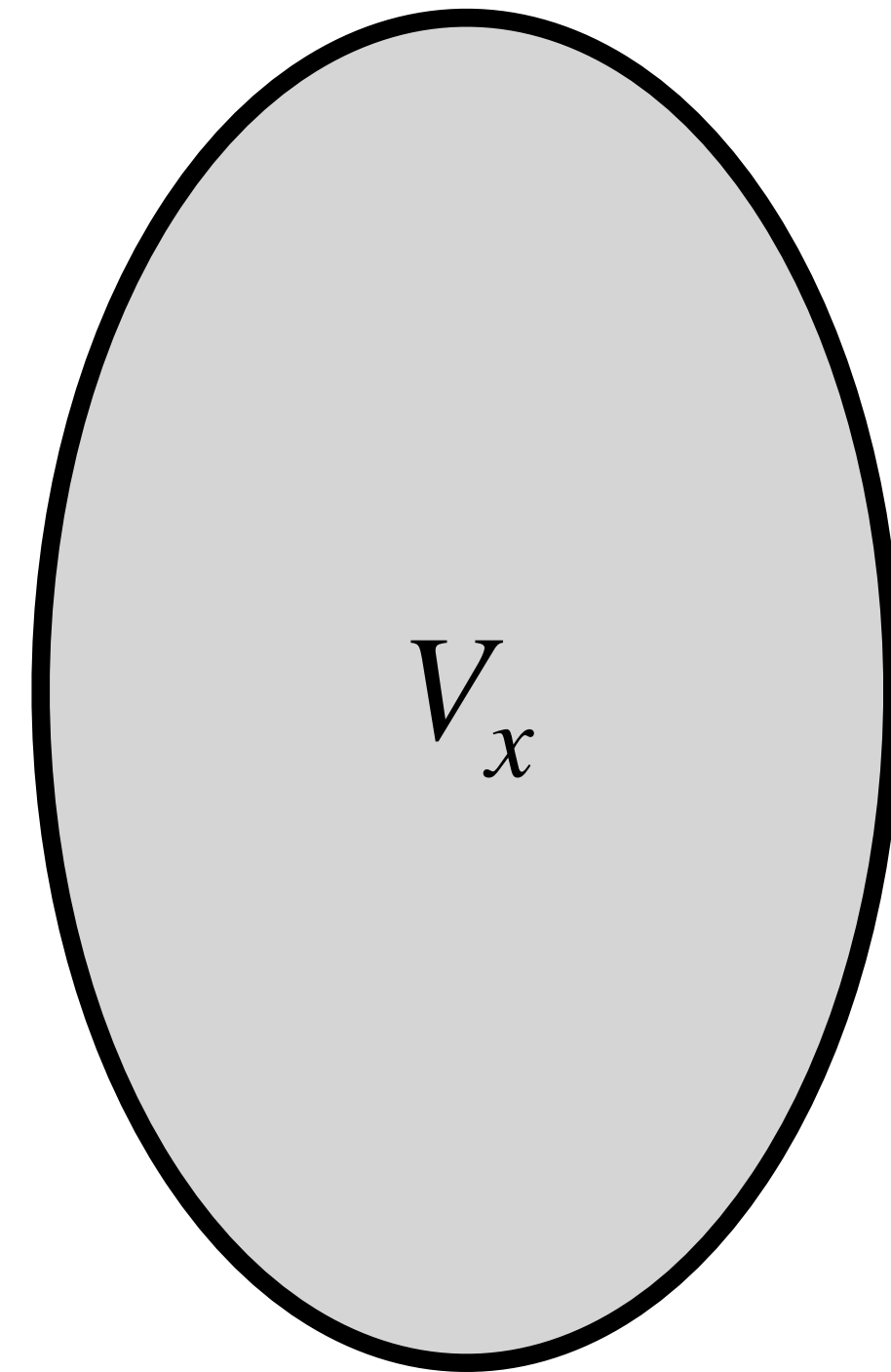


Bob

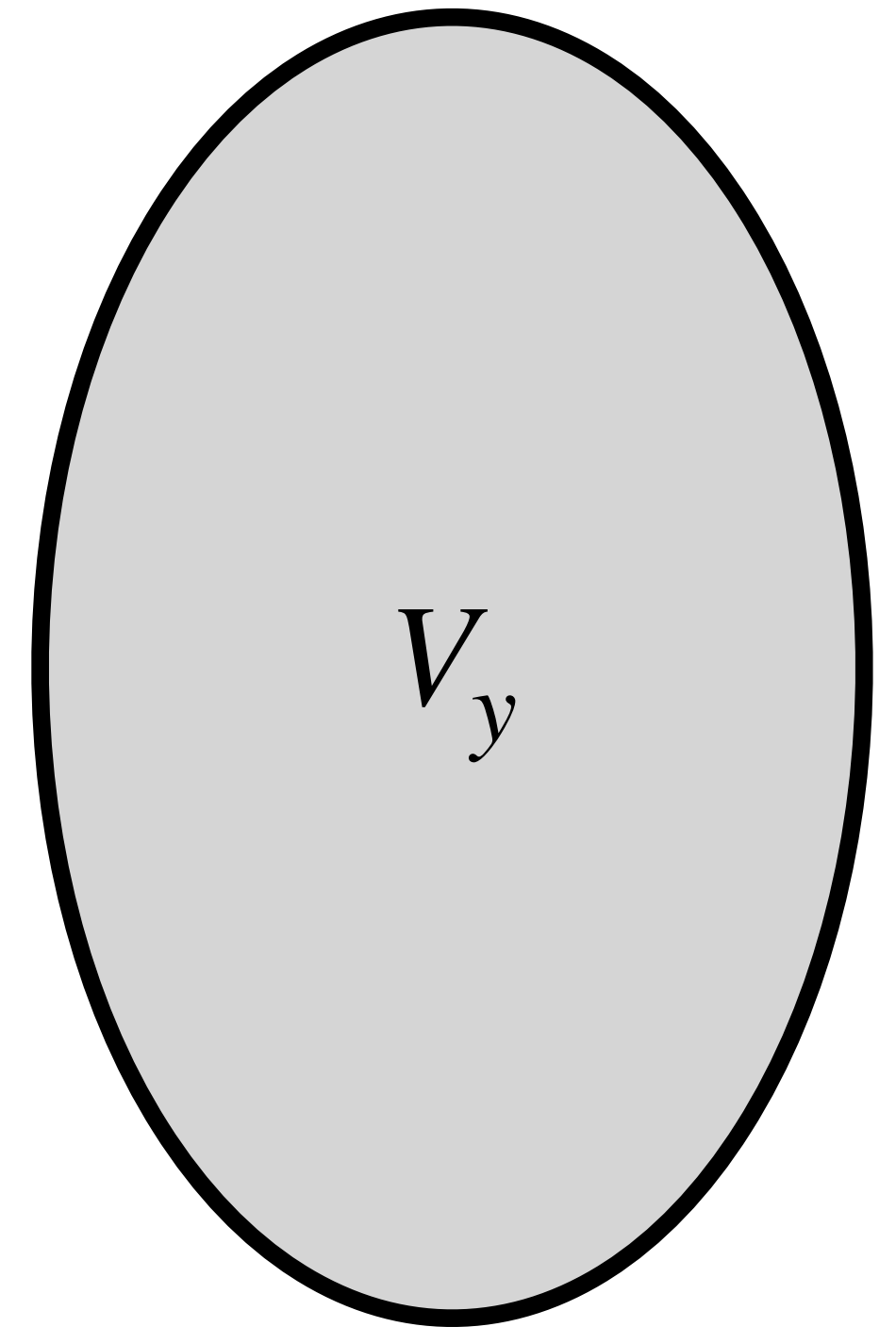


Message Lower Bound?

Alice

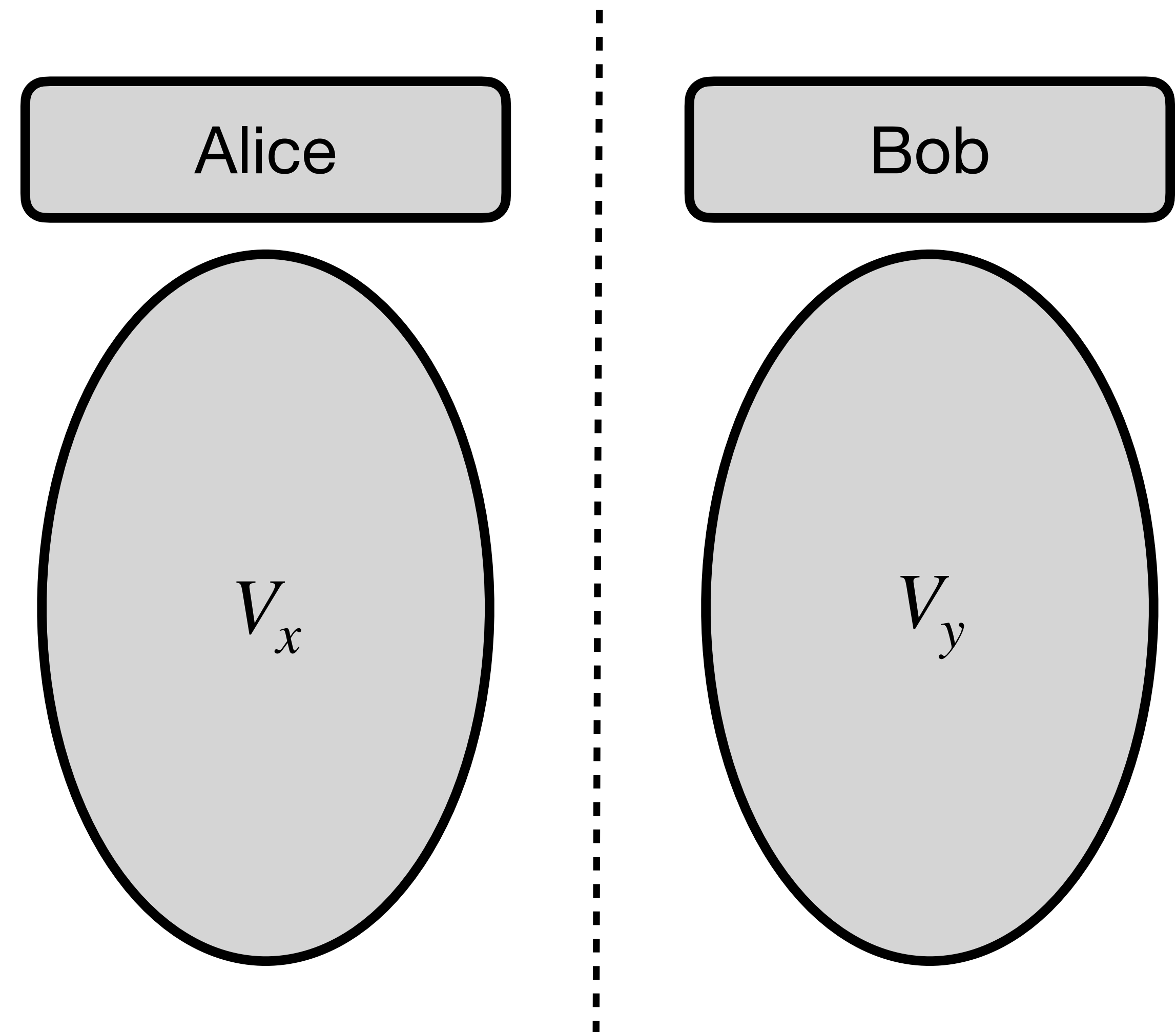


Bob



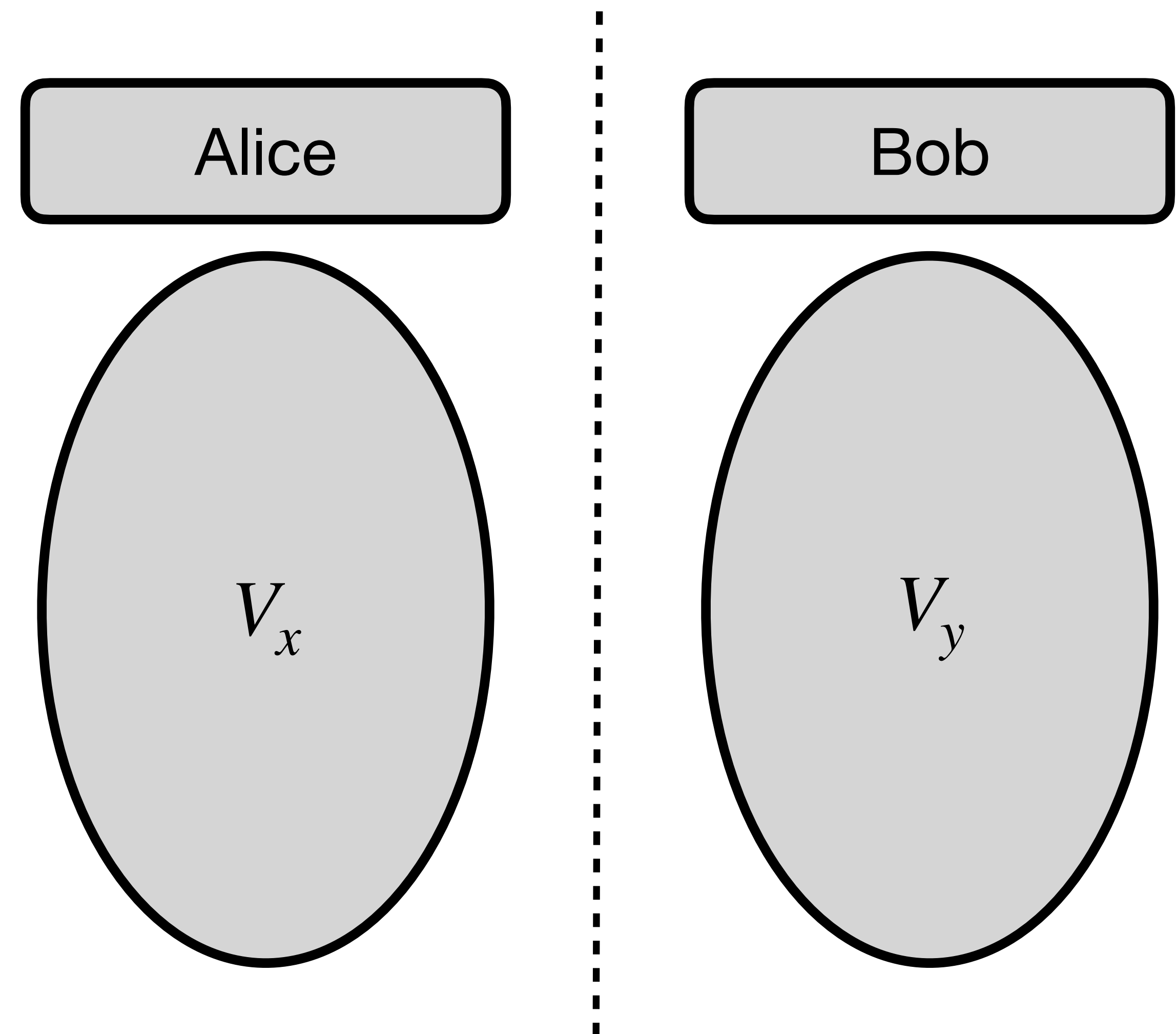
Message Lower Bound?

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Message Lower Bound?

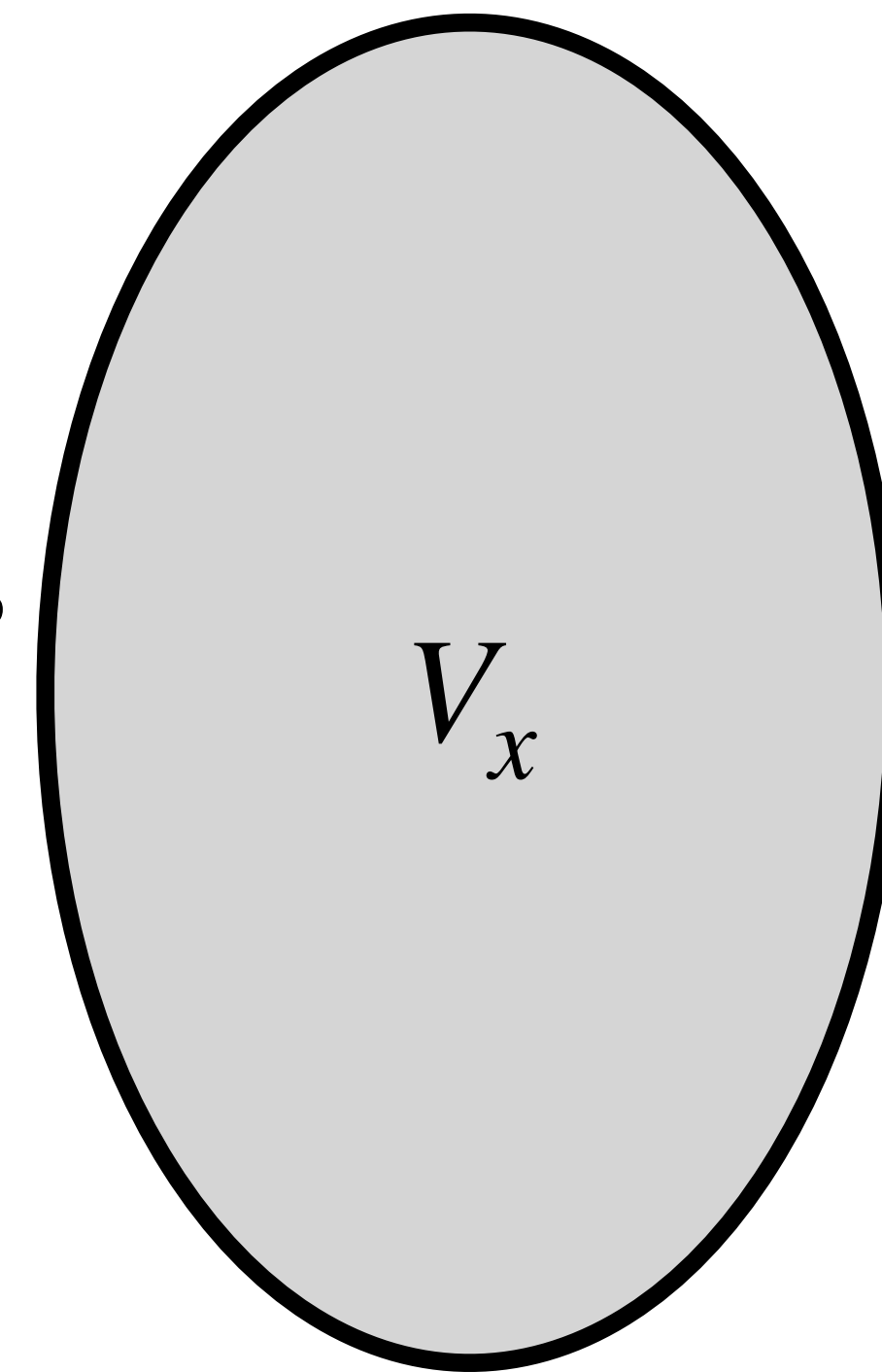
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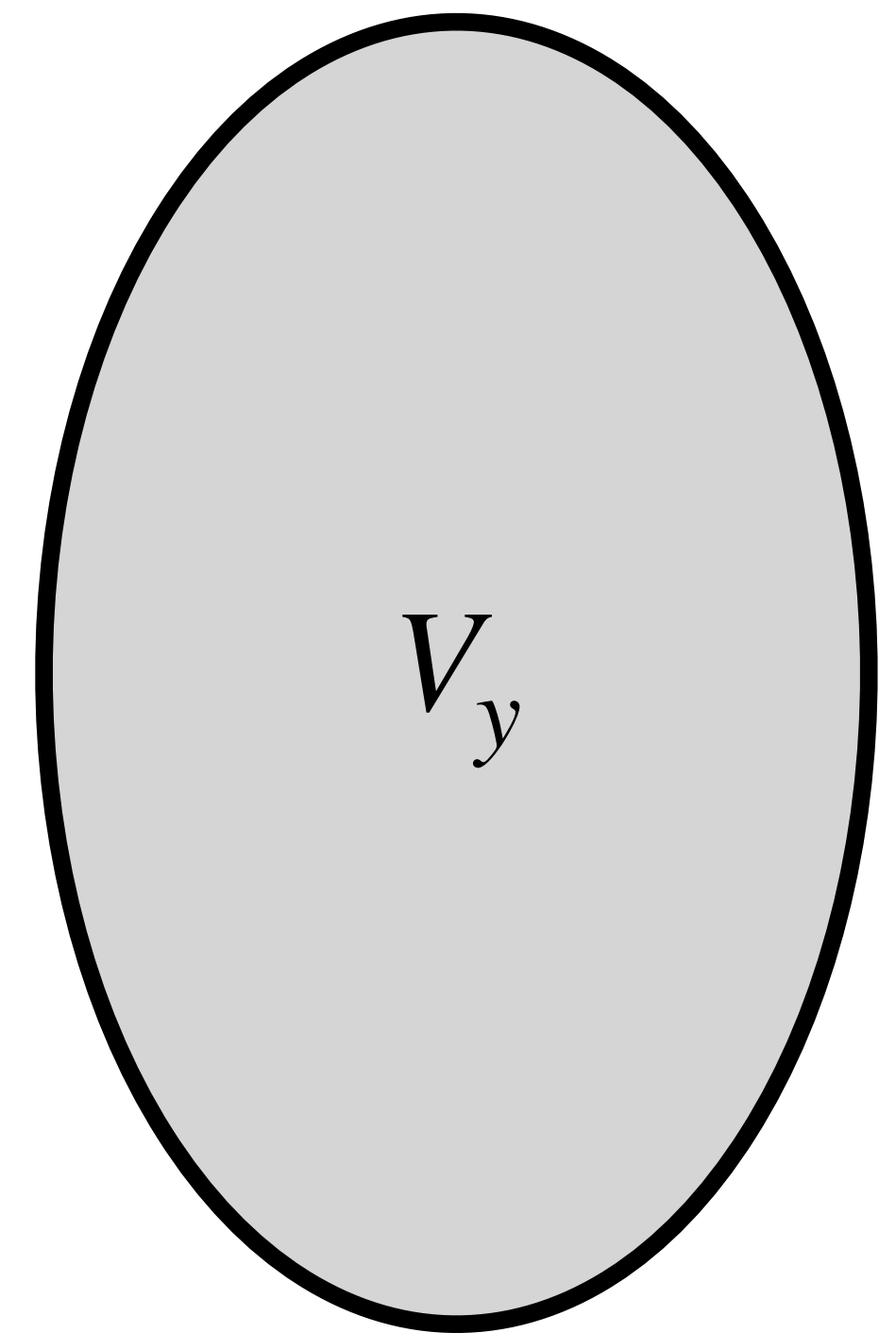
Message Lower Bound?

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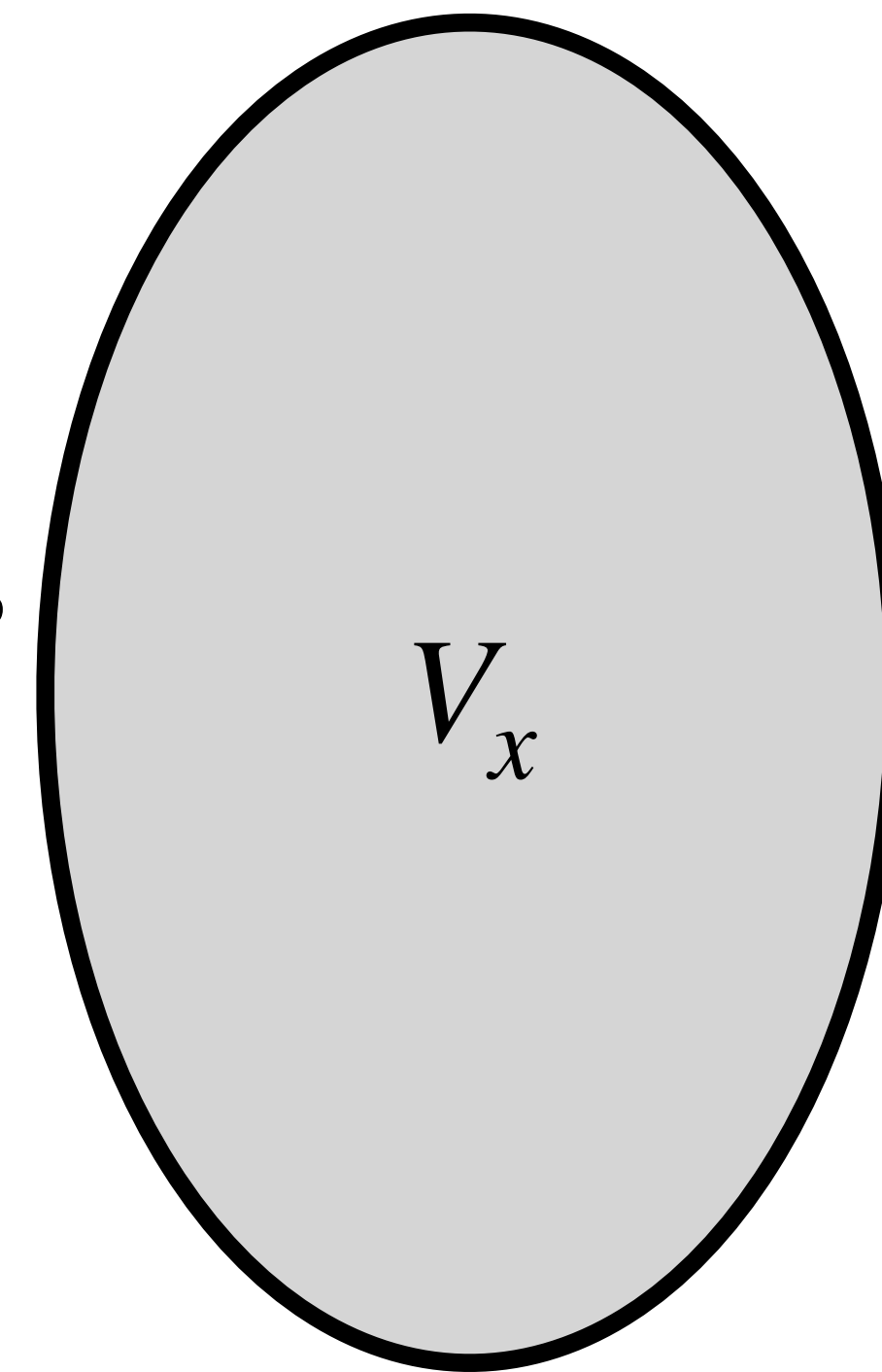
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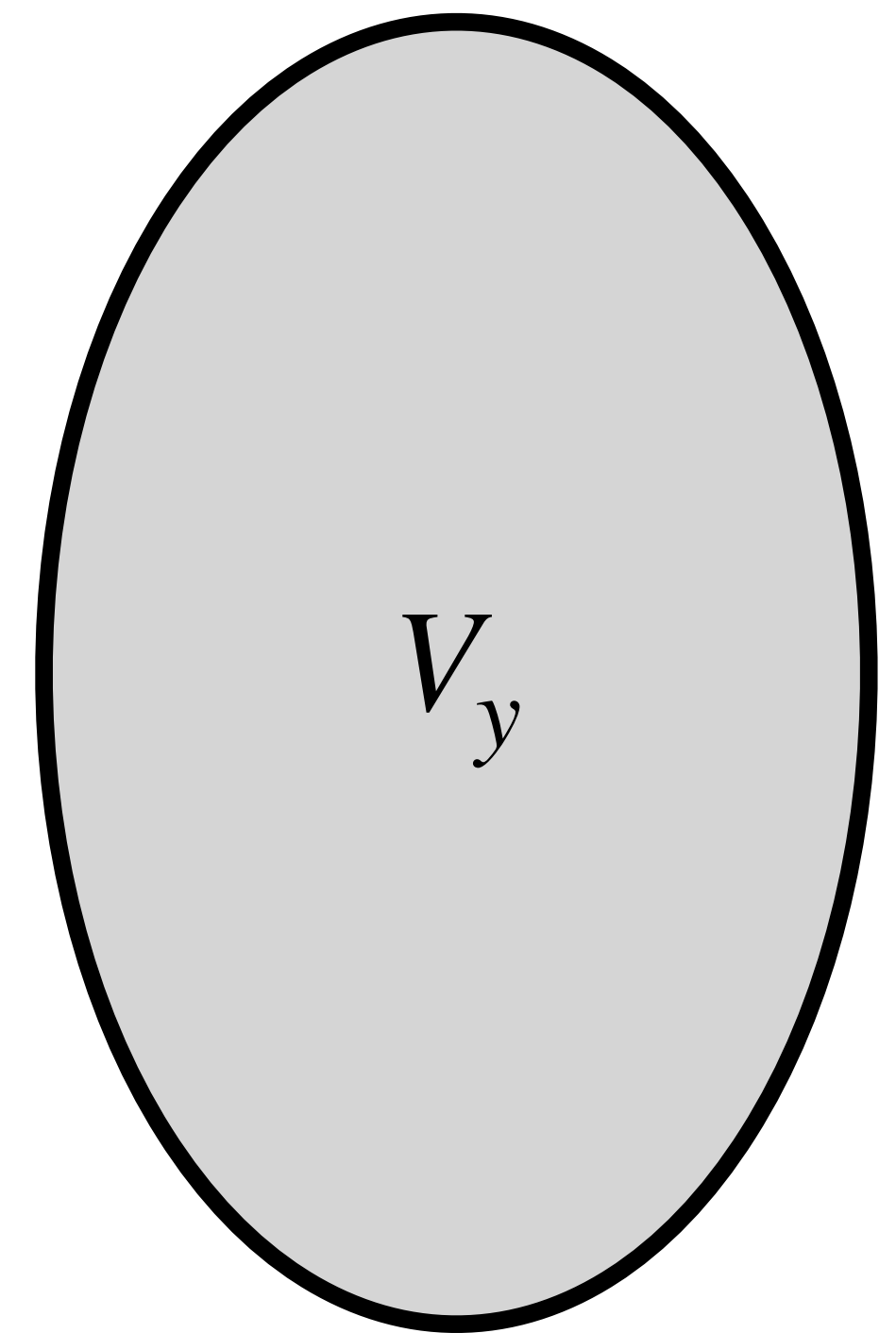
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Alice



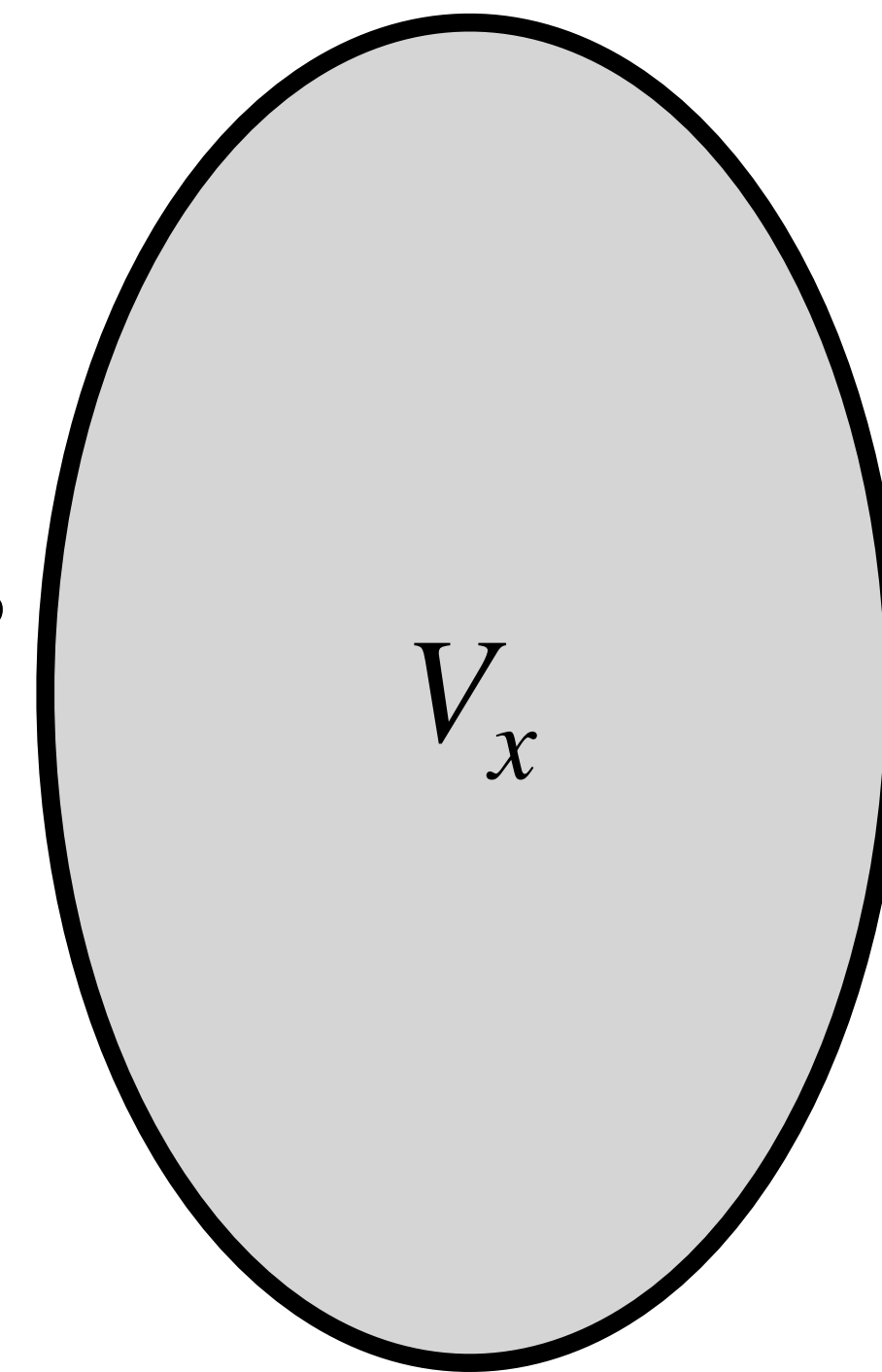
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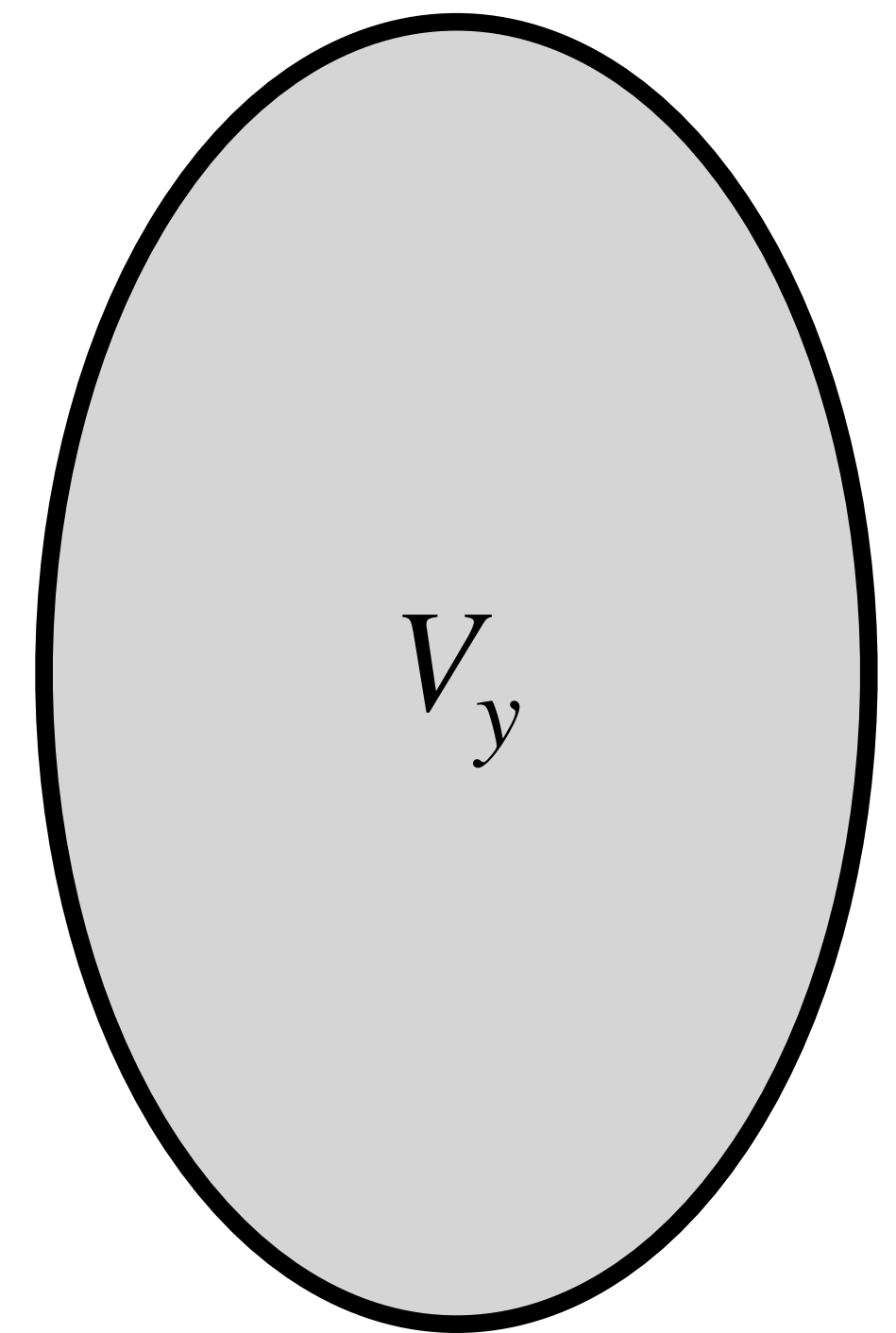
Message Lower Bound?

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 - Need $o(n^2)$ round budget.
 - Can we do better?

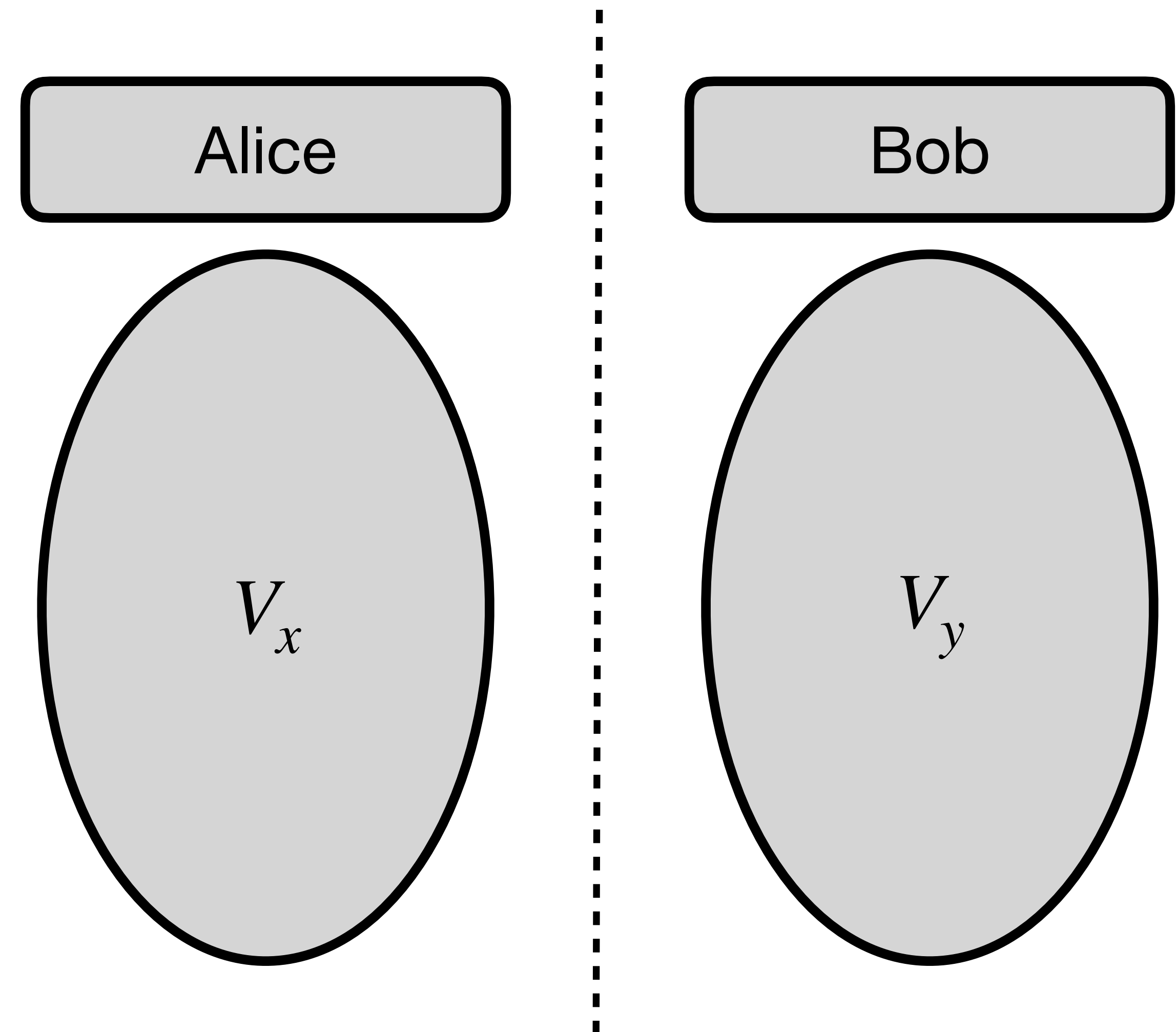
Alice



Bob



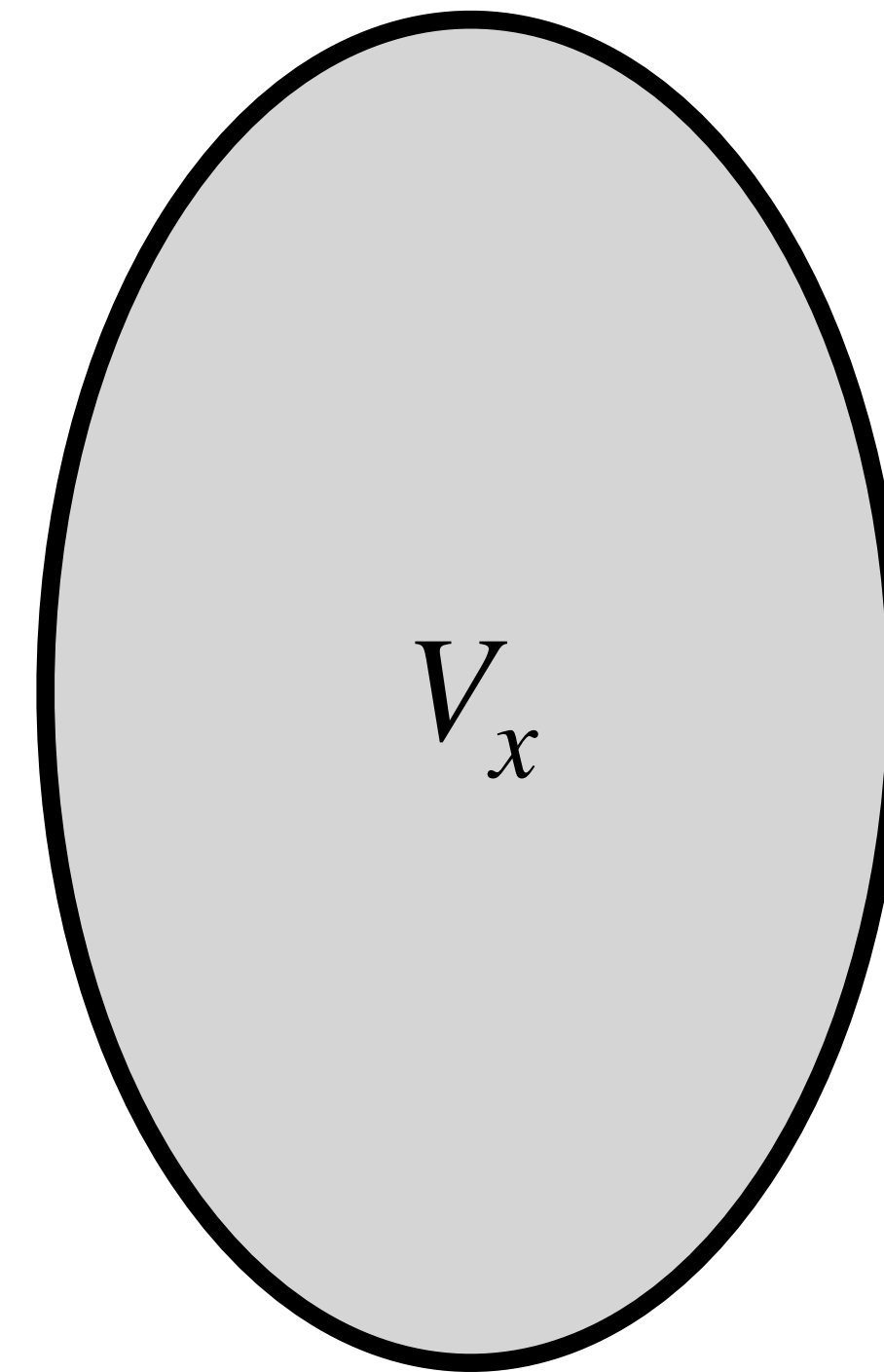
Synchronous CC



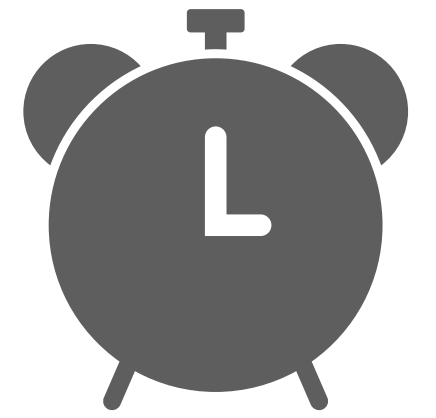
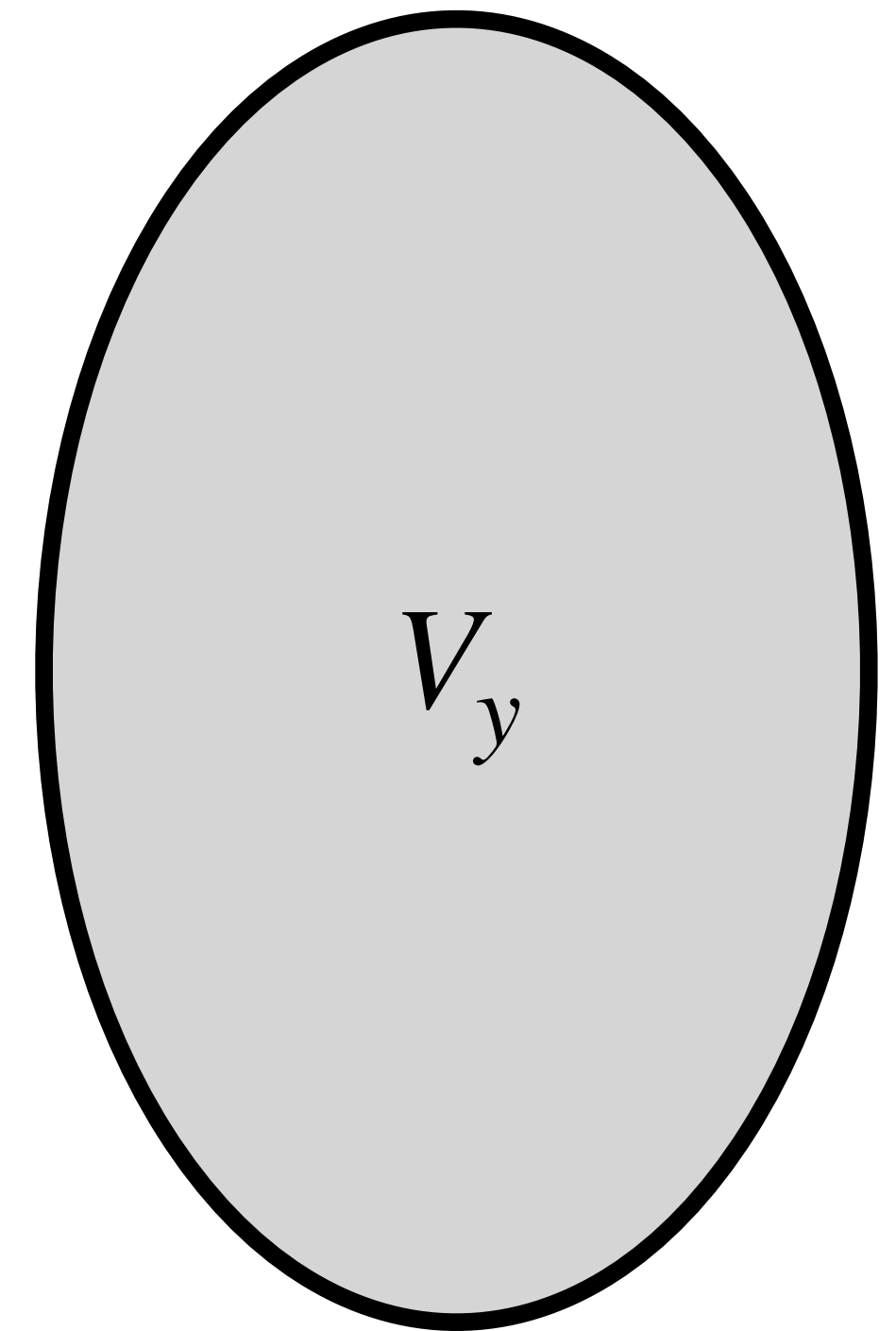
Synchronous CC

- If Alice and Bob had a clock, then they can simulate any R round CONGEST algorithm.

Alice



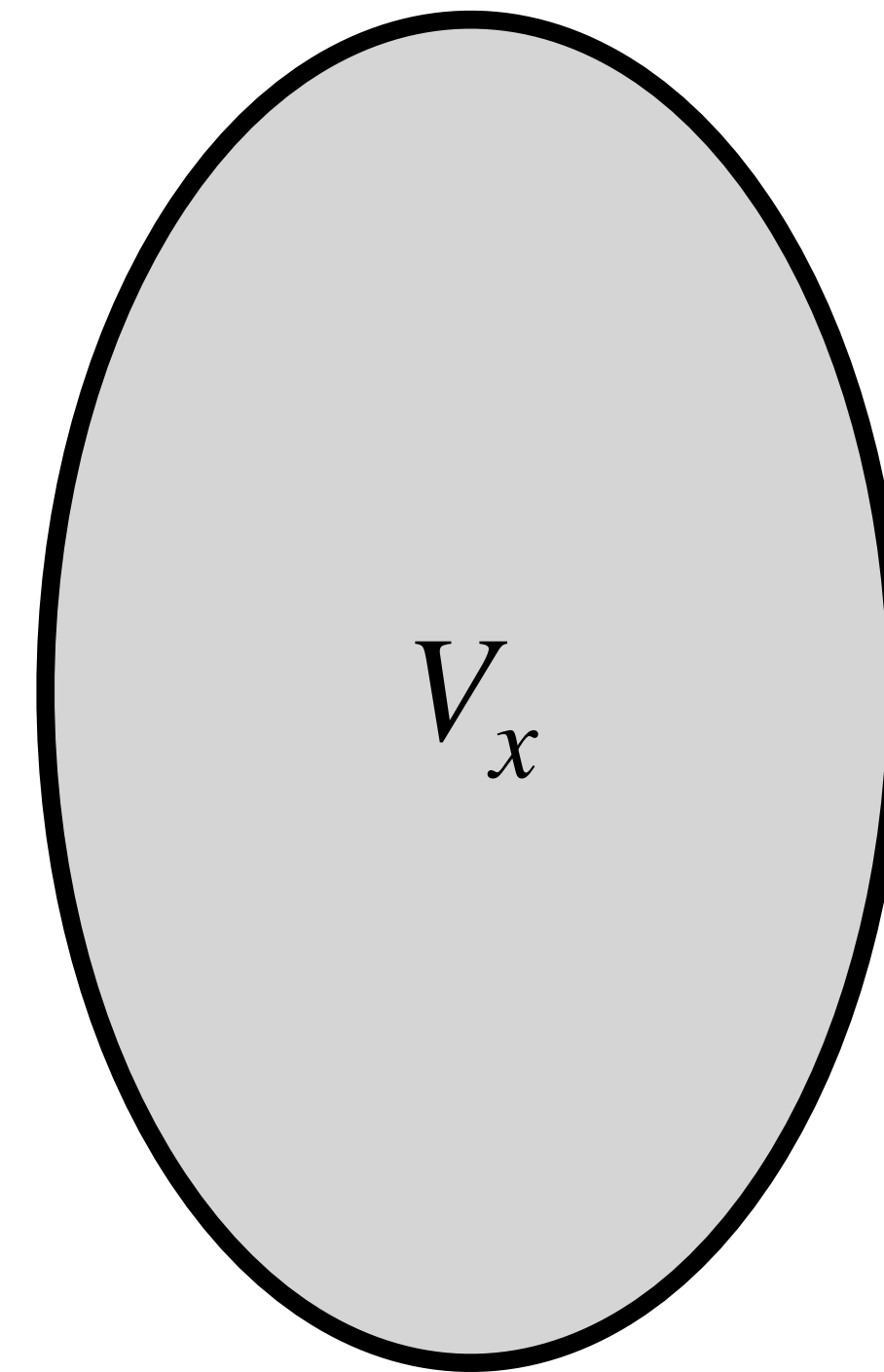
Bob



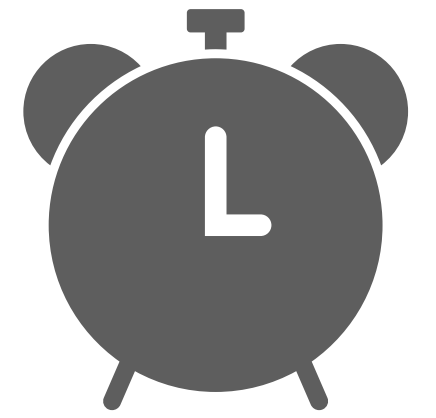
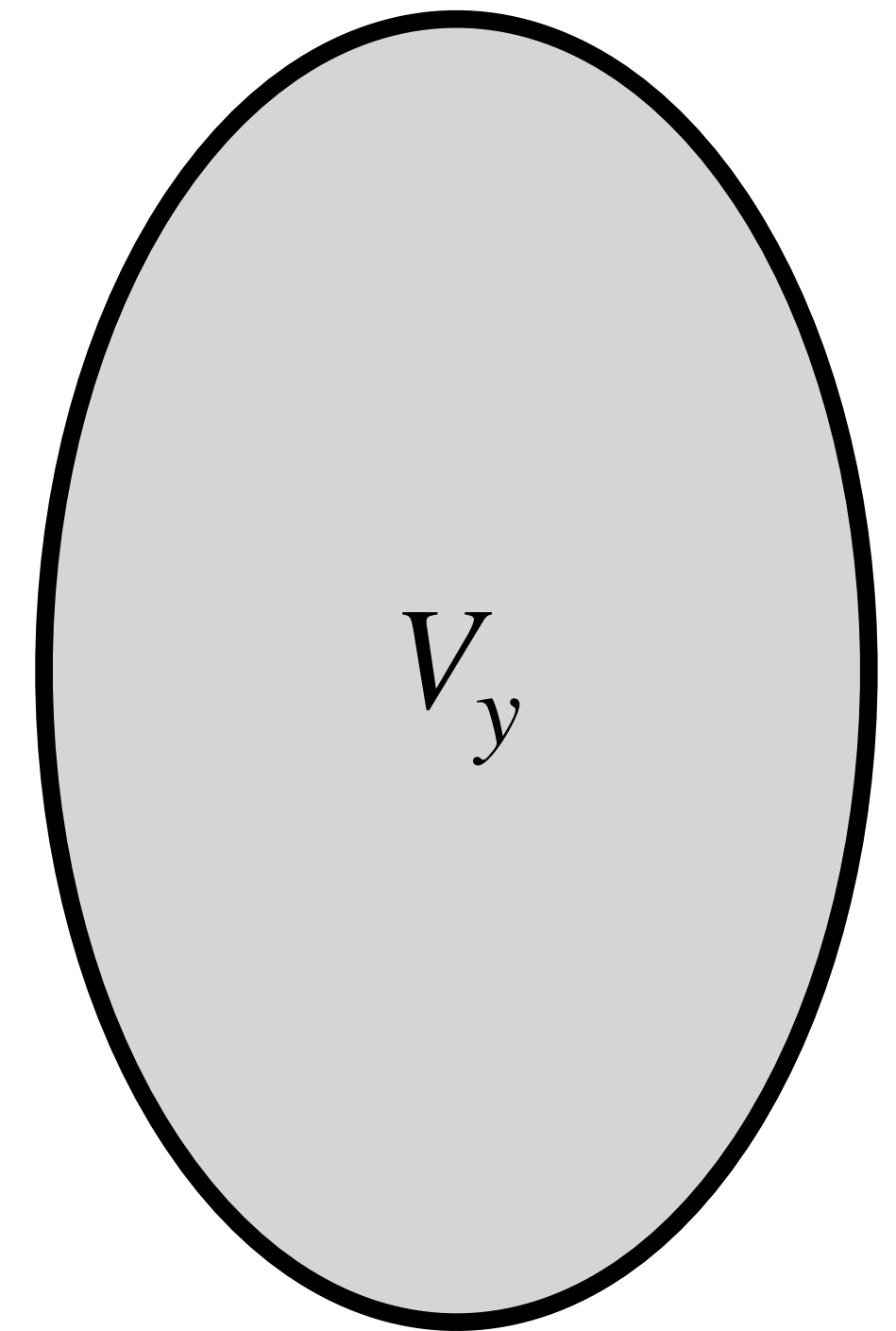
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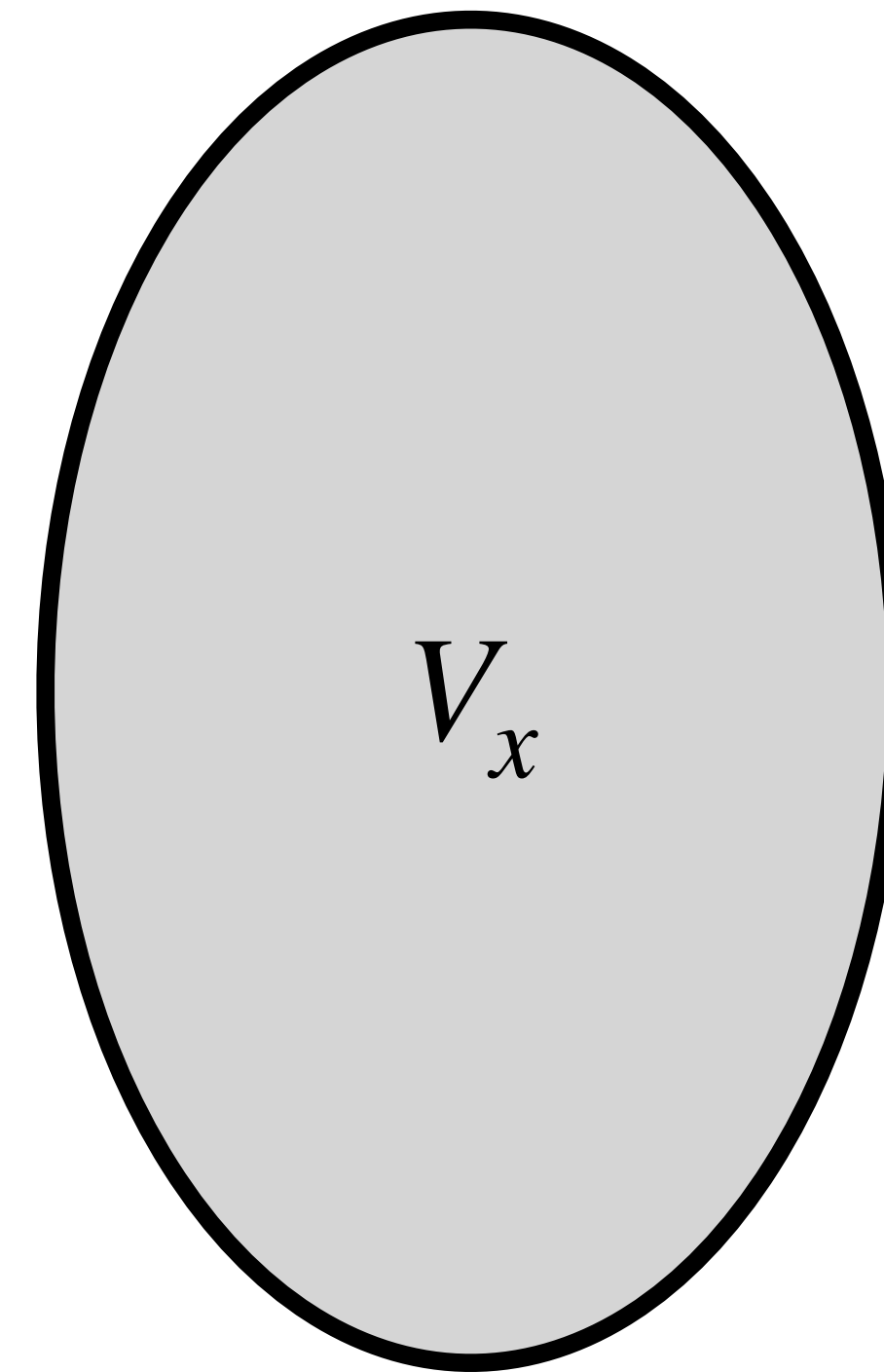
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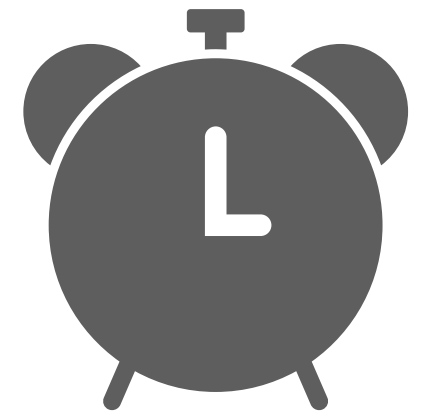
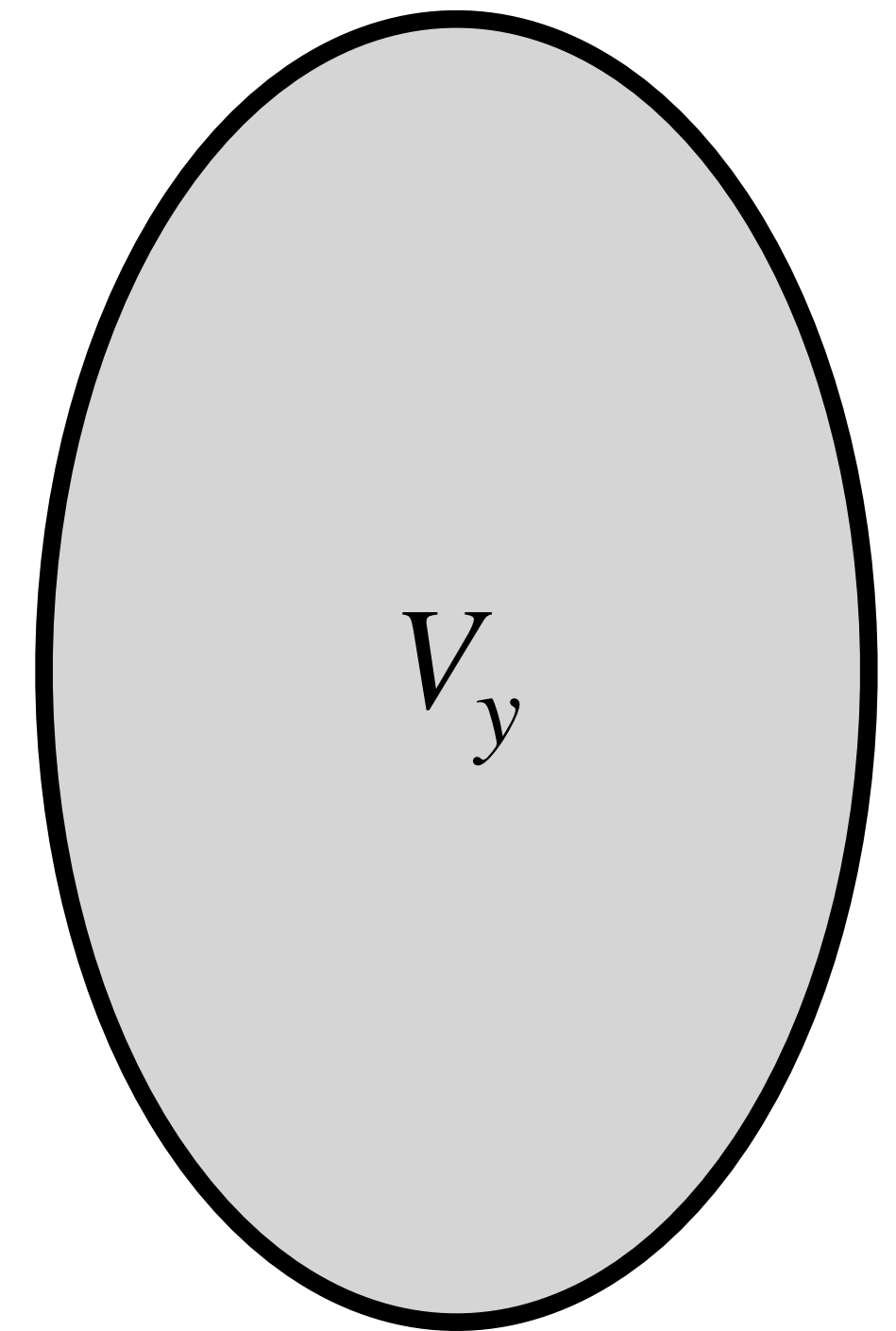
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- If Alice and Bob had a clock, then they can simulate any R round CONGEST algorithm.
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- How strong are the lower bounds for synchronous communication complexity?

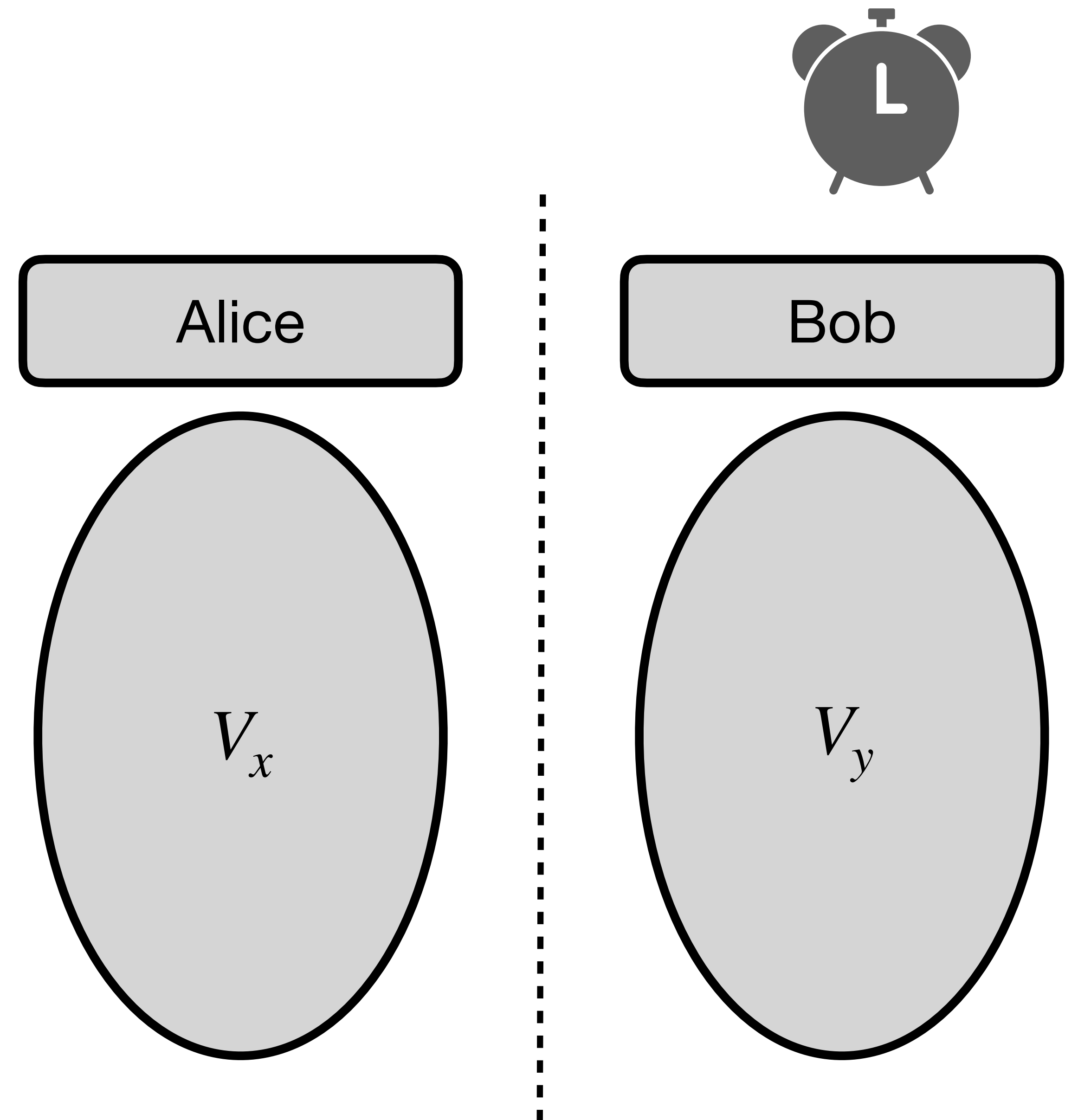
Alice



Bob



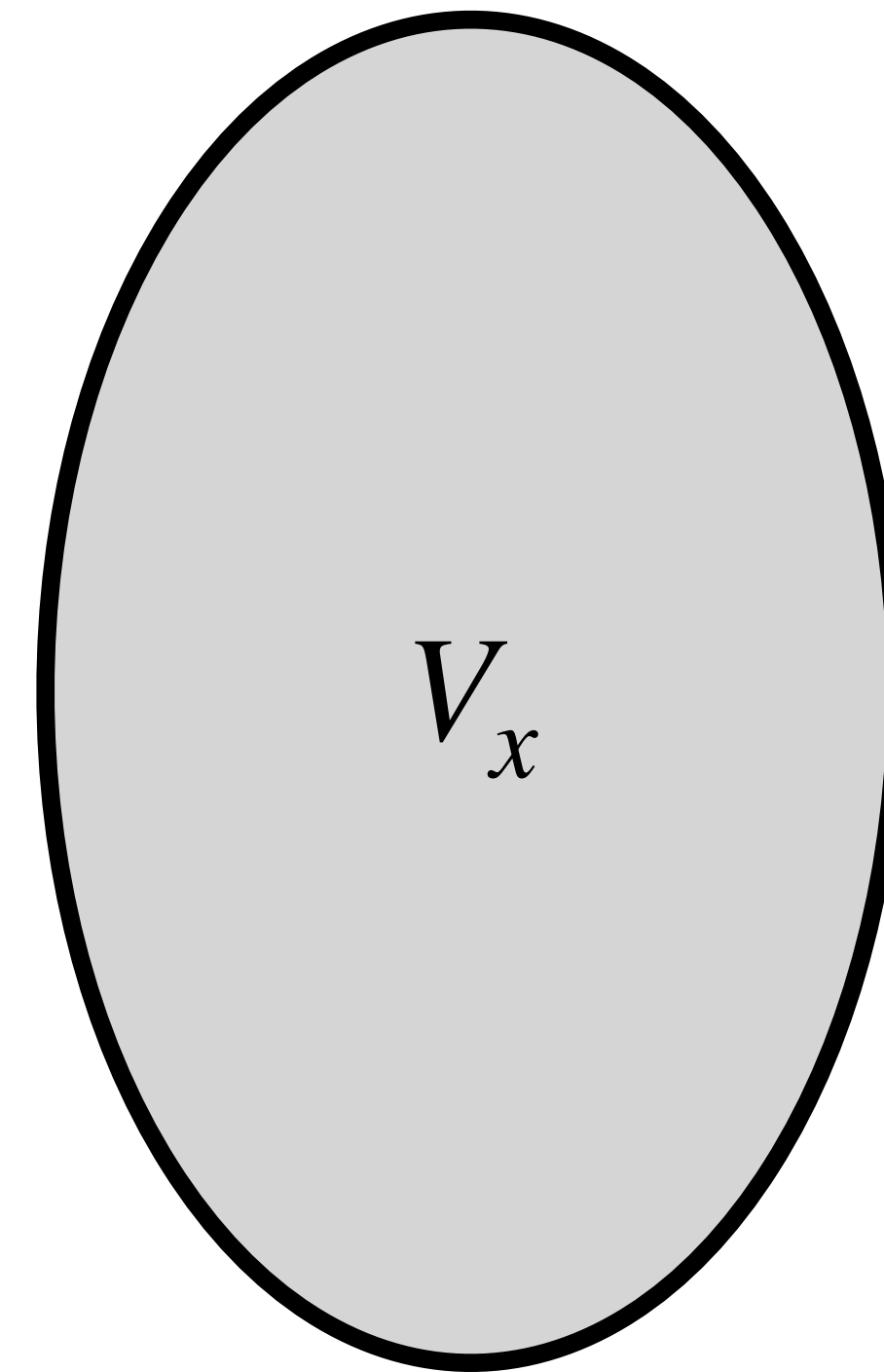
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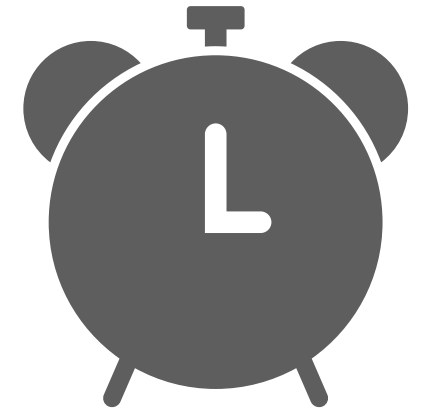
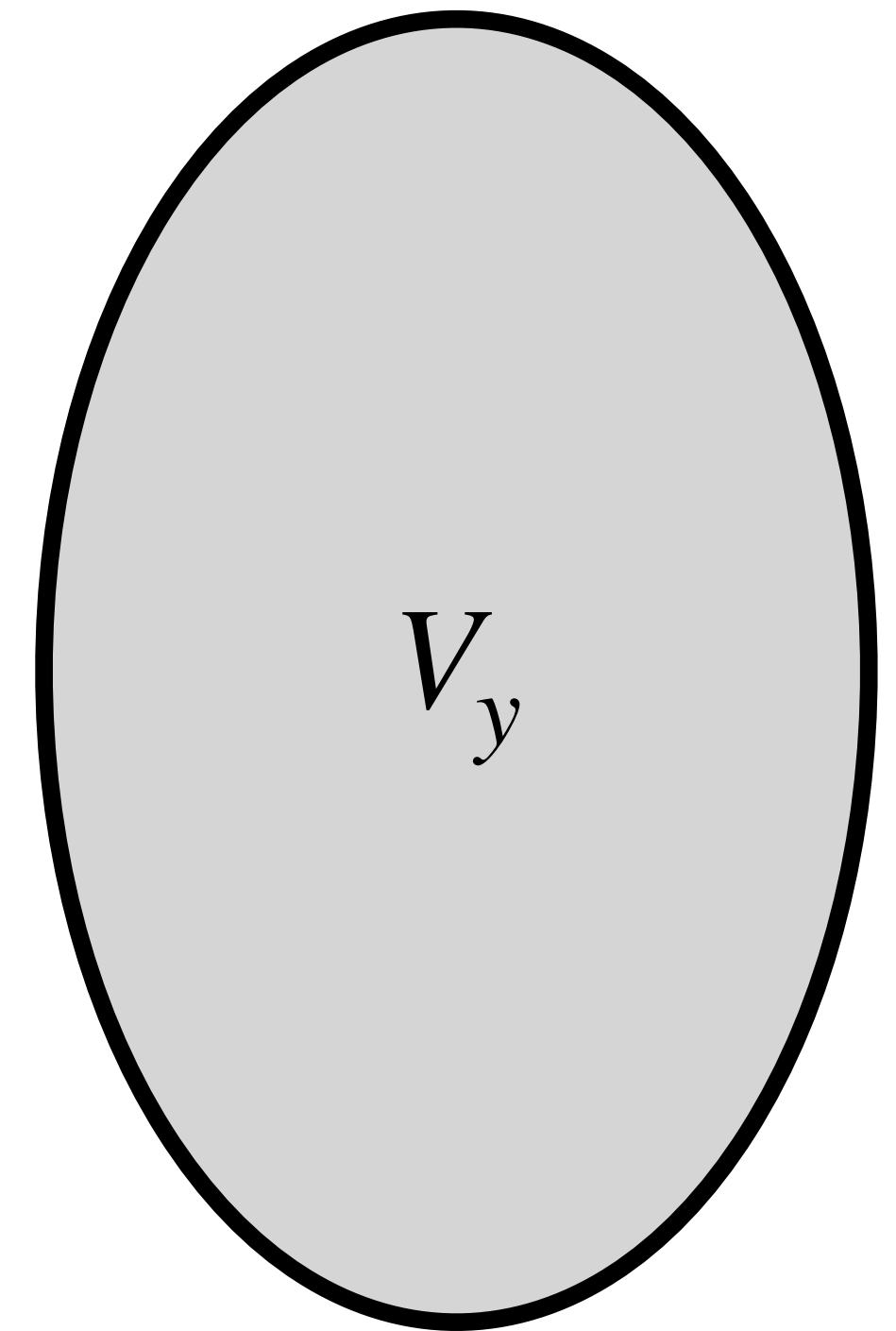
Synchronous CC

- [PPS20] give a message efficient synchronizer for clique networks which implies:

Alice



Bob



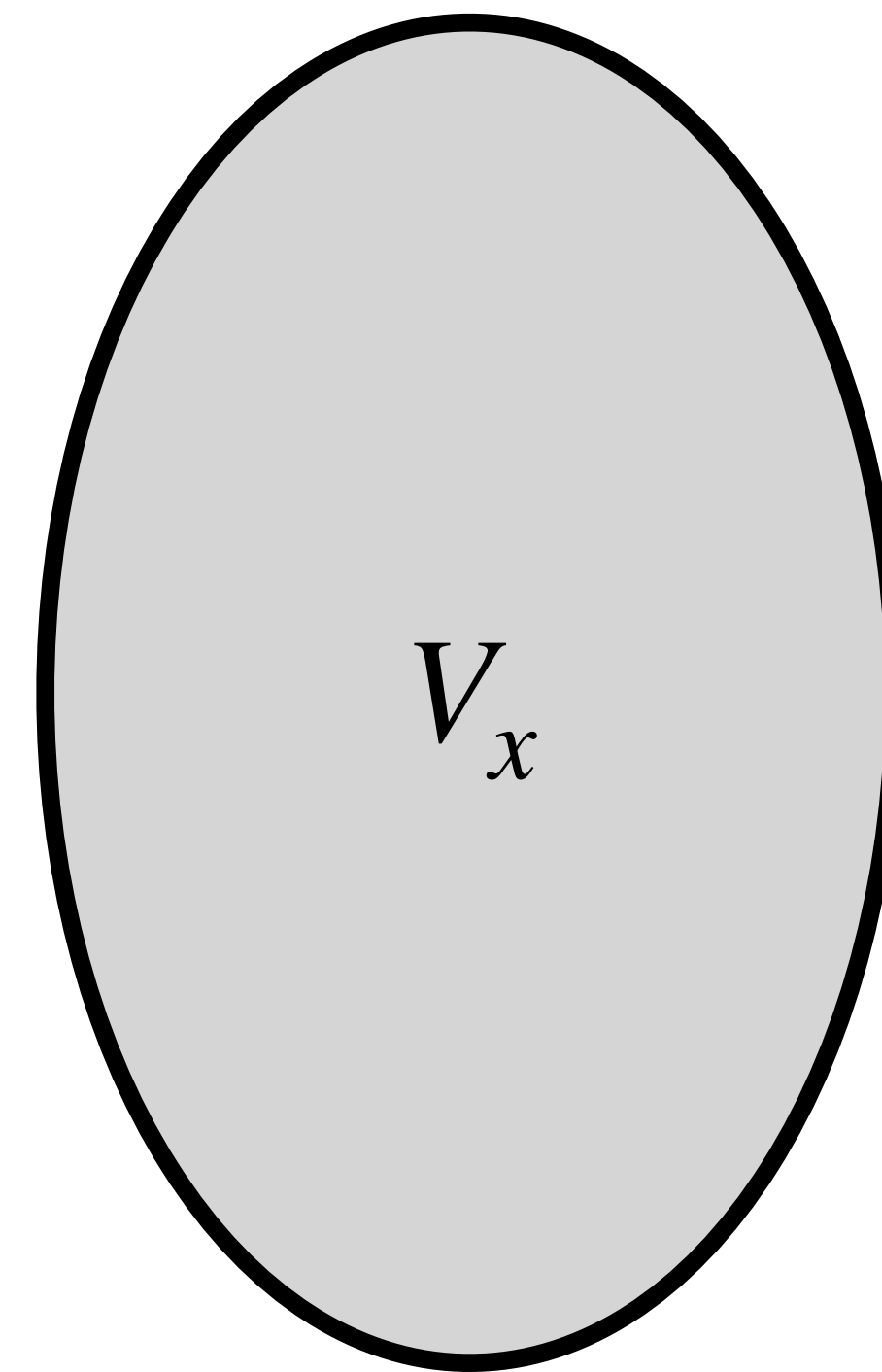
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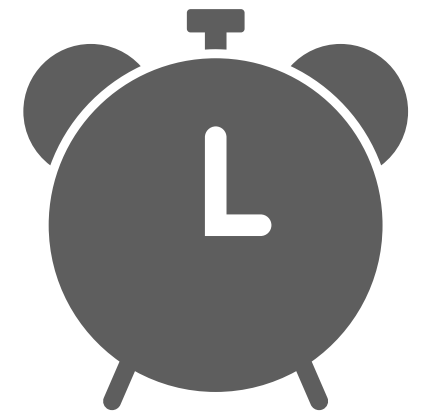
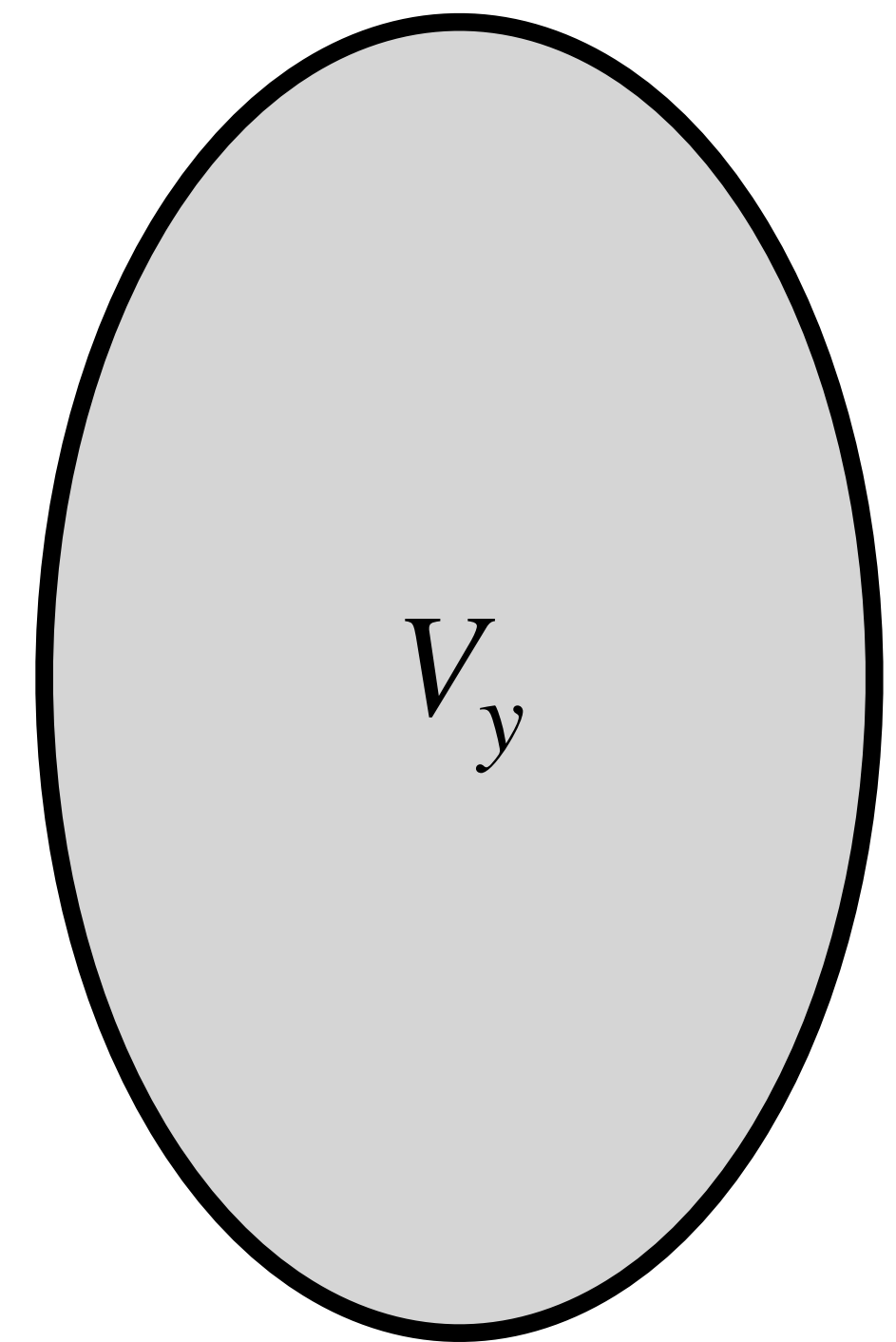
$$SCC_r(f) \geq \Omega \left(\frac{CC(f)}{1 + \log r} \right)$$

[PPS20] Pandurangan, Peleg, Squizzato. TCS 2020

Alice



Bob

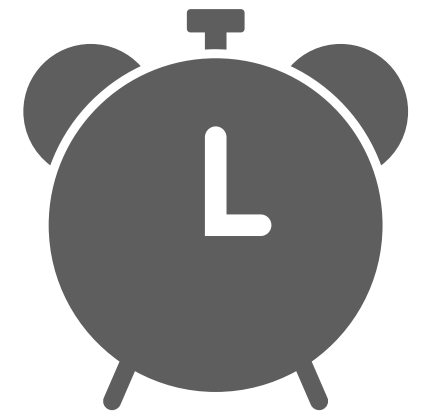


Synchronous CC

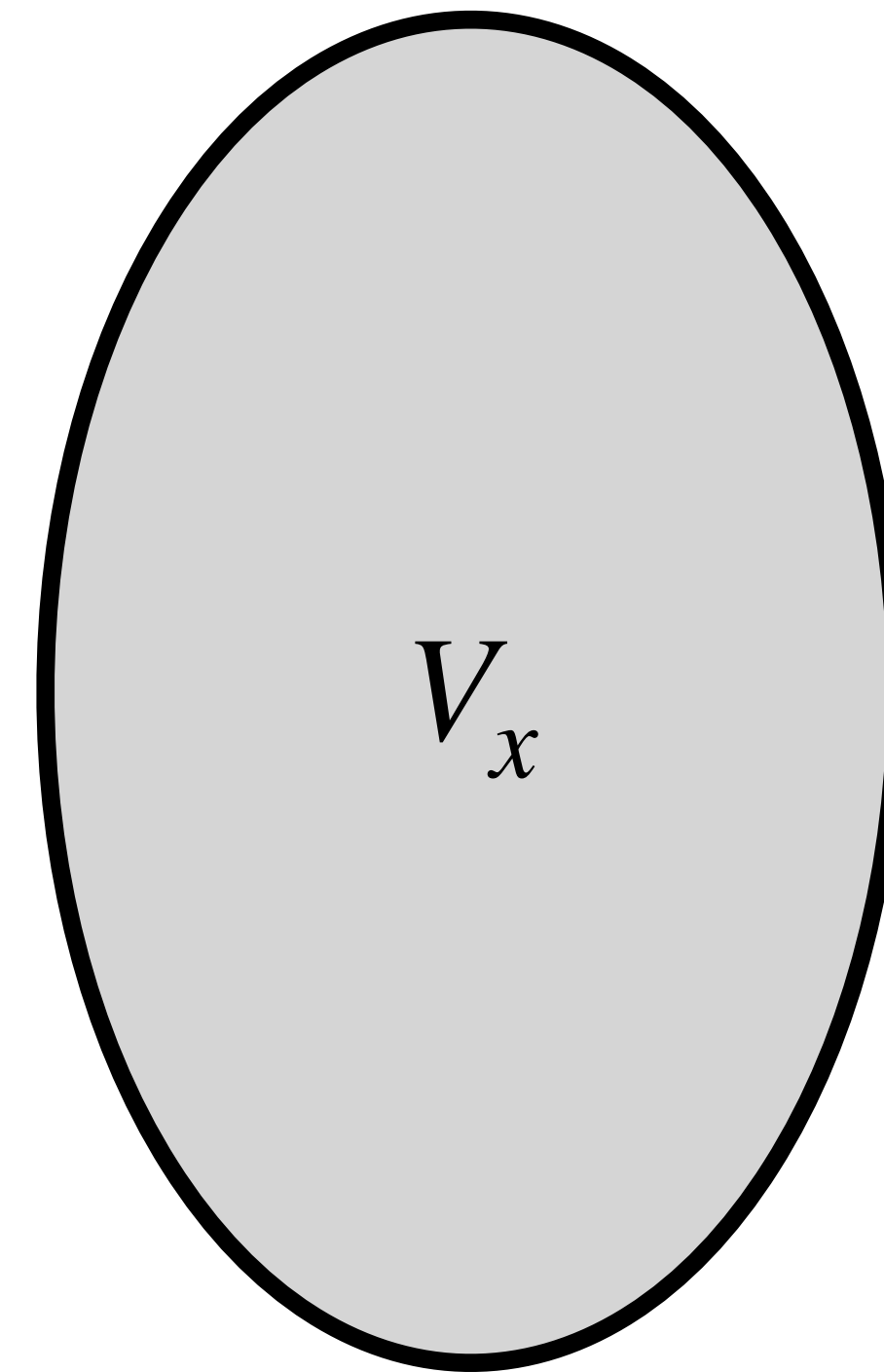
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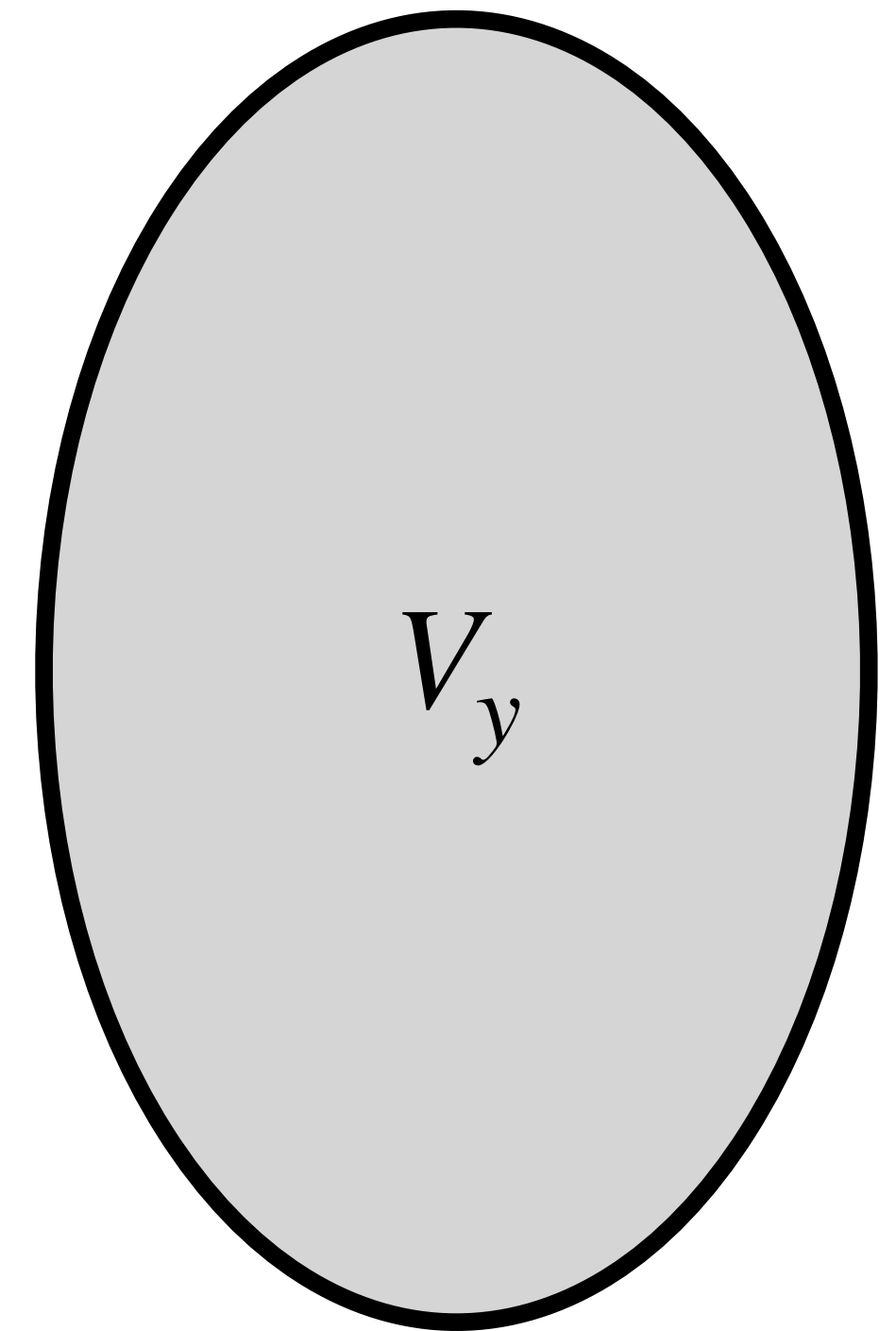
- So for poly(n) round algorithms we do not pay much.



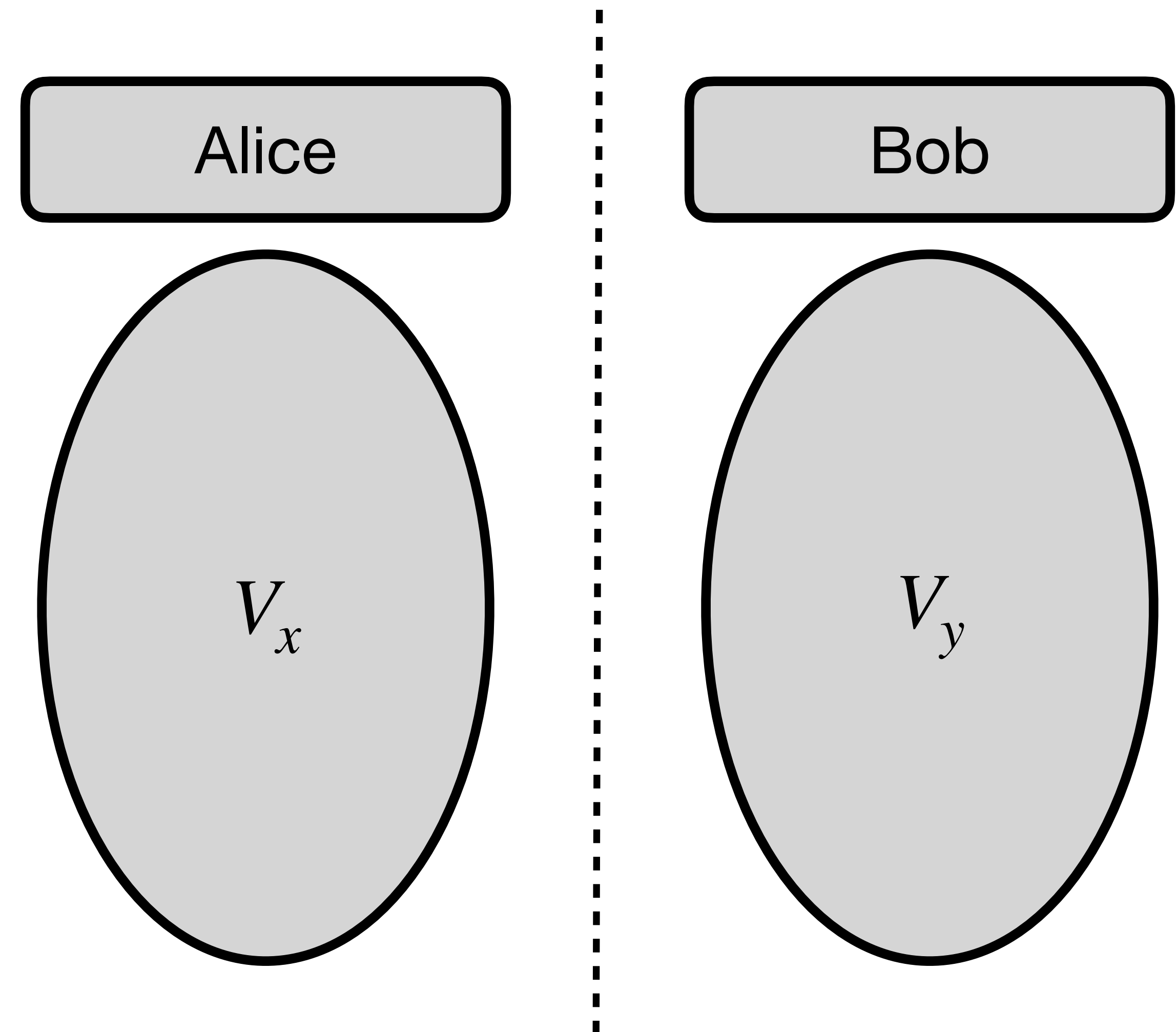
Alice



Bob

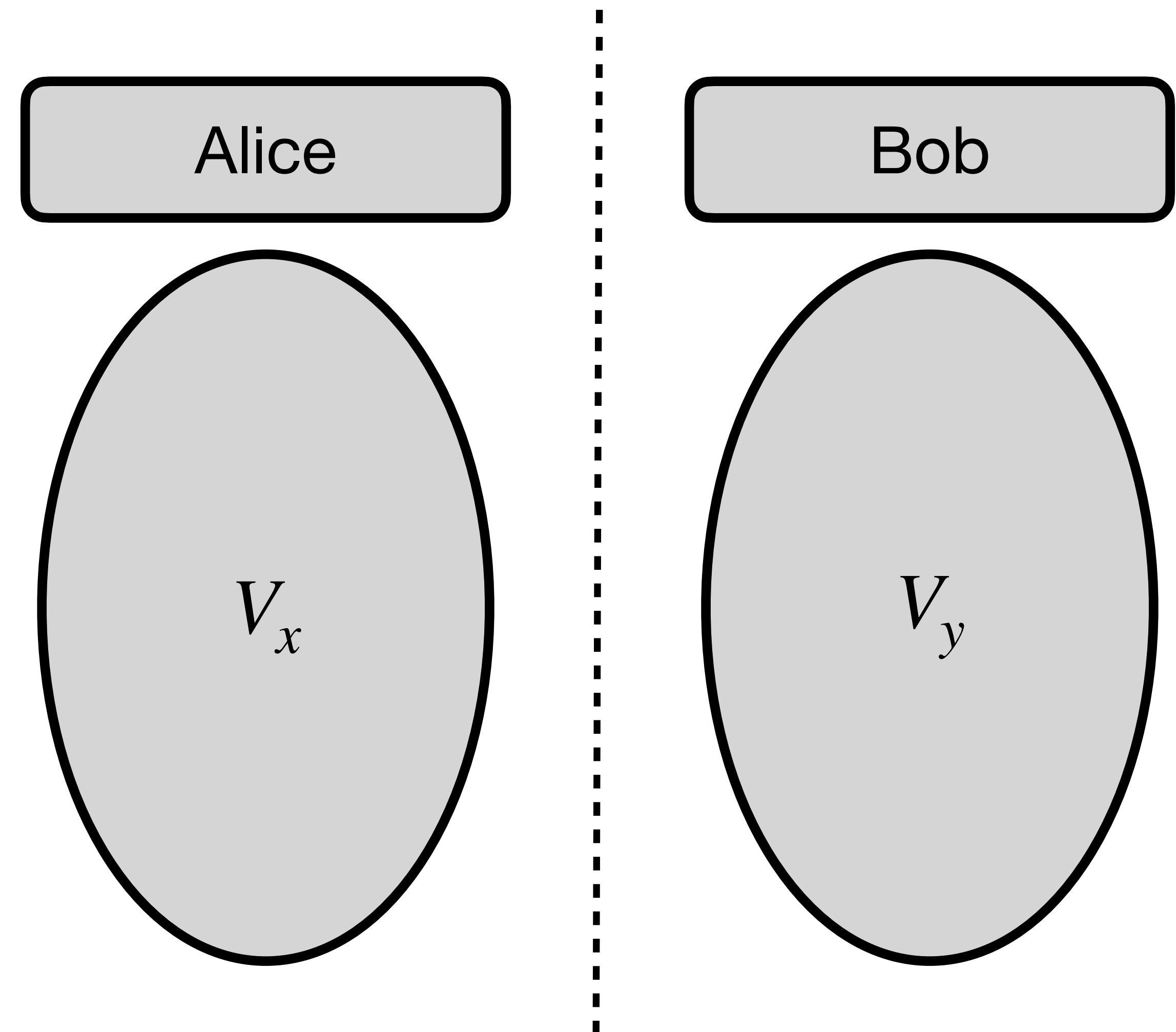


Message Complexity of MVC



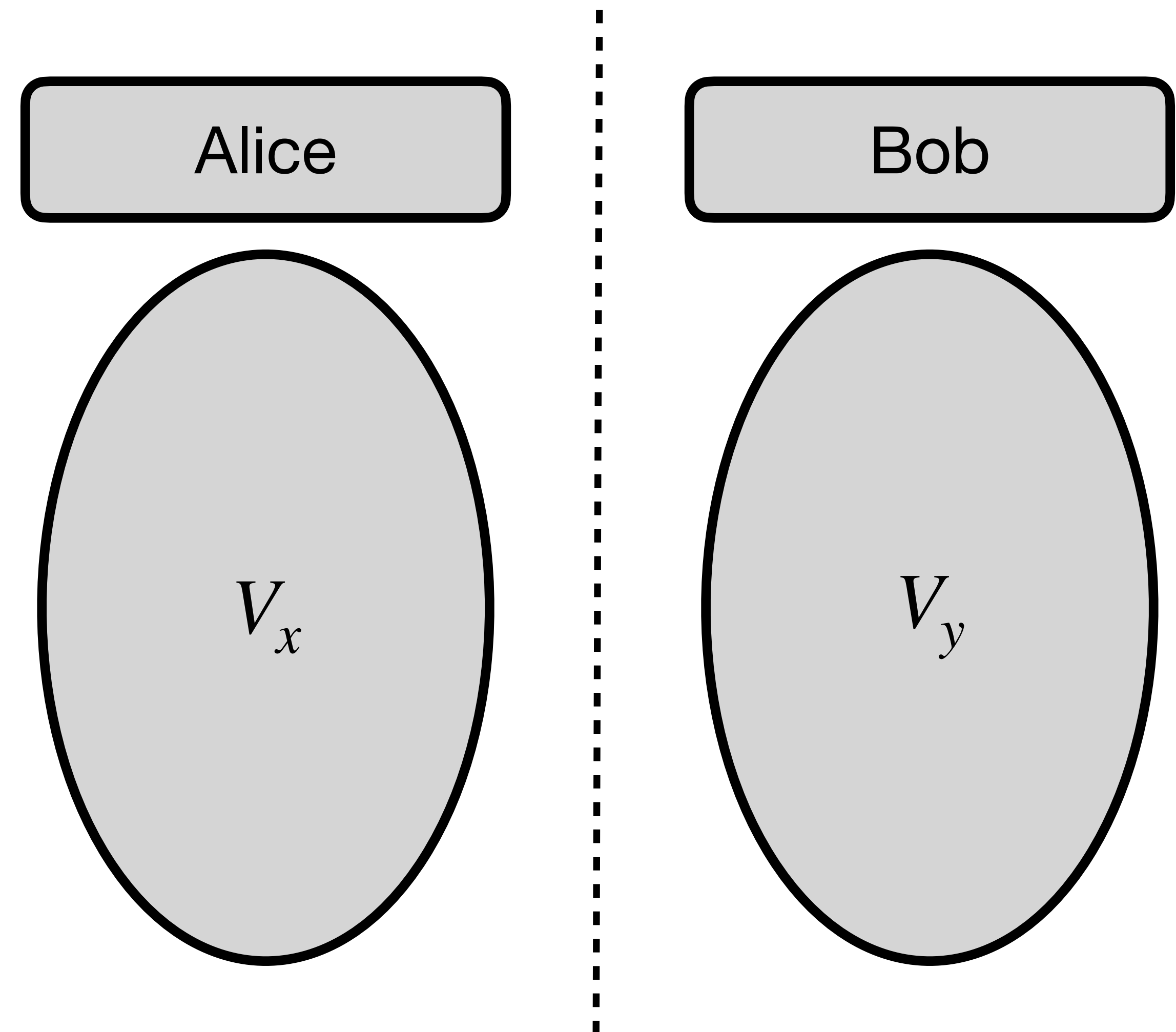
Message Complexity of MVC

- Any $\text{poly}(n)$ round CONGEST algorithm requires $\tilde{\Omega}(n^2)$ messages.



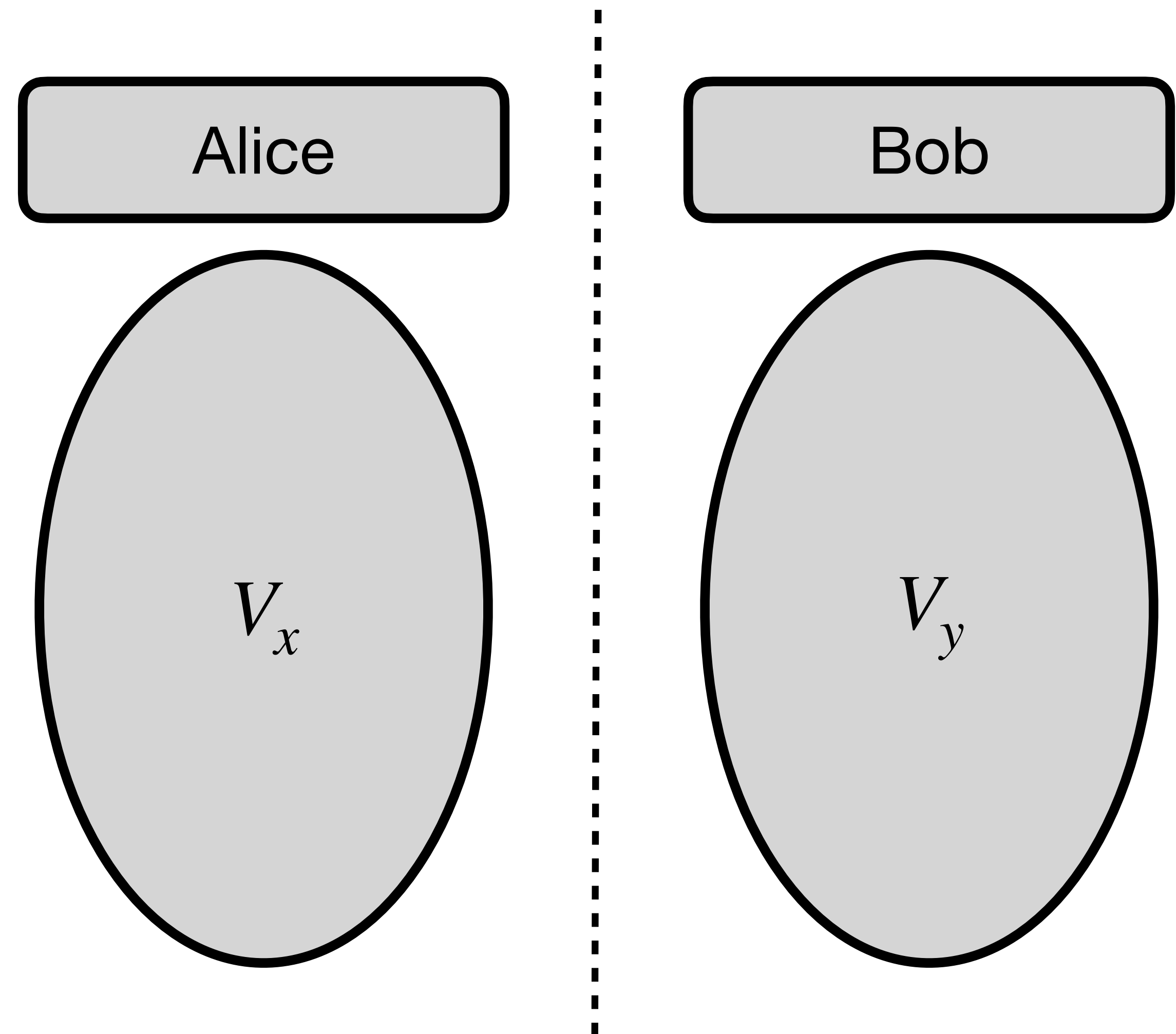
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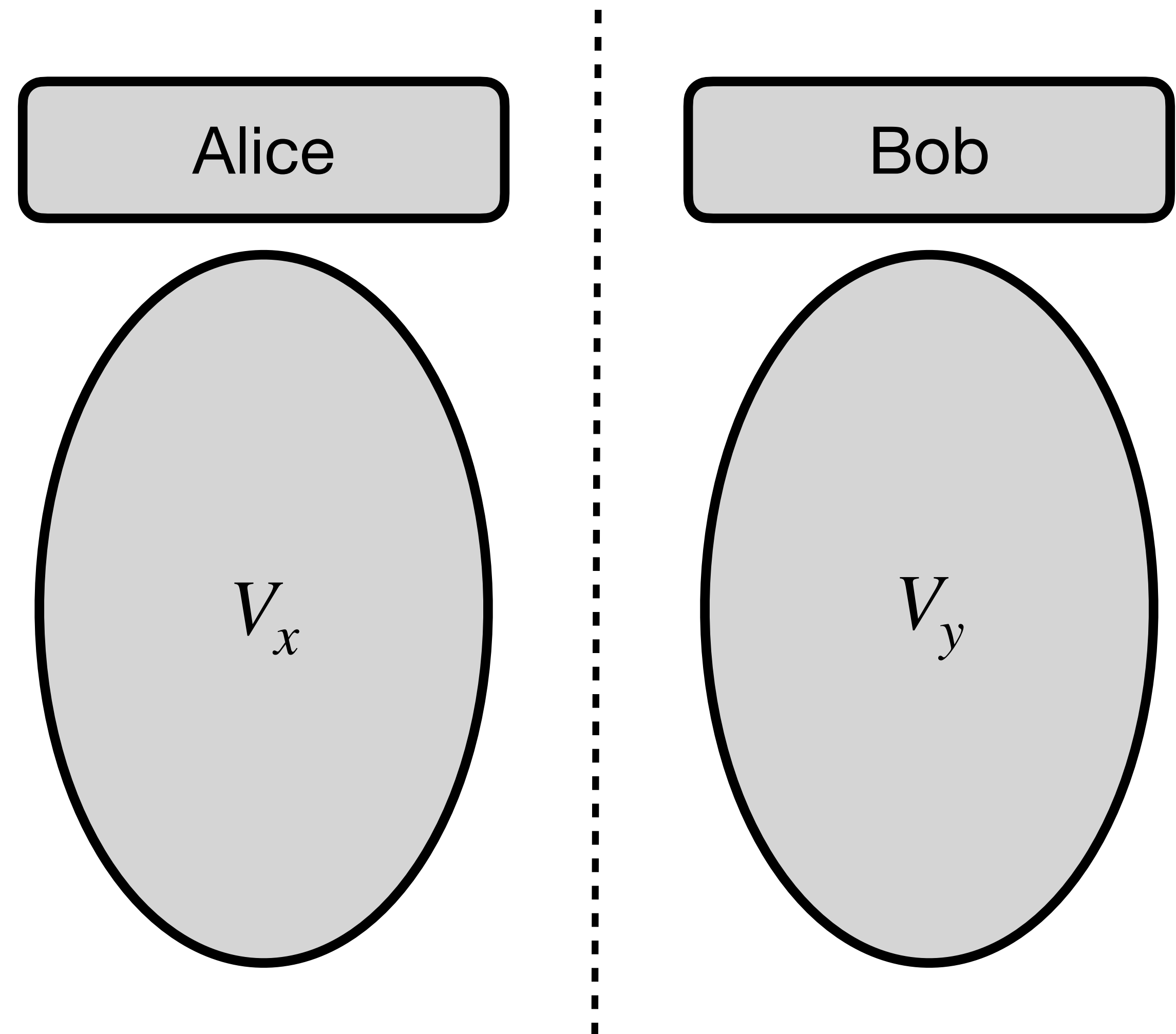
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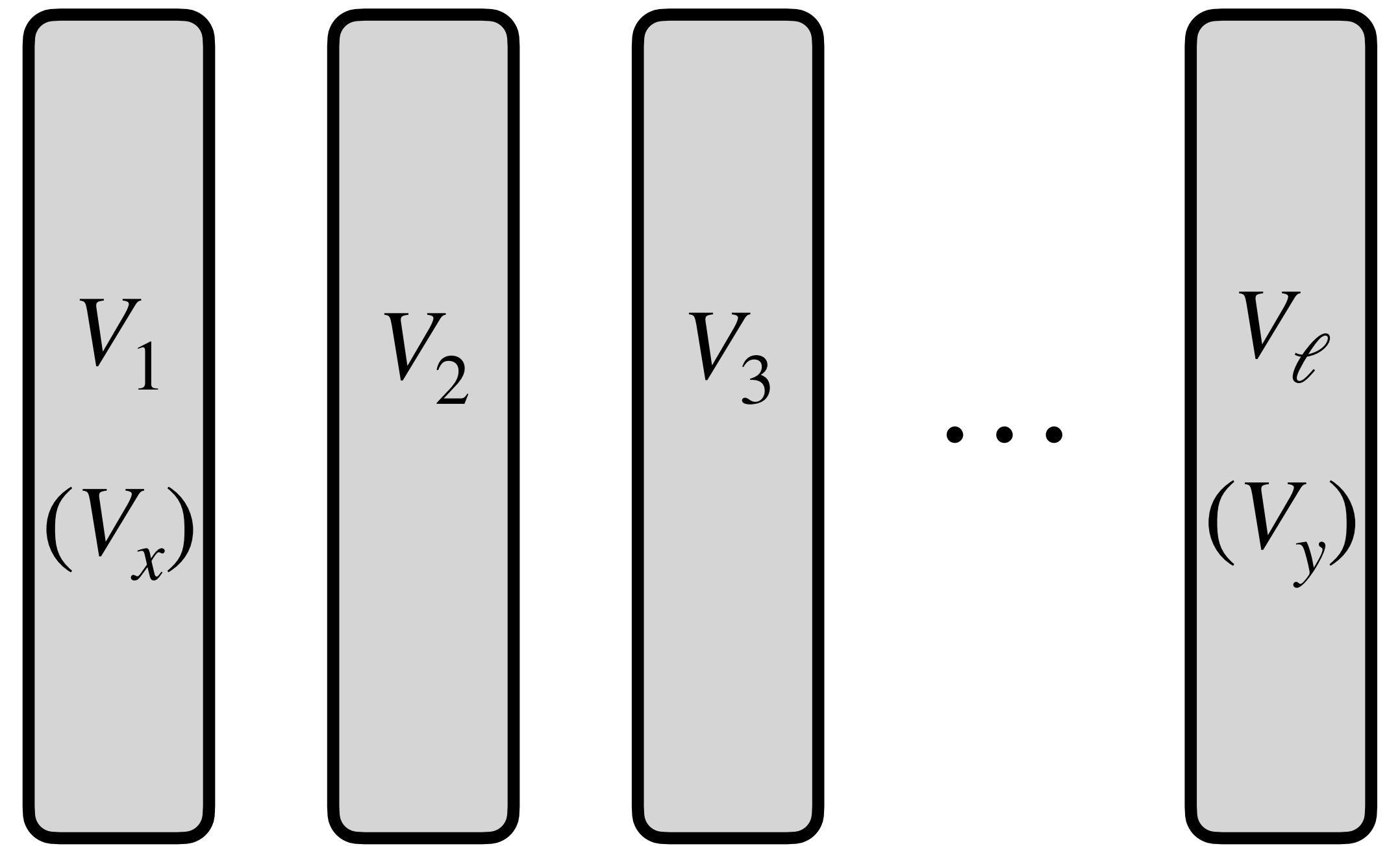


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- But we were aiming for $\Omega(m \cdot D)$ which can be as large as n^3 .
- $G_{x,y}$ as described has constant diameter.
- Can we “stretch” the graph to get a higher lower bound?

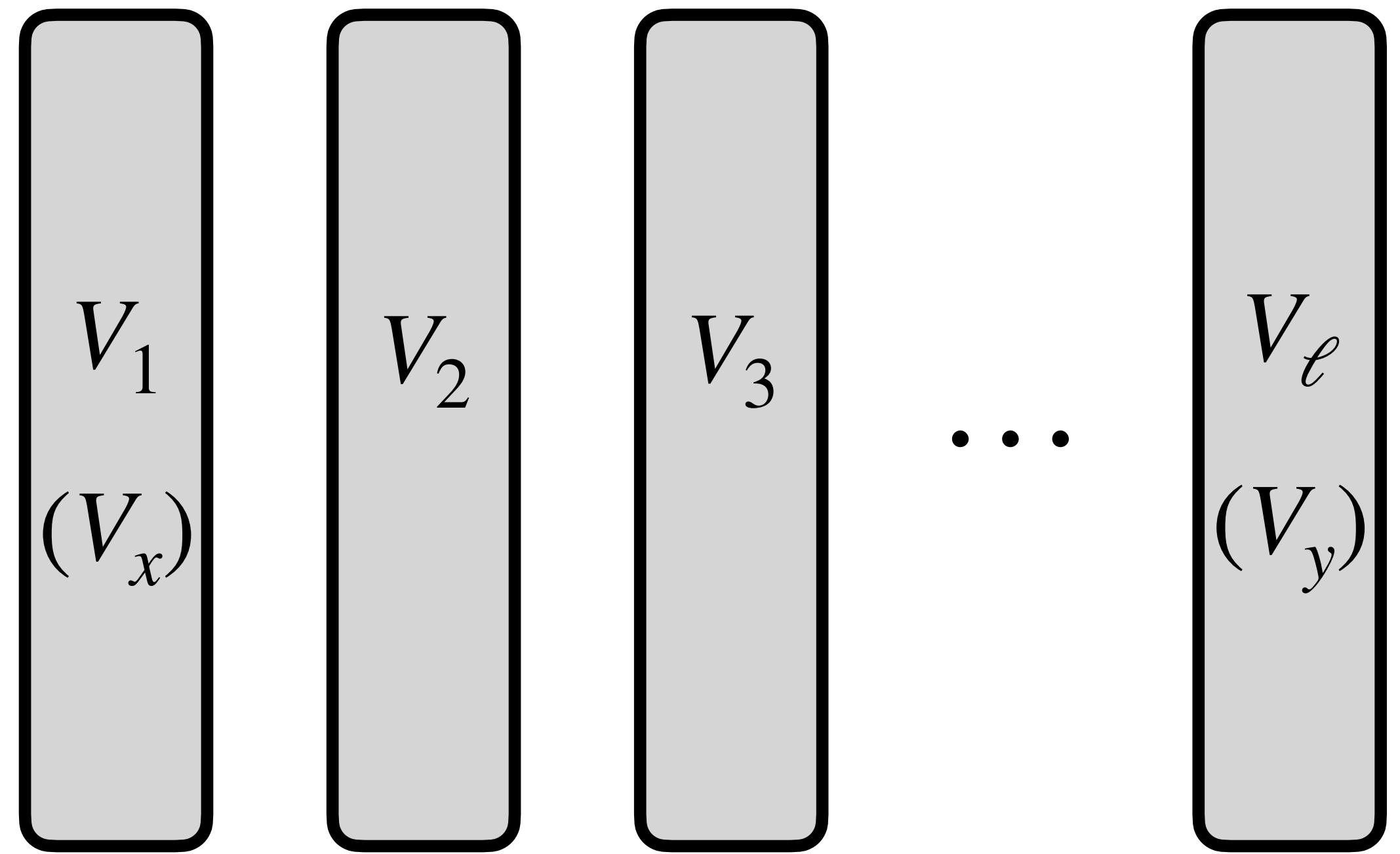


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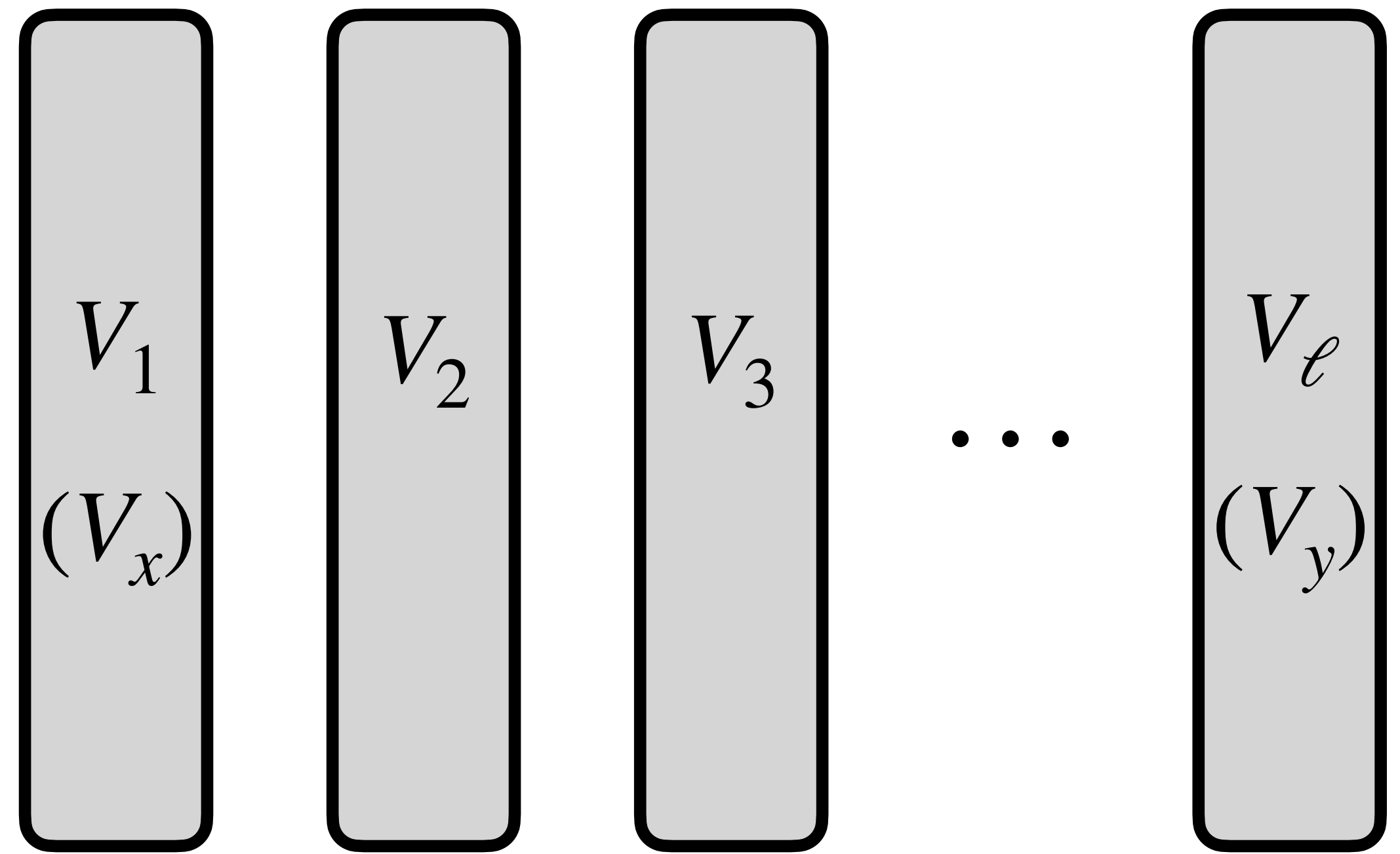
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- Instead of two parts, we have ℓ parts.



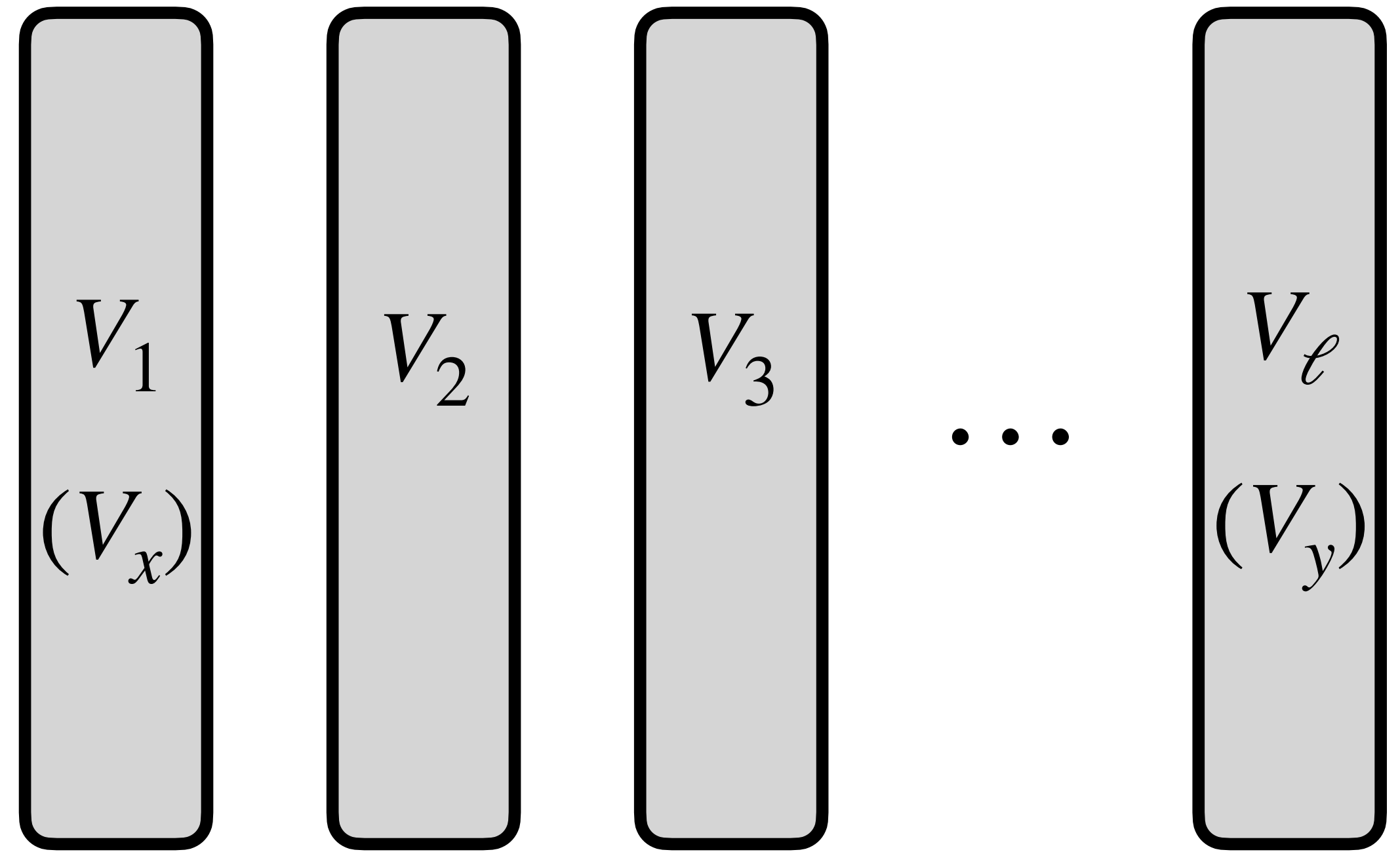
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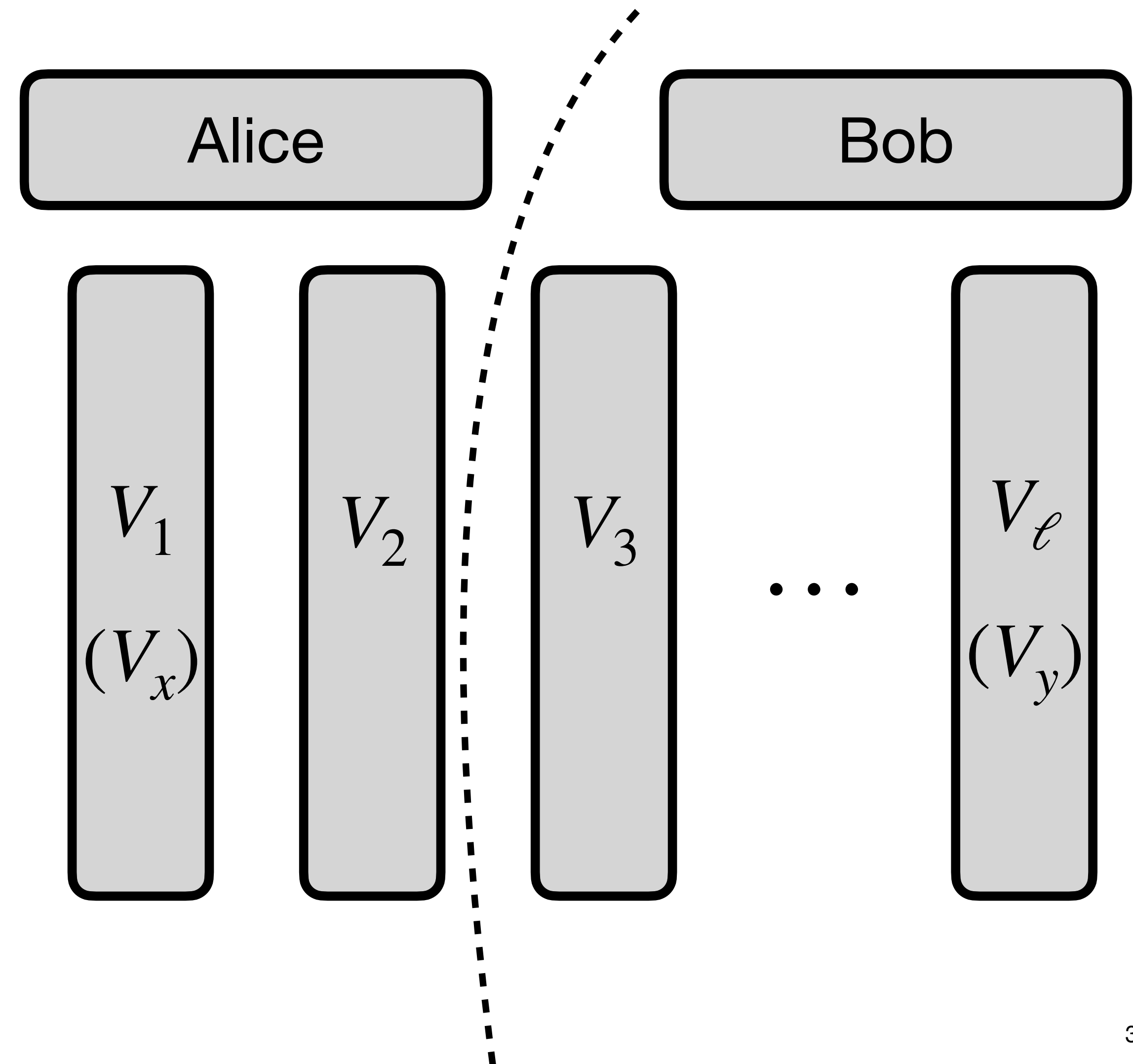
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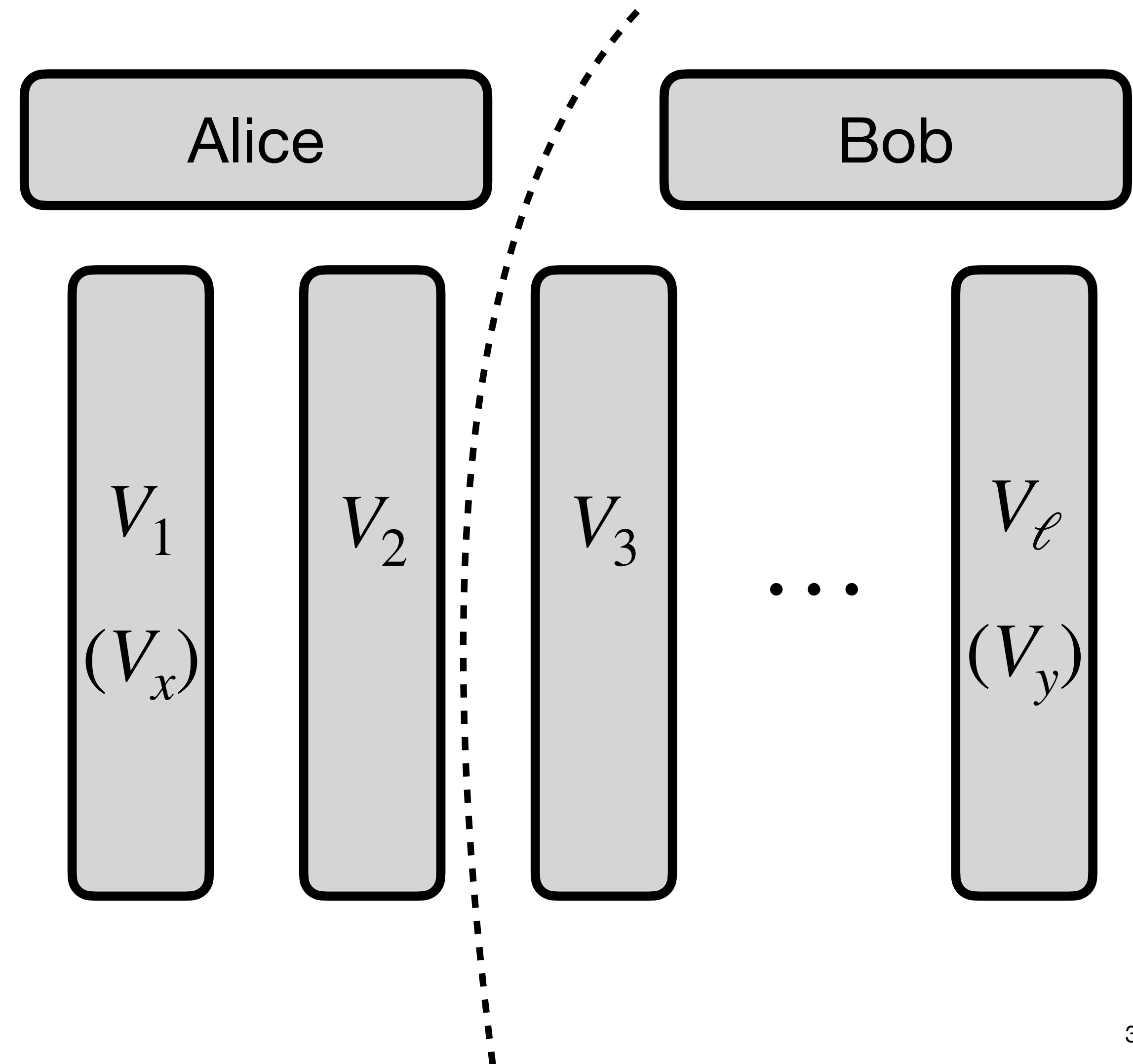
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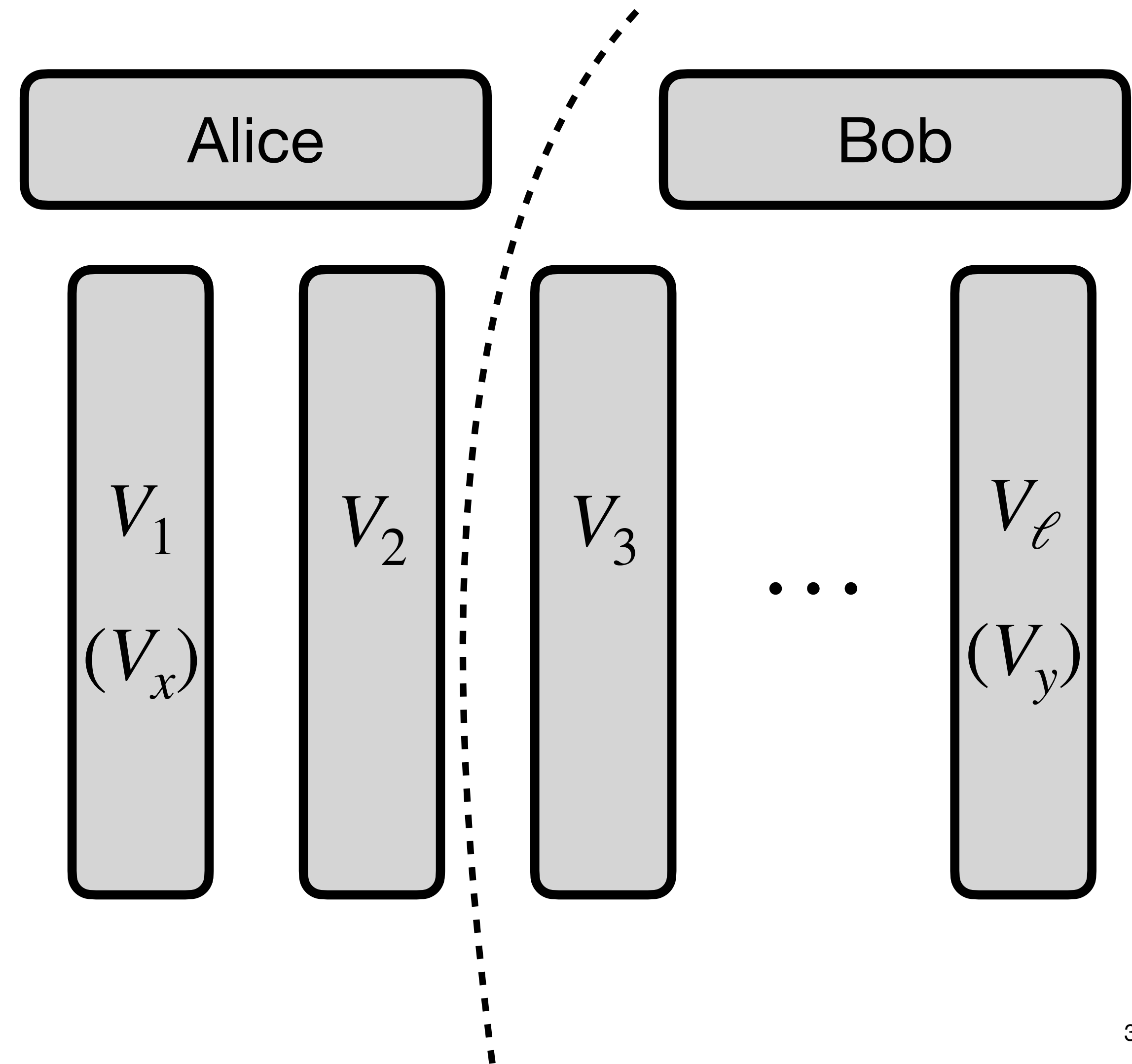


Message Complexity of MVC

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- Message complexity will be increased by an ℓ factor!

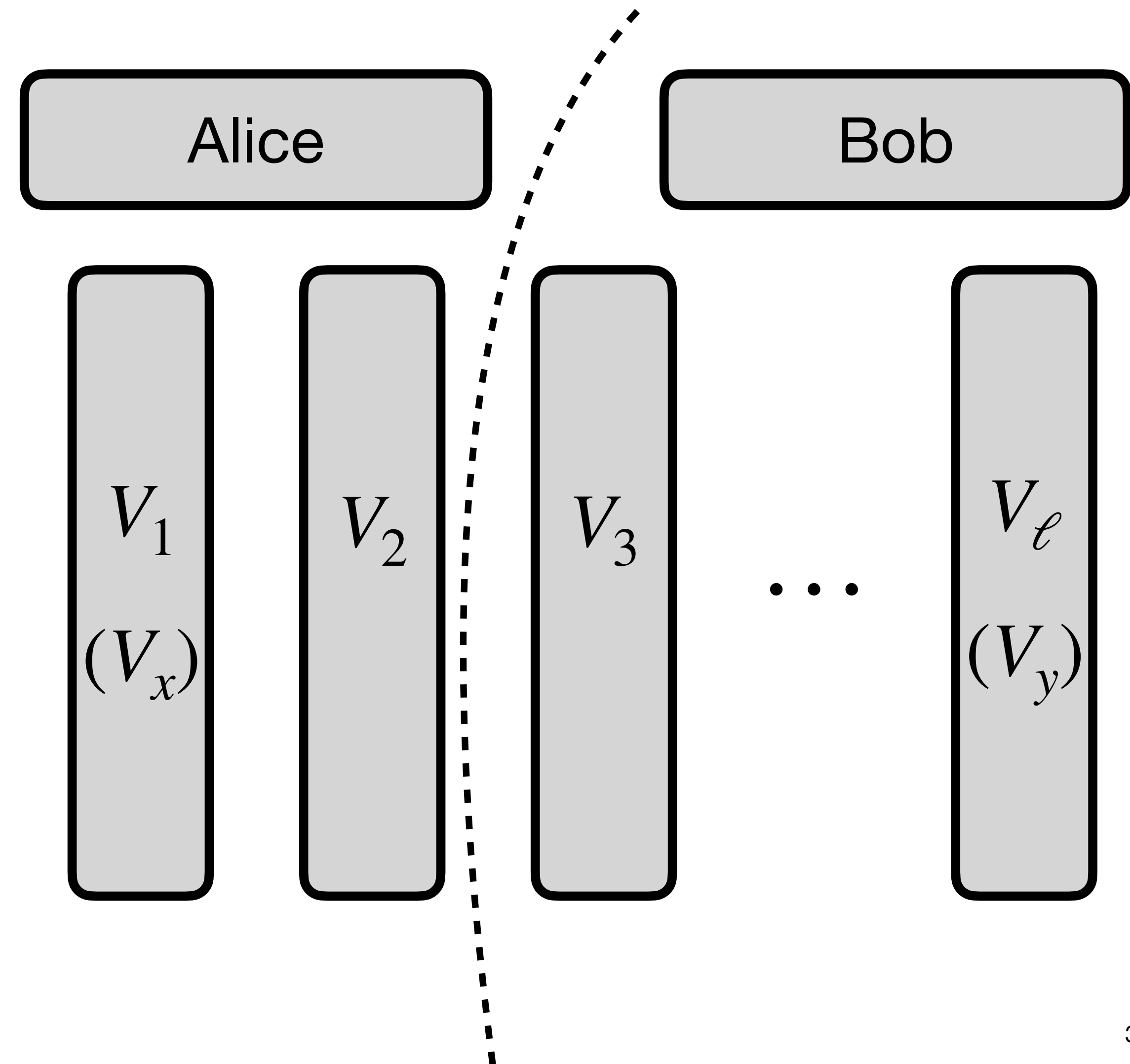


Message Complexity of MVC



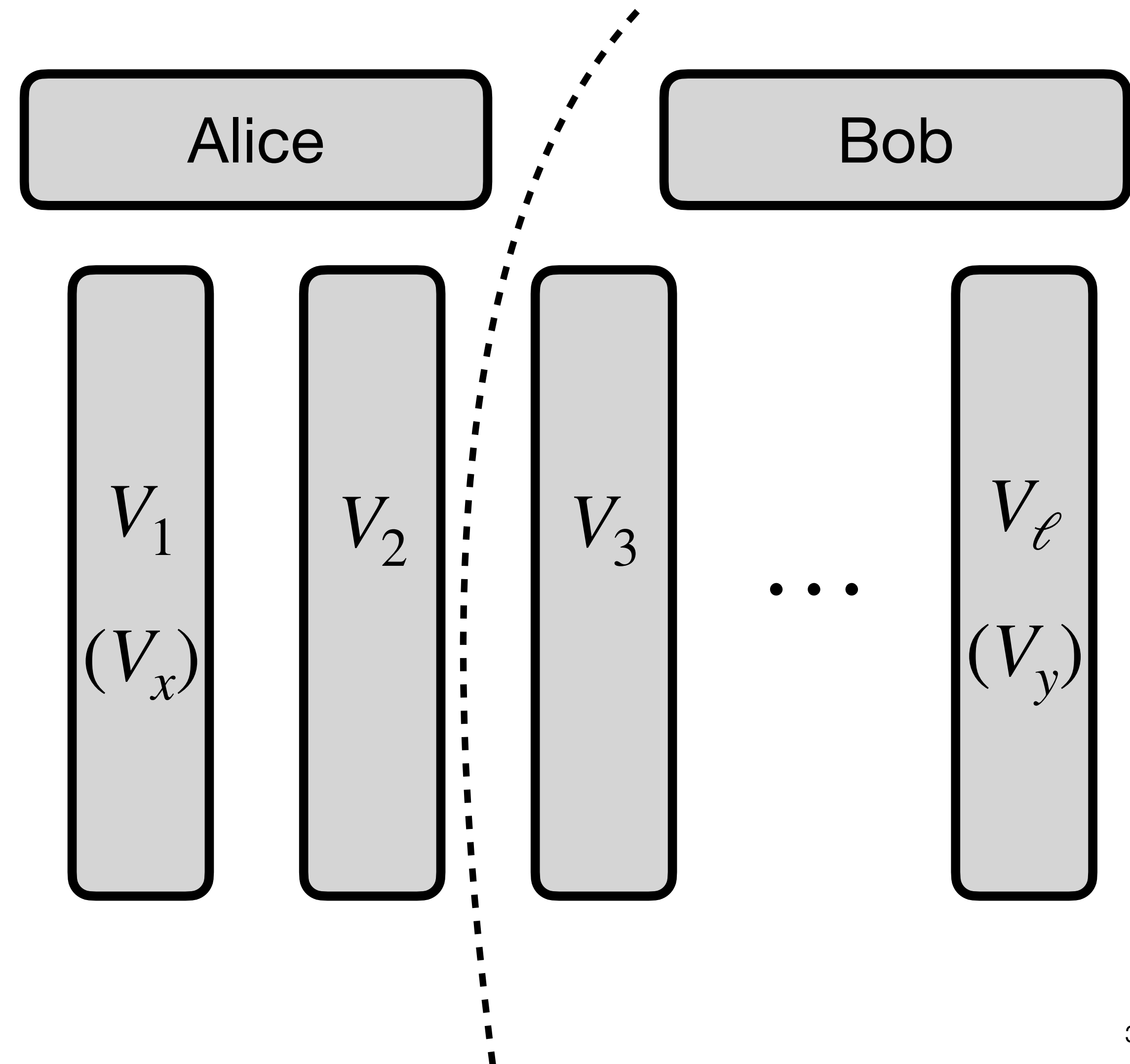
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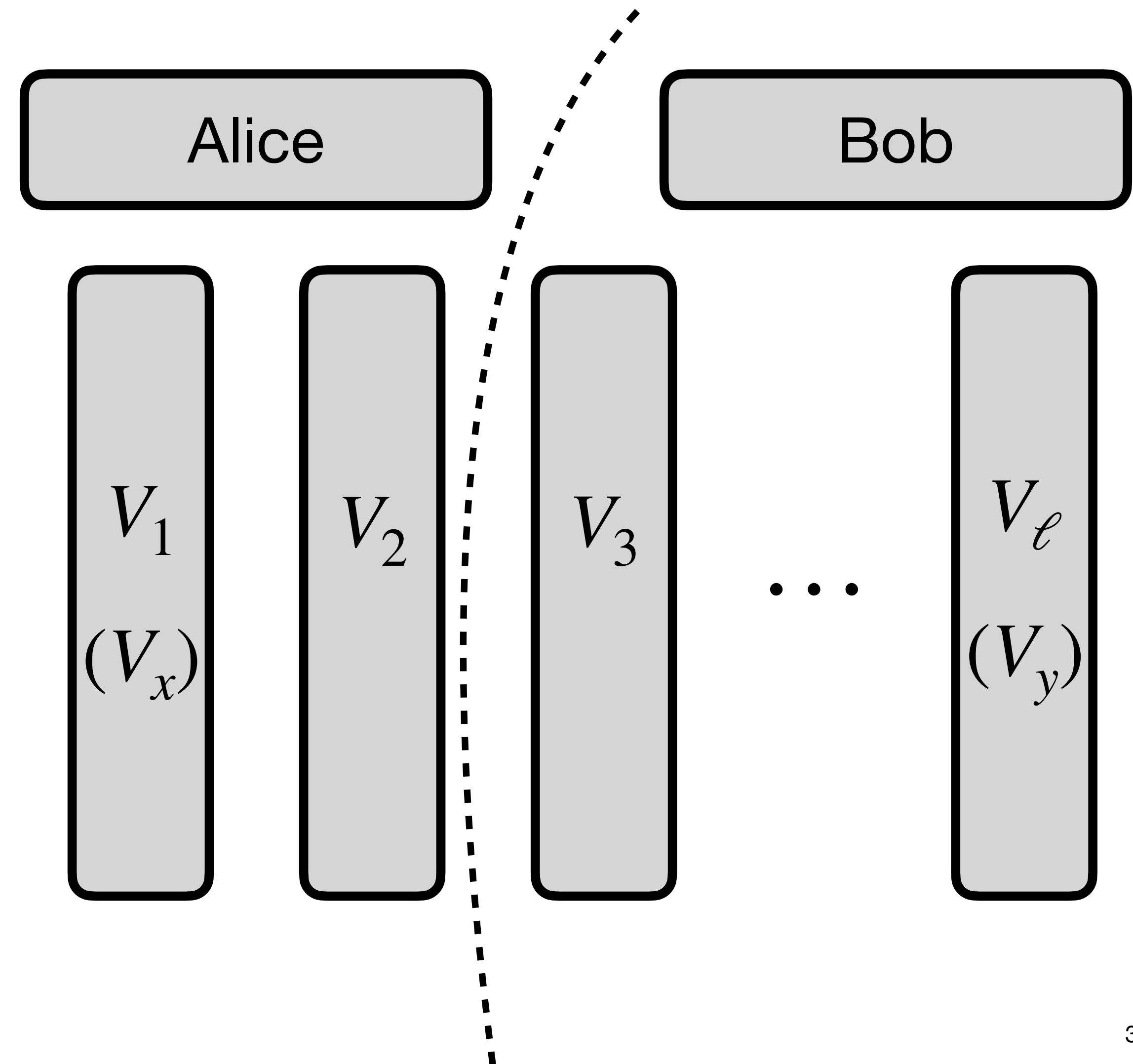
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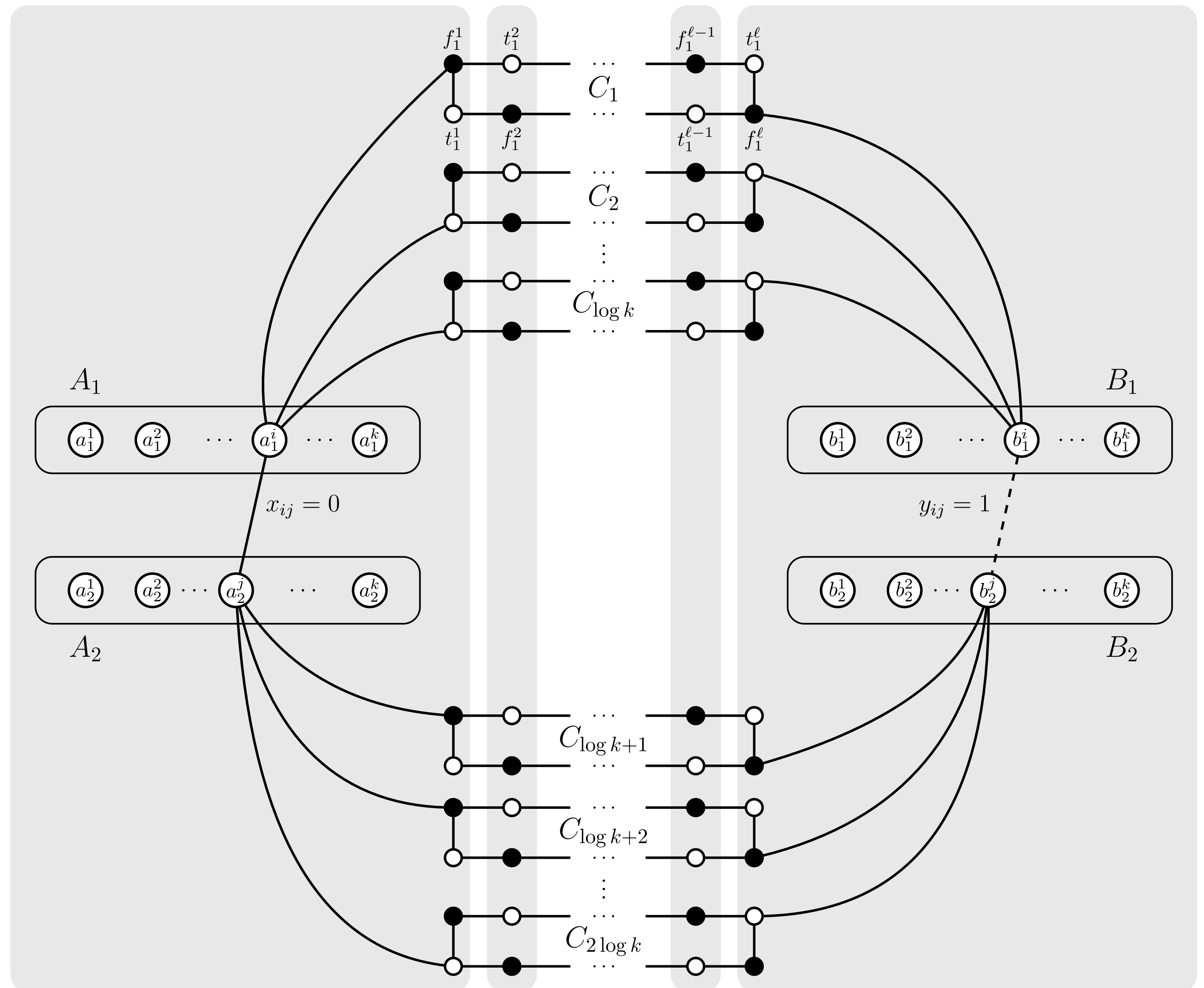
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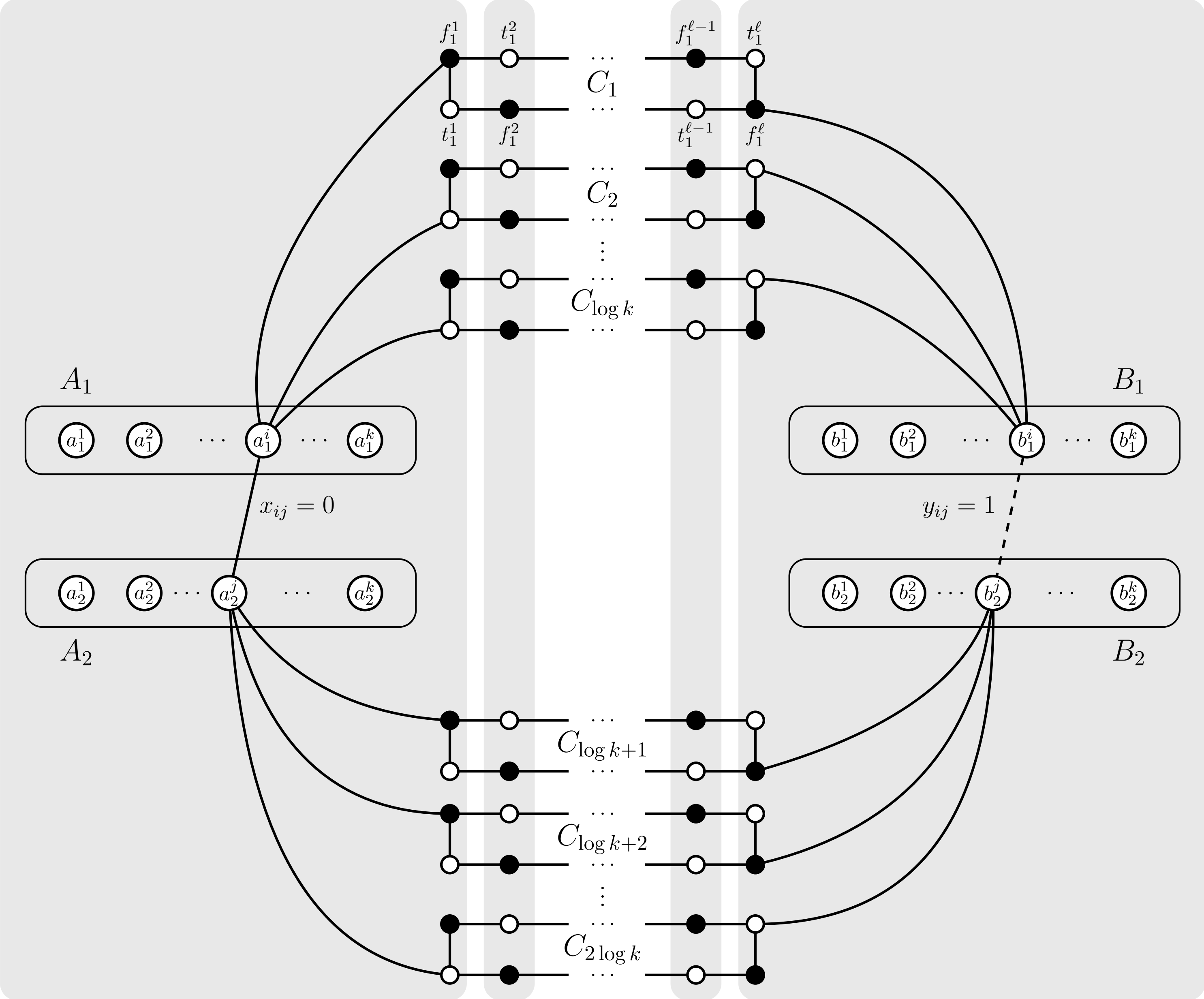
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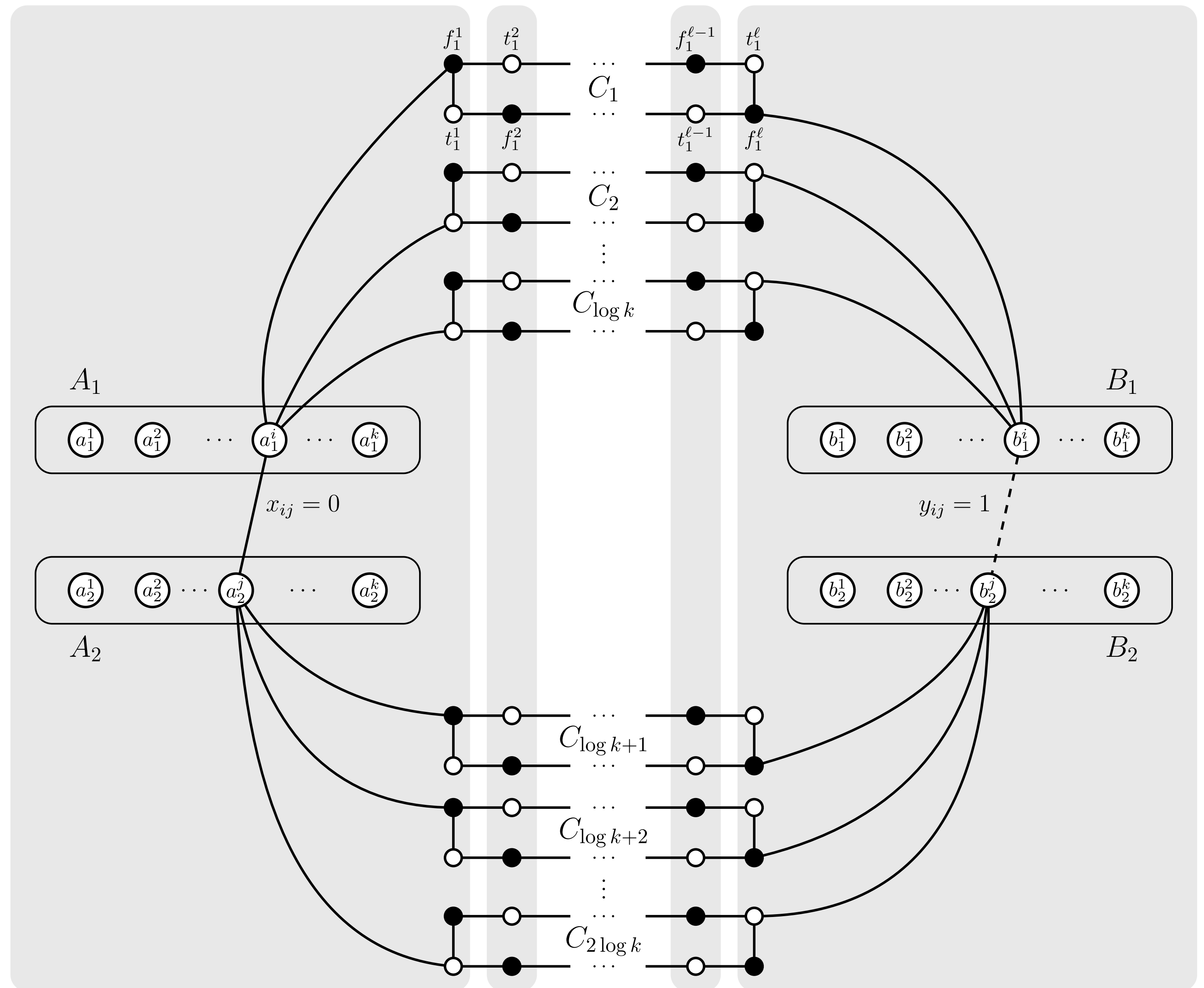


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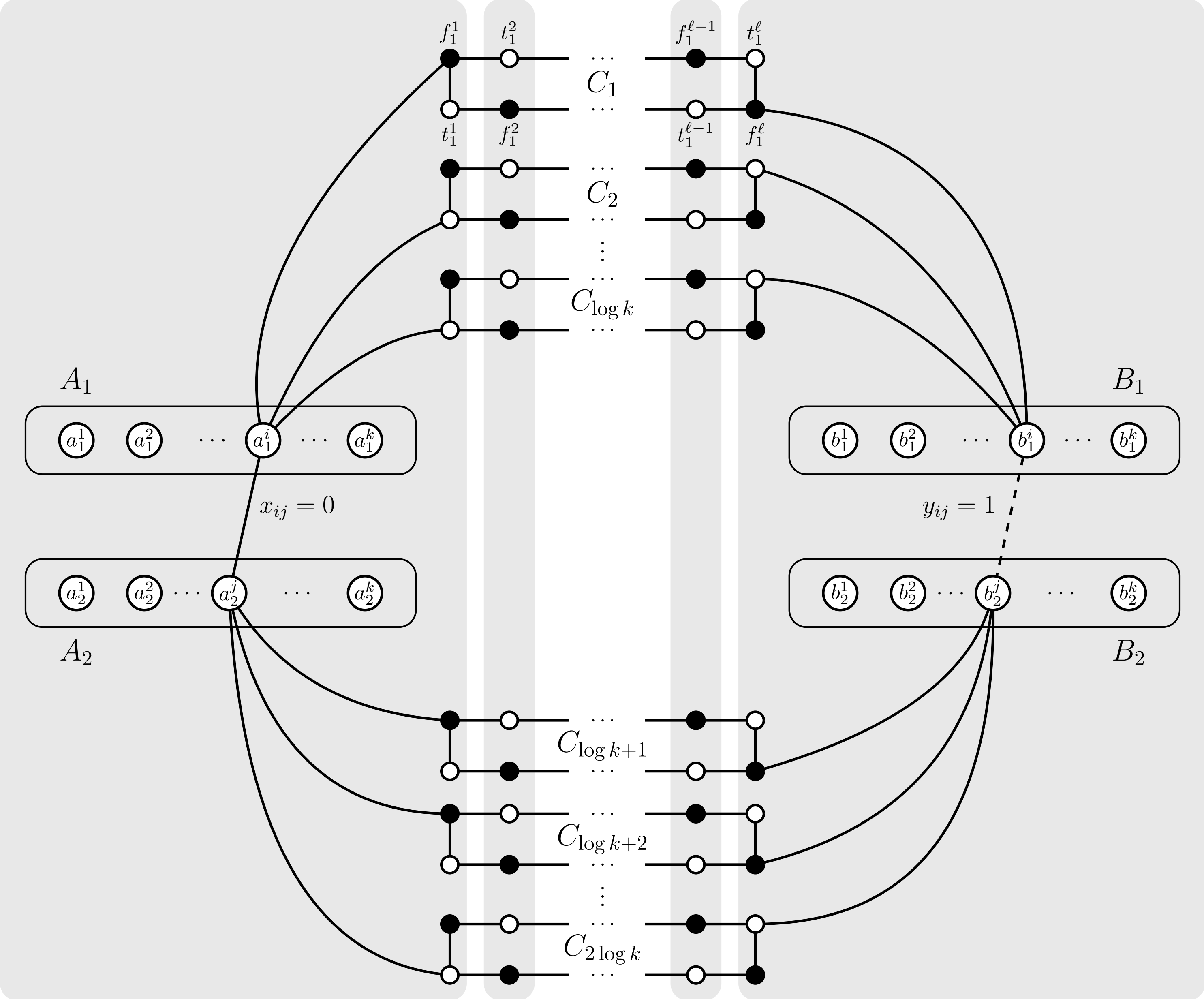
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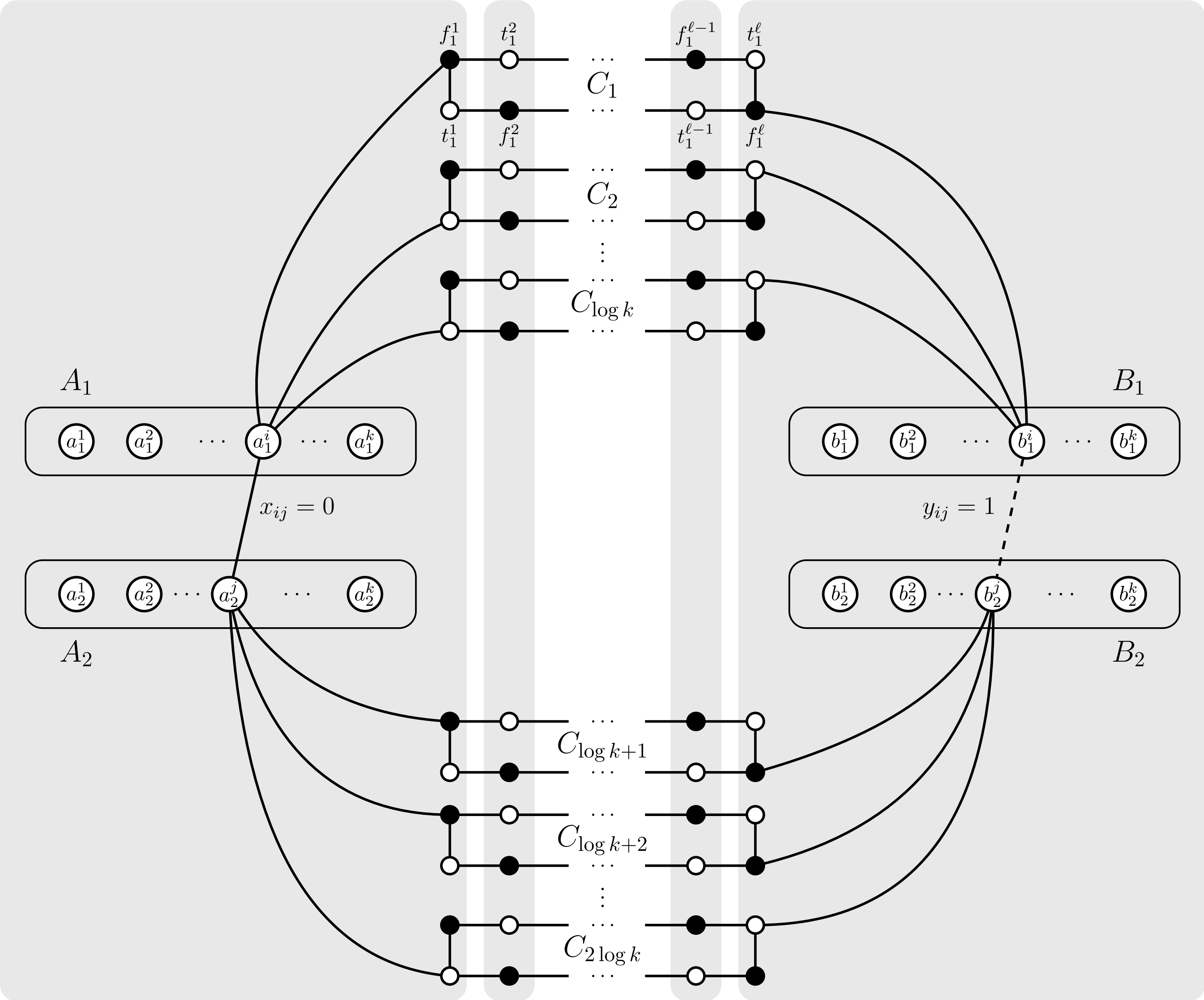


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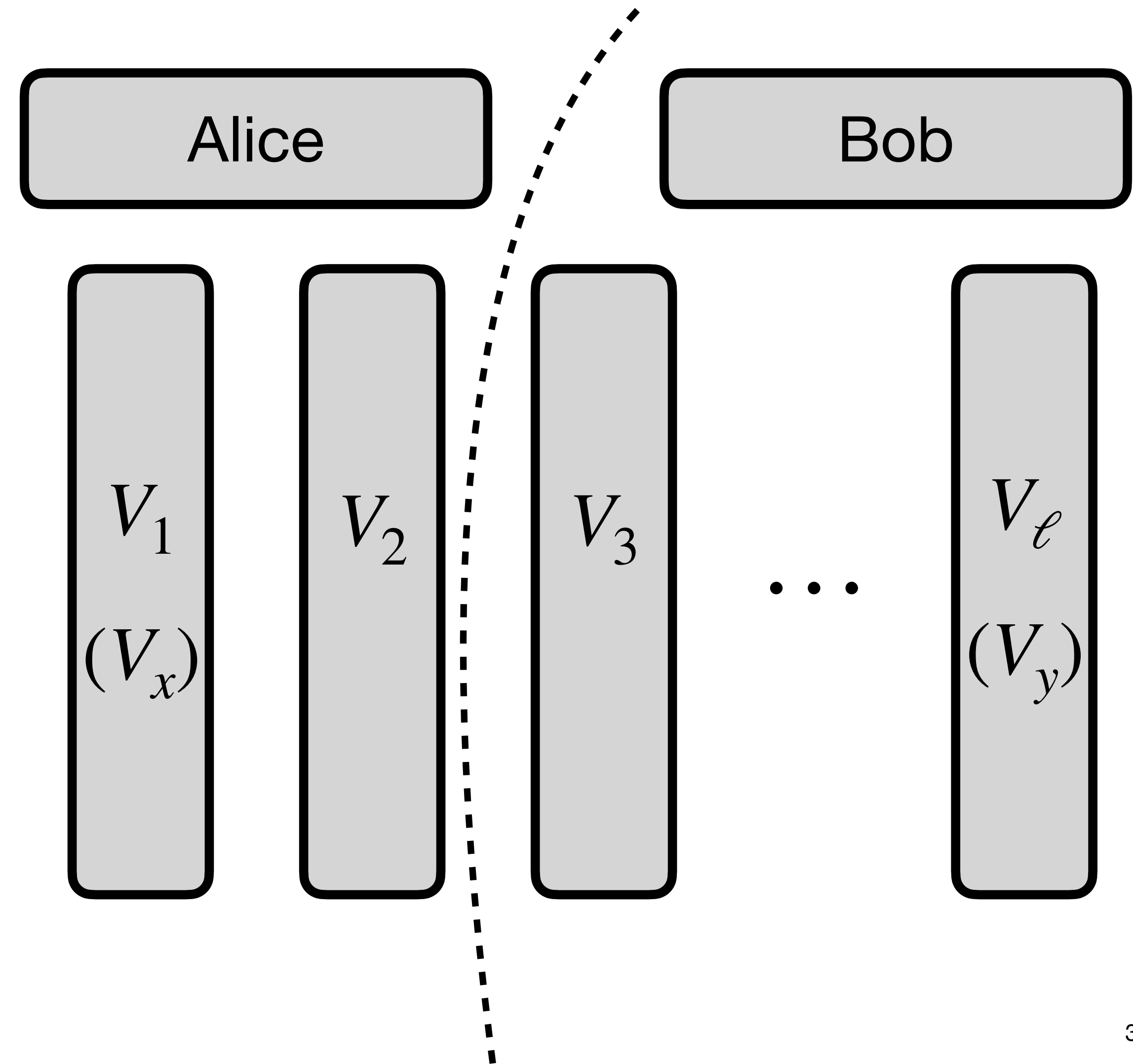
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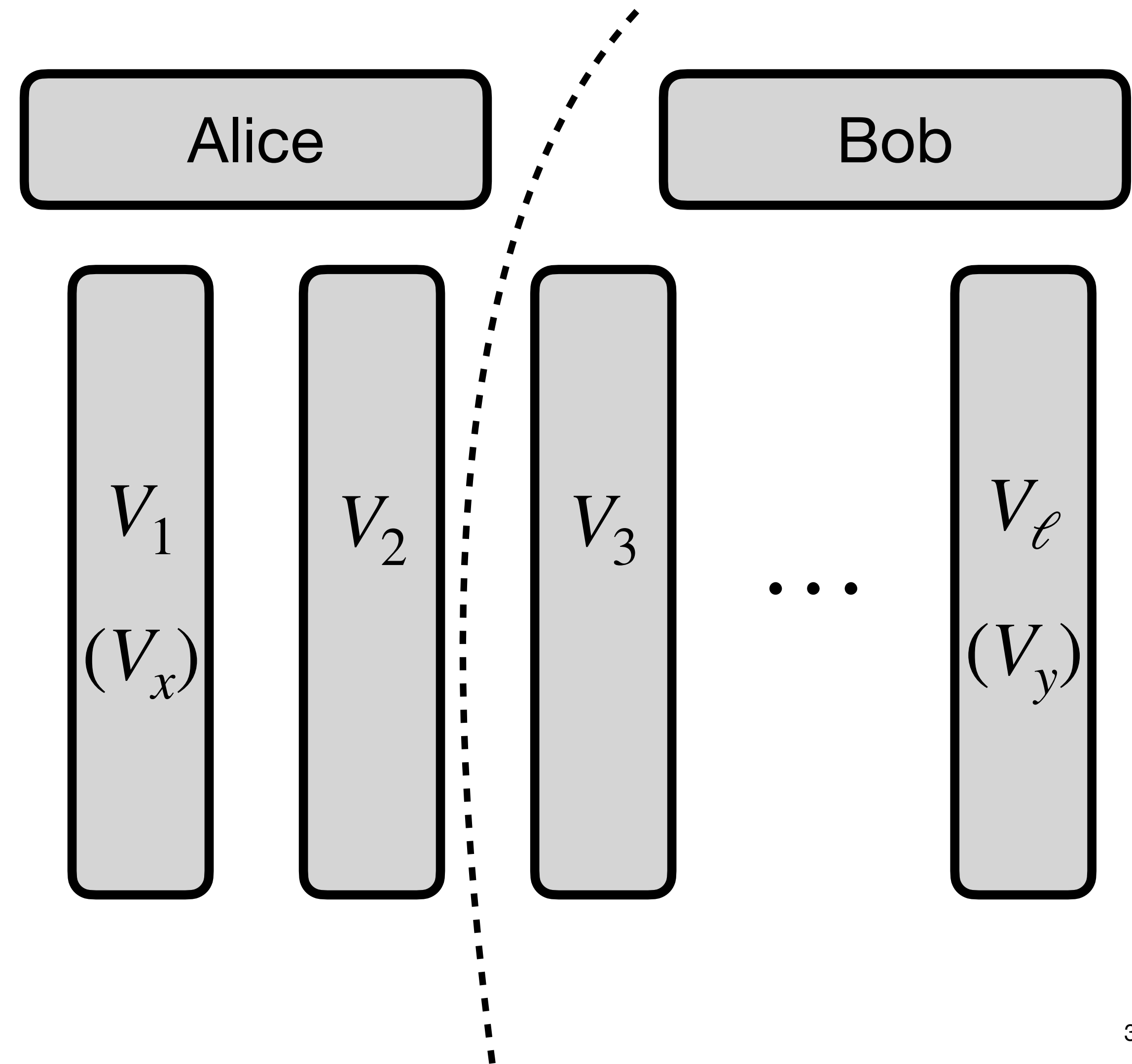


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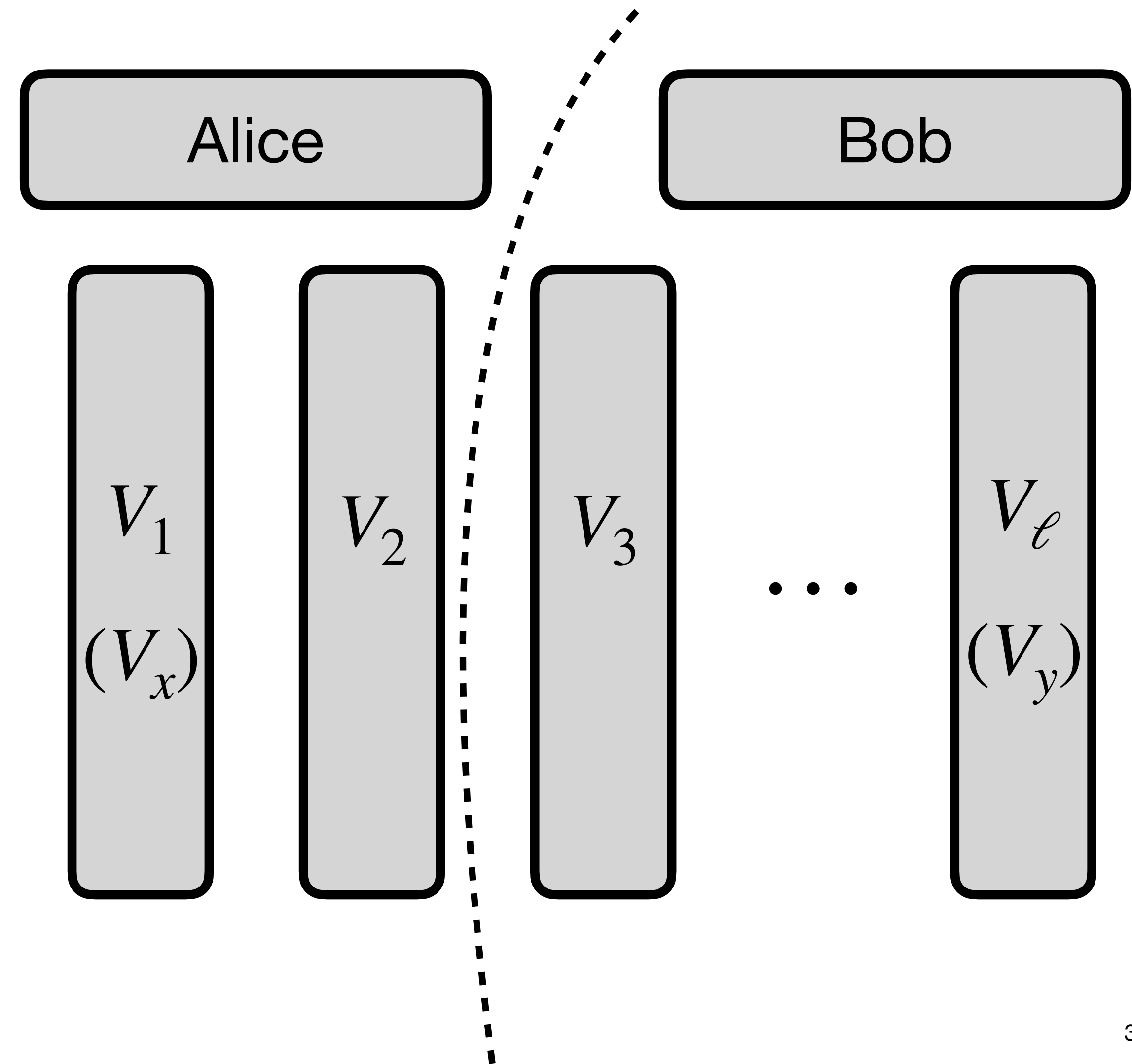
Message Complexity of MVC

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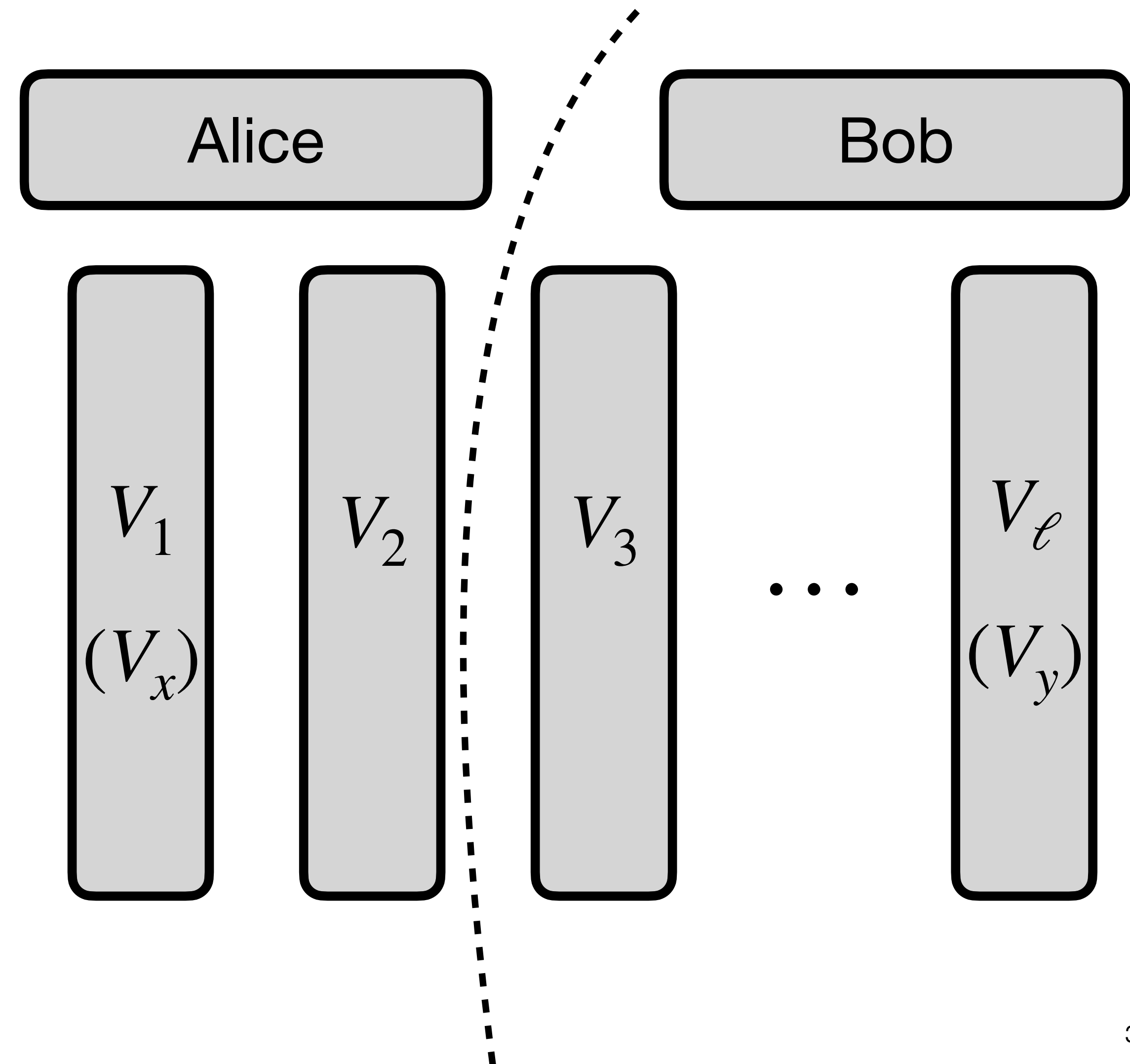
Message Complexity of MVC

- Alice and Bob first construct $G_{x,y}$
- Then they pick an $i \in \{1, \dots, \ell - 1\}$ uniformly at random.

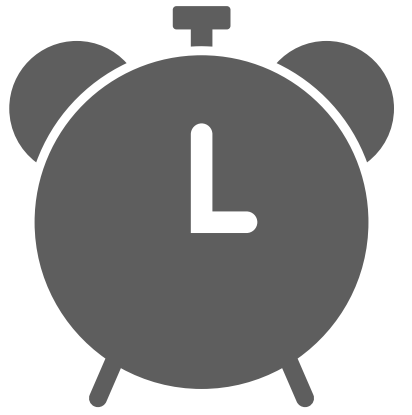


Message Complexity of MVC

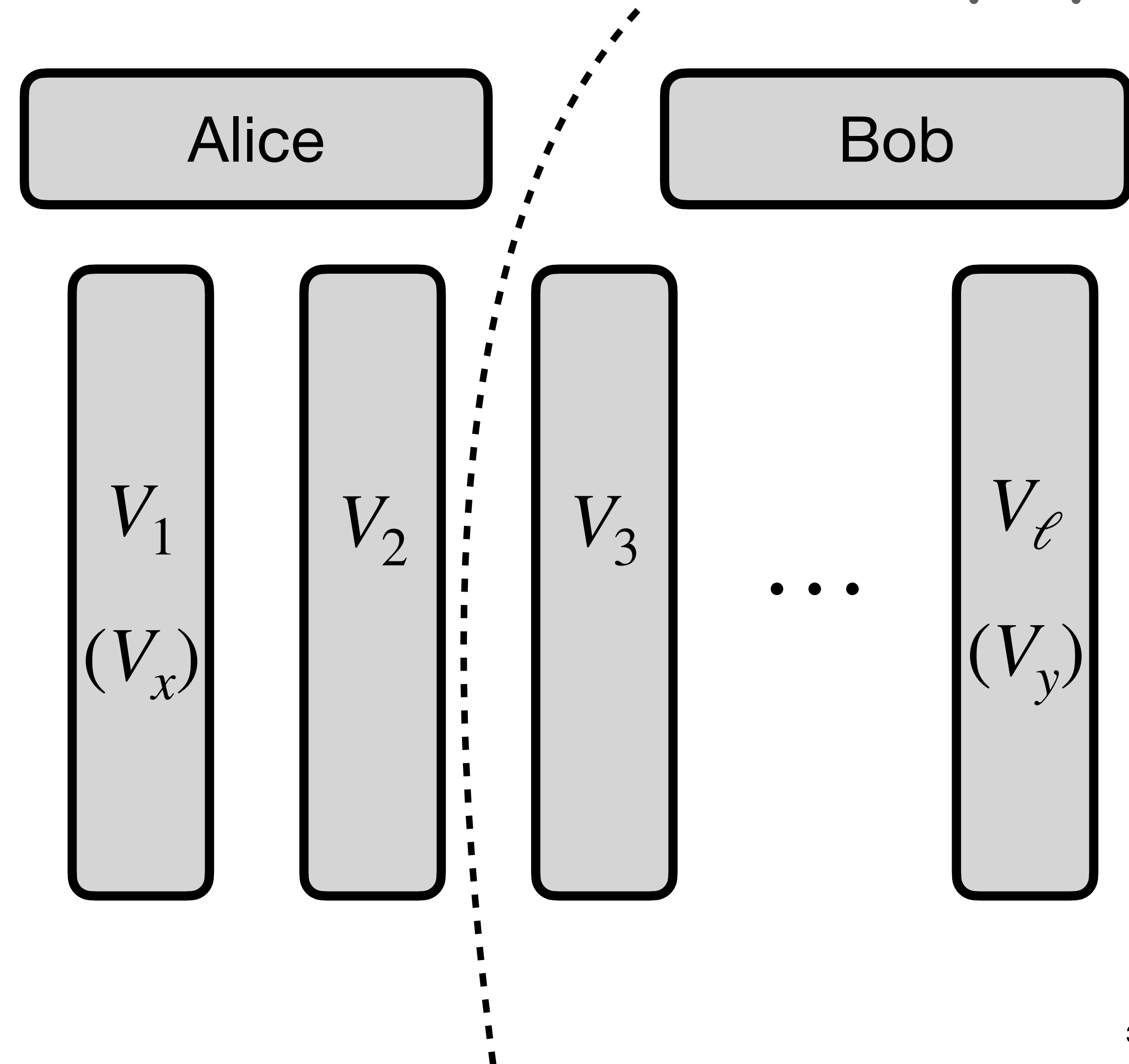
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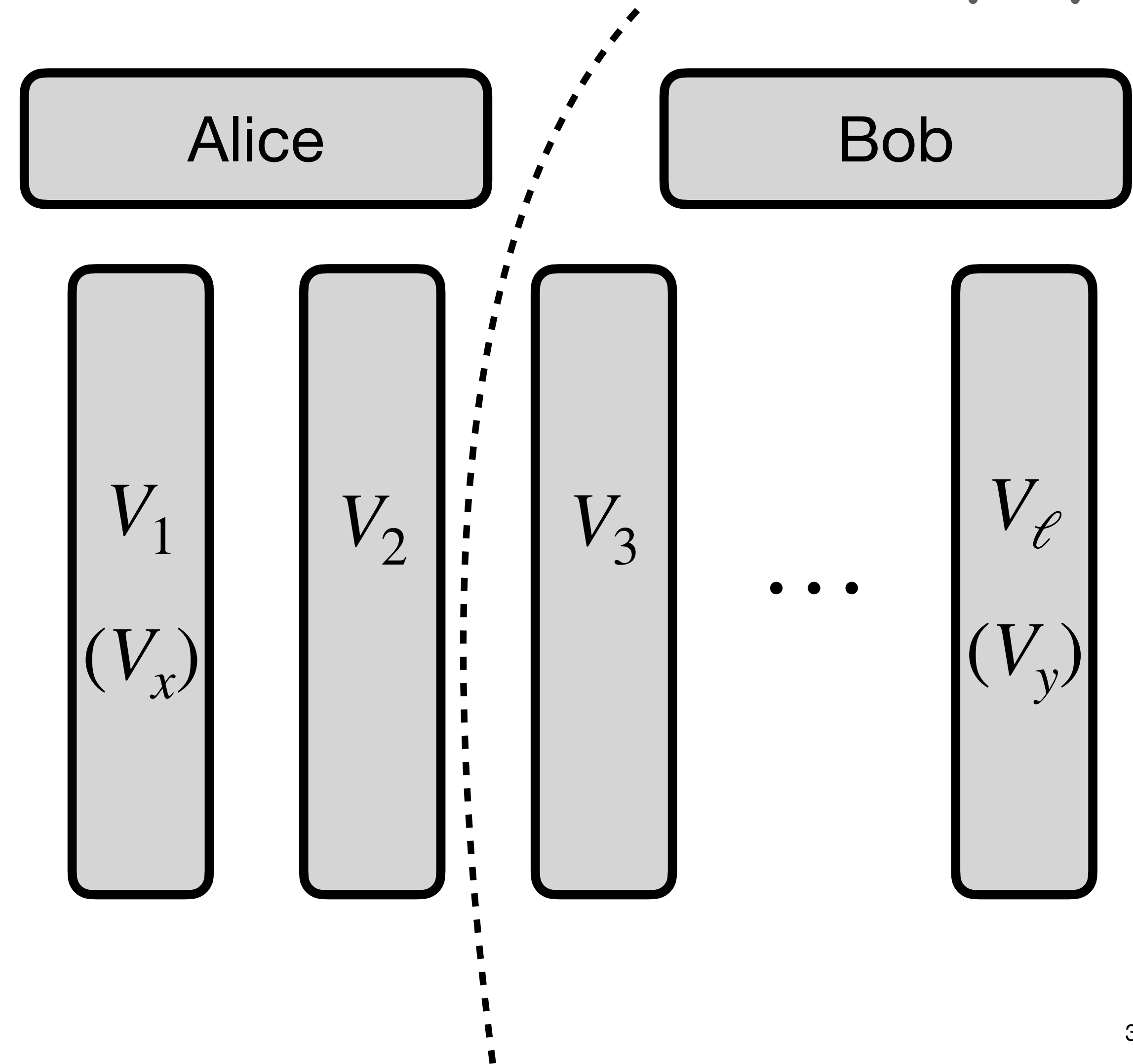
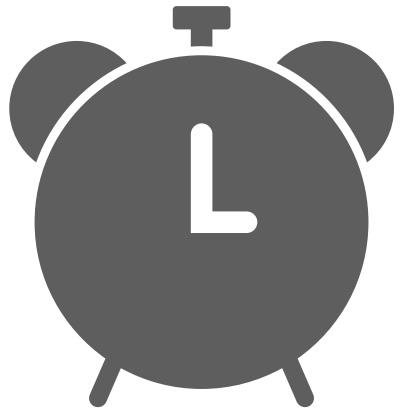
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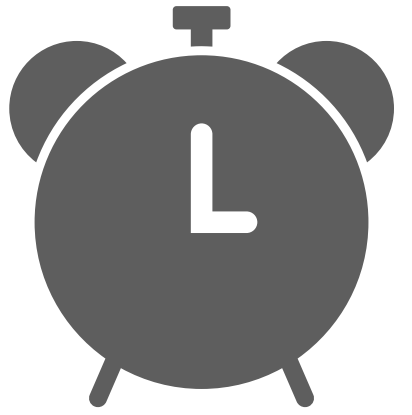
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 - Use synchronous clock for efficient simulation.



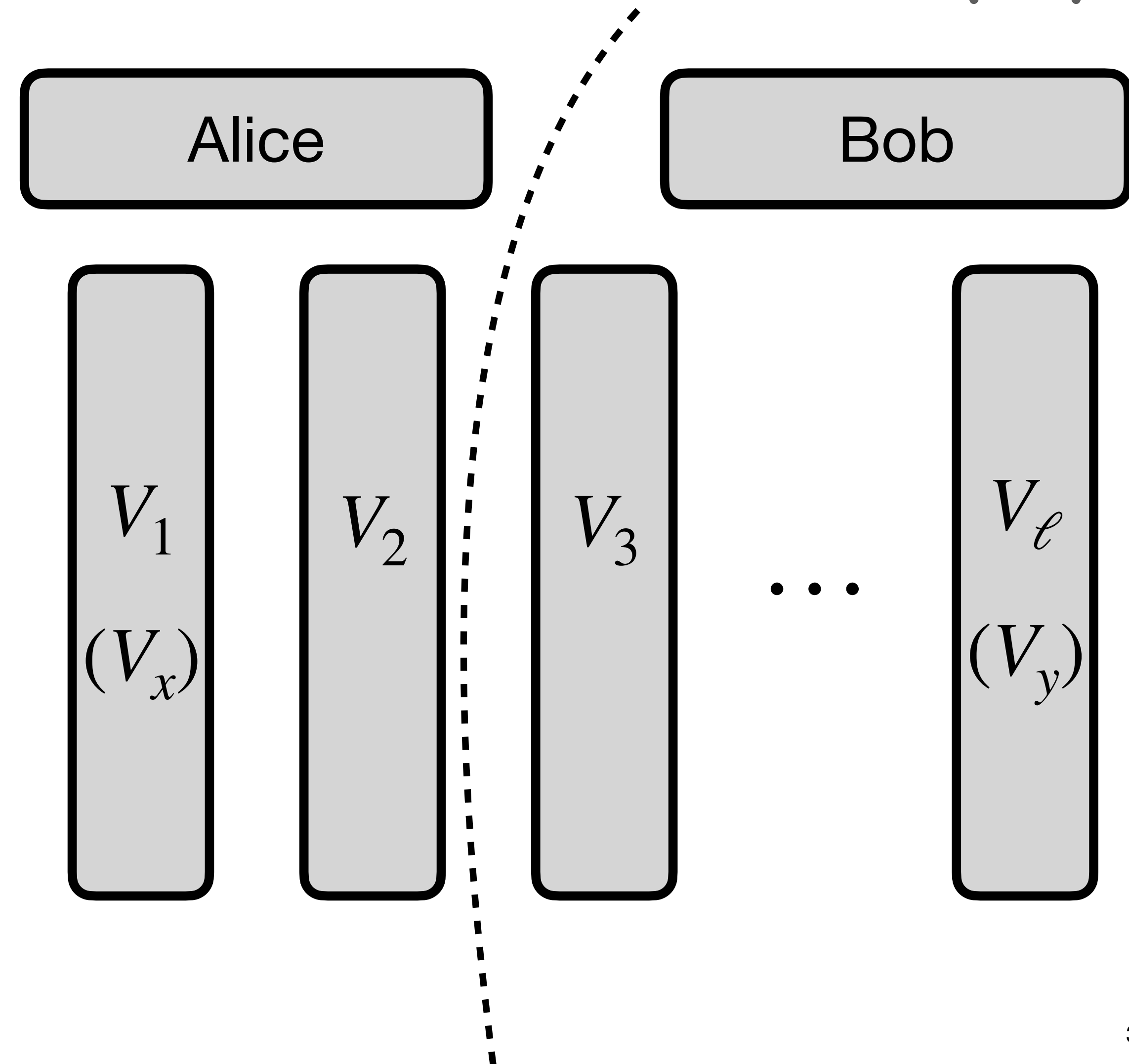
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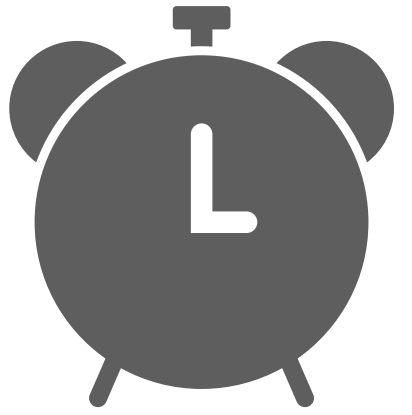
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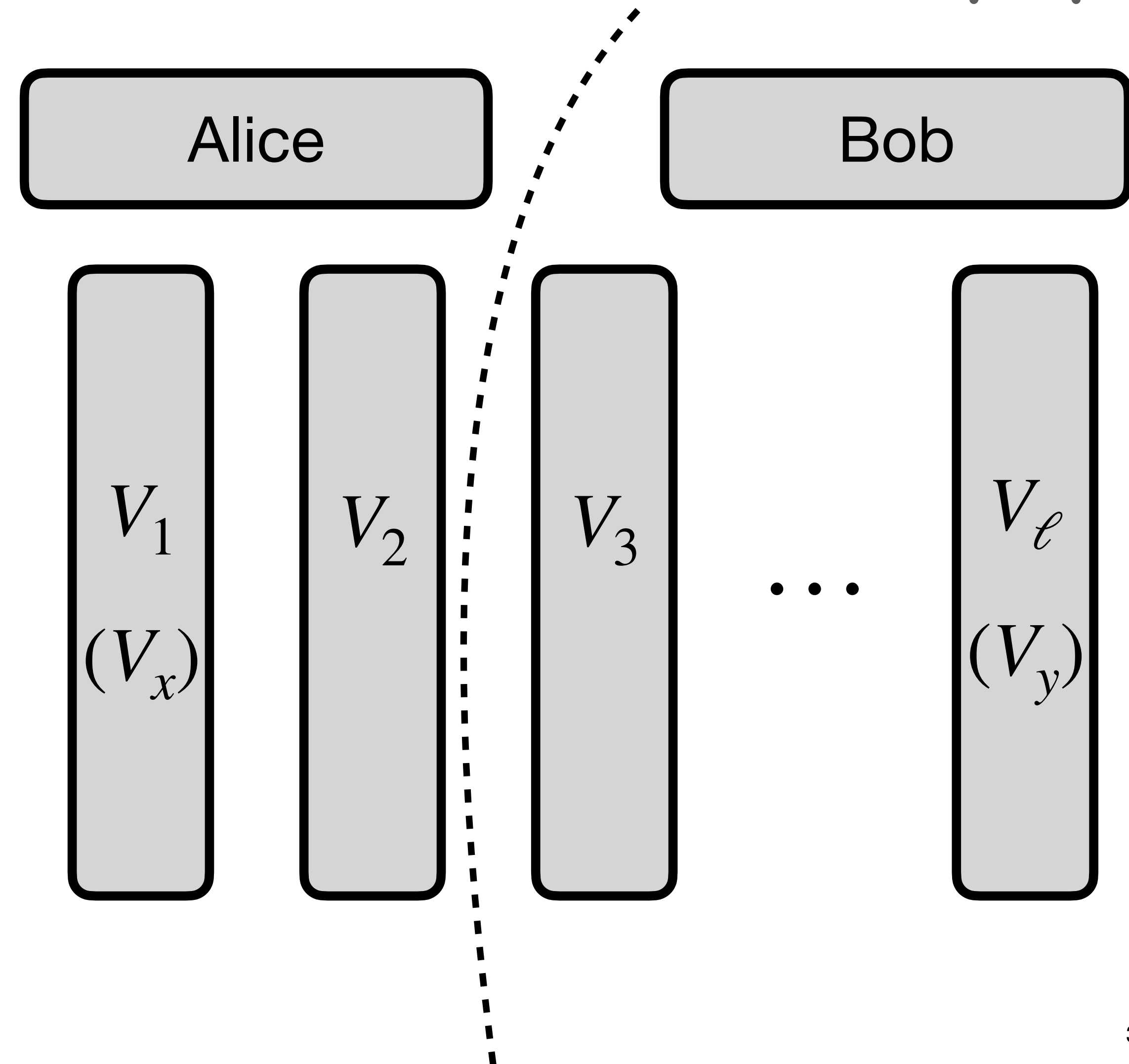


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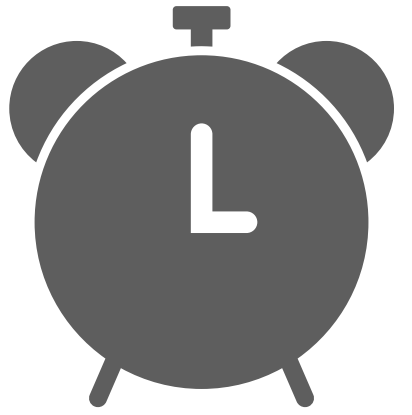


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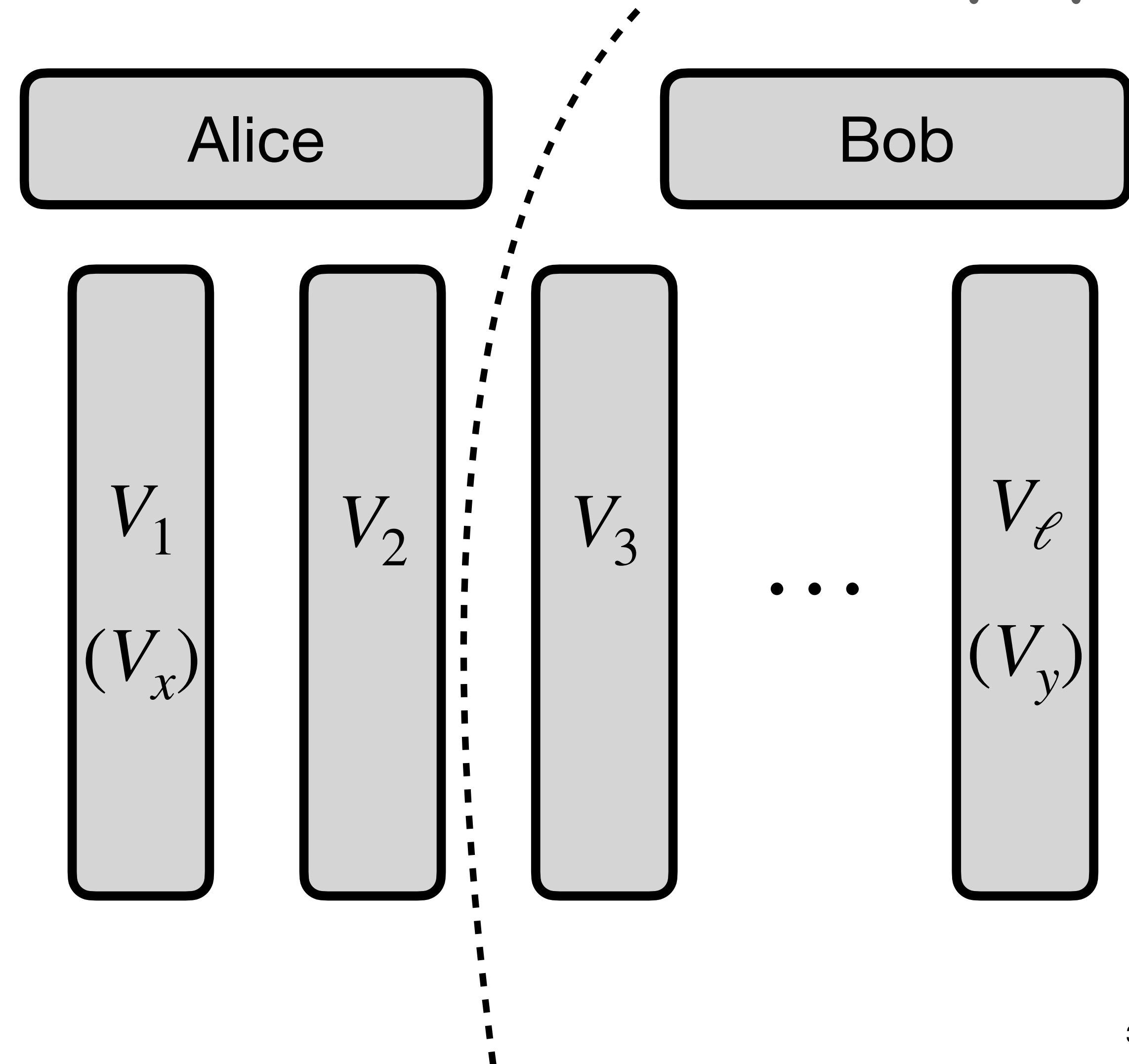
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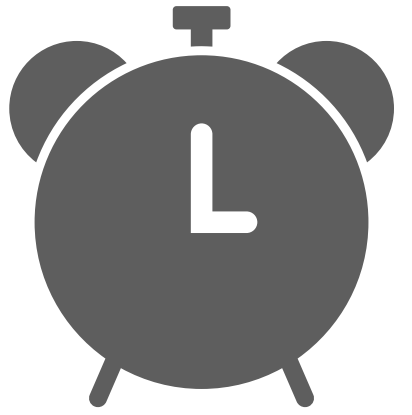
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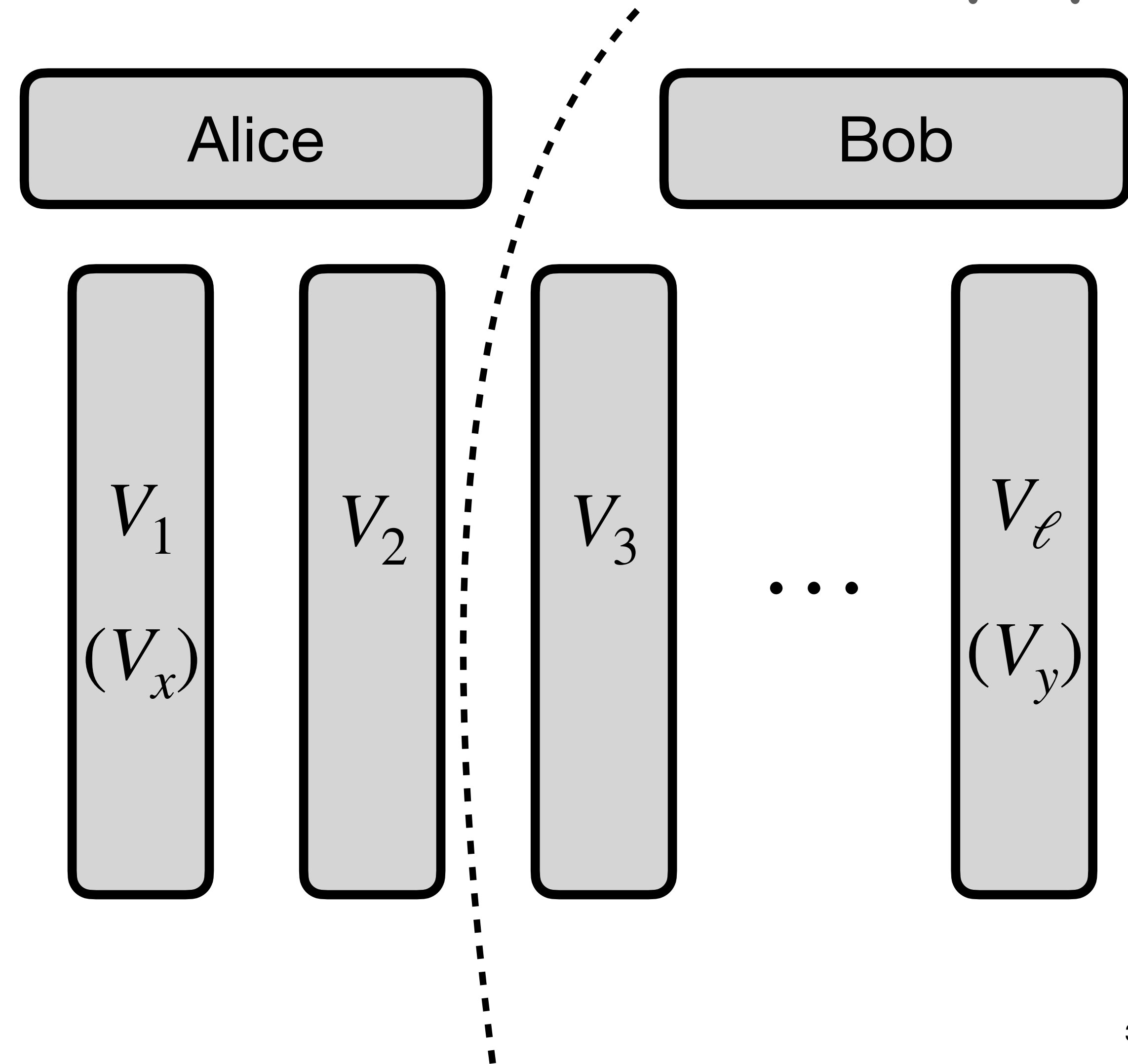


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$$\text{Message complexity} = \tilde{\Omega}\left(\frac{\ell \cdot k^2}{1 + \log r}\right)$$



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- This will give a cubic lower bound for ρ as large as $O(n/\log n)$.

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- What other problems require $\Omega(n^3)$ messages?
- What about Maximum Matching?
 - Can we get an $O(n^2)$ message algorithm with reasonable round complexity?

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Time for Questions